

CS 611

Advanced Programming Languages

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Lecture 26
Type reconstruction
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Type reconstruction

Simple typed language:

$$\begin{aligned} e ::= & x \mid b \mid \lambda x:\tau . e \mid e_1 e_2 \mid e_1 + e_2 \\ & \mid \text{if } e_0 \text{ then } e_1 \text{ else } e_2 \mid \text{let } x=e_1 \text{ in } e_2 \\ & \mid \text{rec } y:\tau_1 \rightarrow \tau_2 . (\lambda x.e) \\ \tau ::= & \text{unit} \mid \text{bool} \mid \text{int} \mid \tau_1 \rightarrow \tau_2 \end{aligned}$$

- Question: Do we really need to write type declarations?

$$e ::= \dots \mid \lambda x.e \mid \dots \mid \text{rec } y.(\lambda x.e)$$

Typing rules

$e ::= x \mid b \mid \lambda x.e \mid e_1 e_2 \mid e_1 \oplus e_2$
 $\mid \text{if } e_0 \text{ then } e_1 \text{ else } e_2 \mid \text{let } x=e_1 \text{ in } e_2 \mid \text{rec } y.\lambda x.e$

$$\frac{\Gamma, x:\tau \vdash e : \tau'}{\Gamma \vdash \lambda x . e : \tau \rightarrow \tau'}$$

Problem: how
does type checker
construct proof?

$$\frac{\Gamma, y:\tau \rightarrow \tau', x:\tau \vdash e : \tau'}{\Gamma \vdash \text{rec } y.\lambda x . e : \tau \rightarrow \tau'}$$

Guess τ, τ' ?

Example

let square = $\lambda z.z * z$ in
 ($\lambda f.\lambda x.\lambda y.$
 if (f x y)
 then (f (square x) y)
 else (f x (f x y)))

What is the type of this program?

Manual type inference

```
let square = λz.z*z in
  (λf.λx.λy.
    if (f x y)
      then (f (square x) y)
      else (f x (f x y)))
```

$z : \text{int}$

$s, \text{square} : \text{int} \rightarrow \text{int}$

$f : \tau_x \rightarrow \tau_y \rightarrow \text{bool}$

$y : \tau_y = \text{bool}$

$x : \tau_x = \text{int}$

Answer:

$(\text{int} \rightarrow \text{bool} \rightarrow \text{bool}) \rightarrow \text{int} \rightarrow \text{bool} \rightarrow \text{bool}$

Type inference

- Goal: reconstruct types even after erasure
- Idea: run ordinary type-checking algorithm, generate *type equations* on *type variables*

$f:T2, x:T5 \vdash f : \text{int} \rightarrow T6 \quad f:T2, x:T5 \vdash 1 : \text{int}$

$f:T2, x:T5 \vdash f \ 1 : T6$

$f:T2 \vdash \lambda x. f \ 1 : T1 \quad (=T5 \rightarrow T6) \quad \frac{}{y:T3 \vdash y : T4} (T3=T4)$

$\vdash \lambda f. \lambda x. f \ 1 : T2 \rightarrow T1 \quad \vdash (\lambda y. y) : T2 \quad (T2=T3 \rightarrow T4)$

$\vdash (\lambda f. \lambda x. (f \ 1)) (\lambda y. y) : T1$

$T2 = T3 \rightarrow T4, T3 = T4, T1 = T5 \rightarrow T6, T2 = \text{int} \rightarrow T6$

