## **HW** 1

You may (and should) talk about problems with each other and with me, providing attribution for any good ideas you might get. Your final write-up should be your own.

1: A problem of performance Matlab supports both sparse and dense matrix data structures, and they have different performance characteristics. For a variety of square matrices of size n and sparsity level s (where s is the fraction of entries that are nonzero), compare the speed of dense and sparse matrix-vector multiply. You may use As = sparse(A) to make a sparse version of a dense matrix A. What do you observe about the relative performance of these options?

*Note:* Your performance will vary depending on your machine and MAT-LAB version. Feel free to write these experiments using Octave, Python, or Julia if you prefer.

**2: Toeplitz and transforms** Consider a circulant matrix C whose first column is c, i.e.

$$C = \begin{bmatrix} c_1 & c_n & c_{n-1} & \dots & c_2 \\ c_2 & c_1 & c_n & \dots & c_3 \\ \vdots & & & & \vdots \\ c_n & c_{n-1} & c_{n-2} & \dots & c_1 \end{bmatrix}.$$

The following MATLAB code computes a matrix-vector product with C in  $O(n \log n)$  time:

```
y = ifft(fft(c) .* fft(x)); % Equivalent to <math>y = C*x
```

Using the circulant multiply as a building block and following the approach sketched in the notes from the first week, write an  $O(n \log n)$  multiply for the Toeplitz matrix T with first row r and first column c, i.e. a fast version of

```
y = toeplitz(c, r) *x;
```

**3: Low-rank limbo** Suppose  $A = xy^T$  where  $x \in \mathbb{R}^m$  and  $y \in \mathbb{R}^n$ . Show that  $||A||_2 = ||A||_F = ||x||_2 ||y||_2$ ,  $||A||_1 = ||x||_1 ||y||_{\infty}$ , and  $||A||_{\infty} = ||x||_{\infty} ||y||_1$ .

- **4: Noodling with Neumann** Suppose that if  $A \in \mathbb{R}^{n \times n}$  satisfies |A| < M (interpreted elementwise) for some  $M \in \mathbb{R}^{n \times n}$ . Show that if ||M|| < 1 in some consistent norm, then both  $(I A)^{-1}$  and  $(I M)^{-1}$  exist and  $|(I A)^{-1}| \le (I M)^{-1}$ .
- **5: Simple substitutions** Consider the code for forward substitution to solve the linear system Lx = b where L is lower triangular:

```
for i = 1:n
    x(i) = ( b(i)-L(i,1:i-1)*x(1:i-1) )/L(i,i);
end
```

Show that the vector  $\hat{x}$  computed in floating point arithmetic satisfies

$$(L + \delta L)\hat{x} = b$$

where  $|\delta l_{ij}| \leq n\epsilon_{\text{mach}}|l_{ij}| + O(\epsilon_{\text{mach}}^2)$ .