

8 Oct 2021

Simplex Algorithm and LP Duality

To-do list:

- ① wlog $\vec{0}$ is a vertex of P .
- ② Recap local search procedure.
- ③ Deal with "degeneracy": $|J(x)| > n$.
- ④ Prove correctness
~k.a. "strong LP duality."

$$P = \left\{ x \mid a_i \cdot x \leq b_i; \forall i = 1, \dots, m \right\}$$
$$\max \left\{ c \cdot x \mid x \in P \right\}.$$

Simplex alg.: Start at any vertex x of P
while $\exists x'$ neighboring x s.t.
 $c \cdot x' > c \cdot x$
 update $x \leftarrow x'$
endwhile
output x

The wlog assumption is no longer $\vec{0} \in P$.
It is that P is nonempty and we
can efficiently find $x \in P$ vertex.

Step 1. WLOG $\{x_i \geq 0 \forall i\}$ are among the constraints of P .

Given any LP with n variables z_1, \dots, z_n modify to LP with $2n$ variables

$$x_1, \dots, x_n \geq 0$$

$$y_1, \dots, y_n \geq 0$$

Substitute $x_i - y_i$ for z_i in each constraint of original LP, Also same substitution in objective func.

Step 2. Solve a "preliminary LP" to find an initial vertex of P .

$$\text{If } P = \left\{ x \mid \begin{array}{l} a_i \cdot x \leq b_i, \forall i=1, \dots, m \\ x_j \geq 0 \quad \forall j=1, \dots, n \end{array} \right\}$$

let

$$Q = \left\{ (x, s) \mid \begin{array}{l} a_i \cdot x - s \leq b_i, \forall i=1, \dots, m \\ x_j \geq 0 \quad \forall j=1, \dots, n \\ s \geq 0 \end{array} \right\}$$

Solve $\min s$ st. $(x, s) \in Q$.

$x=0, s = 0 \vee \max_i \{-b_i\}$ is a vtx of Q .

If $s > 0$ at optimality, P is empty.

If $s=0$, then x' is a vertex of P .

② vertices, adjacency, finding an adjacent vertex where $c \cdot x' > c \cdot x$.

Recap. $\{a_i \cdot x \leq b_i\}$ can be summarized as

$$Ax \leq b$$



Coordinatewise
 \leq relation
on vectors.

$$A = \begin{bmatrix} -a_1^T \\ -a_2^T \\ \vdots \\ -a_m^T \end{bmatrix}$$

For $J \subseteq [m]$ let A_J, b_J denote the submatrix (subvector) of A (b) obtained by selecting the rows indexed by J .

$$\mathcal{B}(A) = \left\{ J \mid A_J \text{ is an invertible square matrix} \right\}$$

For $J \in \mathcal{B}(A)$, the constraints $\{a_i \cdot x \leq b_i \mid i \in J\}$ are simultaneously tight at one

unique vector

$x_J = A_J^{-1} b_J$
and this is a vertex of P
if it belongs to P .

Two vertices $x_J, x_{J'}$ are
quasi-adjacent if $|J \cap J'| = n-1$.
This means either $x_J, x_{J'}$ lie
along an edge of P
or $x_J = x_{J'}$.

Adjacent: quasi-adjacent and

$$A_J^{-1} b_J \neq A_{J'}^{-1} b_{J'}$$

Given vertex $x = x_J$ if we want
to find all quasi-adjacent
vertices $x_{J'}$ we do the following

for all $i \in J$

for all $i' \in [m] \setminus J$

let $J' = (J \setminus \{i\}) \cup \{i'\}$

if $\det(A_{J'}) \neq 0$

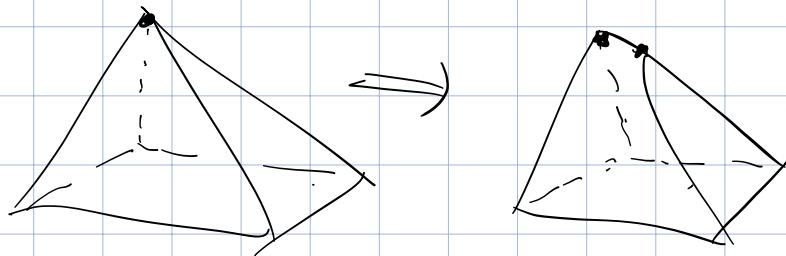
$$x_{J'} = A_{J'}^{-1} b_{J'}$$

is quasi-adj to x_J .

General case of LP reduces to
"non-degenerate" case where every

vertex has exactly n tight constraints, not more, by "perturbation".

Take $Ax \leq b$, perturb to $Ax \leq b + \vec{\epsilon}$



Make b into a vector with coordinates in $\mathbb{R}[\epsilon]$, ordered by comparing polynomials lexicographically.

$$b + \vec{\epsilon} = \begin{bmatrix} b_1 + \epsilon \\ b_2 + \epsilon^2 \\ b_3 + \epsilon^3 \\ \vdots \\ b_n + \epsilon^n \end{bmatrix}$$

If there is $\vec{x} \in \mathbb{R}[\epsilon]^n$ that satisfies $A\vec{x} = (b + \vec{\epsilon})$, then $|J| \leq n$.

This is because every coordinate of the vector $A\vec{x}$ is a linear combination (with \mathbb{R} coeffs) of x_1, x_2, \dots, x_n .

The coords of $A_j \vec{x}$ lie in an n -dim'd linear subspace of $\mathbb{R}[\epsilon]$.

But the coords of $b + \vec{\epsilon}$ are all linearly indep.
 $\Rightarrow |J| \leq n$.

Conclusion: simplex algorithm always terminates (finds a locally optimal vertex).