Typing rules

$$\begin{array}{c}
 \frac{}{\Gamma \vdash n : \text{int}} \qquad \frac{x \in \text{dom}(\Gamma)}{\Gamma \vdash x : \Gamma(x)} \qquad \frac{\Gamma, x:\mathbf{T}_x \vdash e : \tau}{\Gamma \vdash \lambda x. e : \mathbf{T}_x \rightarrow \tau} \\
 \\
 \frac{\Gamma \vdash e_0 : \tau_0 \quad \Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2 \quad \tau_1 = \tau_2, \tau_0 = \text{bool}}{\Gamma \vdash \text{if } e_0 \text{ then } e_1 \text{ else } e_2 : \tau_1} \\
 \\
 \frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma, x:\tau_1 \vdash e_2 : \tau_2}{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau_2} \qquad \frac{\Gamma, x:\mathbf{T}_1, y:\mathbf{T}_1 \rightarrow \mathbf{T}_2 \vdash e : \tau \quad \tau = \mathbf{T}_2}{\Gamma \vdash \text{rec } y. \lambda x. e : \mathbf{T}_1 \rightarrow \mathbf{T}_2} \\
 \\
 \frac{\Gamma \vdash e_0 : \tau_0 \quad \Gamma \vdash e_1 : \tau_1 \quad \tau_0 = \tau_1 \rightarrow \mathbf{T}_2}{\Gamma \vdash e_0 e_1 : \mathbf{T}_2}
 \end{array}$$

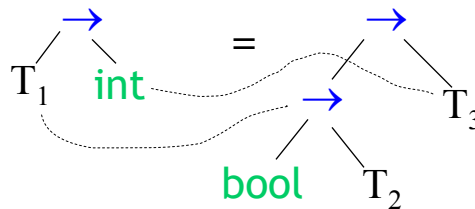
Only type metavariables on RHS of premises

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Unification

- How to solve equations?
- Idea: given equation $\tau_1 = \tau_2$, *unify* type expressions to solve for variables in both
- Example: $\mathbf{T}_1 \rightarrow \text{int} = (\text{bool} \rightarrow \mathbf{T}_2) \rightarrow \mathbf{T}_3$
- Result: *substitution* $\mathbf{T}_1 \mapsto \text{bool} \rightarrow \mathbf{T}_2, \mathbf{T}_3 \mapsto \text{int}$



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Robinson's algorithm (1965)

- *Unification* produces *weakest substitution* that equates two trees
 - $T_1 \rightarrow \text{int} = (\text{bool} \rightarrow T_2) \rightarrow T_3$ equated by any
 $T_1 \mapsto \text{bool} \rightarrow T_2, T_3 \mapsto \text{int}, T_2 \mapsto \tau$
 - **Defn.** S_1 is weaker than S_2 if $S_2 = S_3 \circ S_1$ for S_3 a non-trivial substitution
- **Unify**(E) where E is set of equations gives weakest equating substitution: define recursively

Unify($T = \tau, E$) = **Unify**($E\{\tau/T\}$) $\circ [T \mapsto \tau]$
 (if $T \notin \text{FTV}(\tau)$)

Rest of algorithm

Unify($T = \tau, E$) = **Unify**($E\{\tau/T\}$) $\circ [T \mapsto \tau]$
 (if $T \notin \text{FTV}[\tau]$)

Unify($\emptyset$) = $\emptyset$

Unify($B = B, E$) = **Unify**(E)

Unify($B_1 = B_2, E$) = ?

Unify($T = T, E$) = **Unify**(E)

Unify($\tau_1 \rightarrow \tau_2 = \tau_3 \rightarrow \tau_4, E$)

= **Unify**($\tau_1 = \tau_3, \tau_2 = \tau_4, E$)

Termination? *Degree* = (#vars, size(eqns))

Type inference algorithm

- $\mathcal{R}(e, \Gamma, S) = \langle \tau, S' \rangle$ means
 “Reconstructing the type of e in typing context Γ with respect to substitution S yields type τ , identical or stronger substitution S' or
 “ S' is weakest substitution no weaker than than S such that $S'(\Gamma) \vdash e : S'(\tau)$ ”

Define: **Unify**(E, S) = **Unify**(SE) $\circ S$

– solve substituted equations E and fold in new substitutions

Inductive defn of inference

- $\mathcal{R}(e, \Gamma, S) = \langle \tau, S' \rangle \Leftrightarrow$ “ S' is weakest substitution stronger than (or same as) S such that $S'(\Gamma) \vdash e : S'(\tau)$ ”
- **Unify**(E, S) = **Unify**(SE) $\circ S$

