CS6480: Real-Time and Composition

Robbert van Renesse

Cornell University

Based on Chapters 9 and 10 of "Specifying Systems" by Leslie Lamport

Recall: HourClock

MODULE HourClock

EXTENDS Naturals VARIABLE hr $HCini \triangleq hr \in (1 ... 12)$ $HCnxt \triangleq hr' = \text{IF } hr = 12 \text{ THEN } 1 \text{ ELSE } hr + 1$ $HC \triangleq HCini \land \Box [HCnxt]_{hr} \land WF_{hr}(HCnxt)$

Recall: HourClock

MODULE HourClock

EXTENDS Naturals VARIABLE hr $HCini \triangleq hr \in (1 ... 12)$ $HCnxt \triangleq hr' = \text{IF } hr = 12 \text{ THEN } 1 \text{ ELSE } hr + 1$ $HC \triangleq HCini \land \Box [HCnxt]_{hr} \land WF_{hr}(HCnxt)$ Can we create an HourClock that ticks (approximately) once an hour?

Specifying Real-Time

MODULE RealTime —

EXTENDS *Reals* VARIABLE *now*

$$\begin{array}{ll} RTini \ \triangleq \ now \in Real \\ RTnxt \ \triangleq \ now' \in \{r \in Real : r > now\} \\ RT \ \triangleq \ \land RTini \\ & \land \Box [RTnxt]_{now} \\ & \land \forall r \in Real : WF_{now}(RTnxt \land (now' > r)) \end{array}$$

Note: takes discrete steps

Specifying Real-Time

MODULE RealTime —

EXTENDS *Reals* VARIABLE *now*

$$\begin{array}{ll} RTini \ \triangleq \ now \in Real \\ RTnxt \ \triangleq \ now' \in \{r \in Real : r > now\} \\ RT \ \triangleq \ \land RTini \\ \land \Box [RTnxt]_{now} \\ \land \forall r \in Real : WF_{now}(RTnxt \land (now' > r)) \end{array}$$
 Why this?

Composing HourClock and RealTime

Can we create a spec that extends HourClock to "tick" at (approximately) regular intervals, like a physical clock?

Allowed steps in composition:

$$\begin{bmatrix} hr = 12\\ now = \sqrt{2.47} \end{bmatrix} \rightarrow \begin{bmatrix} hr = 1\\ now = \sqrt{2.47} \end{bmatrix}$$

Clock ticks are instantaneous

$$\begin{bmatrix} hr &= 11\\ now &= 23.4 \end{bmatrix} \rightarrow \begin{bmatrix} hr &= 11\\ now &= 23.5 \end{bmatrix}$$

Time progresses between ticks

Real-time HourClock

- Want time between HCnxt steps to be approximately one hour on the real-time clock
 - Real clocks drift!!
- If t is the time in seconds between two steps, then we want
 - $3600 \rho \le t \le 3600 + \rho$
 - We call ρ the "drift" of a clock (not to be confused with "skew" δ)

Bounding time between HCnxt steps

CONSTANT Rho A positive real number.

VARIABLE tt is the elapsed time since the last HCnxt step. $TNext \triangleq t' = \text{IF } HCnxt$ THEN 0 ELSE t + (now' - now) $Timer \triangleq (t = 0) \land \Box[TNext]_{\langle t, hr, now \rangle}$ $MaxTime \triangleq \Box(t \le 3600 + Rho)$ t is always at most 3600 + Rho. $MinTime \triangleq \Box[HCnxt \Rightarrow t \ge 3600 - Rho]_{hr}$ $An \ HCnxt$ step can occur only if $t \ge 3600 - Rho$. $HCTime \triangleq Timer \land MaxTime \land MinTime$

Bounding time between HCnxt steps



Real-Time HourClock

- MODULE RealTimeHourClock -

EXTENDS Reals, HourClock

VARIABLE now The current time, measured in seconds.

