

15 Oct 2021

Ellipsoid Algorithm

Recap of LP Duality:

$$\max \{ c^T x \mid Ax \leq b \} = \min \{ b^T y \mid A^T y = c, y \geq 0 \}$$

Suppose we want to solve

$$\max \{ c^T x \mid Ax \leq b, x \geq 0 \}.$$

Then letting $\mathbb{1}$ denote $n \times n$ identity,
 $x \geq 0$ can be written $-\mathbb{1}x \leq 0$.

$$\begin{aligned} \max \{ c^T x \mid Ax \leq b, x \geq 0 \} &= \max \left\{ c^T x \mid \begin{bmatrix} A \\ -\mathbb{1} \end{bmatrix} x \leq \begin{bmatrix} b \\ 0 \end{bmatrix} \right\} \\ &= \min \left\{ \begin{bmatrix} b & 0 \end{bmatrix}^T \begin{bmatrix} y \\ z \end{bmatrix} \mid \begin{bmatrix} A^T & -\mathbb{1} \end{bmatrix} \begin{bmatrix} y \\ z \end{bmatrix} = c, \begin{bmatrix} y \\ z \end{bmatrix} \geq 0 \right\} \\ &= \min \{ b^T y \mid A^T y - z = c, y \geq 0, z \geq 0 \} \\ &= \min \{ b^T y \mid A^T y \geq c, y \geq 0 \} \end{aligned}$$

Next unfinished business...

LP feasibility \leq_p LP search \leq_p LP optimization

Now to show: LP optimization \leq_p LP search

To solve $\max \{ c^T x \mid Ax \leq b \}$
search for $(x, y) \in \mathbb{R}^n \times \mathbb{R}^m$
satisfying

$$P' = \{ Ax \leq b, A^T y = c, y \geq 0, c^T x = b^T y \}.$$

In proving LP duality we showed that
if $\{ x \mid Ax \leq b \} \neq \emptyset$ and $\max \{ c^T x \mid Ax \leq b \} < \infty$
then $P' \neq \emptyset$ and any $(x, y) \in P'$ satisfies

$$c^T x = \max \{ c^T x' \mid Ax' \leq b \}$$

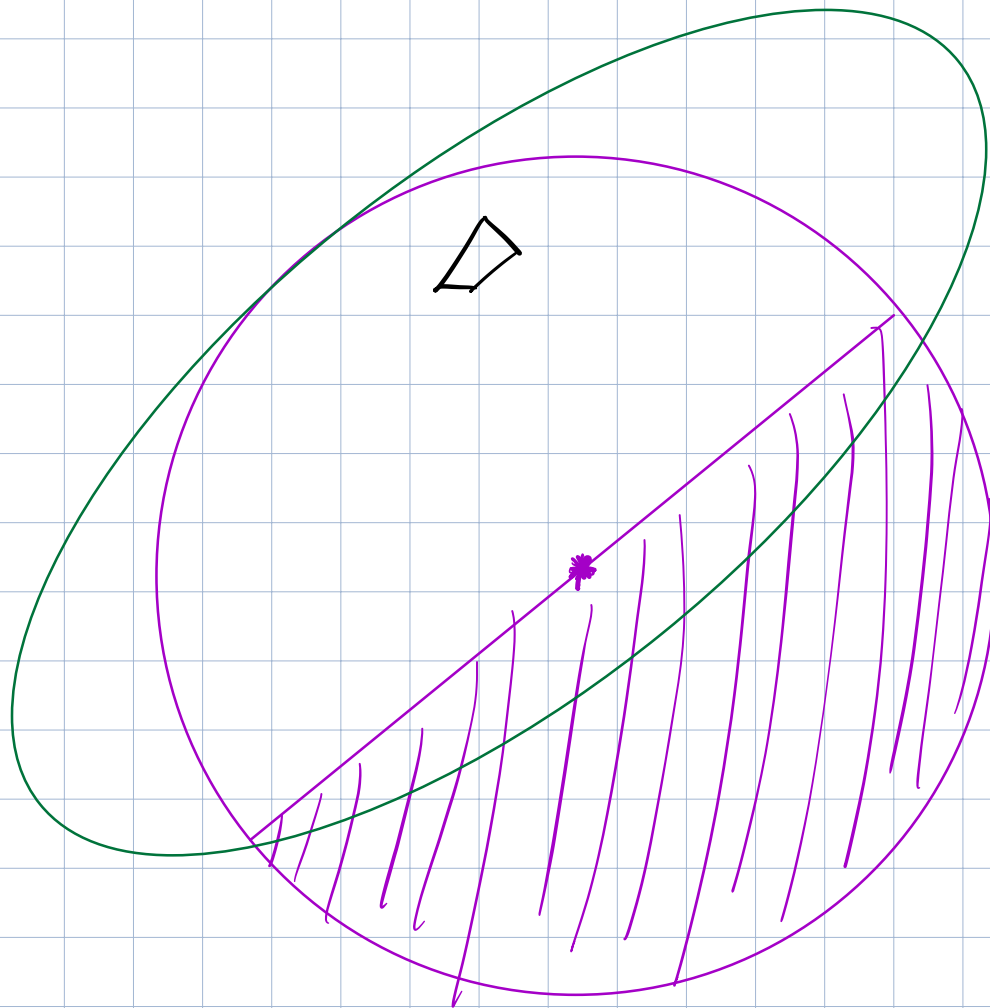
In other words searching for $(x, y) \in P'$
has two outcomes:

