

# Numerical and semi-analytical structure-preserving model reduction for MEMS

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ICIAM 07, 18 Jul 2007

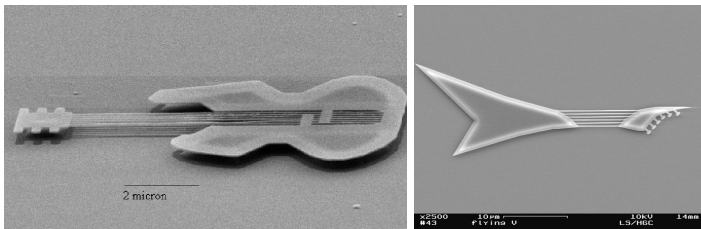
# Collaborators

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- Sanjay Govindjee
- Sunil Bhave
- Emmanuel Quévy
- Zhaojun Bai

# Resonant MEMS

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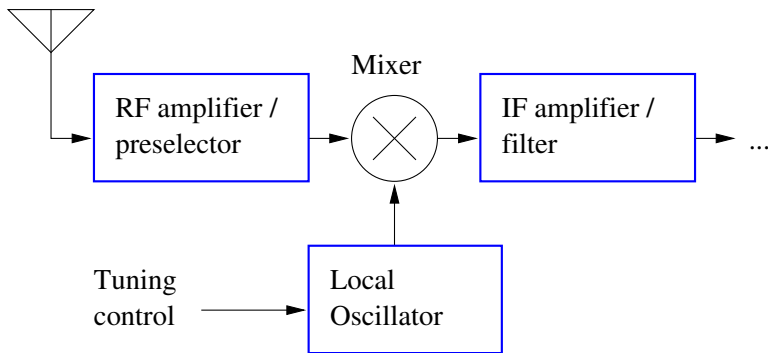


Microguitars from Cornell University (1997 and 2003)

- MHz-GHz mechanical resonators
- Favorite application: radio on chip
- Close second: really high-pitch guitars

# The Mechanical Cell Phone

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- Your cell phone has many moving parts!
- What if we replace them with integrated MEMS?

# Ultimate Success

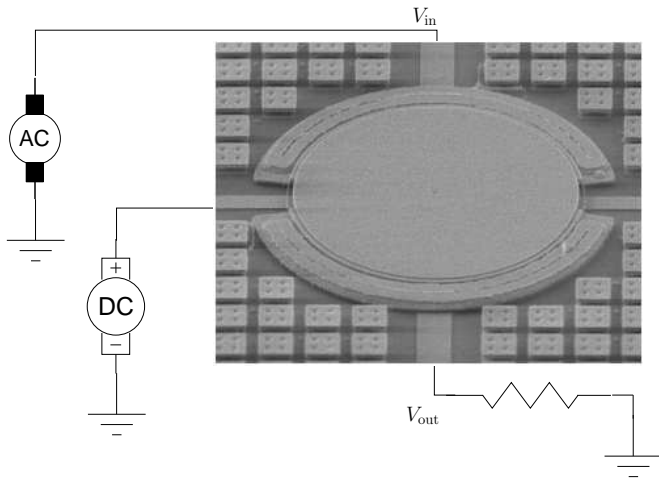
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“Calling Dick Tracy!”



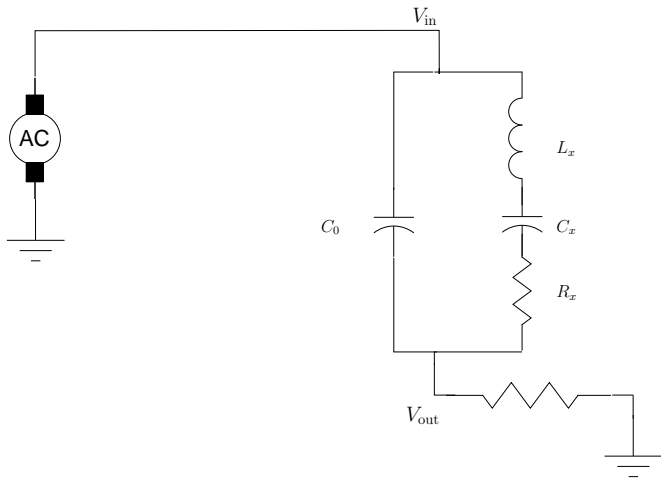
# Example Resonant System

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# Example Resonant System

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# The Designer's Dream

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Ideally, would like

- Simple models for behavioral simulation
- Parameterized for design optimization
- Including all relevant physics
- With reasonably fast and accurate set-up

We aren't there yet.



