Computer-Aided Design of MEMS

Eigenvalues, Energy Losses, and Dick Tracy Watches

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Outline

» Outline
MEMS Basics
Anchor loss
Thormoolastic damping

- Thermoelastic damping
- Filter design
- Conclusions

- MEMS (Micro-Electro-Mechanical Systems) basics and RF (Radio Frequency) MEMS
- Disk resonators and perfectly matched layers
- Beam resonators and thermoelastic damping
- Model reduction, mode tracking, and optimization
- Conclusions

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What are MEMS?

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MEMS Basics

» What are MEMS?

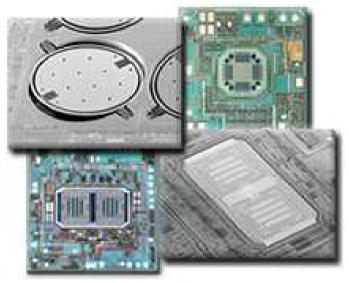
- » MEMS Basics
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- » Fabrication result
- » Fabrication characteristics
- » RF MEMS
- » Micromechanical filters
- » Damping and Q
- » Sources of damping

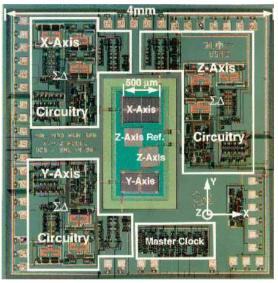
Anchor loss

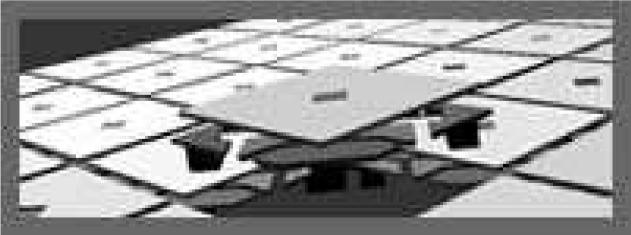
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MEMS Basics

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- Micro-electro-mechanical systems
 - ◆ Chemical, fluid, thermal, optical (MECFTOMS?)
- Applications:
 - Sensors (inertial, chemical, pressure)
 - Ink jet printers, biolab chips
 - RF devices: cell phones, inventory tags, pico radio
 - ◆ "Smart dust"
- Use integrated circuit (IC) fabrication technology
- Large surface area / volume ratio
- Still mostly classical (vs. nanosystems)

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300 um

1. Si wafer

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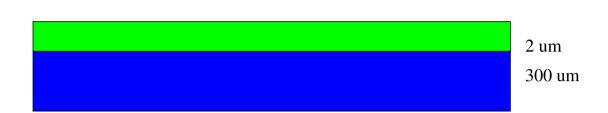
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- 1. Si wafer
- 2. Deposit 2 microns SiO2

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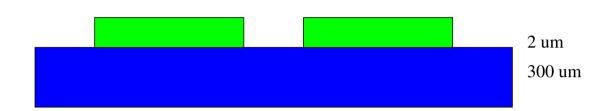
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- 1. Si wafer
- 2. Deposit 2 microns SiO2
- 3. Pattern and etch SiO2 layer

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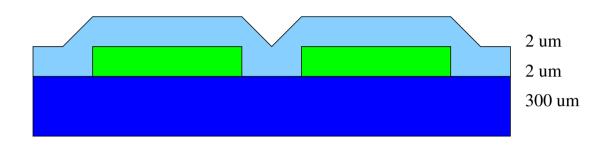
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- 1. Si wafer
- 2. Deposit 2 microns SiO2
- 3. Pattern and etch SiO2 layer
- 4. Deposit 2 microns polycrystalline Si

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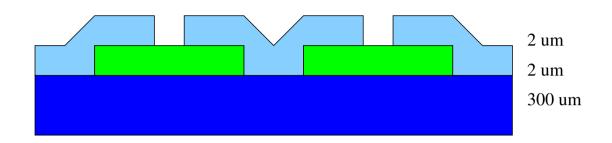
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- 2. Deposit 2 microns SiO2
- 3. Pattern and etch SiO2 layer
- 4. Deposit 2 microns polycrystalline Si
- 5. Pattern and etch Si layer

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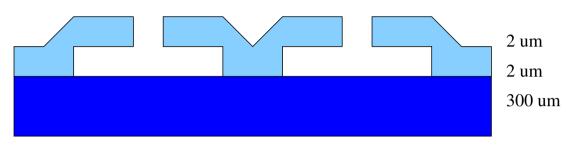
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- 2. Deposit 2 microns SiO2
- 3. Pattern and etch SiO2 layer
- 4. Deposit 2 microns polycrystalline Si
- 5. Pattern and etch Si layer
- 6. Release etch remaining SiO2