- find $(x, y) \in P' \Rightarrow x$ is optimal for $\max \{ c^T x \mid Ax \leq b \}$.
- discover $P' = \emptyset \Rightarrow$ maximum in LP opt. is undefined.

Solving LP search in poly time.

Idea: "Multidimensional binary search,"

Trying to find $x \in P$.



Def. An ellipsoid E in \mathbb{R}^n is the image of the unit ball under an invertible affine transformation. Equivalently it is a set that can be described by

$$E = \left\{ x \in \mathbb{R}^n \mid \|T(x-x_0)\|_2 \leq 1 \right\}$$

for some invertible $n \times n$ matrix T and point $x_0 \in \mathbb{R}^n$ called the center of E .

Def. A separation oracle for a convex set $P \subseteq \mathbb{R}^n$ is a subroutine that accepts a query point x and returns either:

(i) assertion $x \in P$.

(ii) pair $(a, b) \in \mathbb{R}^n \times \mathbb{R}$ such that

$$P \subseteq \mathcal{H}(a, b) = \{x \mid a \cdot x \leq b\}$$

but $x \notin \mathcal{H}(a, b)$.

Suppose we are given a
"numerical complexity bound", B .
(Think: B is # of digits
in the input data)

Then ellipsoid alg runs in $\text{poly}(n, B)$
time assuming:

(1) Separation oracle queries can be
answered in $\text{poly}(n, B)$ time

(2a) We are given an ^{ellipsoid} $E_0 \supseteq P$
such that $\text{vol}(E_0) \leq 2^{\text{poly}(n, B)} \cdot \text{vol}(P)$.

OR

(2b) We are promised that the
separation oracle always
outputs $(a, b) \in \mathbb{Z}^n \times \mathbb{Z}$

$$\|a\|_\infty, |b| < 2^{\text{poly}(n, B)}$$

Lemma. If $B^n = \{x \in \mathbb{R}^n \mid \|x\|_2 \leq 1\}$
 and $\mathcal{H} = \{x \in \mathbb{R}^n \mid x_1 \geq 0\}$

then $B^n \cap \mathcal{H} \subseteq \mathcal{E}$ where

$$\mathcal{E} = \left\{ x \in \mathbb{R}^n \mid \left\| D \cdot \left(x - \frac{1}{n+1} \hat{e}_1 \right) \right\| \leq 1 \right\}$$

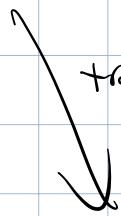
and

$$D = \left(\frac{n+1}{n} \right)^2 \begin{pmatrix} 1 & & & & \\ & 1 - \frac{2}{n+1} & & & \\ & & 1 - \frac{2}{n+1} & & \\ & & & \ddots & \\ & & & & 1 - \frac{2}{n+1} \end{pmatrix}$$

and $\text{vol}(\mathcal{E}) < \exp\left(-\frac{1}{n+1}\right) \cdot \text{vol}(B^n)$.

Ellipsoid \mathcal{E}'

Halfspace \mathcal{H}' thru $\text{ctr}(\mathcal{E}')$



transf T

$$(\mathcal{E}', \mathcal{H}') \mapsto (B^n, \mathcal{H})$$

$$\begin{matrix} \mathcal{E}' & \xleftarrow{T^{-1}} & B^n \\ \mathcal{H}' & \xleftarrow{T^{-1}} & \mathcal{H} \end{matrix}$$