

CS5630 Physically Based Realistic Rendering

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Spring 2026

13 Camera modeling

Topics

(Shading and geometric normals)

Cameras and camera optics (in the real world)

Modeling cameras in rendering

Aliasing and pixel filters

The measurement equation

Cameras

Roles of camera in a renderer

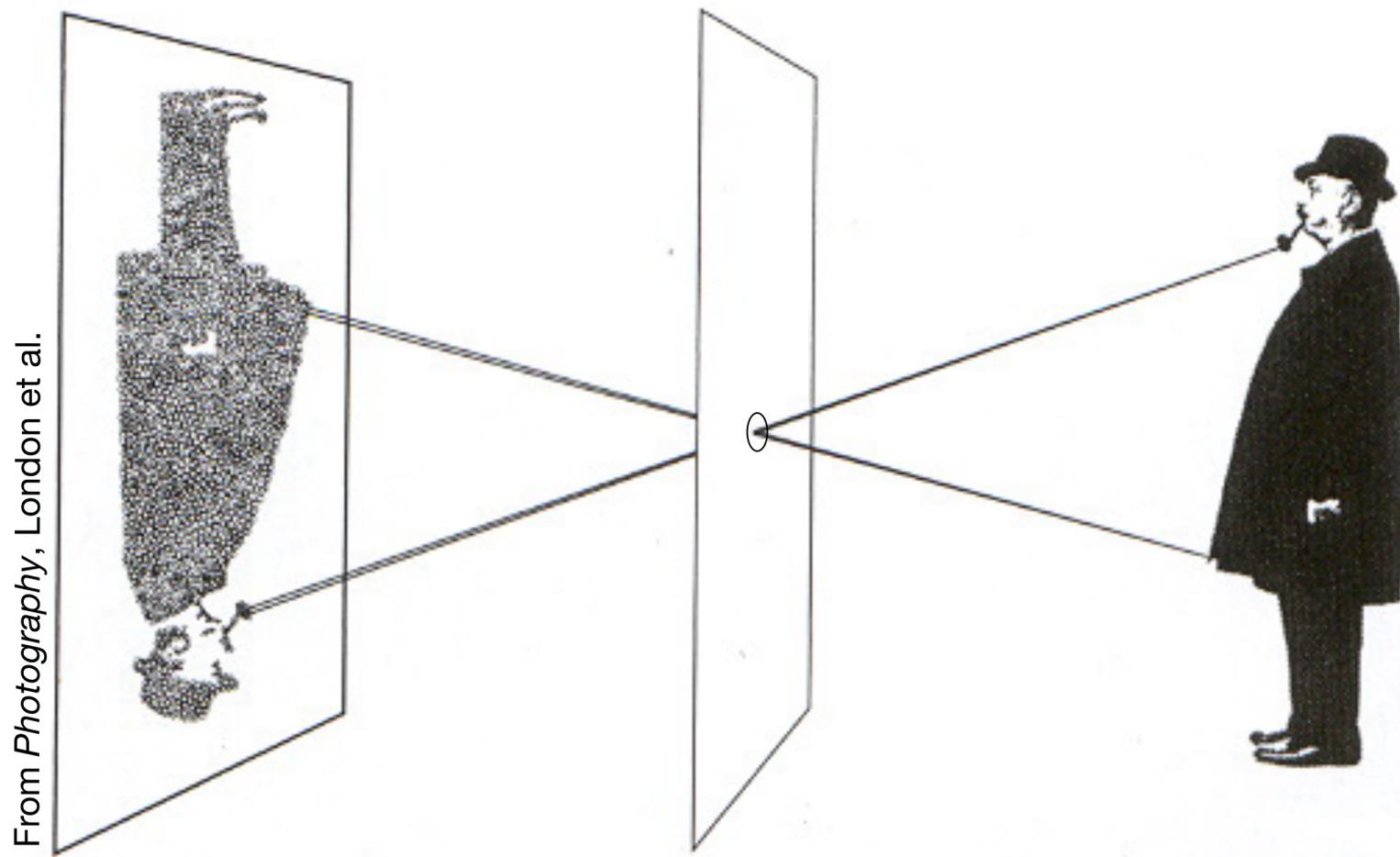
- controls generation of viewing rays
- determines what part of the scene each pixel sees
- models camera optics to create photographic/cinematographic look

Goals in designing camera model

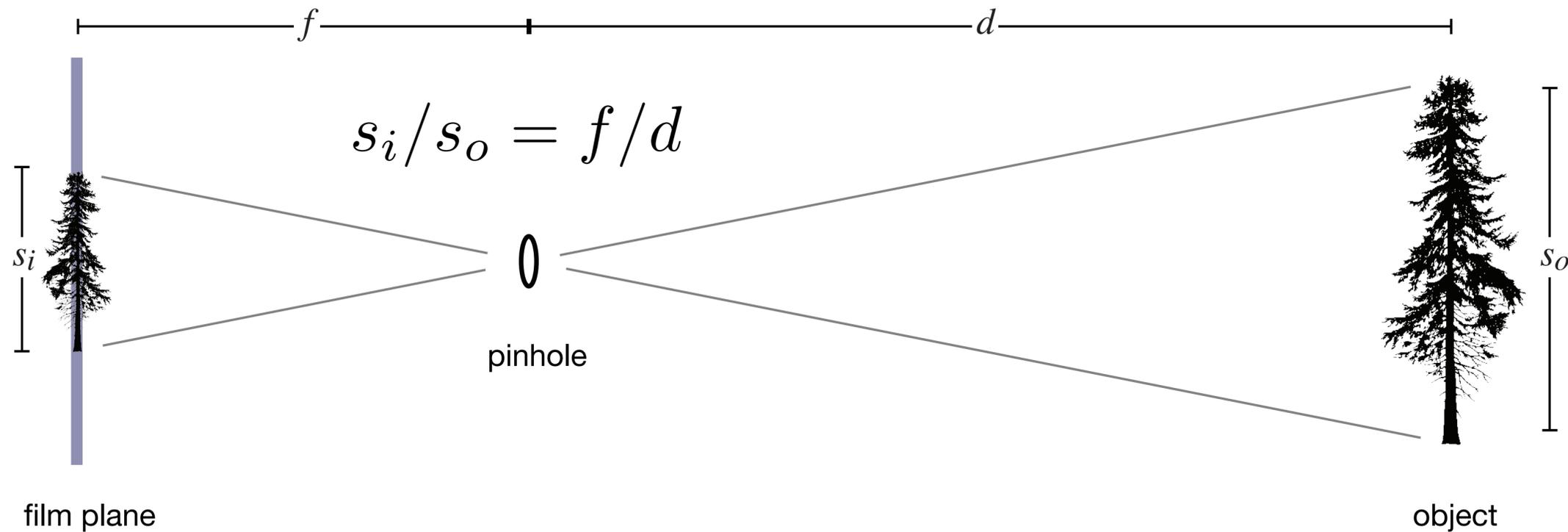
- reasonable efficiency
- mimic the most obvious effects of camera optics
- sometimes: mimic the look of a particular camera lens

Pinhole camera

- **Simplest possible camera**
 1. light tight box with hole
 2. film
- **Rays are selected simply by occlusion**



“Focal” length



- **Double “focal length” leads to**
image twice as large
one fourth as much illumination at image plane

Field of view

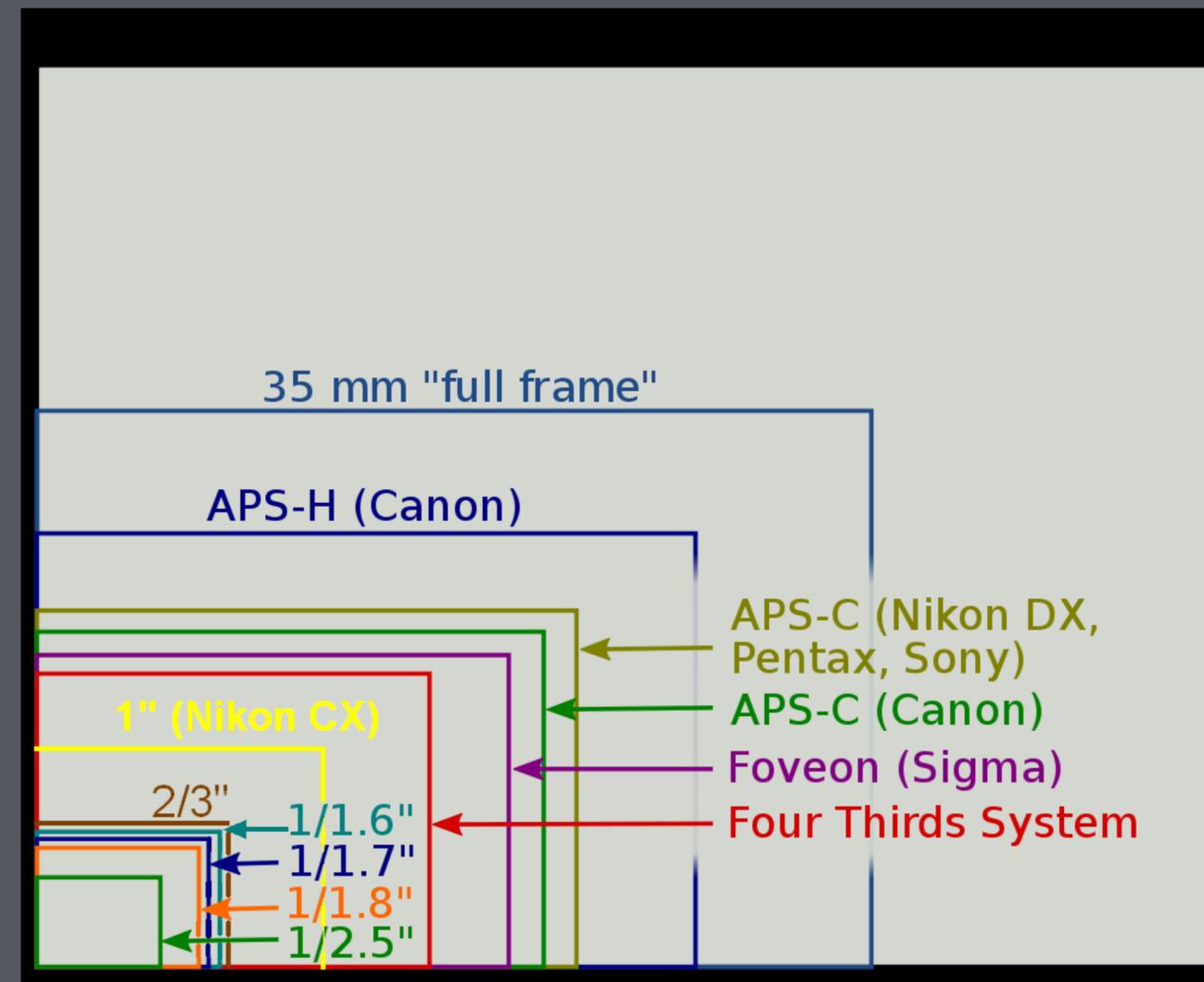
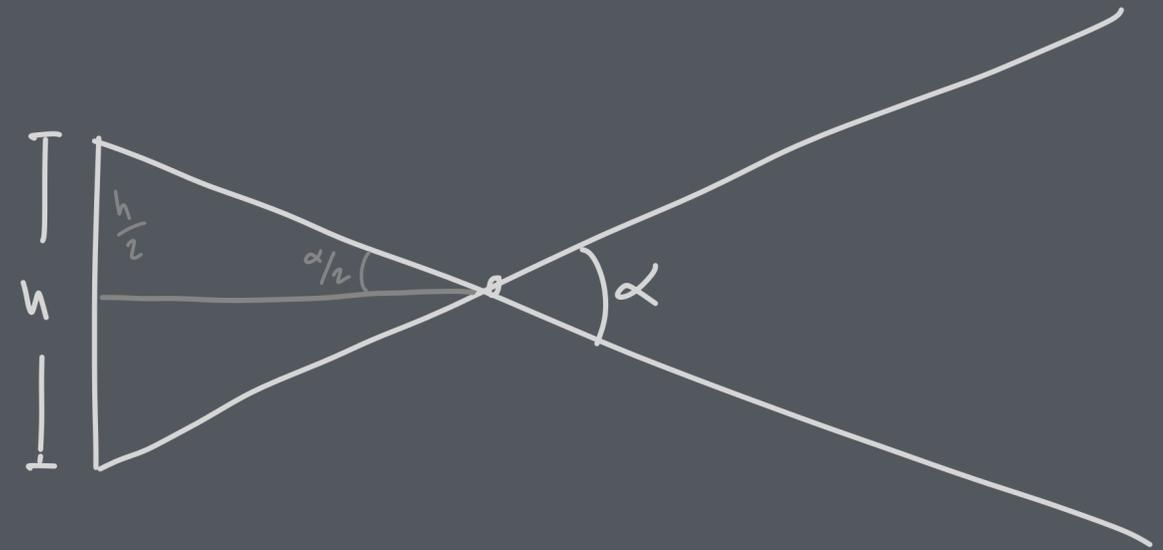
Depends on focal length and image size

