

A NEARLY-TIGHT SUM-OF-SQUARES LOWER BOUND FOR PLANTED CLIQUE

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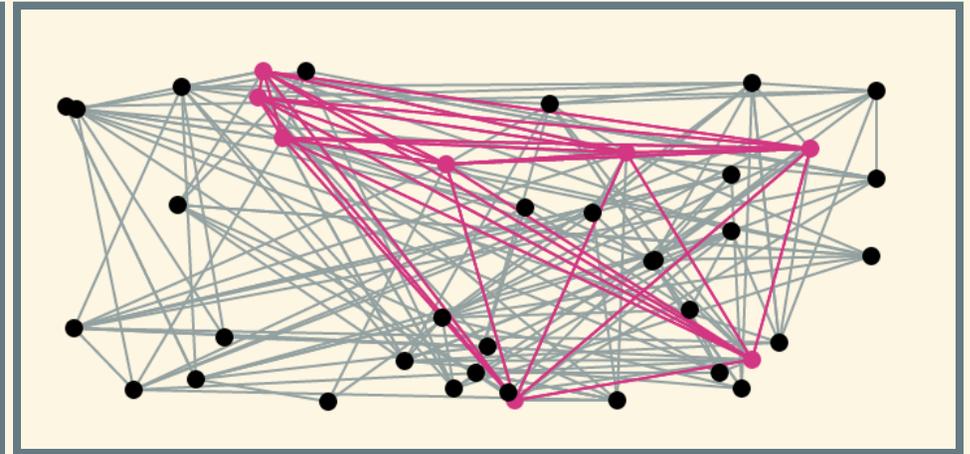
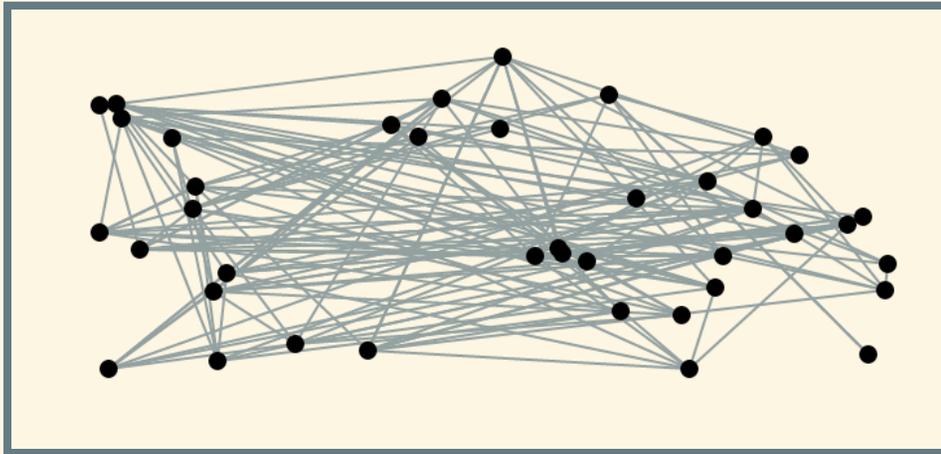
PLANTED CLIQUE ("DISTINGUISHING")

Input: graph G

Goal: determine (with high probability) whether

$G \sim \mathbb{G} \left(n, \frac{1}{2} \right)$ ("random distribution"), or

$G \sim \mathbb{G} \left(n, \frac{1}{2} \right) + k\text{-clique}$ ("planted distribution").



FOR WHAT k IS THIS POSSIBLE IN POLYNOMIAL TIME?

BASICS

$k = O(1)$: information-theoretically-impossible

BRUTE FORCE

$k > \max \text{clique in } \mathbb{G} \left(n, \frac{1}{2} \right) \approx 2 \log n$ [GM '75, M '76, BE '78]

requires $n^{O(\log n)}$ time ("quasipolynomial")

SPECTRAL (ADJACENCY MATRIX)

$k > \sqrt{n}$, polynomial time [AKS '98]

**HYPOTHESIS: NO POLYNOMIAL-TIME
ALGORITHM FOR $k = n^{0.49}$**

"SPECTRAL IS BEST"

IF SPECTRAL IS BEST, HARDNESS RESULTS GALORE!