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Fabrication result

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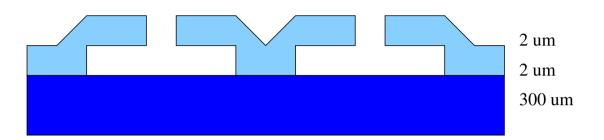
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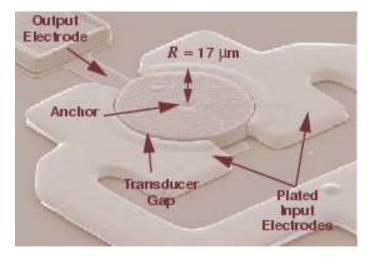
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(C. Nguyen, iMEMS 01)

Fabrication characteristics

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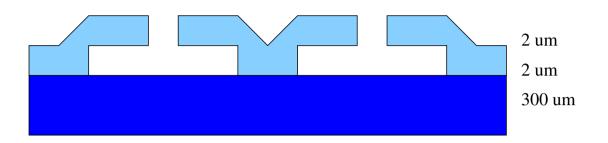
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- Characteristic dimensions: microns
- Geometry is "2.5" dimensional
- Relatively loose fabrication tolerances
- Difficult to characterize

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RF MEMS

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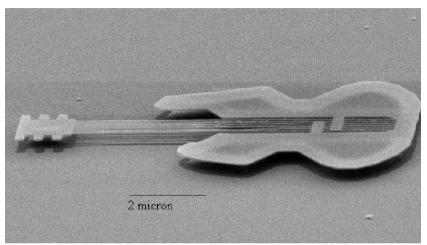
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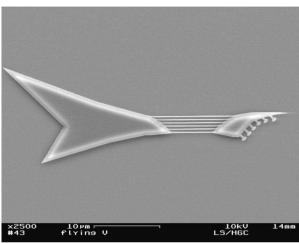
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Microguitars from Cornell University (1997 and 2003)

- MHz-GHz mechanical resonators
- Impact: smaller, lower-power cell phones
 - ♦ Replace quartz freq references, filter elements
 - ◆ Integrate into CMOS stack
- Other uses:
 - Sensing elements (e.g. chemical sensors)
 - Really high-pitch guitars

Micromechanical filters

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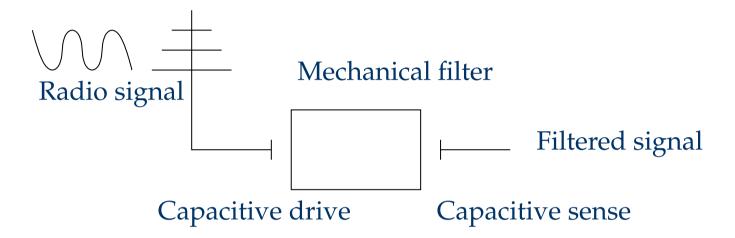
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- Mechanical high-frequency (high MHz-GHz) filter
 - Your cell phone is mechanical!
- Advantage over quartz surface acoustic wave filters
 - Integrated into chip
 - ◆ Low power

Success ⇒ "Calling Dick Tracy!"

Damping and Q

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- Want to minimize damping
 - Electronic filters have too much
 - Understanding of damping in MEMS resonators is lacking
- Engineers want one number: Q
 - ♦ Non-dimensionalized damping in a one-variable system:

$$\frac{d^2u}{dt^2} + Q^{-1}\frac{du}{dt} + u = F(t)$$

• For a resonant mode with frequency $\omega \in \mathbb{C}$:

$$Q := \frac{\Re(\omega)}{2\Im(\omega)} = \frac{\text{Stored energy}}{\text{Energy loss per radian}}$$

■ Goal: Make Q big

Sources of damping

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Conclusions

- Fluid damping
 - Air is a viscous fluid (Re $\ll 1$)
 - Can operate in a vacuum
 - Shown not to dominate in many RF designs
- Anchor loss
 - ♦ Elastic waves radiate from structure
- Thermoelastic damping
 - Volume changes induce temperature change
 - ◆ Diffusion of heat leads to mechanical loss
- Material losses (catch-all)
 - ◆ Low intrinsic losses in silicon, diamond, germanium, etc.
 - ◆ Terrible material losses in metals

Sources of damping

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Disk resonator

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MEMS Basics

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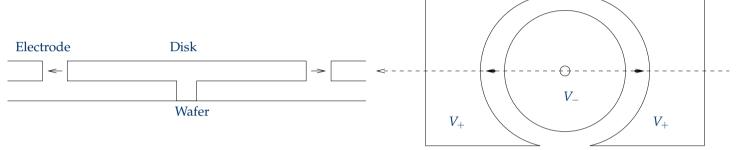
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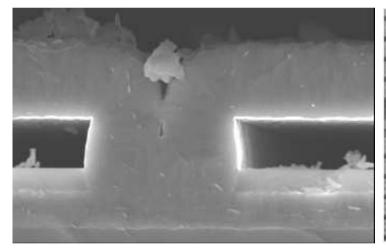
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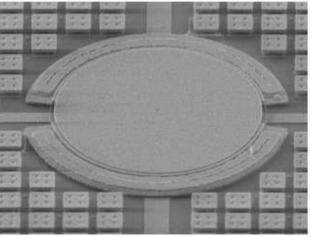
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- SiGe disk resonators built by E. Quévy
- Axisymmetric model with bicubic mesh, about 10K nodal points