$$\alpha = 2 \tan^{-1} \frac{h}{2f}$$

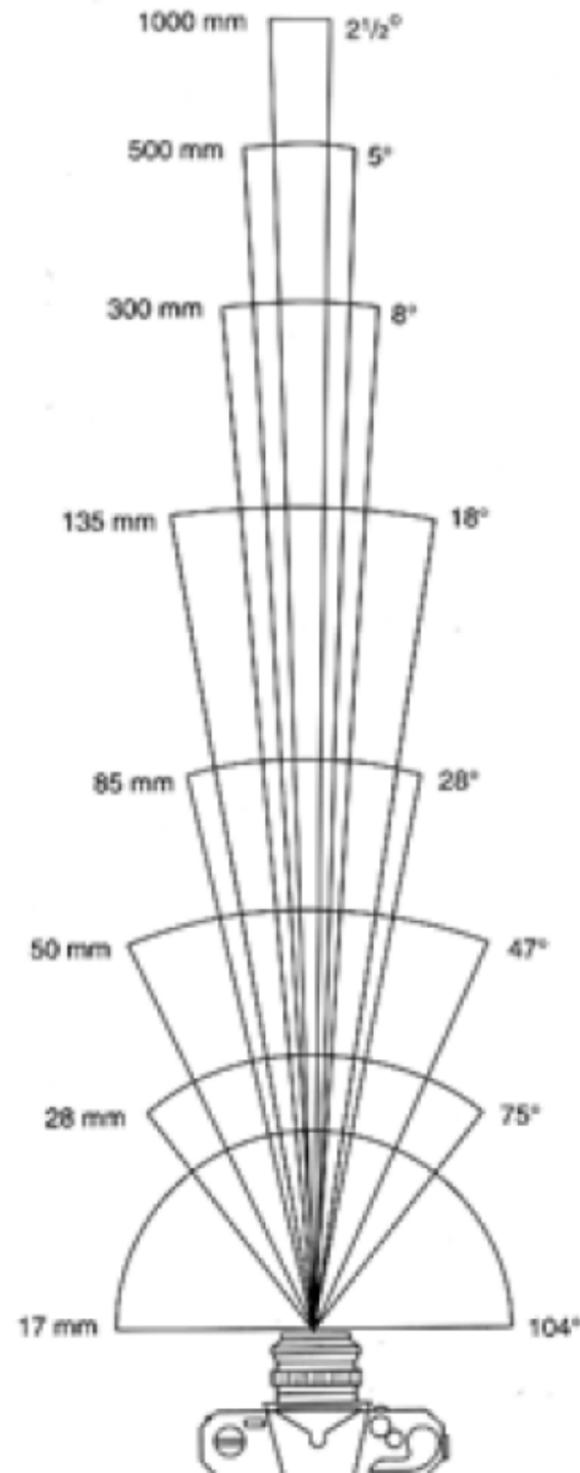
- h is the size of the image; α is the field of view

Habits were formed with 35mm film cameras

- image is 36 x 24 mm
- fields of view are often discussed in terms of the corresponding focal length in 35mm format
 - 18mm = 67° v.f.o.v. — super-wide angle
 - 28mm = 46° v.f.o.v. — wide angle
 - 50mm = 27° v.f.o.v. — “normal”
 - 100mm = 14° v.f.o.v. — narrow angle (“telephoto”)



Changing FOV—viewpoint constant



slide by Alyosha Efros, CMU



17mm



28mm



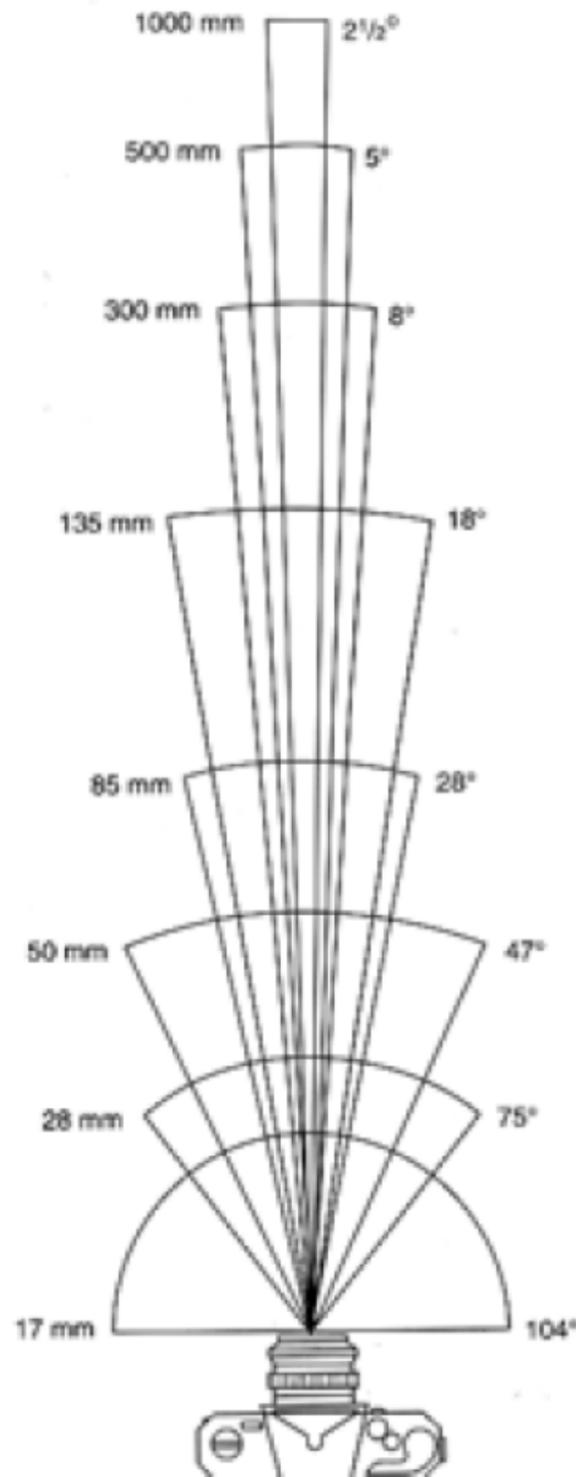
50mm



85mm

From London and Upton

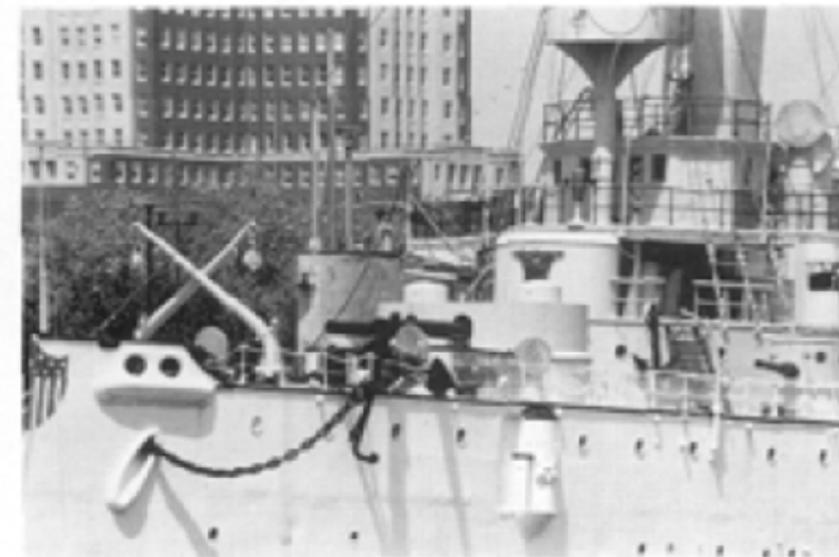
Changing FOV—viewpoint constant



slide by Alyosha Efros, CMU



135mm



300mm



50mm



17mm

From London and Upton

Changing FOV—magnification constant



Photos: Micaël Reynaud

Changing FOV — magnification constant



close viewpoint
wide angle
large scale differences



far viewpoint
narrow angle
small scale differences

[Ansel Adams]

Perspective vs. viewpoint

- **Portrait: distortion with wide angle**
- **Why?**



Wide angle



Standard



Telephoto

Fields of view in a modern smartphone

wide/normal

“1/1.28 type” 10x7.5mm sensor
“24mm equivalent” is 53°
f = ~7.5mm

ultra-wide

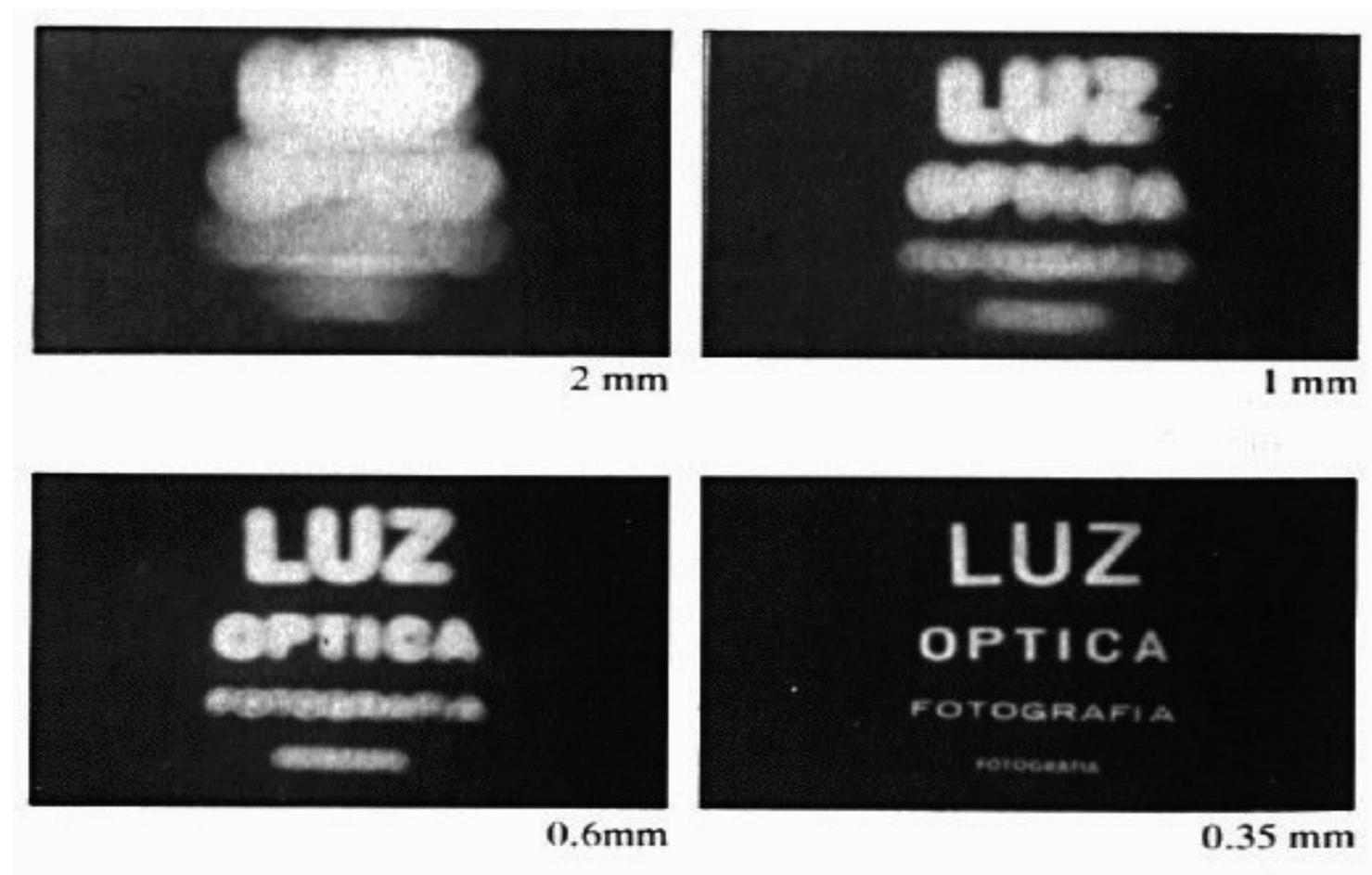
“1/2.55 type” 5.7x4.2mm sensor
“13mm equivalent” is 85°
f = ~2.3mm

telephoto

“1/2.55 type” 5.7x4.2mm sensor
“100mm equivalent” is 14°
f = ~17mm



Smaller pinhole is sharper ...to a point



Slide after Steve Seitz, U. Washington

Camera, version 0: box with hole

- **Simple, distortion-free, charmingly analog, but:**

Large pinholes produce blurry images

Small pinholes produce dim images

Diffraction limits sharpness for very small pinholes



Francesco Capponi

Blown egg transformed
into a wide-angle
pinhole camera

[http://www.petapixel.com/2011/04/25/
eggs-transformed-into-pinhole-cameras/](http://www.petapixel.com/2011/04/25/eggs-transformed-into-pinhole-cameras/)