# The Hero of the Hour

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Major theme: use problem structure for better models

- ODE structure
- Complex symmetric structure
- Perturbative structure
- Geometric structure

# SOAR and ODE structure

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Damped second-order system:

$$\begin{aligned}Mu'' + Cu' + Ku &= P\phi \\ y &= V^T u.\end{aligned}$$

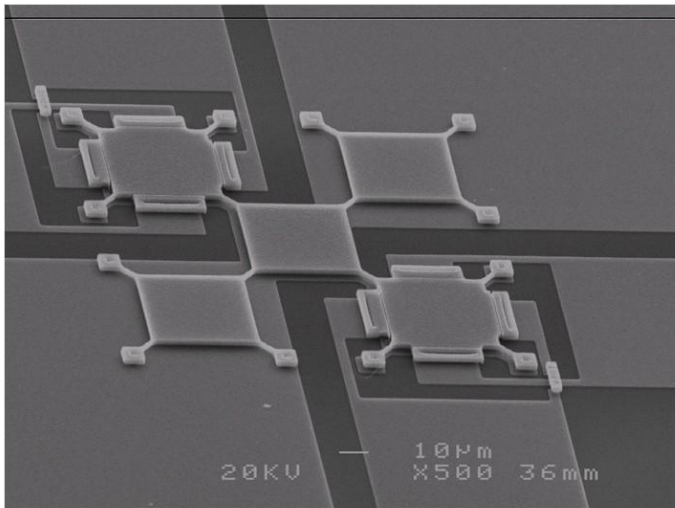
Projection basis  $Q_n$  with Second Order ARnoldi (SOAR):

$$\begin{aligned}M_n u_n'' + C_n u_n' + K_n u_n &= P_n \phi \\ y &= V_n^T u\end{aligned}$$

where  $P_n = Q_n^T P$ ,  $V_n = Q_n^T V$ ,  $M_n = Q_n^T M Q_n, \dots$

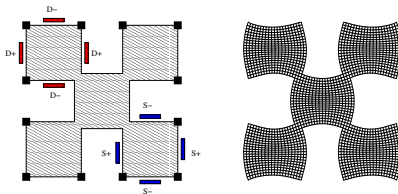
# Checkerboard Resonator

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# Checkerboard Resonator

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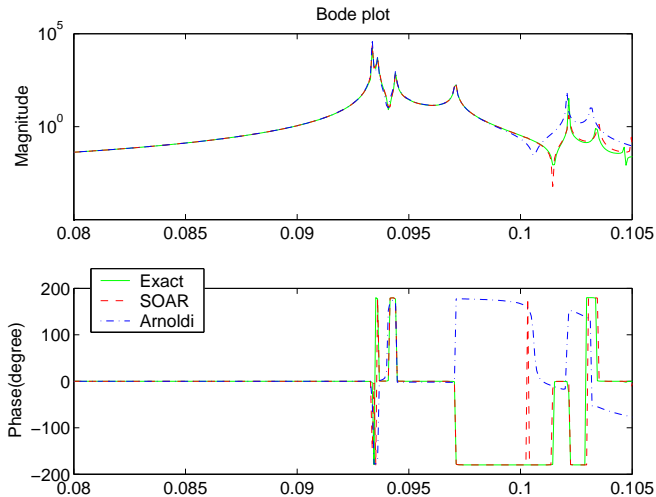


- Anchored at outside corners
- Excited at **northwest** corner
- Sensed at **southeast** corner
- Surfaces move only a few nanometers

# Performance of SOAR vs Arnoldi

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$$N = 2154 \rightarrow n = 80$$



# Complex Symmetry

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Model with radiation damping (PML) gives complex problem:

$$(K - \omega^2 M)u = f, \text{ where } K = K^T, M = M^T$$

Forced solution  $u$  is a stationary point of

$$I(u) = \frac{1}{2}u^T(K - \omega^2 M)u - u^T f.$$

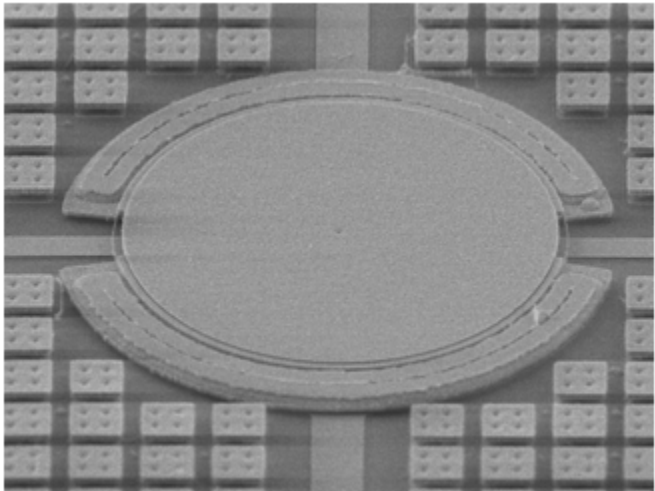
Eigenvalues of  $(K, M)$  are stationary points of

