

Notes for 2016-10-14

1 Similarity transforms

When we talked about least squares problems, we spent some time discussing the transformations that preserve the Euclidean norm: orthogonal transformations. It is worth spending a moment now to give a name to the transformations that preserve the eigenvalue structure of a matrix. These are *similarity* transformations.

Suppose $A \in \mathbb{C}^{n \times n}$ is a square matrix, and $X \in \mathbb{C}^{n \times n}$ is invertible. Then the matrix XAX^{-1} is said to be *similar* to A , and the mapping from A to XAX^{-1} is a *similarity transformation*. If A is the matrix for an operator from $\mathbb{C}^n$ onto itself, then XAX^{-1} is the matrix for the same operator in a different basis. The eigenvalues and the Jordan block structure of a matrix are preserved under similarity, and the matrix X gives a relationship between the eigenvectors of A and those of XAX^{-1} . Note that this goes both ways: two matrices have the same eigenvalues and Jordan block structure iff they are similar.

2 Eigenvalue perturbations: a 2-by-2 illustration

Consider the matrix

$$A(\epsilon) = \begin{bmatrix} \lambda & 1 \\ \epsilon & \lambda \end{bmatrix}.$$

The characteristic polynomial of $A(\epsilon)$ is $p(z) = z^2 - 2\lambda z + (\lambda^2 - \epsilon)$, which has roots $\lambda \pm \sqrt{\epsilon}$. These eigenvalues are *continuous* functions of ϵ at $\epsilon = 0$, but they are not differentiable functions. This is a more general phenomenon: an $O(\epsilon)$ perturbation to a matrix with an eigenvalue with multiplicity m usually splits the eigenvalue into m distinct eigenvalues, each of which is moved from the original position by $O(\epsilon^{1/m})$. We expect, then, that it will be difficult to accurately compute multiple eigenvalues of general nonsymmetric matrices in floating point. If we are properly suspicious, we should suspect that *nearly* multiple eigenvalues are almost as troublesome — and indeed they are. On the other hand, while we usually lose some accuracy when trying to compute

nearly multiple eigenvalues, we should not always expect to lose *all* digits of accuracy.

The next lecture or two will be spent developing the perturbation theory we will need in order to figure out what we can and cannot expect from our eigenvalue computations.

3 First-order perturbation theory

Suppose $A \in \mathbb{C}^{n \times n}$ has a simple¹ eigenvalue λ with corresponding column eigenvector v and row eigenvector w^* . We would like to understand how λ changes under small perturbations to A . If we formally differentiate the eigenvalue equation $Av = v\lambda$, we have

$$(\delta A)v + A(\delta v) = (\delta v)\lambda + v(\delta \lambda).$$

If we multiply this equation by w^* , we have

$$w^*(\delta A)v + w^*A(\delta v) = \lambda w^*(\delta v) + w^*v(\delta \lambda).$$

Note that $w^*A = \lambda w^*$, so that we have

$$w^*(\delta A)v = w^*v(\delta \lambda),$$

which we rearrange to get

$$(1) \quad \delta \lambda = \frac{w^*(\delta A)v}{w^*v}.$$

This formal derivation of the first-order sensitivity of an eigenvalue only goes awry if $w^*v = 0$, which we can show is not possible if λ is simple.

We can use formula (1) to get a condition number for the eigenvalue λ as follows:

$$\frac{|\delta \lambda|}{|\lambda|} = \frac{|w^*(\delta A)v|}{|w^*v||\lambda|} \leq \frac{\|w\|_2\|v\|_2\|\delta A\|_2}{|w^*v||\lambda|} = \sec \theta \frac{\|\delta A\|_2}{|\lambda|}.$$

where θ is the acute angle between the spaces spanned by v and by w . When this angle is large, very small perturbations can drastically change the eigenvalue.

¹ An eigenvalue is simple if it is not multiple.

4 Gershgorin theory

The first-order perturbation theory outlined in the previous section is very useful, but it is also useful to consider the effects of *finite* (rather than infinitesimal) perturbations to A . One of our main tools in this consideration will be Gershgorin's theorem.

Here is the idea. We know that diagonally dominant matrices are nonsingular, so if $A - \lambda I$ is diagonally dominant, then λ cannot be an eigenvalue. Contraposing this statement, λ can be an eigenvalue only if $A - \lambda I$ is *not* diagonally dominant. The set of points where $A - \lambda I$ is not diagonally dominant is a union of sets $\cup_j G_j$, where each G_j is a *Gershgorin disk*:

$$G_j = B_{\rho_j}(a_{jj}) = \left\{ z \in \mathbb{C} : |a_{jj} - z| \leq \rho_j \text{ where } \rho_j = \sum_{i \neq j} |a_{ij}| \right\}.$$

Our strategy now, which we will pursue in detail next time, is to use similarity transforms based on A to make a perturbed matrix $A + E$ look “almost” diagonal, and then use Gershgorin theory to turn that “almost” diagonality into bounds on where the eigenvalues can be.

We now argue that we can extract even more information from the Gershgorin disks: we can get *counts* of how many eigenvalues are in different parts of the union of Gershgorin disks.

Suppose that $\mathcal{G}$ is a connected component of $\cup_j G_j$; in other words, suppose that $\mathcal{G} = \cup_{j \in S} G_j$ for some set of indices S , and that $\mathcal{G} \cap G_k = \emptyset$ for $k \notin S$. Then the number of eigenvalues of A in $\mathcal{G}$ (counting eigenvalues according to multiplicity) is the same as the size of the index set S .