Forming images with lenses



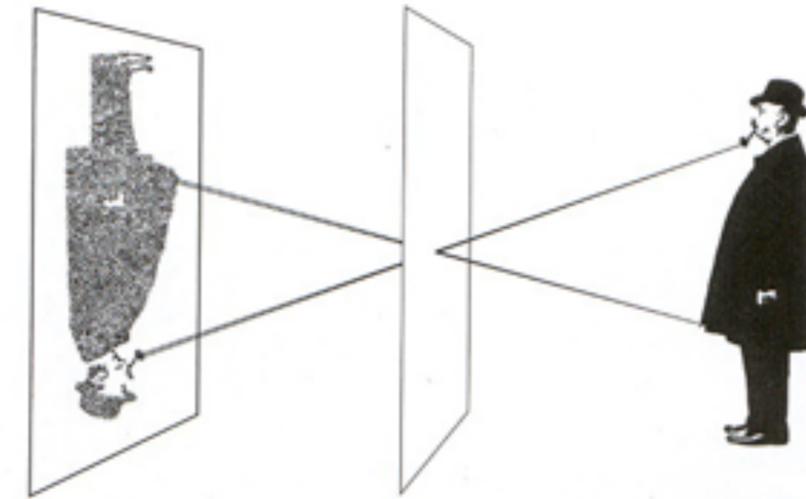
Lenses

- Gather more light!
- But need to be focused

Photograph made with small pinhole



To make this picture, the lens of a camera was replaced with a thin metal disk pierced by a tiny pinhole, equivalent in size to an aperture of $f/182$. Only a few rays of light from each point on the

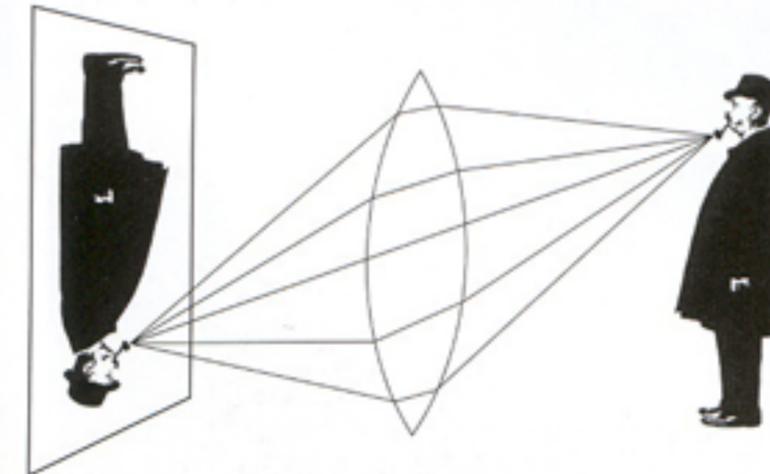


subject got through the tiny opening, producing a soft but acceptably clear photograph. Because of the small size of the pinhole, the exposure had to be 6 sec long.

Photograph made with lens



This time, using a simple convex lens with an $f/16$ aperture, the scene appeared sharper than the one taken with the smaller pinhole, and the exposure time was much shorter, only 1/100 sec.



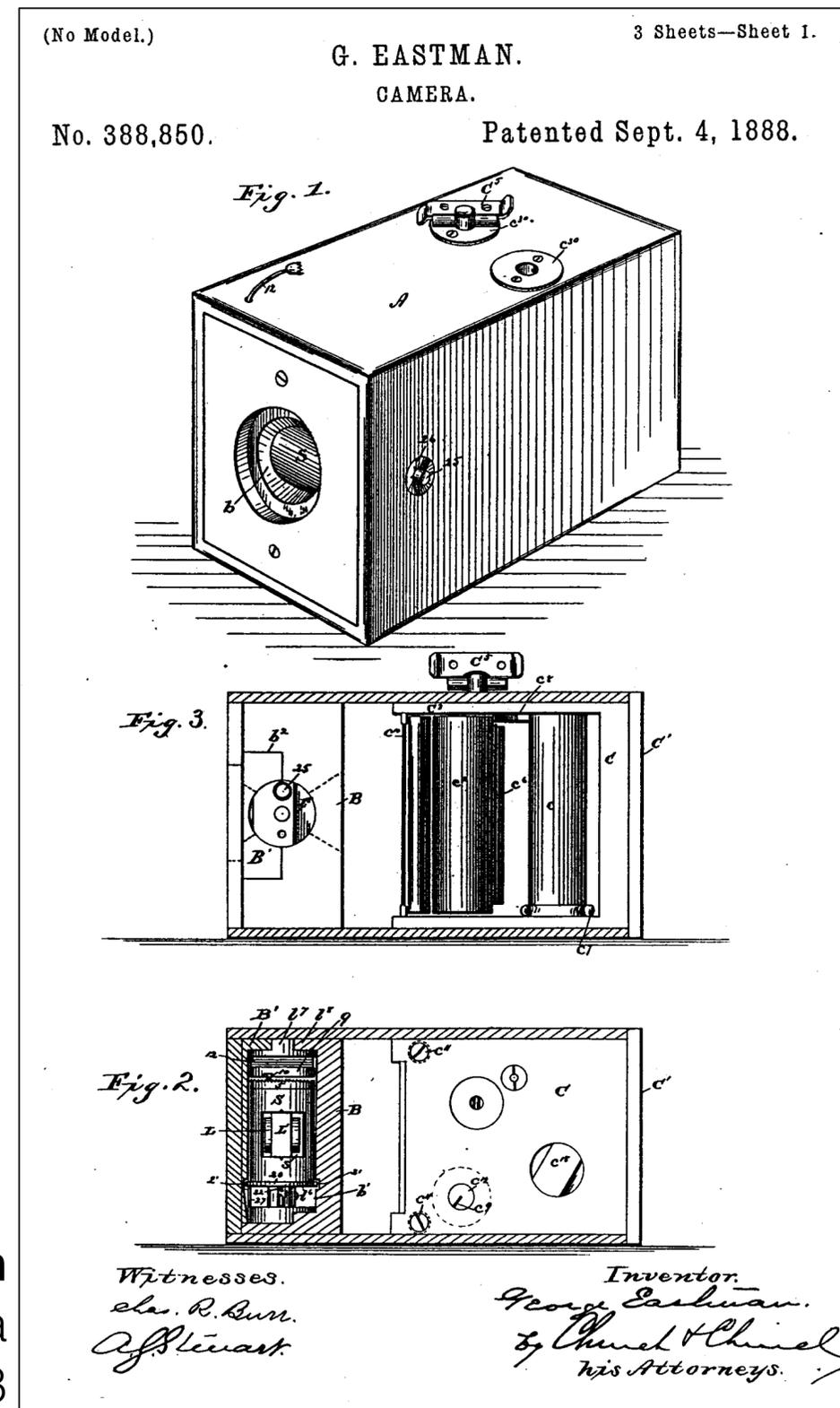
The lens opening was much bigger than the pinhole, letting in far more light, but it focused the rays from each point on the subject precisely so that they were sharp on the film.

From Photography, London et al.

Camera, v. 1: Box with lens & shutter

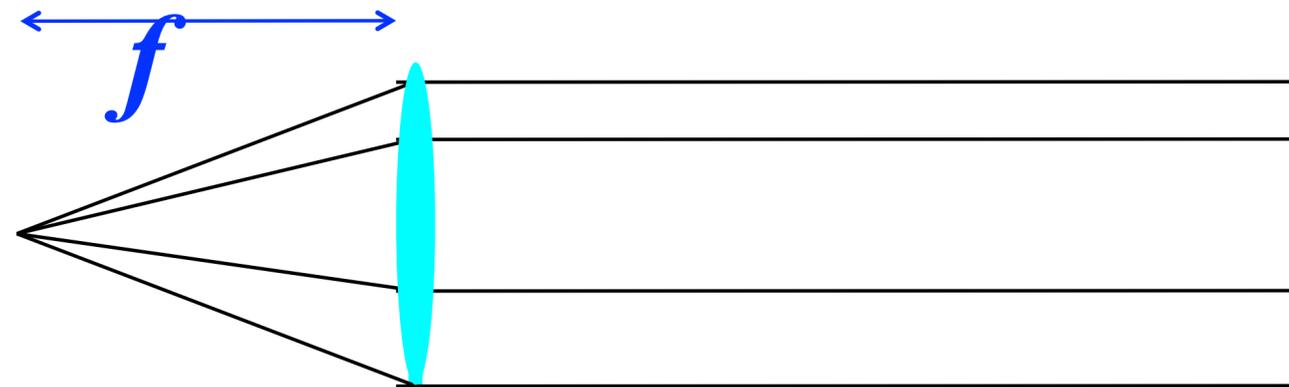
- **First practical cameras had**
 - film (roll film or glass plate)
 - lens (small aperture)
 - mechanism for winding film
 - mechanism for triggering shutter
- **Limitations**
 - cannot control exposure
 - focus is fixed (like an inexpensive cell phone camera today)
 - want to be outdoors in strong light

George Eastman
Kodak Camera
1888

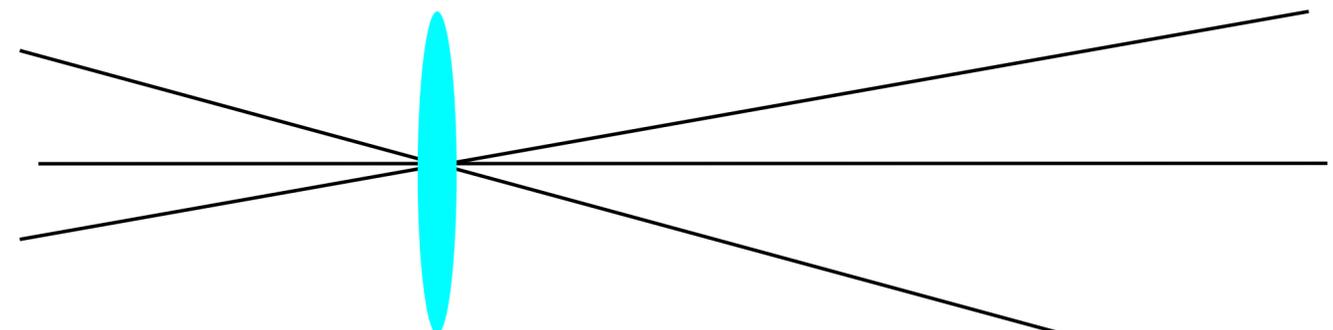


Thin lens optics

- Simplification of geometrical optics for well-behaved lenses
- All parallel rays converge to one point on a plane located at the focal length f

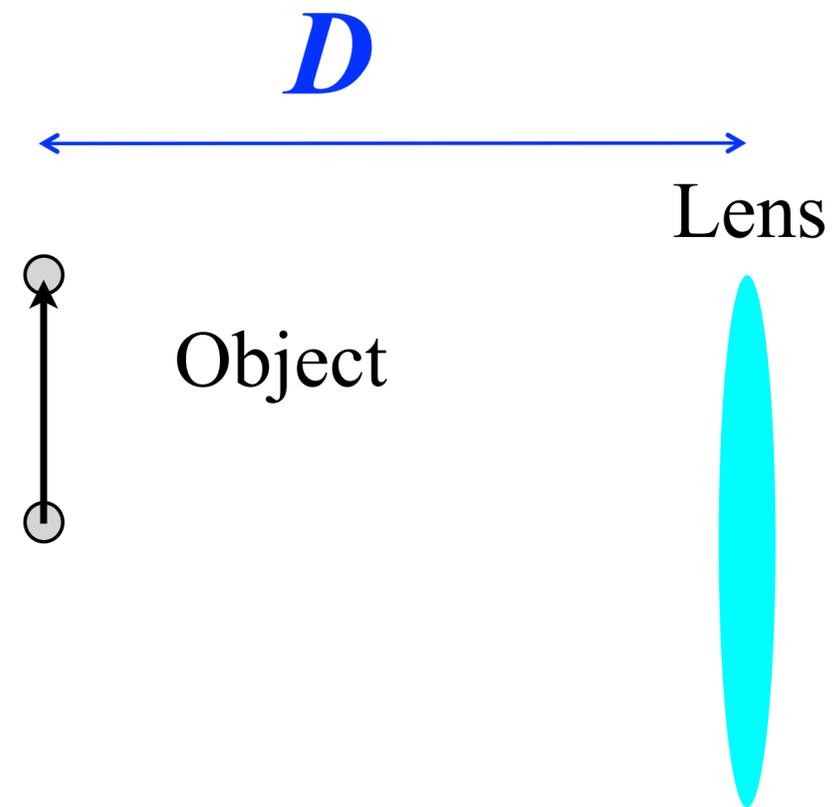


- All rays going through the center are not deviated
 - Hence same perspective as pinhole