$$\rho(u) = \frac{u^T K u}{u^T M u}$$

First-order accurate vectors  $\implies$   
second-order accurate eigenvalues.

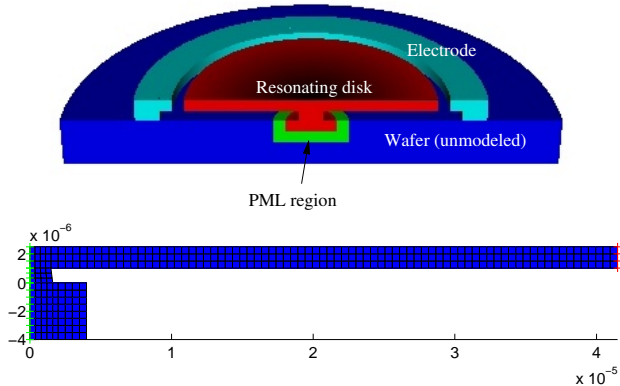
# Disk Resonator Simulations

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# Disk Resonator Mesh

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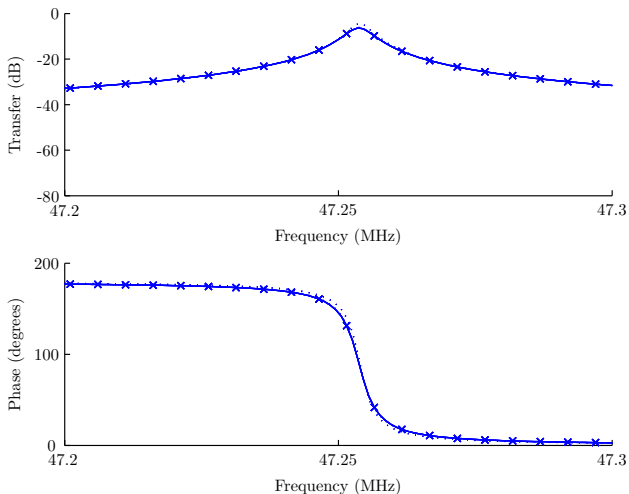


- Axisymmetric model with bicubic mesh
- About 10K nodal points in converged calculation



# Symmetric ROM Accuracy

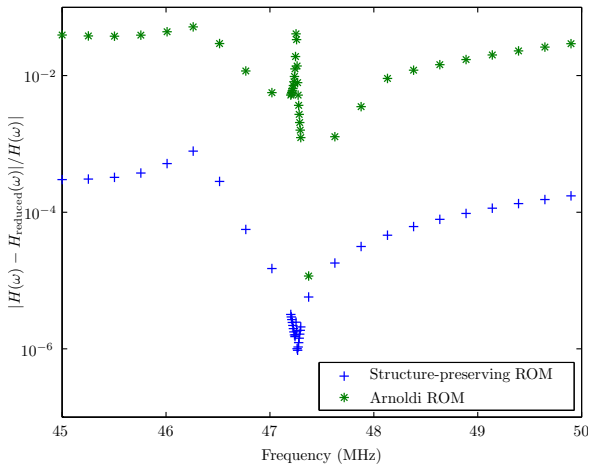
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Results from ROM (solid and dotted lines) near indistinguishable from full model (crosses)

# Symmetric ROM Accuracy

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Preserve structure  $\implies$   
get twice the correct digits