To sketch the proof, we need to know that eigenvalues are continuous functions of the matrix entries. Now, for $s \in [0, 1]$, define

$$H(s) = D + sF$$

where D is the diagonal part of A and $F = A - D$ is the off-diagonal part. The function $H(s)$ is a *homotopy* that continuously takes us from an easy-to-analyze diagonal matrix at $H(0) = D$ to the matrix we care about at $H(1) = A$. At $s = 0$, we know the eigenvalues of A are the diagonal elements of A ; and if we apply the first part of Gershgorin's theorem, we see that the eigenvalues of $H(s)$ always must live inside the union of Gershgorin disks of A for any $0 \leq s \leq 1$. So each of the $|S|$ eigenvalues that start off in the

connected component $\mathcal{G}$ at $H(0) = D$ can move around continuously within $\mathcal{G}$ as we move the matrix continuously to $H(1) = A$, but they cannot “jump” discontinuously across the gap between $\mathcal{G}$ and any of the other Gershgorin disks. So at $s = 1$, there will still be $|S|$ eigenvalues of $H(1) = A$ inside $\mathcal{G}$.

5 Perturbing Gershgorin

Now, let us consider the relation between the Gershgorin disks for a matrix A and a matrix $\hat{A} = A + F$. It is straightforward to write down the Gershgorin disks $\hat{G}_j$ for $\hat{A}$:

$$\hat{G}_j = \mathcal{B}_{\hat{\rho}_j}(\hat{a}_{jj}) = \{z \in \mathbb{C} : |a_{jj} + e_{jj} - z| \leq \hat{\rho}_j\} \text{ where } \hat{\rho}_j = \sum_{i \neq j} |a_{ij} + f_{ij}|.$$

Note that $|a_{jj} + e_{jj} - z| \geq |a_{jj} - z| - |f_{jj}|$ and $|a_{ij} + f_{ij}| \leq |a_{ij}| + |f_{ij}|$, so

$$(2) \quad \hat{G}_j \subseteq \mathcal{B}_{\rho_j + \sum_i |f_{ij}|}(a_{jj}) = \left\{ z \in \mathbb{C} : |a_{jj} - z| \leq \rho_j + \sum_i |f_{ij}| \right\}.$$

We can simplify this expression even further if we are willing to expand the regions a bit:

$$(3) \quad \hat{G}_j \subseteq \mathcal{B}_{\rho_j + \|F\|_1}(a_{jj}).$$

6 The Bauer-Fike theorem

We now apply Gershgorin theory together with a carefully chosen similarity to prove a bound on the eigenvalues of $A + F$ where F is a finite perturbation. This will lead us to the *Bauer-Fike* theorem.

The basic idea is as follows. Suppose that A is a diagonalizable matrix, so that there is a complete basis of column eigenvectors V such that

$$V^{-1}AV = \Lambda.$$

Then we $A + F$ has the same eigenvalues as

$$V^{-1}(A + F)V = \Lambda + V^{-1}FV = \Lambda + \tilde{F}.$$

Now, consider the Gershgorin disks for $\Lambda + \tilde{F}$. The crude bound (3) tells us that all the eigenvalues live in the regions

$$\bigcup_j \mathcal{B}_{\|\tilde{F}\|_1}(\lambda_j) \subseteq \bigcup_j \mathcal{B}_{\kappa_1(V)\|F\|_1}(\lambda_j).$$

This bound really is crude, though; it gives us disks of the same radius around all the eigenvalues λ_j of A , regardless of the conditioning of those eigenvalues. Let's see if we can do better with the sharper bound (2).

To use (2), we need to bound the absolute column sums of $\tilde{F}$. Let e represent the vector of all ones, and let e_j be the j th column of the identity matrix; then the j th absolute column sums of $\tilde{F}$ is $\phi_j \equiv e^T |\tilde{F}| e_j$, which we can bound as $\phi_j \leq e^T |V^{-1}| |F| |V| e_j$. Now, note that we are free to choose the normalization of the eigenvector V ; let us choose the normalization so that each row of $W^* = V^{-1}$. Recall that we defined the angle θ_j by

$$\cos(\theta_j) = \frac{|w_j^* v_j|}{\|w_j\|_2 \|v_j\|_2},$$

where w_j and v_j are the j th row and column eigenvectors; so if we choose $\|w_j\|_2 = 1$ and $w_j^* v_j = 1$ (so $W^* = V^{-1}$), we must have $\|v_j\|_2 = \sec(\theta_j)$. Therefore, $\| |V| e_j \|_2 = \sec(\theta_j)$. Now, note that $e^T |V^{-1}|$ is a sum of n rows of Euclidean length 1, so $\|e^T |V^{-1}|\|_2 \leq n$. Thus, we have

$$\phi_j \leq n \|F\|_2 \sec(\theta_j).$$

Putting this bound on the columns of $\tilde{F}$ together with (2), we have the Bauer-Fike theorem.

Theorem 1 *Suppose $A \in \mathbb{C}^{n \times n}$ is diagonalizable with eigenvalues $\lambda_1, \dots, \lambda_n$. Then all the eigenvalues of $A + F$ are in the region*

$$\bigcup_j \mathcal{B}_{n\|F\|_2 \sec(\theta_j)}(\lambda_j),$$

where θ_j is the acute angle between the row and column eigenvectors for λ_j , and any connected component $\mathcal{G}$ of this region that contains exactly m eigenvalues of A will also contain exactly m eigenvalues of $A + F$.