CONSTANT *Rho* A positive real number.

 $\wedge \Box [NowNext]_{now}$

ASSUME $(Rho \in Real) \land (Rho > 0)$

 $I(t) \stackrel{\Delta}{=}$ INSTANCE Inner

 $RTnow \stackrel{\Delta}{=} \land now \in Real$

 $\begin{array}{ll} NowNext & \triangleq & \land now' \in \{r \in Real : r > now\} \\ & \land \text{ UNCHANGED } hr \end{array} \qquad \begin{array}{ll} A \text{ NowNext step can advance now by any amount} \\ & \text{while leaving } hr \text{ unchanged.} \end{array}$

RTnow specifies how time may change.

 $\wedge \forall r \in Real : WF_{now}(NowNext \land (now' > r))$

 $RTHC \triangleq HC \land RTnow \land (\exists t : I(t)! HCTime)$ The complete specification.

Real-Time HourClock

- MODULE RealTimeHourClock -

EXTENDS Reals, HourClock

VARIABLE *now* The current time, measured in seconds.

CONSTANT *Rho* A positive real number.

ASSUME $(Rho \in Real) \land (Rho > 0)$

 $I(t) \stackrel{\Delta}{=}$ INSTANCE Inner

 $NowNext \triangleq \land now' \in \{r \in Real : r > now\} \land NowNext \text{ step can advance } now \text{ by any amount} \\ \land \text{UNCHANGED } hr \qquad \qquad \text{A NowNext step can advance } now \text{ by any amount} \\ RTnow \triangleq \land now \in Real \\ \land \Box[NowNext]_{now} \\ \land \forall r \in Real : WF_{now}(NowNext \land (now' > r)) \\ RTHC \triangleq HC \land RTnow \land (\exists t : I(t)! HCTime) \qquad \text{The complete specification.}$

Why do we need this?

Composition of Specifications

- Given two or more specifications, looking for set of behaviors that satisfy all specifications
- →Composition is the conjunction of specifications

Let's compose two instantiations of HourClock and see what happens...

Rewriting HourClock a bit

MODULE *HourClock*

EXTENDS Naturals VARIABLE hr

$$HCN(h) \triangleq h' = (h\%12) + 1$$

$$\begin{array}{ll} HCini \ \stackrel{\Delta}{=} \ hr \in (1 \dots 12) \\ HCnxt \ \stackrel{\Delta}{=} \ HCN(hr) \\ HC \ \stackrel{\Delta}{=} \ HCini \wedge \Box [HCnxt]_{hr} \end{array}$$

$$TwoClocks \stackrel{\Delta}{=} \land (x \in 1 \dots 12) \land \Box[HCN(x)]_x \land (y \in 1 \dots 12) \land \Box[HCN(y)]_y$$

$$TwoClocks \stackrel{\Delta}{=} \land (x \in 1 \dots 12) \land \Box[HCN(x)]_x$$
$$\land (y \in 1 \dots 12) \land \Box[HCN(y)]_y$$

Not in the "standard" form $Init \wedge \Box [Next]_{vars}$

$$TwoClocks \stackrel{\Delta}{=} \land (x \in 1 \dots 12) \land \Box[HCN(x)]_x$$
$$\land (y \in 1 \dots 12) \land \Box[HCN(y)]_y$$

 $= \land (x \in 1 \dots 12) \land (y \in 1 \dots 12)$ $\land \Box ([HCN(x)]_x \land [HCN(y)]_y)$ $\equiv \land (x \in 1 \dots 12) \land (y \in 1 \dots 12)$ $\land \Box (\land HCN(x) \lor x' = x$ $\land HCN(y) \lor y' = y)$

Because $\Box(F \land G) \equiv (\Box F) \land (\Box G)$.

By definition of $[\ldots]_x$ and $[\ldots]_y$.