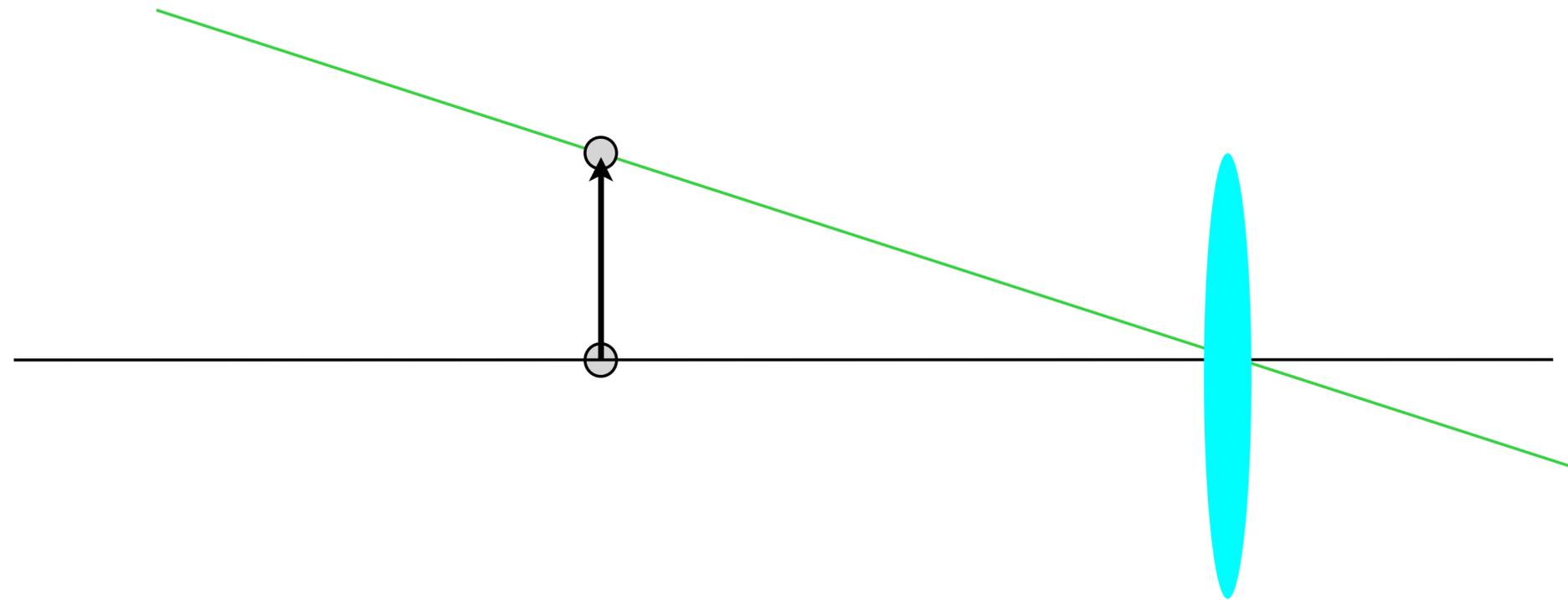
How lenses focus

- Let's look at an object at distance D



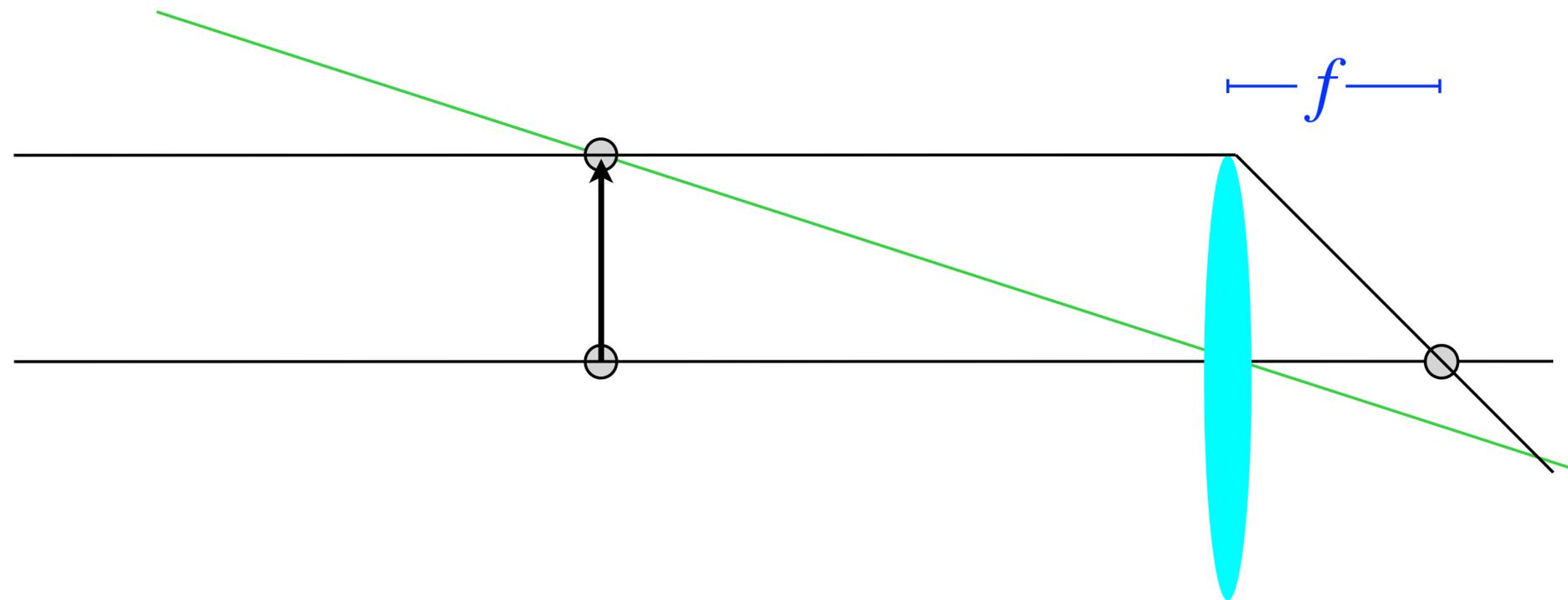
How to trace rays

- Start by rays through the center



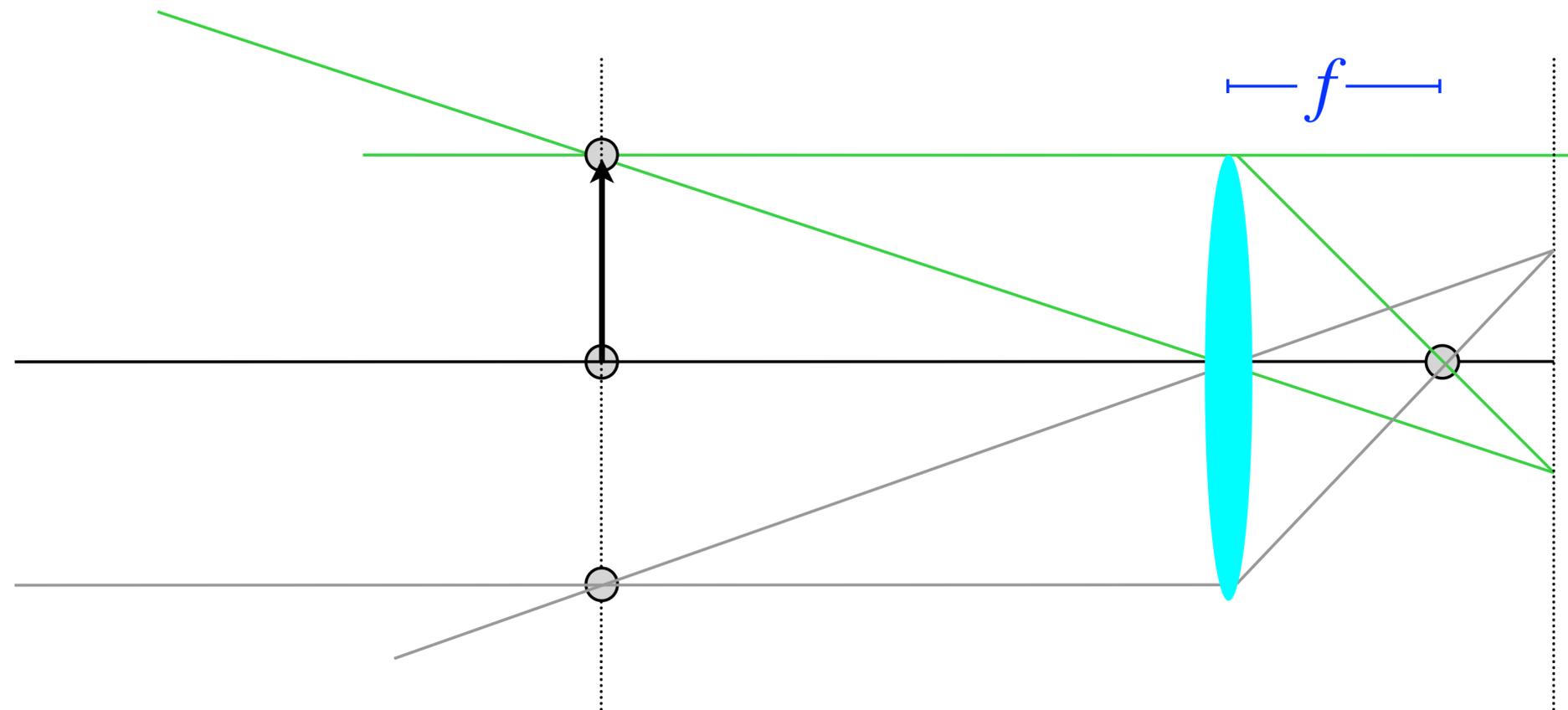
How to trace rays

- Start by rays through the center
- Choose focal length, trace parallels

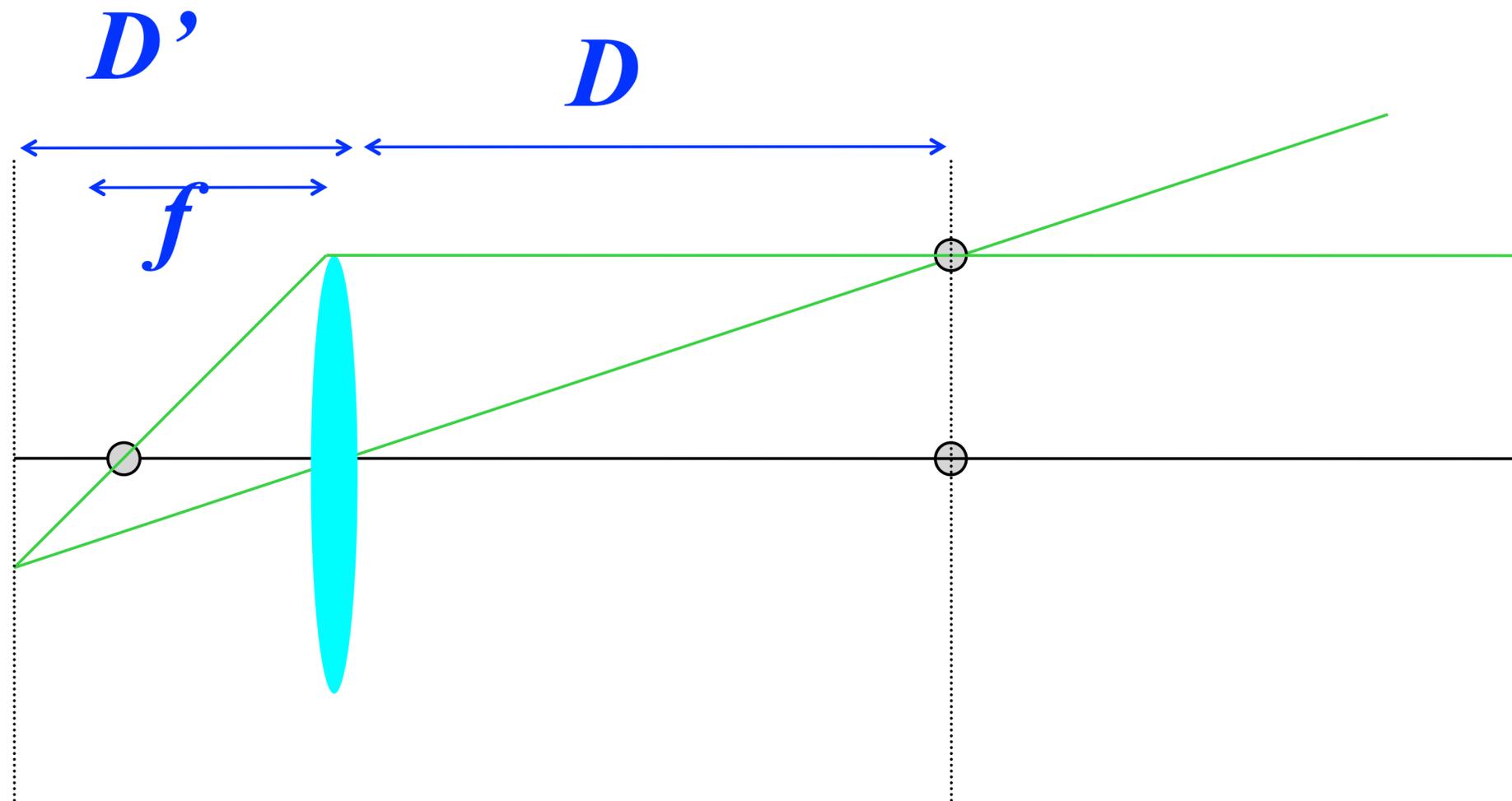


How to trace rays

- Start by rays through the center
- Choose focal length, trace parallels
- You get the focus plane for a given scene plane
 - All rays coming from points on a plane parallel to the lens are focused on another plane parallel to the lens

