Thur Nov 17, 2011

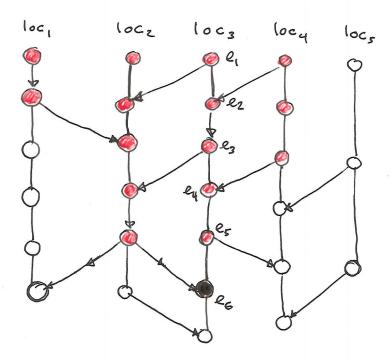
A theory of Events in First-Order Logic

Last time we defined the very important causal order relation, e, (ez. It is the transitive closure of Pred(x,y).

Now we will show that this is a decidable relation, i.e.

YXE. YX: E. ((X<y) u ~ (X<y))

We first look closely at the possible structure of this ordering and review its definition. We use message sequence diagrams



The red events show those which are causally before eg at loc3. The arrows (->) indicate messages are sent, so the target of the arrow is a receive event. The lines without arrows, (-), Say from es to eg at loc3 shows a simple predecessor teletion, event es might change the state at loc3 and can affect what happens after eg.

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A theory of Events in FOL

We can define the predecessor events at a location as a list, say at loc3 the predecessor events of le are, so the list before(le) = [les,lu,l3,l2,li]. The events causally before an event form a tree which we call the cone of the event.

Definition before(e) = if first(e) then [e, nil]

else cons(e, before (pred (e)))

where cons(e, [e,...,en, nil]) =

[e, e, ..., en, nil]

Definition

Cone (e) =

If rov?(e) then if first(e)

then (e, loc(e), some (sender(e)))

else (e, cone(pred(e)), cone(sender(e)))

else if first(e)

then (e, loce), nil)

else (e, cone(pred(e)), nil)

One way to decide whether e, < ez is to form cone(ez) and then check to see if e, e cone(ez) using the fact that equality of events is decidable.

Another way is to prove it by induction of causal order.

Theorem Yx, y: E. (x<y) v ~ (x<y) - causal order is decidable.

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The induction principle for causal order is this

Axion Yx: E. (Yxx => P(y)) => P(x)) => Yx: E. P(x)

This is like complete induction on N, recall

$$\forall n((\forall y.(y< n \Rightarrow P(y)) \Rightarrow P(n)) \Rightarrow \forall x. P(x)$$

See the supplemental notes for Tue Nov 15 for an argument that causal order is strongly well founded, given in the technical report A Causal Logic of Events in Formalized Computational type theory.

In that article we do not discuss the idea of a choice function of that maps E to natural numbers N. Thus that account does not take into acce consideration the kinds of nondeterminism that arise in real word systems. Such an account depends on some mechanism to introduce choice or uncertainty in the model. This choice arises from not knowins in advance the arrival order of messages destined for a location. We can conduct a "tour" of event orderioss only after the fact. We do not have time in this course to discuss the mechanisms for non determinism in detail. We will however examine the notion in more detail when we study consensus profocols next week. We will sketch the idea of choice sequences.

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Next we examine the notion of state at a location. We imagine that processes at loci have access to local state accessible by identifiers, another basic sort of the theory denoted Id(x). The state stores data or values. We say

Vi,x, (Loca) & Id(x) => For Value (v) & St(i,x,v))

We assume only finitely many identifiers for the examples we consider, denoted x, x, x2, ... We can specify the initial values x initially i is the initial value of identifier x at location i.

We also introduce the temporal operators

x when e

Axion Ye: E. - first(e) => (x when e) = (x after pred(e))

Define & De Iff & after e + & when e This is the change operator.

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Mossage Automata Realizers for event statements

- 1. Ci p(x initially)) realizes Yeer. first(e) => p(x when e)
- 2. Ei TCY (v) effect x:=f(s,v) for s the state at i
 realizes

 VN: Value. Yl:Link. Yebi. l=toy(v) => (x after e) = f(s,v)
- 4. @i only Laffects & for La list of actions. realizes

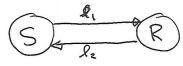
 Veei. Kind(e) & L => (x De) & (x De => kind(e) & L)

 This is called a frame condition.
- 5. @l' only L sends (v, tag) realizes

 Ve @dest(l). kind(e) = rcv_e((v, tas)) => kind(sender(e)) EL.

 This is called a sends frame condition.

Now we are prepared to treat the acknowledgement protocol from Nov10 in more detail. Recall the context.



S and R are processes linked by FIFO communication channels li, lz.

As an example, suppose we want a system of processes \mathcal{P} with the property that two of its processes, say S and R connected by link ℓ_1 from S to R and ℓ_2 from R to S should operate using explicit acknowledgement. So when S sends to R on ℓ_1 with tag tg, it will not send again on ℓ_1 with this tag until receiving an acknowledgement tag, ack, on ℓ_2 . The specification can be stated as a theorem about event structures arising from extensions mathcal(P)' of \mathcal{P} , namely:

Theorem 1 For any distributed system \mathcal{P} with two designated processes S and R linked by $S \xrightarrow{\ell_1} R$ and $R \xrightarrow{\ell_2} S$ with two new tags, tg and ack, we can construct an extension \mathcal{P}' of \mathcal{P} such that the following specification holds: $\forall e_1, e_2 : E.loc(e_1) = loc(e_2) = S \& kind(e_1) = kind(e_2) = send(\ell_1, tg). e_1 < e_2 \Rightarrow \exists r : E. loc(r) = S \& kind(r) = rcv(\ell_2, ack). e_1 < r < e_2.$

This theorem is true because we know how to add clauses to processes S and R to achieve the specification, which means that the specification is constructively achievable. We can prove the theorem constructively and in the process define the extension \mathcal{P}' implicitly. Here is how.

Proof: What would be required of \mathcal{P}' to meet the specification? Suppose in \mathcal{P}' we have $e_1 < e_2$ as described in the theorem. We need to know more than the obvious fact that two send events occurred namely $< tg, m_1 >, < tg, m_2 >$ were sent to R. One way to have more information is to remember the first event in the state. Suppose we use a new Boolean state variable of S, called rdy, and we require that a send on ℓ_1 with tag tg happens only if rdy = true and that after the send, rdy = false. Suppose we also stipulate in a frame condition that only a receive on ℓ_2 sets ready to true, then we know that rdy when $e_1 = true$, rdy after $e_1 = false$ and rdy when $e_2 = true$. So between e_1 and e_2 , some event e' must happen at S that sets rdy to true. But since only a $rcv(\ell_2, ack)$ can do so, then e' must be the receive required by the specification.

This argument proves constructively that \mathcal{P}' exists, and it is clear that the proof shows how to extend process S namely add these clauses:

$$\begin{array}{l} a: \textbf{if} \ rdy = true \textbf{then} \\ send(\ell_1, < tg, m >); rdy := false \\ r: \textbf{rcv}(\ell_2, ack) \ \textbf{effect} \ rdy := true \\ only[a, r] \ \textbf{affect} \ rdy \end{array}$$

QED

We could add a liveness condition that a send will occur by initializing rdy to true. If we want a live dialogue we would need to extend R by

$$rcv(\ell_1, < tg, m >)$$
 effect send (ℓ_2, ack)

but our theorem did not require liveness.