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Substrate model

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Conclusions

Goal: Understand energy loss in this resonator

- Dominant loss is elastic radiation from anchor.
- Disk resonator is much smaller than substrate
- Very little energy leaving the post is reflected back
 - Substrate is semi-infinite from disk's perspective
- Possible semi-infinite models
 - Matched asymptotic modes
 - Dirichlet-to-Neumann maps
 - Boundary dampers
 - Perfectly matched layers

Substrate model

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Perfectly matched layers

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Conclusions

- Apply a complex coordinate transformation
- Generates a non-physical absorbing layer
- No impedance mismatch between the computational domain and the absorbing layer
- Idea works with general linear wave equations
 - First applied to Maxwell's equations (Berengér 95)
 - ◆ Similar idea introduced earlier in quantum mechanics (exterior complex scaling, Simon 79)

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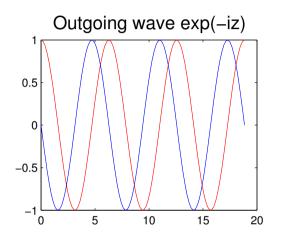
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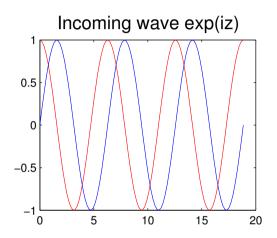
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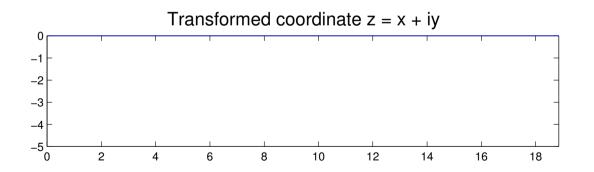
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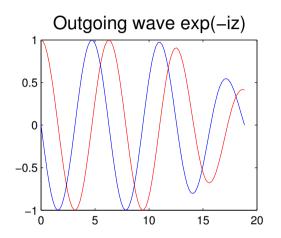
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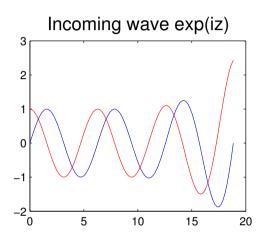
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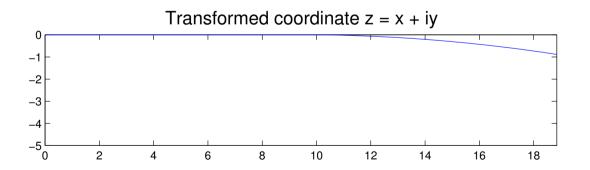
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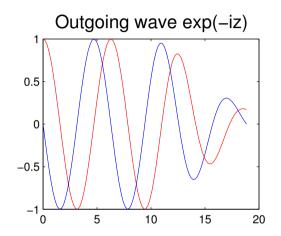
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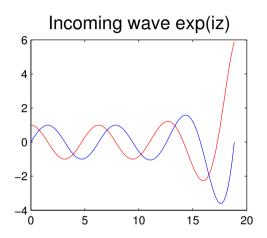
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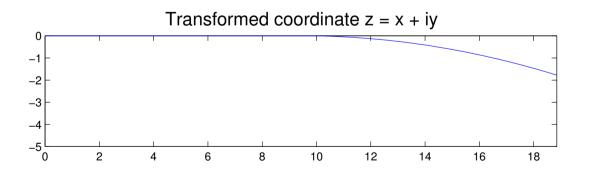
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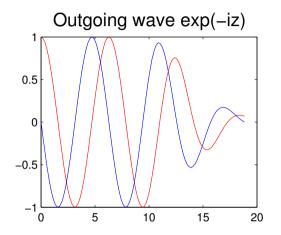
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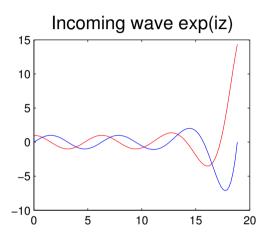
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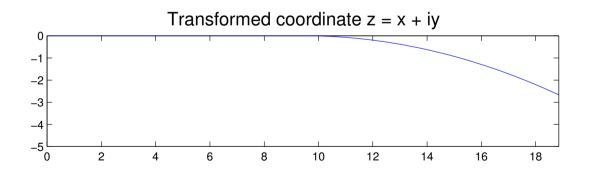
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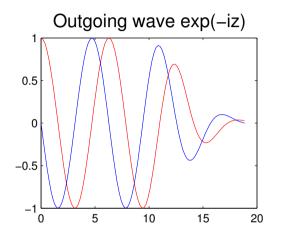
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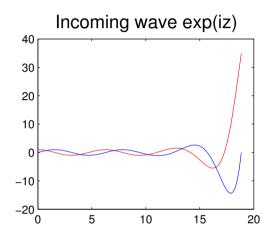
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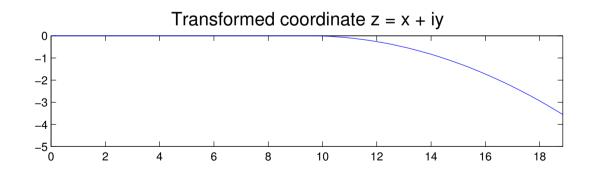
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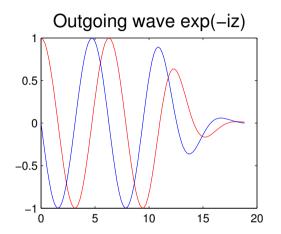
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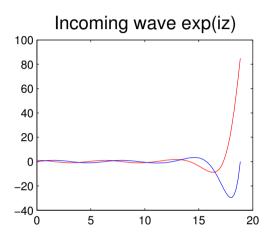
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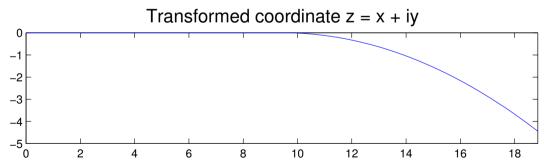
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Clamp solution at transformed end to isolate outgoing wave.