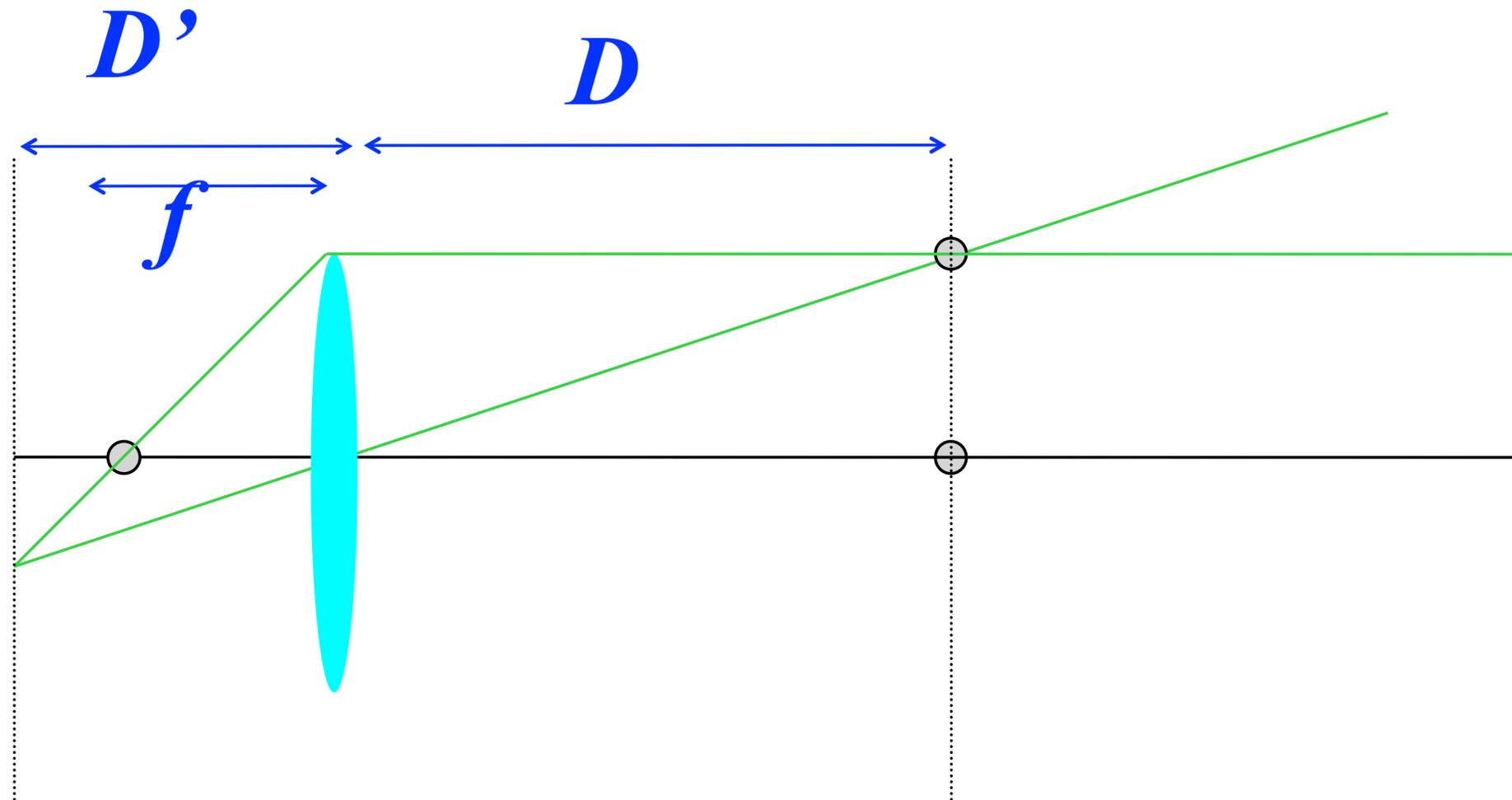


Thin lens formula



Thin lens formula

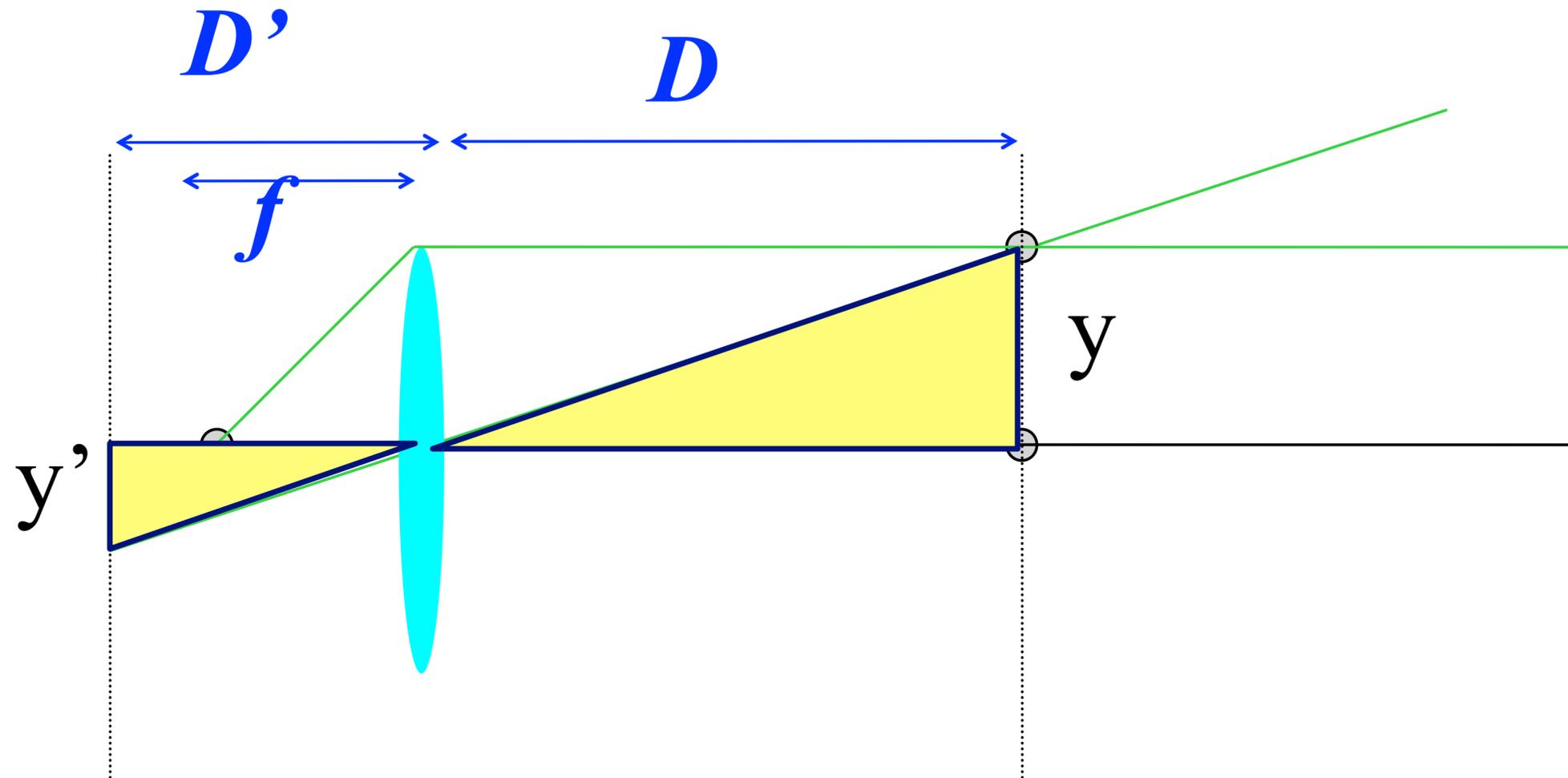
Similar triangles everywhere!



Thin lens formula

Similar triangles everywhere!

$$y'/y = D'/D$$

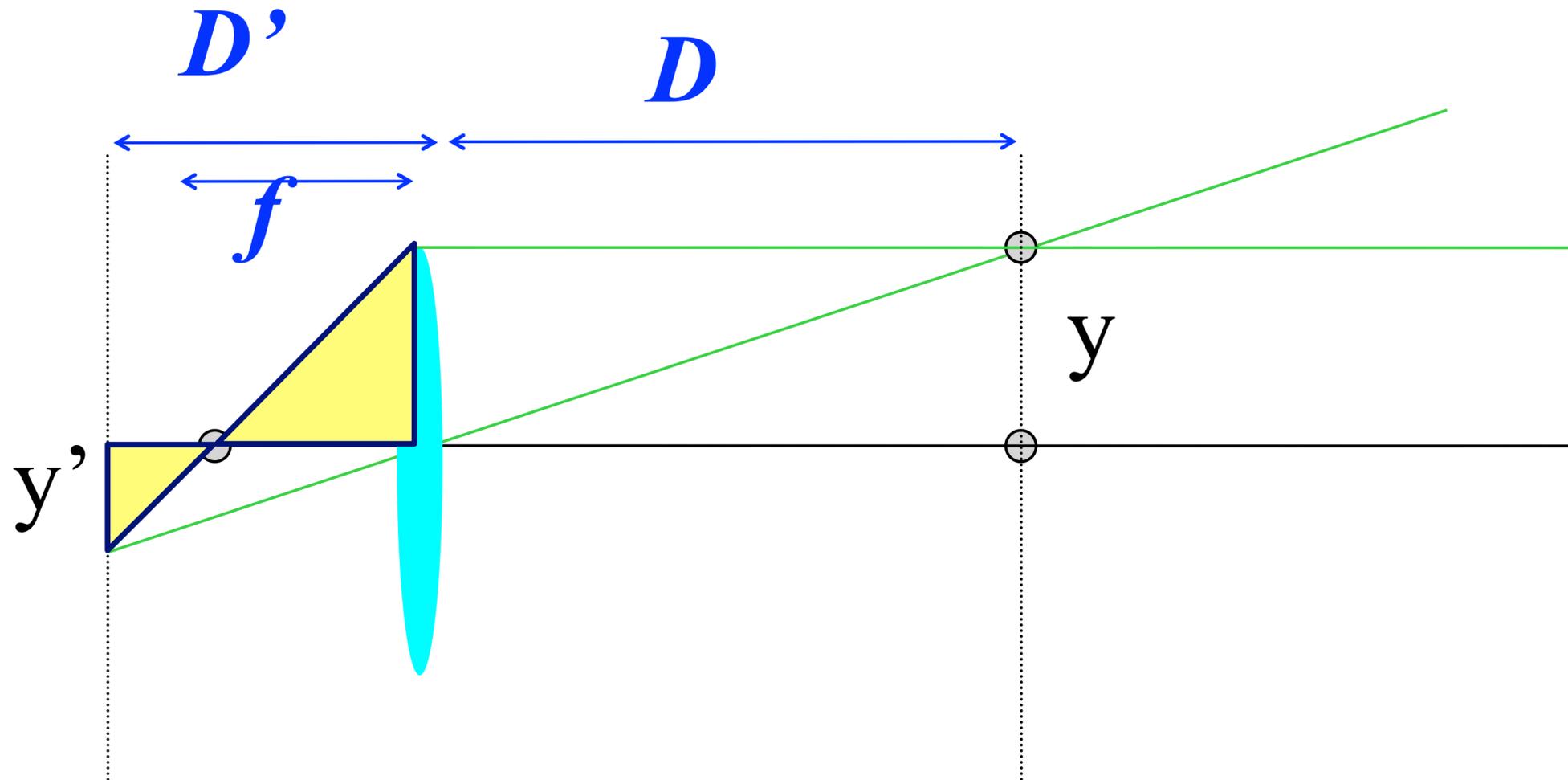


Thin lens formula

Similar triangles everywhere!