Sparse PCA [BR '13]

Compressed Sensing [KZ '14]

Property Testing [AAK+ '07]

Mathematical Finance [DBL '10]

Cryptography [JP '00, ABW '10]

Computational Biology [PS00, MSOI+ '04]

Best Nash Equilibrium [HK '11, ABC '13]

(and $P \neq NP$)

Problems which have:
a distribution on inputs
 $n^{O(\log n)}$ -time algorithms

TO BEAT SPECTRAL SEEMS TO REQUIRE **NEW ALGORITHMIC IDEAS**

WHY BELIEVE SPECTRAL IS BEST?

no algorithmic progress in 20 years?

bad science

reductions? (3SAT \leq planted clique)

distribution on inputs

Rule out large classes of algorithms

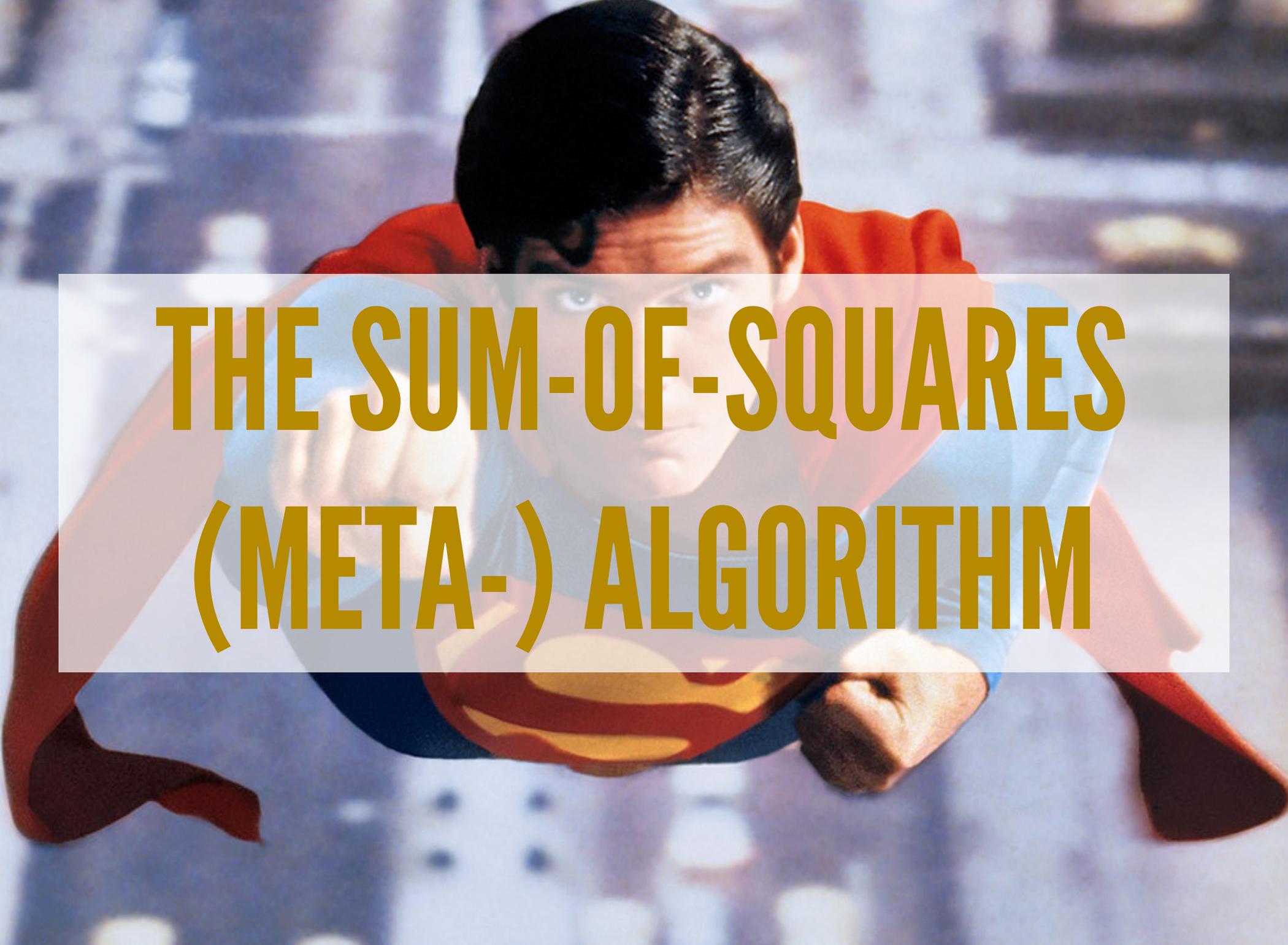
Markov-Chain Monte Carlo [Jerrum '93]