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PML weak form

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Conclusions

Weak form of time-harmonic elasticity equations:

$$-\omega^2 \int_{\Omega} \rho w \cdot u \, d\Omega + \int_{\Omega} \epsilon(w) : \mathbf{C} : \epsilon(u) d\Omega = \int_{\Gamma} w \cdot t \, d\Gamma$$

Weak form of time-harmonic PML equation:

$$-\omega^2 \int_{\Omega} \rho w \cdot u \, Jd\Omega + \int_{\Omega} \tilde{\epsilon}(w) : \mathbf{C} : \tilde{\epsilon}(u) \, Jd\Omega = \int_{\Gamma} w \cdot \tilde{t} \, Jd\Gamma$$

Bubnov-Galerkin finite element discretization leads to

$$-\omega^2 M u + K u = F$$

But in PML case, *M* and *K* are *complex symmetric*.

Finite elements

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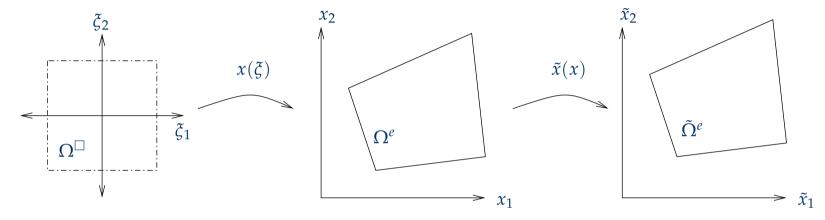
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Conclusions



- Isoparametric elements already use mapped integration
- View PML as an added coordinate transformation
 - ♦ Requires little modification to existing elements
 - ♦ Just transform derivatives and Jacobian determinant

Eigenstructure

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Conclusions

- Complex symmetry implies row and column eigenvectors are (non-conjugated) transposes.
- Can therefore achieve second-order accuracy with a modified Rayleigh quotient:

$$\theta(v) = (v^T K v) / (v^T M v)$$

- It *is* possible to have $v^T M v \approx 0$
 - Propagating modes (continuous spectrum)
 - Not the modes of interest for resonators

Perturbation analysis

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Conclusions

Know first-order perturbation behavior of eigenvalues:

$$(\omega + \delta\omega)^2 = \frac{v^T(K + \delta K)v}{v^T(M + \delta M)v}$$

Useful for sensitivity analysis.