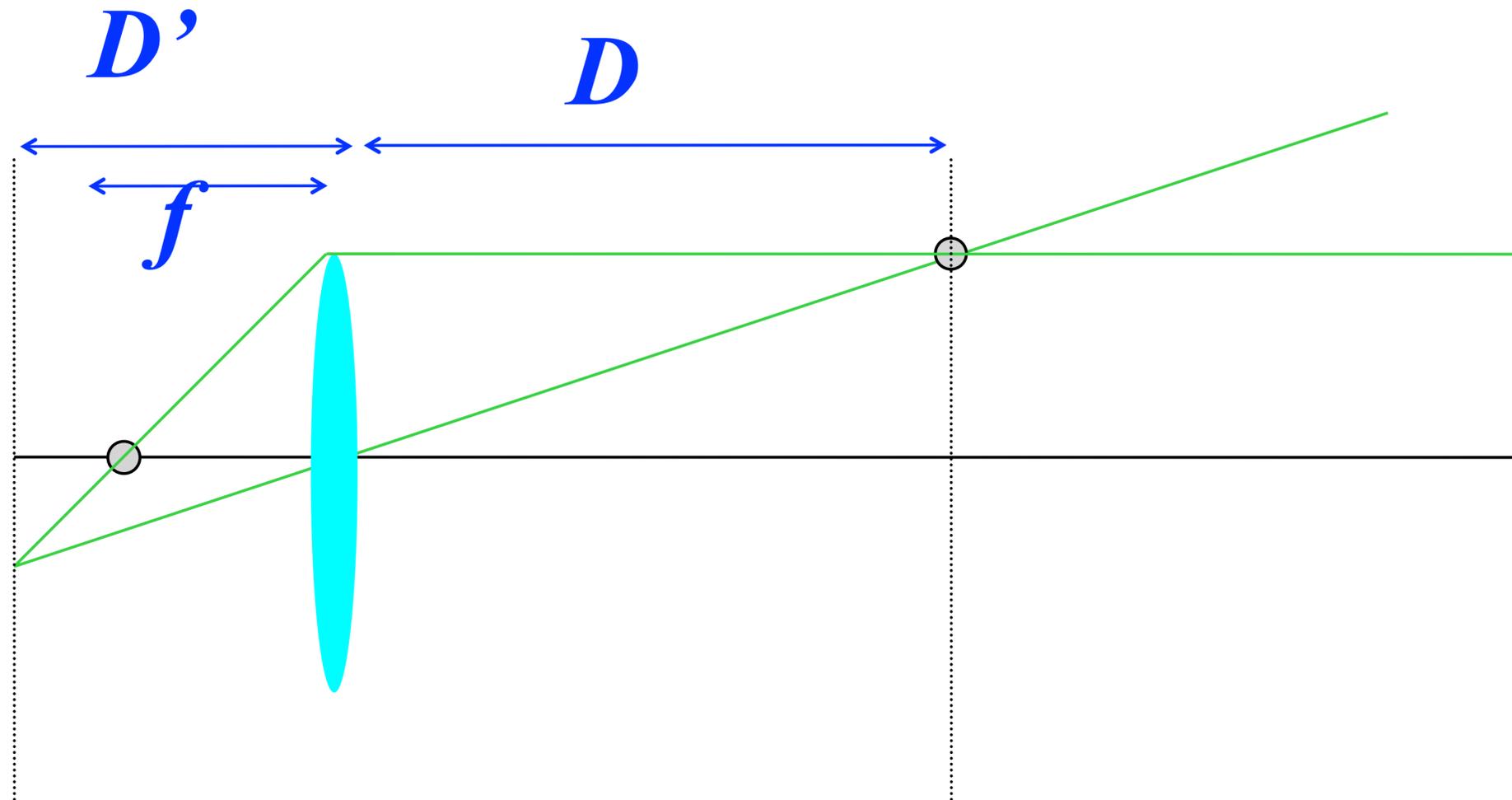
$$y'/y = D'/D$$

$$y'/y = (D' - f)/f$$



Thin lens formula

$$\frac{1}{D'} + \frac{1}{D} = \frac{1}{f}$$



Thin lens focusing

How to focus on things closer than infinity?

- move the lens farther from the image sensor

$$\frac{1}{f} = \frac{1}{D_{\text{obj}}} + \frac{1}{D_{\text{img}}}$$

- focus at infinity: $D_{\text{obj}} = 0$ and $D_{\text{img}} = f$
- symmetric focus ($4f$ optical system): $D_{\text{obj}} = D_{\text{img}} = 2f$
- can approach focusing at $D_{\text{obj}} \approx f$ by moving image sensor far away, but not so practical

So in a camera, make D_{img} adjustable

- put the lens on a fine-thread screw
- user adjusts to focus on desired subject

More ingredients

- **Timed shutter**

with a UI for setting the duration of the exposure (“**exposure time**”)

- **Variable aperture**

effective size of the hole through which light enters can be changed with a UI for setting the size (“**aperture**”)

- **Viewfinder**

some way better than guessing to tell what you are photographing



photo: Ken Rockwell

Camera, v. 2: 3 variables, 5 controls

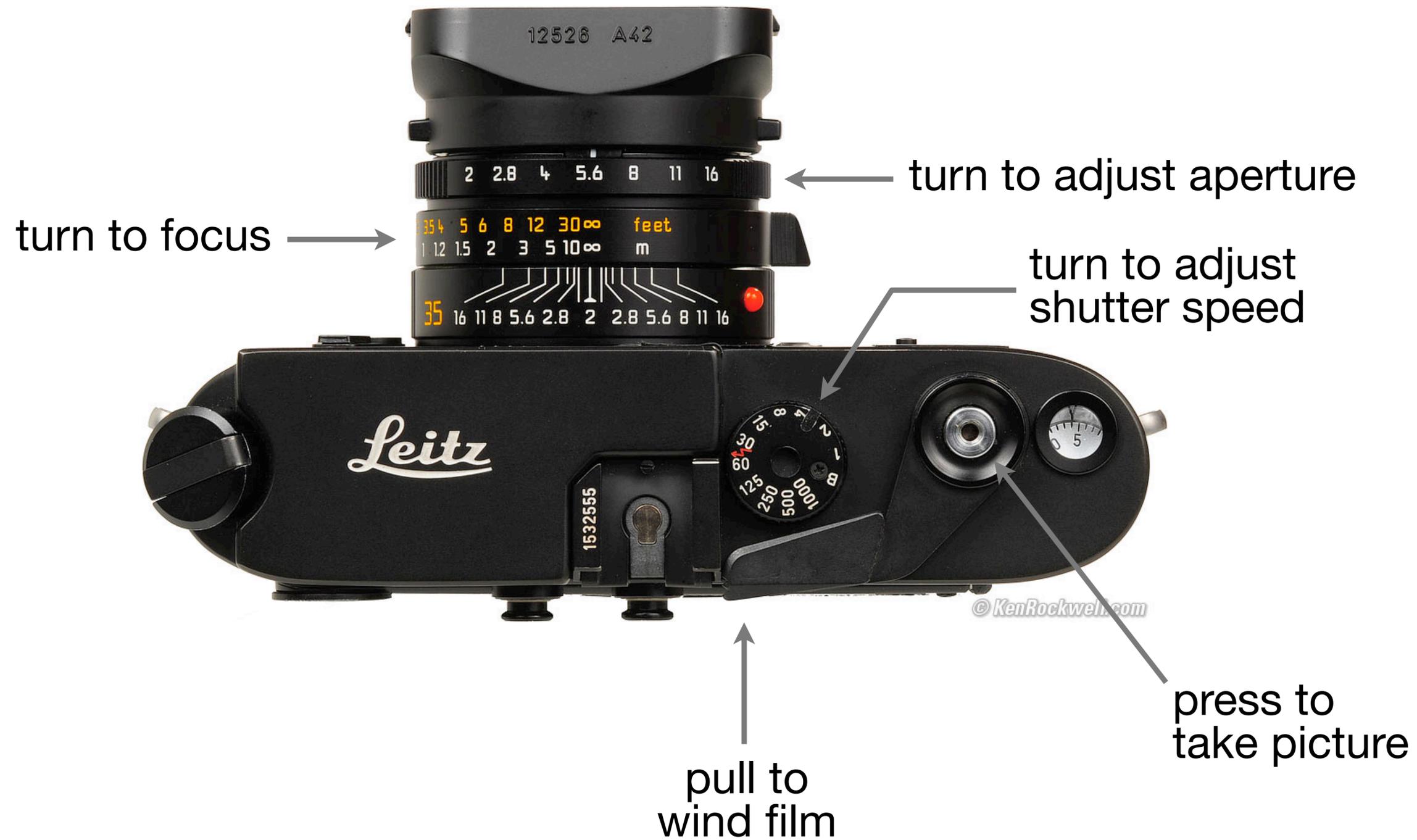
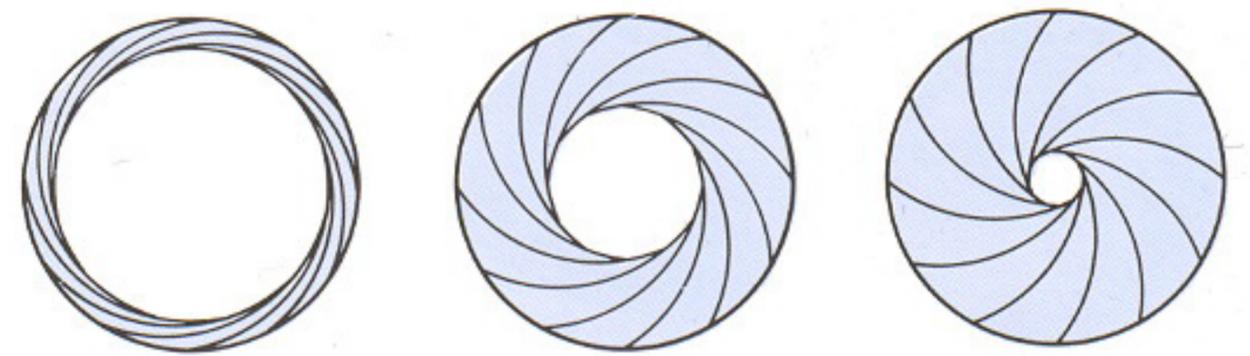


photo: Ken Rockwell



Aperture

- **Diameter of the lens opening (controlled by diaphragm)**
- **Expressed as a fraction of focal length, in f-number**
 - $f/2.0$ on a 50mm means that the aperture is 25mm
 - $f/2.0$ on a 100mm means that the aperture is 50mm
- **Disconcerting: small f number = big aperture**
- **What happens to the area of the aperture when going from $f/2.0$ to $f/4.0$?** divided by 4 (square of f number ratio)
- **Typical f numbers are $f/2.0, f/2.8, f/4, f/5.6, f/8, f/11, f/16, f/22, f/32$**
 - See the pattern?