$$\begin{aligned}
 \mathcal{R}(n, \Gamma, S) &= \langle \text{int}, S \rangle & \mathcal{R}(\text{true}, \Gamma, S) &= \langle \text{bool}, S \rangle \\
 \mathcal{R}(x, \Gamma, S) &= \langle \Gamma(x), S \rangle \\
 \mathcal{R}(e_1 e_2, \Gamma, S) &= \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(e_1, \Gamma, S) \text{ in} \\
 &\quad \text{let } \langle T_2, S_2 \rangle = \mathcal{R}(e_2, \Gamma, S_1) \text{ in} \\
 &\quad \langle T_f, \text{Unify}(T_1 = T_2 \rightarrow T_f, S_2) \rangle \\
 \mathcal{R}(\lambda x. e, \Gamma, S) &= \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(e, \Gamma[x \mapsto T_f], S) \text{ in} \\
 &\quad \langle T_f \rightarrow T_1, S_1 \rangle
 \end{aligned}$$

where T_f is “fresh” (not mentioned anywhere in e, Γ, S)

Example

$$\begin{aligned}
 \mathcal{R}((\lambda x.x) \ 1, \emptyset, \emptyset) &= \\
 &\text{let } \langle T_1, S_1 \rangle = \mathcal{R}(\lambda x.x, \emptyset, \emptyset) \text{ in} \\
 &\quad \text{let } \langle T_2, S_2 \rangle = \mathcal{R}(1, \emptyset, S_1) \text{ in} \\
 &\quad \quad \langle T_3, \text{Unify}(T_1 \rightarrow T_2 = T_2, S_2) \rangle \\
 &\quad \quad \boxed{\mathcal{R}(\lambda x.x, \emptyset, \emptyset) = \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(x, \Gamma[x \mapsto T_4], \emptyset) \text{ in} \\
 &\quad \quad \quad \langle T_4 \rightarrow T_1, S_1 \rangle \\
 &\quad \quad \quad = \langle T_4 \rightarrow T_4, \emptyset \rangle} \\
 &= \text{let } \langle T_2, S_2 \rangle = \mathcal{R}(1, \emptyset, \emptyset) \text{ in} \\
 &\quad \langle T_3, \text{Unify}(T_2 \rightarrow T_3 = T_4 \rightarrow T_4, \emptyset) \rangle \\
 &= \langle T_3, \text{Unify}(\text{int} \rightarrow T_3 = T_4 \rightarrow T_4, \emptyset) \rangle \\
 &= \langle T_3, \text{Unify}(\text{int} = T_4, T_3 = T_4, \emptyset) \rangle \\
 &= \langle T_3, \text{Unify}(T_3 = \text{int}, [T_4 \mapsto \text{int}]) \rangle \\
 &= \langle T_3, [T_3 \mapsto \text{int}, T_4 \mapsto \text{int}] \rangle
 \end{aligned}$$

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Implementation

- Can implement with imperative update:

```

datatype type = Int | Bool | Arrow of type * type
              | TypeVar of type option ref

fun freshTypeVar() =
  TypeVar(ref NONE)

fun resolve(t: type) = case t of
  TypeVar(ref (SOME t')) => t'
| _ => t

fun unify(t1: type, t2: type) : unit =
  case (resolve t1, resolve t2) of
  (TypeVar(r as ref NONE), t2) => r := t2
| (t1, TypeVar(r as ref NONE)) => r := t1
| (Arrow(t1,t2), Arrow(t3,t4)) =>
  unify(t1,t3); unify(t2,t4)
| (Int, Int) => () | (Bool, Bool) => ()
| _ => raise Fail "Can't unify types"

```

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Polymorphism

$$\begin{aligned}\mathcal{R}(\lambda x.x, \emptyset, \emptyset) &= \text{let } \langle T_1, S_1 \rangle = \mathcal{R}(x, \Gamma[x \mapsto T_4], \emptyset) \text{ in} \\ &\quad \langle T_4 \rightarrow T_1, S_1 \rangle \\ &= \langle T_4 \rightarrow T_4, \emptyset \rangle\end{aligned}$$

- Reconstruction algorithm doesn't solve type fully... opportunity!
- $\lambda x.x$ can have type $T_4 \rightarrow T_4$ for any T_4
 - polymorphic (= “many shape”) term
 - Could reuse same expression multiple places in program, with different types:

let id = ($\lambda x.x$) in ... (f id) ... (g x id) ... id