# Perturbative Structure

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Dimensionless continuum equations for thermoelastic damping:

$$\sigma = \hat{C}\epsilon - \xi\theta \mathbf{1}$$

$$\ddot{u} = \nabla \cdot \sigma$$

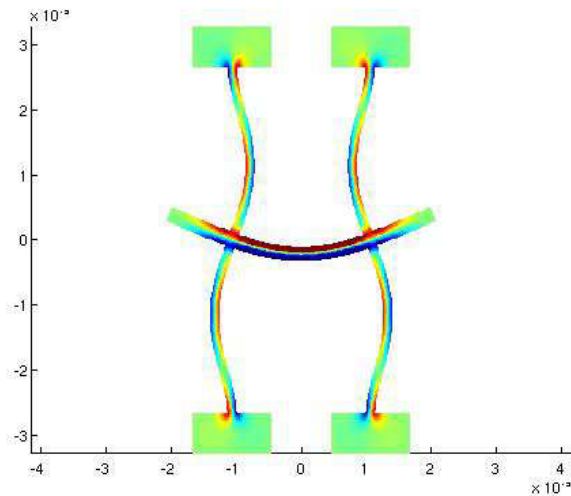
$$\dot{\theta} = \eta \nabla^2 \theta - \text{tr}(\dot{\epsilon})$$

Dimensionless coupling  $\xi$  and heat diffusivity  $\eta$  are  $10^{-4}$   
 $\Rightarrow$  perturbation method (about  $\xi = 0$ ).

Large, non-self-adjoint, first-order coupled problem  $\rightarrow$   
Smaller, self-adjoint, mechanical eigenproblem + symmetric linear solve.

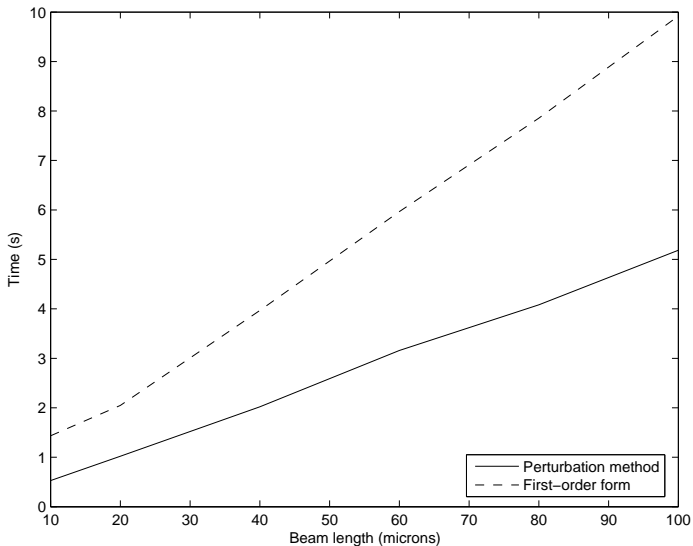
# Thermoelastic Damping Example

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# Performance for Beam Example

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# Aside: Effect of Nondimensionalization

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100  $\mu m$  beam example, first-order form.

Before nondimensionalization

- Time: 180 s
- $\text{nnz}(L) = 11M$

After nondimensionalization

- Time: 10 s
- $\text{nnz}(L) = 380K$

# Semi-Analytical Model Reduction

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We work with hand-build model reduction all the time!

- Circuit elements: Maxwell equation + field assumptions
- Beam theory: Elasticity + kinematic assumptions
- Axisymmetry: 3D problem + kinematic assumption

Idea: Provide *global shapes*

- User defines shapes through a callback
- Mesh serves defines a quadrature rule
- Reduced equations fit known abstractions

# Global Shape Functions

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Normally:

$$u(X) = \sum_j N_j(X) \hat{u}_j$$

Global shape functions:

$$\hat{u} = \hat{u}^l + G(\hat{u}^g)$$

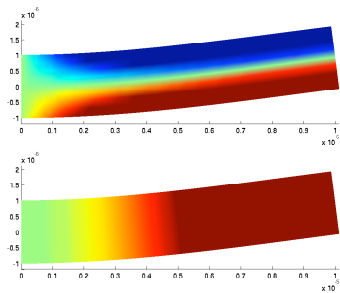
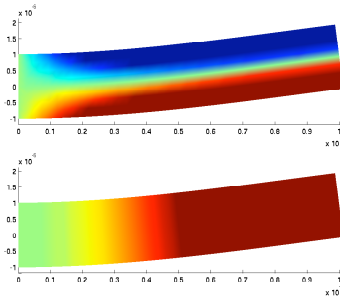
Then constrain values of some components of  $\hat{u}^l$ ,  $\hat{u}^g$ .



# “Hello, World!”

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Which mode shape comes from the reduced model (3 dof)?



(Left: 28 MHz; Right: 31 MHz)

# Conclusions

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Respecting problem structure is a Good Thing!

- ODE structure
- Complex symmetric structure
- Perturbative structure
- Geometric structure

Result:

Better accuracy, faster set-up, better understanding.