Model reduction

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» Model reduction

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- » Effect of varying film thickness
- » Truth in advertising

Thermoelastic damping

Filter design

Conclusions

Would like a reduced model which

- Preserves second-order accuracy for converged eigs
- Keeps at least Arnoldi's accuracy otherwise
- Is physically meaningful

Idea:

- Build an Arnoldi basis V
- Double the size: $W = \operatorname{orth}([\Re(V), \Im(V)])$
- Use W as a projection basis
- Resulting system is still a Galerkin approximation with real shape functions for the continuum PML equations

Q variation

» Outline

MEMS Basics

Anchor loss

- » Disk resonator
- » Substrate model
- » Perfectly matched layers
- » Scalar wave example
- » PML weak form
- » Finite elements
- » Eigenstructure
- » Perturbation analysis
- » Model reduction

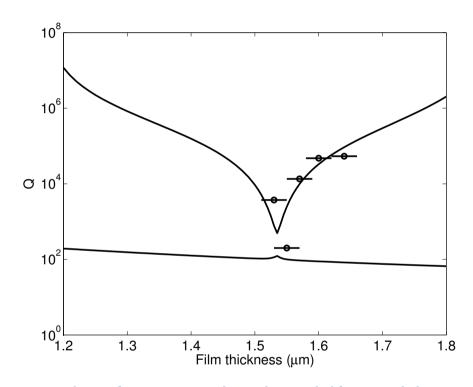
» Q variation

- » Effect of varying film thickness
- » Truth in advertising

Thermoelastic damping

Filter design

Conclusions



- Compute complex frequencies by shift-and-invert Arnoldi with an analytically determined shift
- Surprising variation experimentally observed in *Q* as film thickness changes!

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Effect of varying film thickness

» Outline

MEMS Basics

Anchor loss

- » Disk resonator
- » Substrate model
- » Perfectly matched layers
- » Scalar wave example
- » PML weak form
- » Finite elements
- » Eigenstructure
- » Perturbation analysis
- » Model reduction
- » Q variation

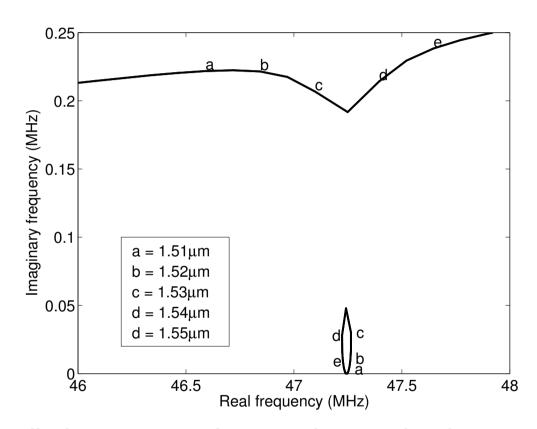
» Effect of varying film thickness

» Truth in advertising

Thermoelastic damping

Filter design

Conclusions



- Sudden dip in Q comes from an interaction between a (mostly) bending mode and a (mostly) radial mode
- Non-normal interaction between the modes

Truth in advertising

» Outline

MEMS Basics

Anchor loss

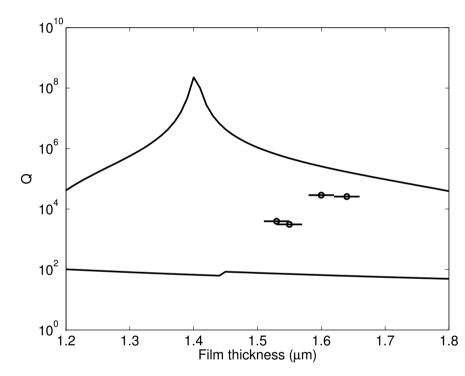
- » Disk resonator
- » Substrate model
- » Perfectly matched layers
- » Scalar wave example
- » PML weak form
- » Finite elements
- » Eigenstructure
- » Perturbation analysis
- » Model reduction
- » O variation
- » Effect of varying film thickness

» Truth in advertising

Thermoelastic damping

Filter design

Conclusions



Data from a set of $30\mu m$ radius disks.

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Thermoelastic damping (TED)

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

» Thermoelastic damping (TED)

- » Nondimensionalization
- » Scaling analysis
- » Discrete mode equations
- » Perturbation computation
- » Comparison to Zener's model

Filter design

Conclusions

u is displacement and $T = T_0 + \theta$ is temperature

$$\begin{aligned}
\sigma &= C\epsilon - \beta\theta 1 \\
\rho u_{tt} &= \nabla \cdot \sigma \\
\rho c_v \theta_t &= \nabla \cdot (\kappa \nabla \theta) - \beta T_0 \operatorname{tr}(\epsilon_t)
\end{aligned}$$

- Volumetric strain rate drives energy transfer from mechanical to thermal domain
 - ♦ Irreversible diffusion ⇒ mechanical damping
 - Not often an important factor at the macro scale
 - Recognized source of damping in microresonators
- Zener: semi-analytical approximation for TED in beams
- We consider the fully coupled system

Nondimensionalization

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

» Thermoelastic damping (TED)

» Nondimensionalization

- » Scaling analysis
- » Discrete mode equations
- » Perturbation computation
- » Comparison to Zener's model