Lovasz-Schrijver+ Convex Hierarchy [Feige-Krauthgamer '04]

Statistical Algorithms [Feldman et al '12]

All do not beat spectral

WHY BELIEVE SPECTRAL COULD BE BEATEN?

A photograph of Superman flying over a city. He is wearing his iconic blue suit with a red and yellow 'S' on the chest and a red cape. He is looking forward with a determined expression. The background is a blurred cityscape with buildings and streets.

THE SUM-OF-SQUARES (META-) ALGORITHM

Generalization of linear programming, basic semidefinite programming, spectral algorithms

Optimal among all (poly-sized) SDPs for constraint satisfaction [LRS '15]

Solves all known hard instances of *unique games*, *max cut* in polynomial time [BBHKSZ '12, OZ '13, DMN '12]

Best known algorithm for many *planted problems*, beating corresponding spectral algorithms!

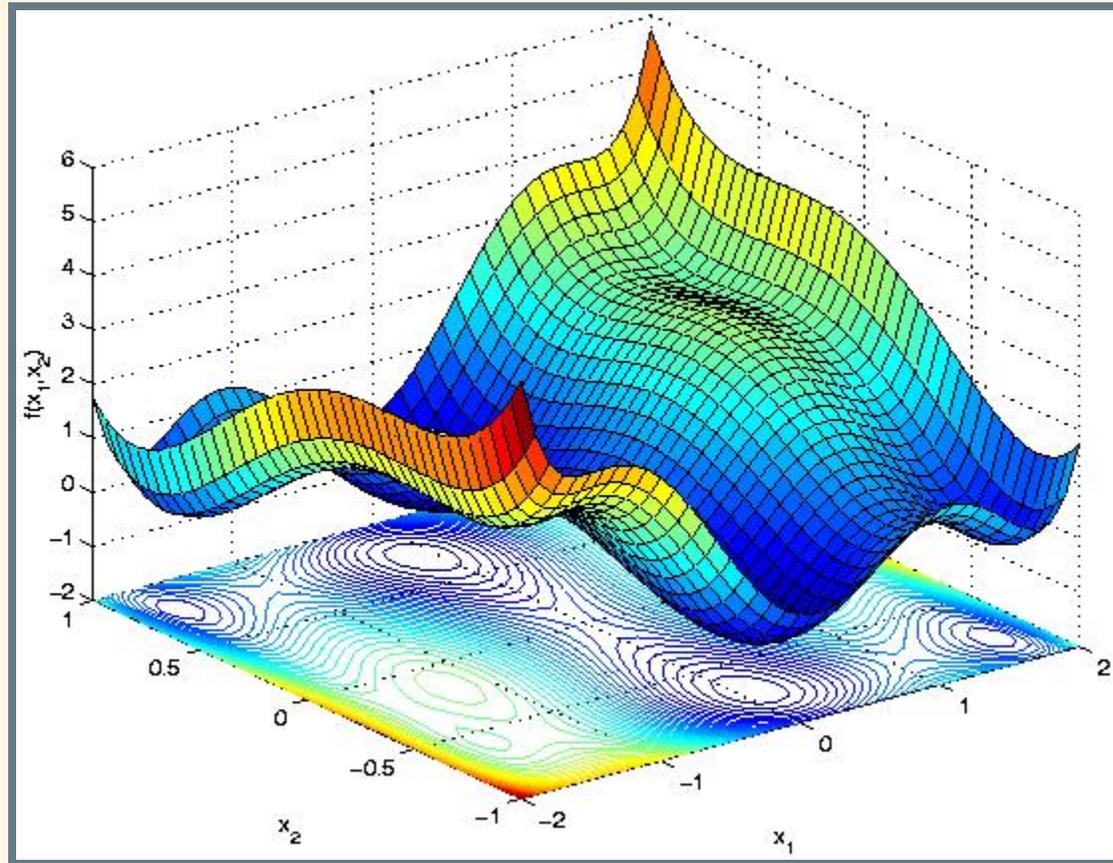
(dictionary learning, planted CSPs, tensor PCA, tensor decomposition, ...) [BKS '15ab, AOW '15, RRS '16, HSS '15, HSSS '16, GM '15, MSS '16, ...]