Full aperture

Medium aperture

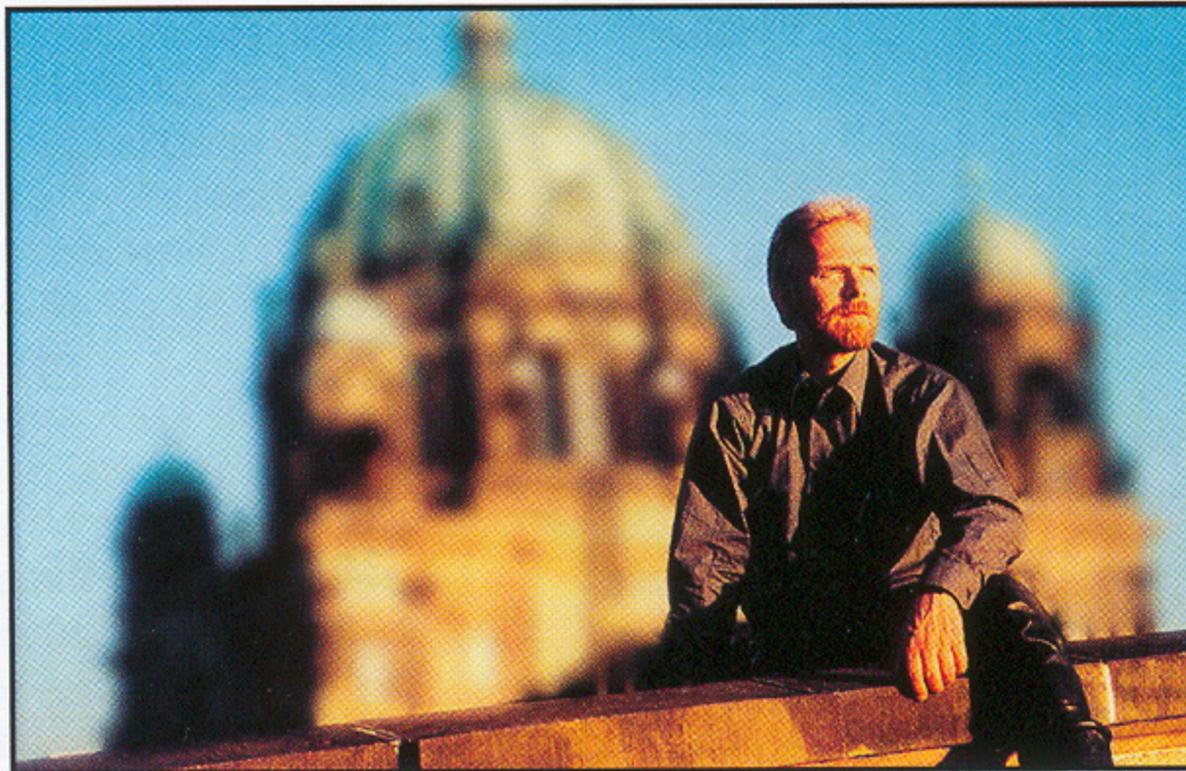
Stopped down

Worth a look:
www.youtube.com/watch?v=KmNlouLByJQ

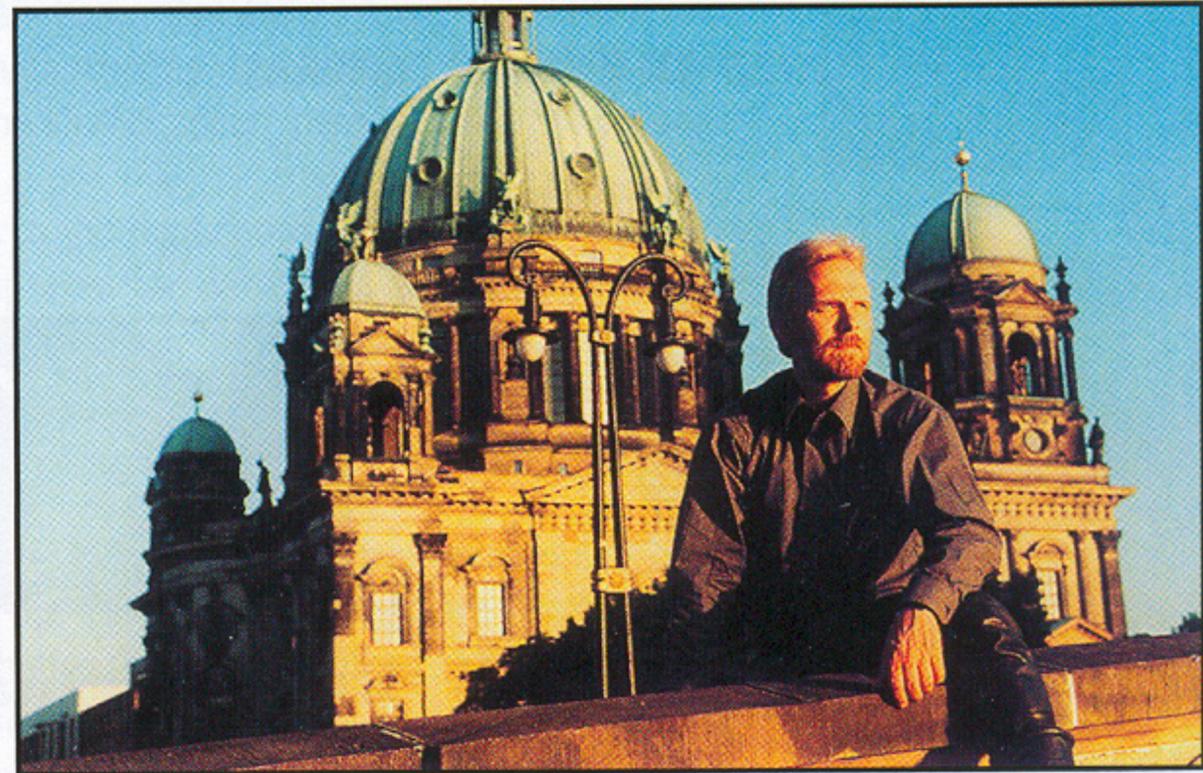
Main effect of aperture

- Depth of field

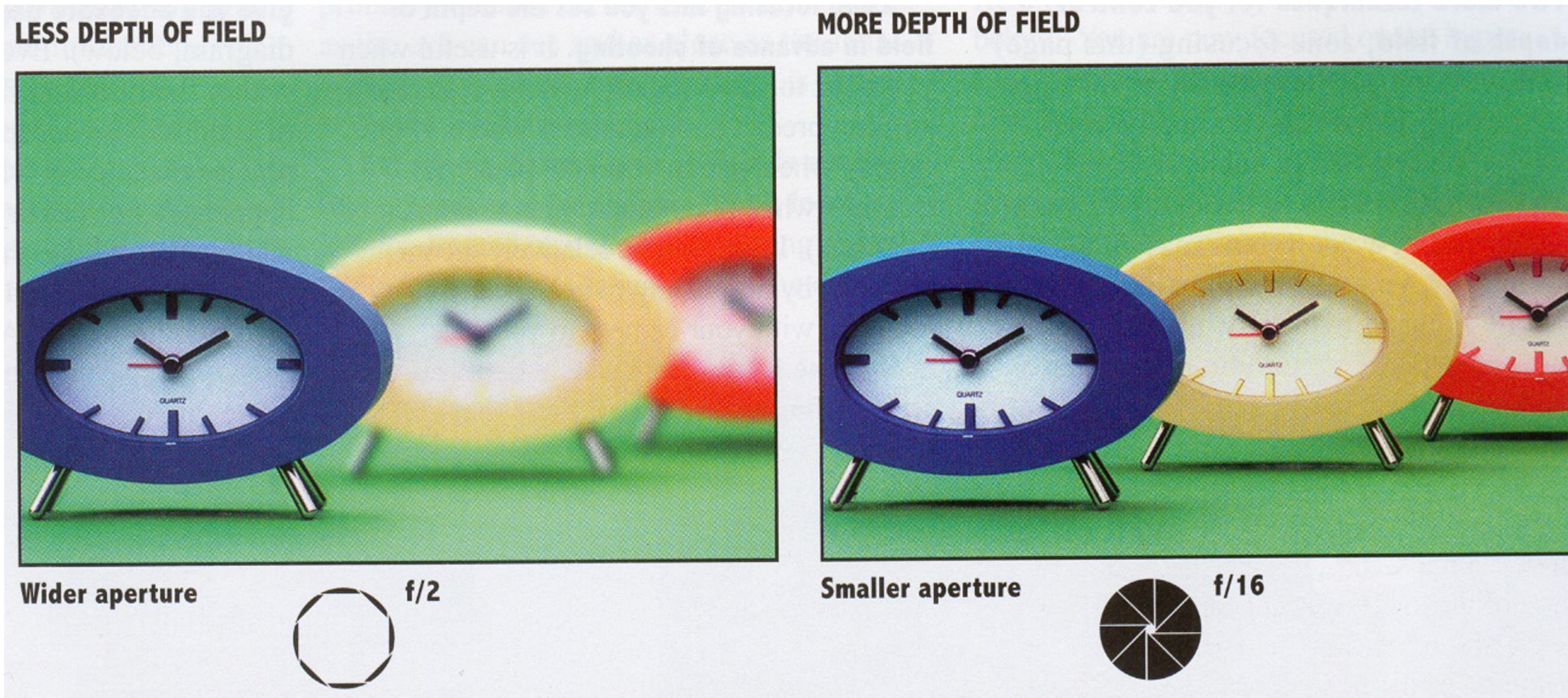
Large aperture opening



Small aperture opening



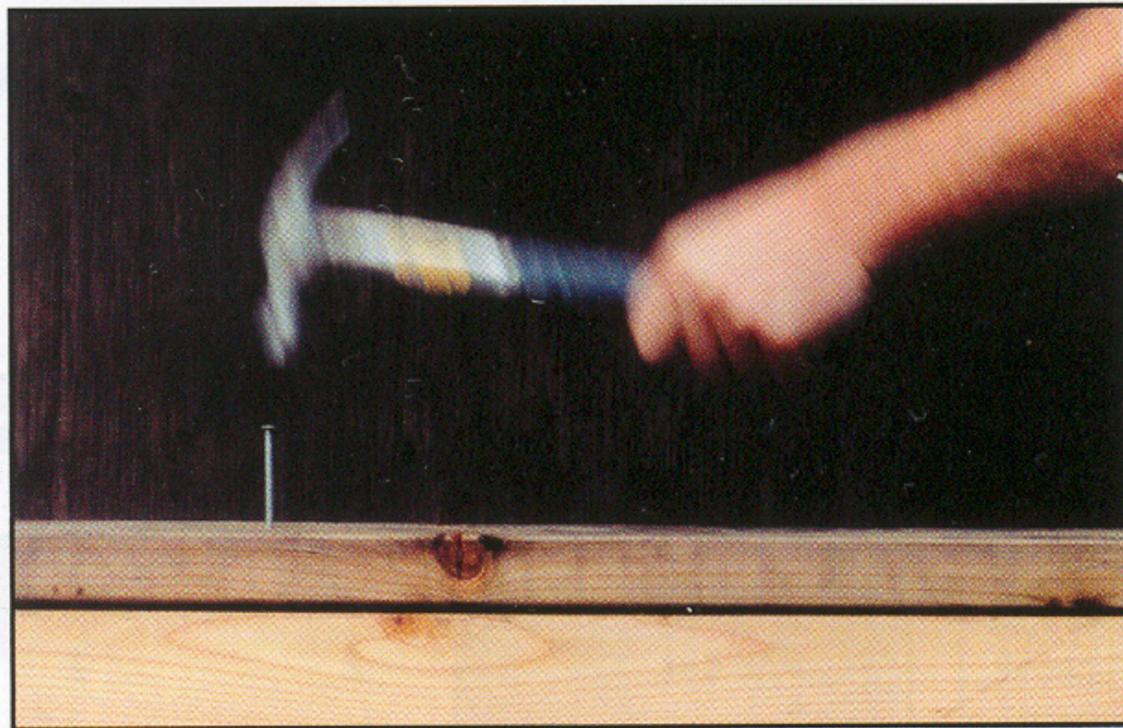
Depth of field



Main effect of shutter speed

- **Motion blur**

Slow shutter speed



Fast shutter speed



From Photography, London et al.

Effect of shutter speed

- Freezing motion

Walking people



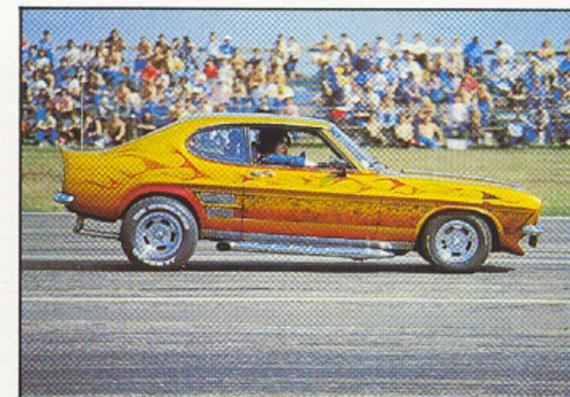
1/125

Running people



1/250

Car



1/500

Fast train



1/1000

Note: it doesn't mean that shutter speed is proportional to the absolute speed of the object. Object distance is very important, and a photographer often tracks the subject.

Variables in photography

Camera pose

- 6 degrees of freedom
 - where is the camera
 - how is it oriented
- in renderers, specified by associating a rigid transformation with the camera

Field of view

- determined by lens-sensor distance (\approx focal length when not focused super close)

Lens aperture and focus distance

- determines what appears in and out of focus

Exposure time

- determines appearance of moving objects

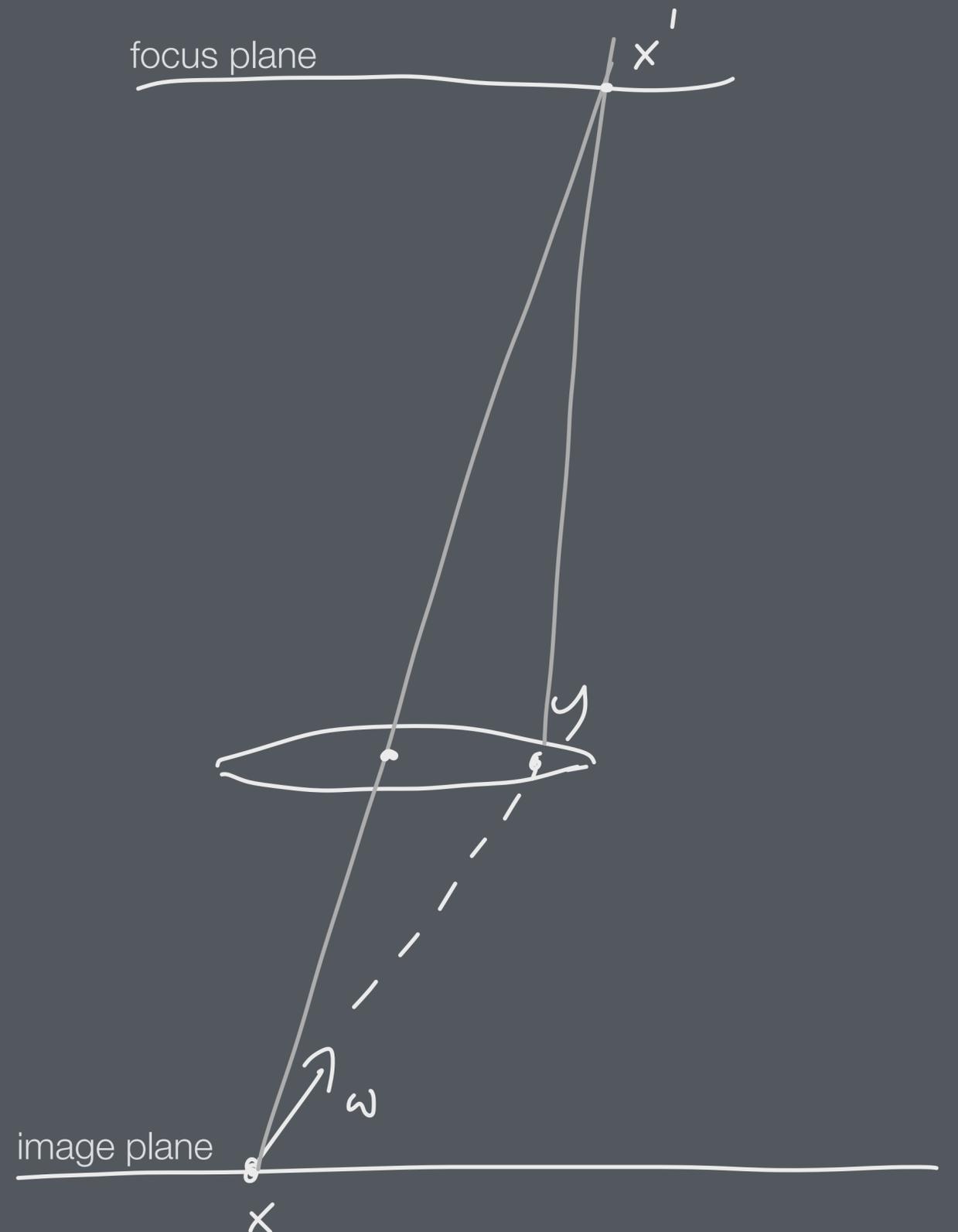
Modeling cameras for rendering

One point on the sensor plane is illuminated by whole aperture

- irradiance on sensor is an integral over the aperture

$$\begin{aligned} E(\mathbf{x}) &= \int_{\Omega_A} L_i(\mathbf{x}, \omega) \cos \theta_{\mathbf{x}} d\omega \\ &= \int_A L(\mathbf{y}, \vec{\mathbf{y}\mathbf{x}}) \frac{\cos \theta_{\mathbf{x}} \cos \theta_{\mathbf{y}}}{\|\mathbf{x} - \mathbf{y}\|^2} d\mathbf{y} \\ &= \frac{1}{f^2} \int_A L(\mathbf{y}, \vec{\mathbf{y}\mathbf{x}}) \cos^4 \theta d\mathbf{y} \\ &= \frac{1}{f^2} \int_A L_i(\mathbf{y}, \vec{\mathbf{y}\mathbf{x}'}) \cos^4 \theta d\mathbf{y} \end{aligned}$$