Filter design

Conclusions

$$\sigma = \hat{C}\epsilon - \xi\theta 1$$

$$u_{tt} = \nabla \cdot \sigma$$

$$\theta_t = \eta \nabla^2 \theta - \operatorname{tr}(\epsilon_t)$$

$$\xi := \left(\frac{\beta}{\rho c}\right)^2 \frac{T_0}{c_v} \text{ and } \eta := \frac{\kappa}{\rho c_v c L}$$

Length
$$\sim L$$
 Time $\sim L/c$, where $c=\sqrt{E/\rho}$ Temperature $\sim T_0 \frac{\beta}{\rho c_v}$

Scaling analysis

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

- » Thermoelastic damping (TED)
- » Nondimensionalization

» Scaling analysis

- » Discrete mode equations
- » Perturbation computation
- » Comparison to Zener's model

Filter design

Conclusions

$$\sigma = \hat{C}\epsilon - \xi\theta 1$$

$$u_{tt} = \nabla \cdot \sigma$$

$$\theta_t = \eta \nabla^2 \theta - \operatorname{tr}(\epsilon_t)$$

$$\xi := \left(\frac{\beta}{\rho c}\right)^2 \frac{T_0}{c_v} \text{ and } \eta := \frac{\kappa}{\rho c_v c L}$$

- Micron-scale poly-Si devices: ξ and η are $\sim 10^{-4}$.
- \blacksquare Small η leads to thermal boundary layers
- Linearize about $\xi = 0$

Discrete mode equations

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

- » Thermoelastic damping (TED)
- » Nondimensionalization
- » Scaling analysis

» Discrete mode equations

- » Perturbation computation
- » Comparison to Zener's model

Filter design

Conclusions

$$\sigma = \hat{C}\epsilon - \xi\theta 1
u_{tt} = \nabla \cdot \sigma
\theta_t = \eta \nabla^2 \theta - \operatorname{tr}(\epsilon_t)$$

$$\sigma = \hat{C}\epsilon - \xi\theta 1$$

$$-\omega^2 u = \nabla \cdot \sigma$$

$$i\omega\theta = \eta \nabla^2 \theta - i\omega \operatorname{tr}(\epsilon)$$

$$-\omega^2 M_{uu}u + K_{uu}u + K_{ut}\theta = 0$$
$$i\omega D_{tt}\theta + K_{tt}\theta + i\omega D_{tu}u = 0$$

Perturbation computation

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

- » Thermoelastic damping (TED)
- » Nondimensionalization
- » Scaling analysis
- » Discrete mode equations

» Perturbation computation

» Comparison to Zener's model

Filter design

Conclusions

$$-\omega^2 M_{uu}u + K_{uu}u + K_{ut}\theta = 0$$
$$i\omega D_{tt}\theta + K_{tt}\theta + i\omega D_{tu}u = 0$$

Approximate ω by perturbation about $K_{ut} = 0$:

$$-\omega_0^2 M_{uu} u_0 + K_{uu} u_0 = 0$$
$$i\omega_0 D_{tt} \theta_0 + K_{tt} \theta_0 + i\omega_0 D_{tu} u_0 = 0$$

Choose $v: v^T u_0 \neq 0$ and compute

$$\begin{bmatrix} (-\omega_0^2 M_{uu} + K_{uu}) & -2\omega_0 M_{uu} u_0 \\ v^T & 0 \end{bmatrix} \begin{bmatrix} \delta u \\ \delta \omega \end{bmatrix} = \begin{bmatrix} -K_{ut} \theta_0 \\ 0 \end{bmatrix}$$

Comparison to Zener's model

» Outline

MEMS Basics

Anchor loss

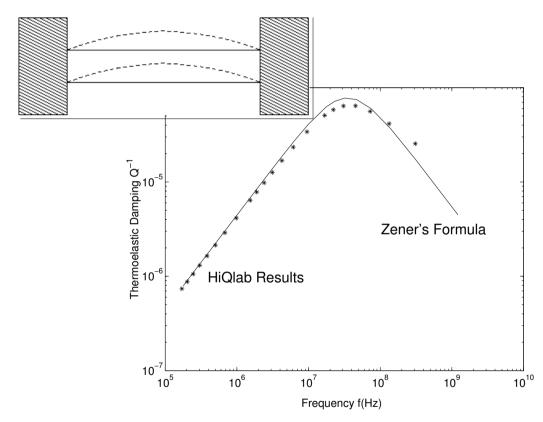
Thermoelastic damping

- » Thermoelastic damping (TED)
- » Nondimensionalization
- » Scaling analysis
- » Discrete mode equations
- » Perturbation computation

» Comparison to Zener's model

Filter design

Conclusions



- Comparison of fully coupled simulation to Zener approximation over a range of frequencies
- Real and imaginary parts after first-order correction agree to about three digits with Arnoldi