QUESTION: DOES SPECTRAL-IS-BEST WITHSTAND THE SUM-OF-SQUARES ALGORITHM?

Theorem (informal): The **Sum-of-Squares hierarchy** requires $n^{\Omega(\log n)}$ **time** to distinguish planted from random when $k = n^{0.49}$.

Spectral-is-best withstands the Sum-of-Squares algorithm.

WHAT IS THE SUM-OF-SQUARES ALGORITHM?



nasty optimization problem

WHAT IS THE SUM-OF-SQUARES ALGORITHM?

$$\max_{S \text{ a clique in } G} |S|$$

WHAT IS THE SUM-OF-SQUARES ALGORITHM?

A *hierarchy* of increasing-strength semidefinite programming (SDP) relaxations of an underlying (nonconvex) problem.

Generalizing linear programming, basic SDP, spectral methods.

WHAT IS THE SUM-OF-SQUARES ALGORITHM?

$$d = n : \underbrace{\left(\right)}_{2^n \times 2^n} \succeq 0$$

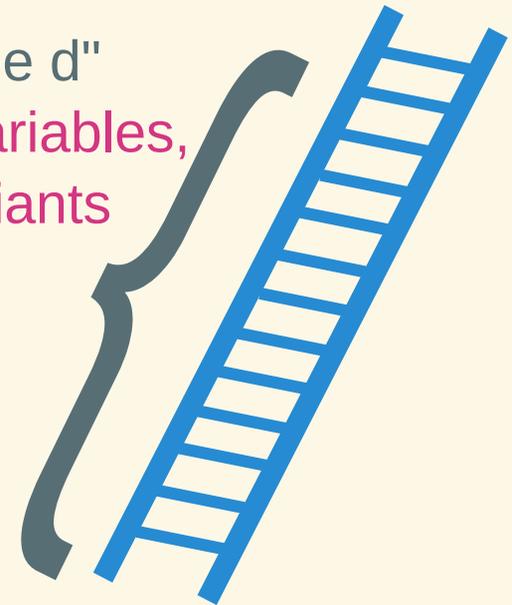
...

$$d = 2 : \underbrace{\left(\right)}_{n^2 \times n^2} \succeq 0$$

$$d = 1 : \underbrace{\left(\right)}_{n \times n} \succeq 0$$

huge, exact SDP

"degree d "
add variables,
constraints



small SDP, weak relaxation

Regime of interest: $d < o(\log n)$.