Cont'd

$$= \land (x \in 1 \dots 12) \land (y \in 1 \dots 12) \land \Box (\land HCN(x) \lor x' = x \land HCN(y) \lor y' = y)$$

$$= \land (x \in 1 \dots 12) \land (y \in 1 \dots 12) \land \Box (\lor HCN(x) \land HCN(y) \lor HCN(x) \land (y' = y) \lor HCN(y) \land (x' = x) \lor (x' = x) \land (y' = y))$$

Because:

$$\begin{pmatrix} \wedge \lor A_1 \\ \lor A_2 \\ \wedge \lor B_1 \\ \lor B_2 \end{pmatrix} \equiv \begin{pmatrix} \lor A_1 \land B_1 \\ \lor A_1 \land B_2 \\ \lor A_2 \land B_1 \\ \lor A_2 \land B_1 \\ \lor A_2 \land B_2 \end{pmatrix}$$

$$TwoClocks \stackrel{\Delta}{=} \land (x \in 1 \dots 12) \land \Box[HCN(x)]_x \land (y \in 1 \dots 12) \land \Box[HCN(y)]_y$$

$$= \land (x \in 1 ... 12) \land (y \in 1 ... 12)$$
By definition of $[...]_{\langle x, y \rangle}$.

$$\land \Box [\lor HCN(x) \land HCN(y) \\ \lor HCN(x) \land (y' = y) \\ \lor HCN(y) \land (x' = x)]_{\langle x, y \rangle}$$
'standard" form $Init \land \Box [TCNxt]_{vars}$

$$TwoClocks \stackrel{\Delta}{=} \land (x \in 1 \dots 12) \land \Box[HCN(x)]_x \land (y \in 1 \dots 12) \land \Box[HCN(y)]_y$$

$$= \land (x \in 1 ... 12) \land (y \in 1 ... 12)$$
 By definition of $[...]_{\langle x, y \rangle}$.

$$\land \Box [\lor HCN(x) \land HCN(y)]$$

$$\lor HCN(x) \land (y' = y)$$
 Clocks can progress simultaneously!

$$TwoClocks \stackrel{\Delta}{=} \land (x \in 1 \dots 12) \land \Box[HCN(x)]_x \land (y \in 1 \dots 12) \land \Box[HCN(y)]_y$$

$$= \land (x \in 1 \dots 12) \land (y \in 1 \dots 12)$$
 By definition of $[\dots]_{\langle x, y \rangle}$.

$$\land \Box \begin{bmatrix} \lor HCN(x) \land HCN(y) \\ \lor HCN(x) \land (y' = y) \\ \lor HCN(y) \land (x' = x) \end{bmatrix}_{\langle x, y \rangle}$$
 Clocks can progress simultaneously!

If we don't want this, can write: $TwoClocks \land \Box[(x'=x) \lor (y'=y)]_{\langle x, y \rangle}$

Performance properties

- 1. Step must complete within δ time: *safety* property
 - "hard real-time"
- 2. Step must complete within δ time on average: *hyperproperty*
 - Implied by 1
- 3. Step must eventually occur: *liveness* property
 - Implied by 1 or 2

TLA+ only allows specifying *properties*

- A *property* is a set of behaviors (infinite traces) each satisfying some predicate
- "response time < δ " is a predicate over a single behavior
- "average response time < δ " is a predicate over a set of behaviors

Tools for checking hyperproperties

- Some hyperproperties just involve small sets of behaviors
- 2-Safety: two behaviors provide a counterexample
- Security example: "Observational Determinism"
 - Behavior of public variables is deterministic
 - Independent of behavior of private variables or scheduler
 - *Bad*: pair of traces that cause system to look nondeterministic to low observer
- Can be handled in TLA+ using "self-composition"
 - Like TwoClocks
 - Can be model-checked, TLAPS, ...
- Still can't handle average response time...
 - Good: average time over all behaviors is low enough
- Alternative tools: HyperLTL, HyperCTL, Hyper modal μ -calculus