Checkerboard resonator

» Outline

MEMS Basics

Anchor loss

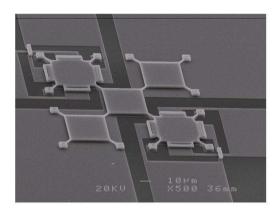
Thermoelastic damping

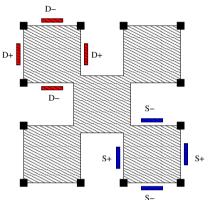
Filter design

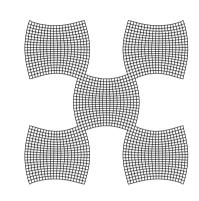
» Checkerboard resonator

- » Checkerboard simulation
- » Checkerboard measurement
- » Transfer function optimization

Conclusions







- Array of loosely coupled resonators
- Anchored at outside corners
- Excited at northwest corner
- Sensed at southeast corner
- Surfaces move only a few nanometers

Checkerboard simulation

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

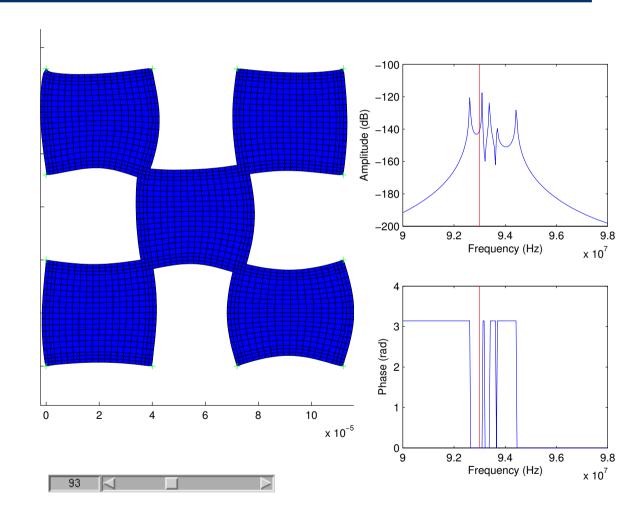
Filter design

» Checkerboard resonator

» Checkerboard simulation

- » Checkerboard measurement
- » Transfer function optimization

Conclusions



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Checkerboard measurement

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

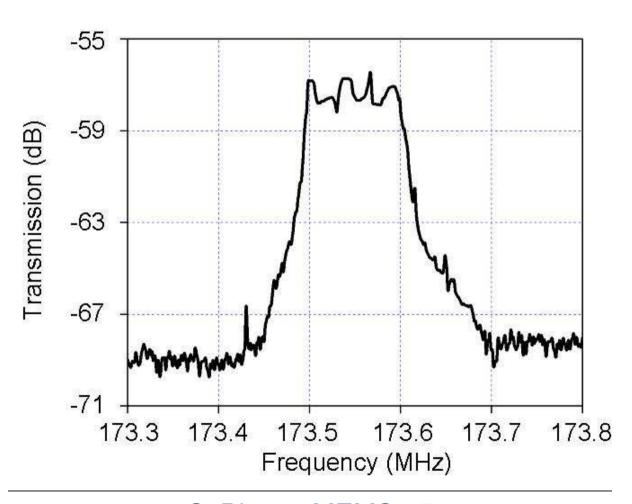
» Checkerboard resonator

» Checkerboard simulation

» Checkerboard measurement

» Transfer function optimization

Conclusions



S. Bhave, MEMS 05

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Transfer function optimization

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

- » Checkerboard resonator
- » Checkerboard simulation
- » Checkerboard measurement

» Transfer function optimization

Conclusions

- Choose geometry to make a good bandpass filter
- What is a "good bandpass filter?"
 - $|H(\omega)|$ is big on $[\omega_l, \omega_r]$
 - $|H(\omega)|$ is tiny outside this interval
- How do we optimize?
 - Overton's gradient sampling method
 - Use Byers-Boyd-Balikrishnan algorithm for distance to instability to minimize $|H(\omega)|$ on $[\omega_l, \omega_r]$
 - ♦ Small Hamiltonian eigenproblem (with ROM)

Contributions

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

Conclusions

- ContributionsThe other talk
- » Conclusions

- Mathematical
 - Reformulation of PML technology
 - Perturbation solution for thermoelastic damping
- Computer science
 - ♦ HiQLab, SUGAR, and FEAPMEX
- Engineering physics
 - ◆ Effects of mode interference in damping
 - Relative importance of anchor loss and TED

The other talk

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

Conclusions

» Contributions

» The other talk

» Conclusions

- CLAPACK
- Finding roots of polynomials
- Continuation of invariant subspaces for sparse problems
- Computer network tomography
- OceanStore and distributed system security
- Pontificating about floating point arithmetic

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Conclusions

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

Conclusions

- » Contributions
- » The other talk
- » Conclusions

- RF MEMS are a great source of problems
 - Interesting applications
 - Interesting physics (and not altogether understood)
 - ♦ Interesting numerical mathematics