Convex Relaxations for Planted Clique



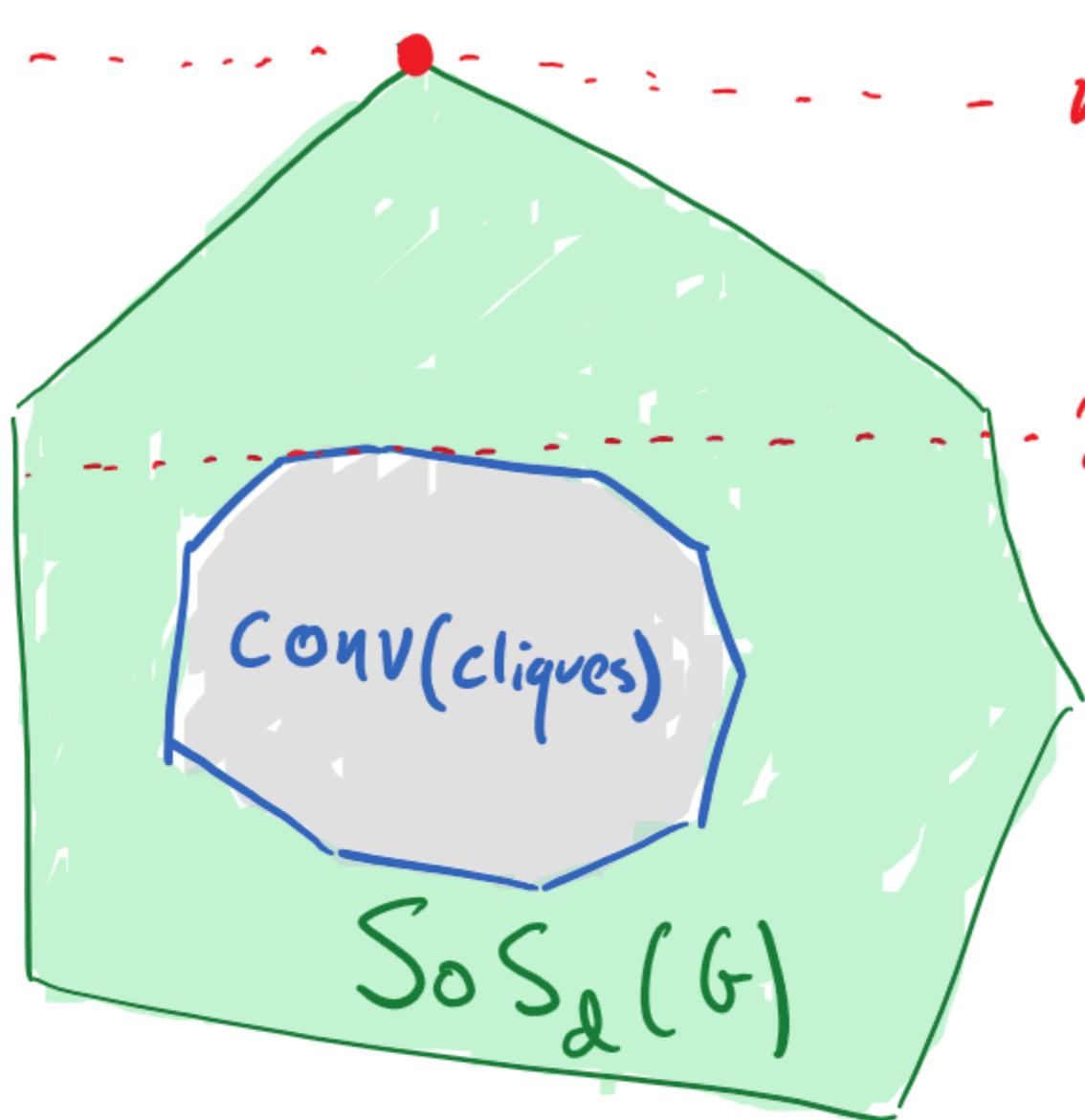
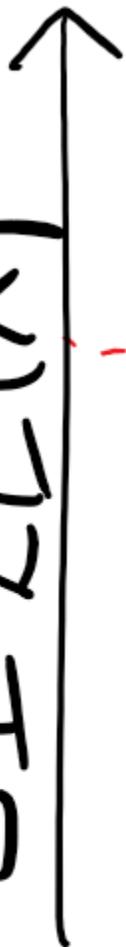
If $\max_{X \in SoS_d(G)} SIZE(X) \geq n^{0.49}$, output PLANTED else
RANDOM.



Question: How big is $\max_{X \in \mathcal{S}_0 \mathcal{S}_d(G)} \text{SIZE}(X)$ in the
random case?

(If $\ll \sqrt{n}$, we can beat the spectral algorithm!)

SIZE(X)



$n^{0.49}$

$2 \log(n)$

CONV(cliques)

$SoS_d(G)$

$$G \sim G(n, \frac{1}{2})$$

Goal: $X = X(G) \in SoS_d(G)$ so that
 $\sqrt{n} \geq \mathbb{E}_{G \sim G(n, 1/2)} \mathit{SIZE}(X(G)) \geq n^{0.49}$

Goal: $X = X(G) \in \text{SoS}_d(G)$ so that

$$\mathbb{E}_{G \sim \mathbb{G}(n, 1/2)} \text{SIZE}(X(G)) \geq n^{0.49}$$

Prior work [FK '04, folklore]:

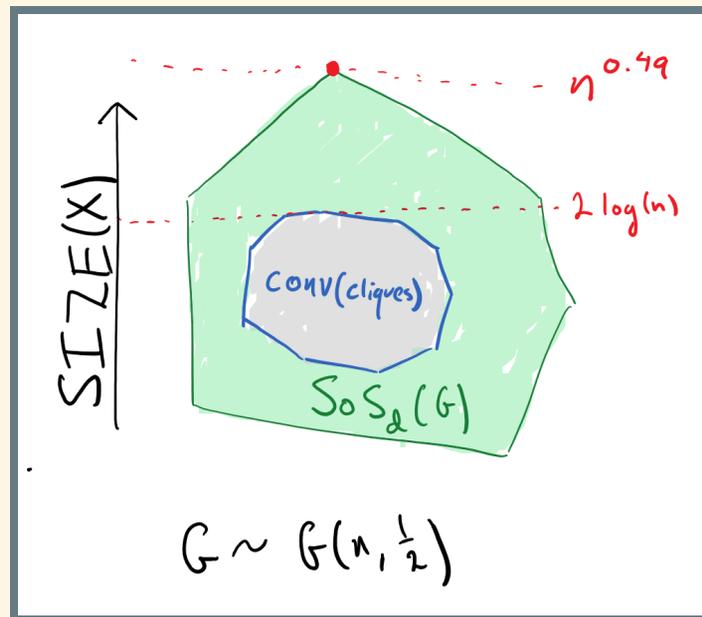
$X(G)$ feasible for LP, basic SDP, spectral, Sherali-Adams, Lovasz-Schrijver+ with $\text{SIZE}(X(G)) \geq n^{0.49}$ w.h.p.

Related [MPW '15, DM '15, HKPRS '16]:

$$X(G) \in \text{SoS}_d(G)$$

$$\mathbb{E}_{G \sim \mathbb{G}(n, 1/2)} \text{SIZE}(X(G)) \geq n^{1/\text{poly}(d)} \approx n^{0.001}$$

Same $X(G)$ cannot work for tight SoS bound [Kelner]



Original Goal: $X = X(G) \in SoS_d(G)$ so that

$$\mathbb{E}_{G \sim G(n, 1/2)} SIZE(X(G)) \geq n^{0.49}$$

Difficult to construct $X(G) \in SoS_d(G)$ (☹ ☹ high-dimensional positive-semidefinite matrices)

New (harder) Goal (*pseudocalibration*): Construct $X = X(G) \in SoS_d(G)$ which shares more properties of a planted clique than just $SIZE(X(G)) \geq n^{0.49}$.

New (harder) Goal (*pseudocalibration*):

$X = X(G) \in SoS_d(G)$ so that

$$\mathbb{E}_{G \sim \mathbb{G}(n, 1/2)} T_G(X(G)) = \mathbb{E}_{\text{planted}} T_G(\mathbf{1}_{\text{clique}})$$

for some family $\{T_G : \mathbb{R}^n \rightarrow \mathbb{R}\}$ of G -dependent linear functions ("tests"), including *SIZE*.

Example: $T_G(\mathbf{1}_{\text{clique}}) =$ number of 4-cliques containing a typical clique vertex.

Lemma: If $\{T_G\}$ = linear functions whose coefficients are low-degree polynomials in entries of A_G and $X(G)$ satisfies

1. $\mathbb{E}_{G \sim \mathbb{G}(n, 1/2)} T_G(X(G)) = \mathbb{E}_{\text{planted}} T_G(\mathbf{1}_{\text{clique}})$
2. $\mathbb{E}_{G \sim \mathbb{G}(n, 1/2)} \|X(G)\|_2^2$ is "small"

then with high probability $X(G) \in SoS_d(G)$ for $d = o(\log n)$ and $SIZE(X(G)) \geq n^{0.49}$.

Lemma: $X(G)$ satisfying these conditions exists.

$SoS_d(G)$ thinks there is an $n^{0.49}$ -size clique in $G \sim \mathbb{G}(n, 1/2)$

$$G \sim \mathbb{G}(n, \frac{1}{2}).$$

WRAPPING UP

(Nearly) resolved "SoS versus planted clique" using new *pseudocalibration* approach.

Future work/open problems: Pseudocalibration suggests SoS lower bound construction for other planted problems.

THANKS! QUESTIONS?