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http://www.cs.berkeley.edu/~dbindel/feapmex.html
http://www.cs.berkeley.edu/~dbindel/hiqlab
http://bsac.berkeley.edu/cadtools/sugar/sugar/
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Role of simulation

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

Conclusions

Backup slides

» Role of simulation

- » Shear ring resonator
- » Mode tracking
- » Mode tracking in a shear resonator
- » Thermoelastic boundary layer

HiQLab: Modeling RF MEMS

- Explore fundamental device physics
 - Particularly details of damping
- Detailed finite element modeling
- Reduced models eventually to go into SUGAR

SUGAR: "Be SPICE to the MEMS world"

- Fast enough for early design stages
- Simple enough to attract users
- Support design, analysis, optimization, synthesis
- Verify models by comparison to measurement

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Shear ring resonator

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

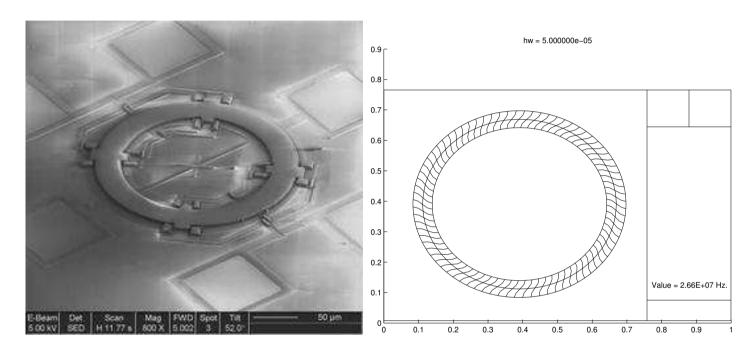
Conclusions

Backup slides

» Role of simulation

» Shear ring resonator

- » Mode tracking
- » Mode tracking in a shear resonator
- » Thermoelastic boundary layer



- Ring is driven in a shearing motion
- Can couple ring to other resonators
- How do we track the desired mode?

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Mode tracking

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

Filter design

Conclusions

Backup slides

- » Role of simulation
- » Shear ring resonator

» Mode tracking

- » Mode tracking in a shear resonator
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Find a continuous solution to

$$\left(K(s) - \omega(s)^2 M(s)\right) u(s) = 0.$$

- K and M are symmetric and M > 0
- Eigenvectors are M-orthogonal
- Perturbation theory gives good shifts
- Look if u(s+h) and u(s) are on the same path by looking at $u(s+h)^T M(s+h) u(s)$
- Many more subtleties in the nonsymmetric case
 - ♦ Focus of the CIS algorithm

Mode tracking in a shear resonator

» Outline

MEMS Basics

Anchor loss

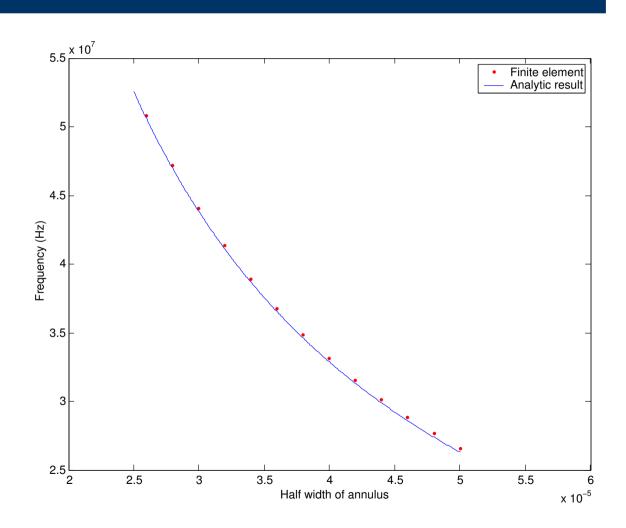
Thermoelastic damping

Filter design

Conclusions

Backup slides

- » Role of simulation
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- » Thermoelastic boundary layer



Thermoelastic boundary layer

» Outline

MEMS Basics

Anchor loss

Thermoelastic damping

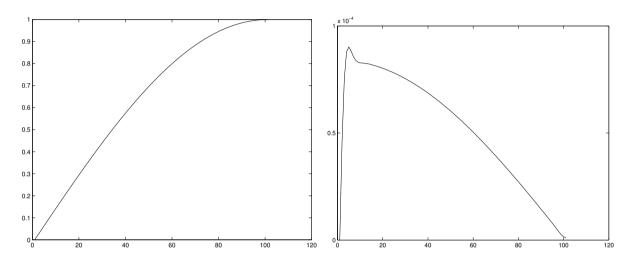
Filter design

Conclusions

Backup slides

- » Role of simulation
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- » Mode tracking
- » Mode tracking in a shear resonator

» Thermoelastic boundary layer



- One-dimensional test problem (longitudinal mode in a bar)
- Fixed temperature and displacement at left
- Free at right

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