- simple camera omit the \cos^4



Time integration

If the shutter time is nonzero, the scene can move

This is simple to model with two extensions

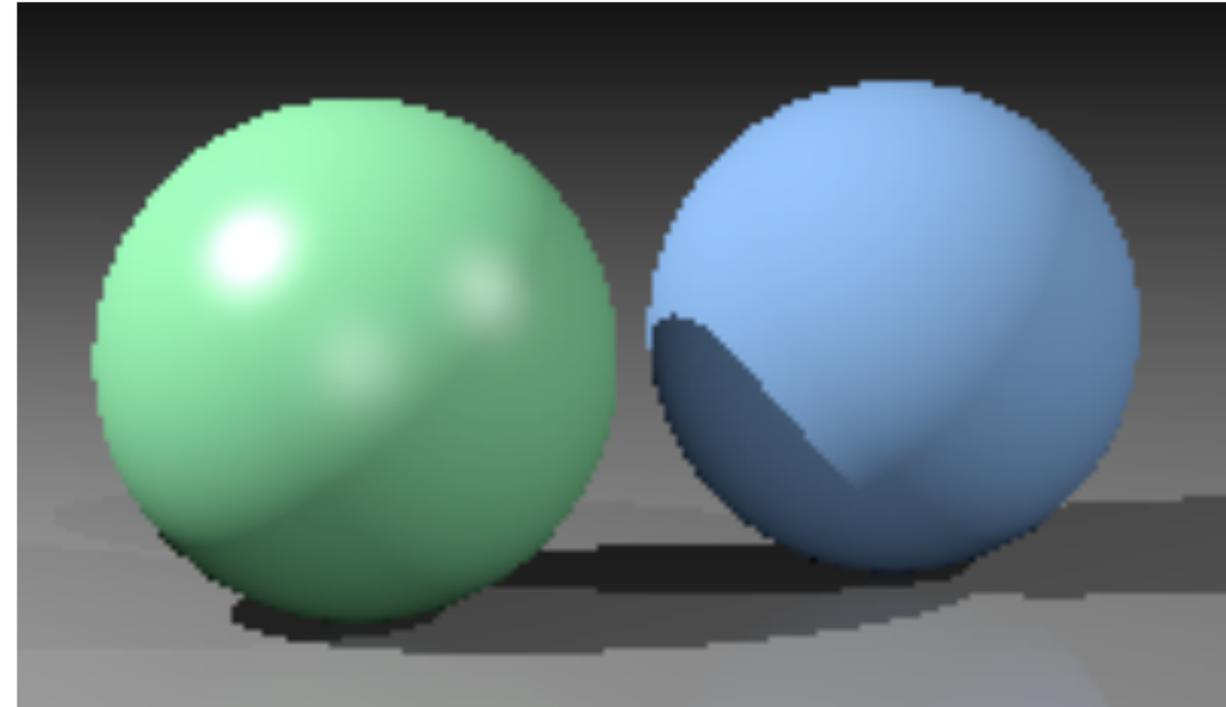
- each ray probing the scene from the camera is tagged with a time
- each moving object pays attention to the time when computing ray intersections



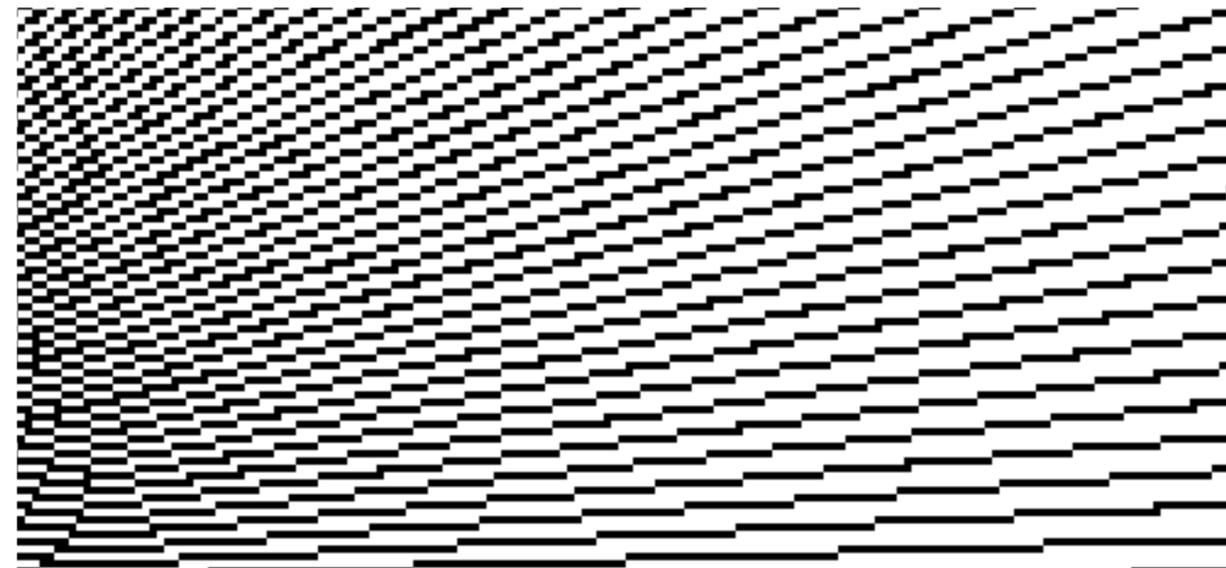
Aliasing

point sampling a
continuous image:

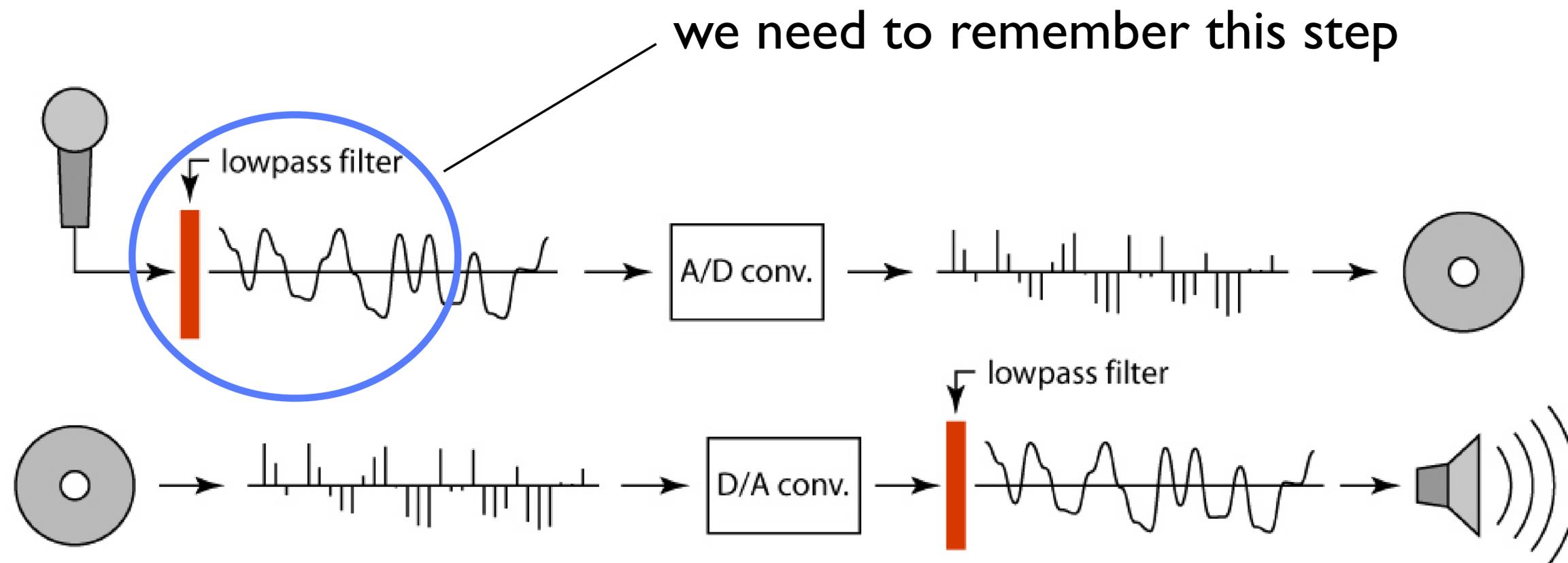
continuous image defined
by ray tracing procedure



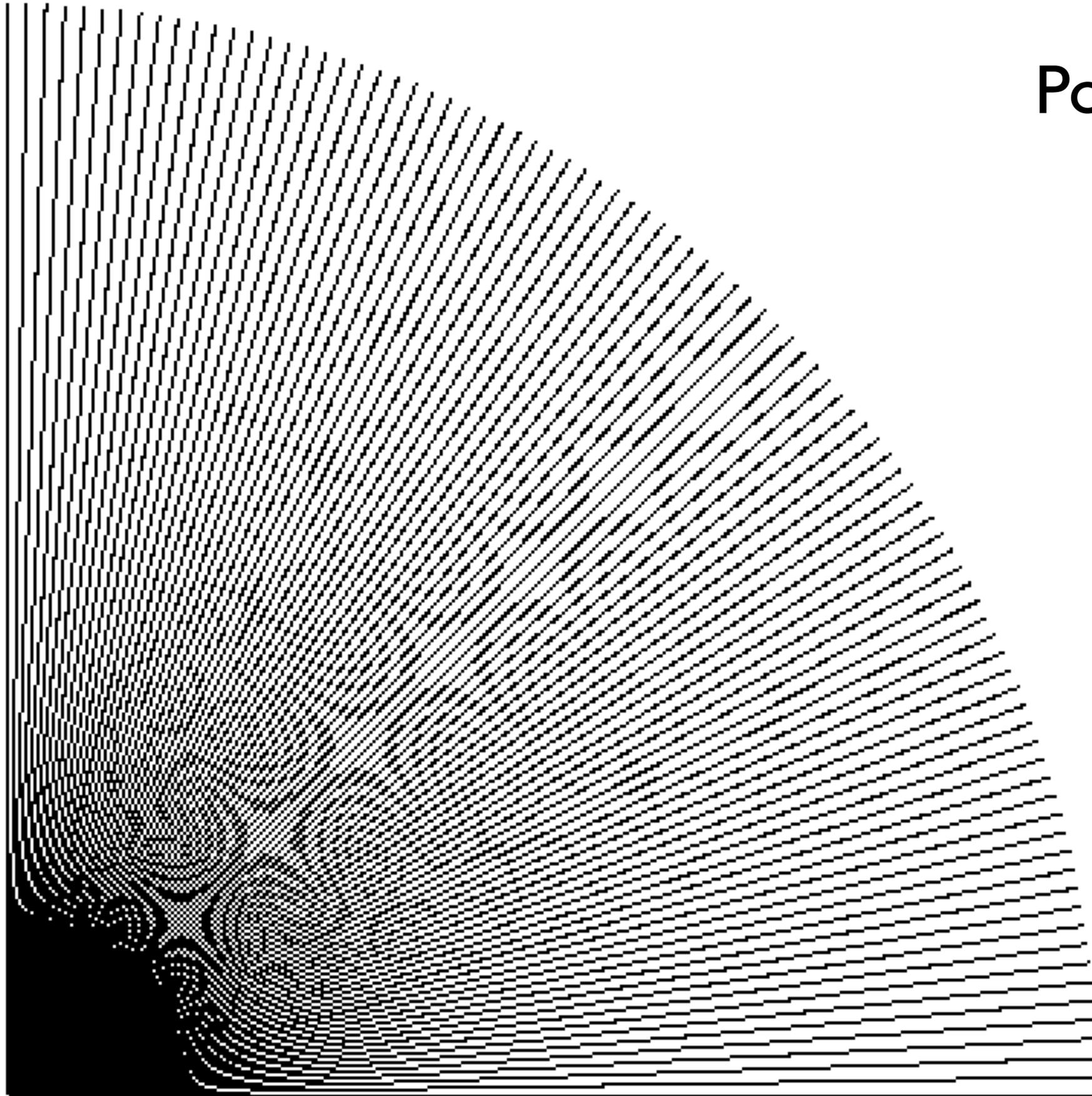
continuous image defined
by a bunch of black rectangles



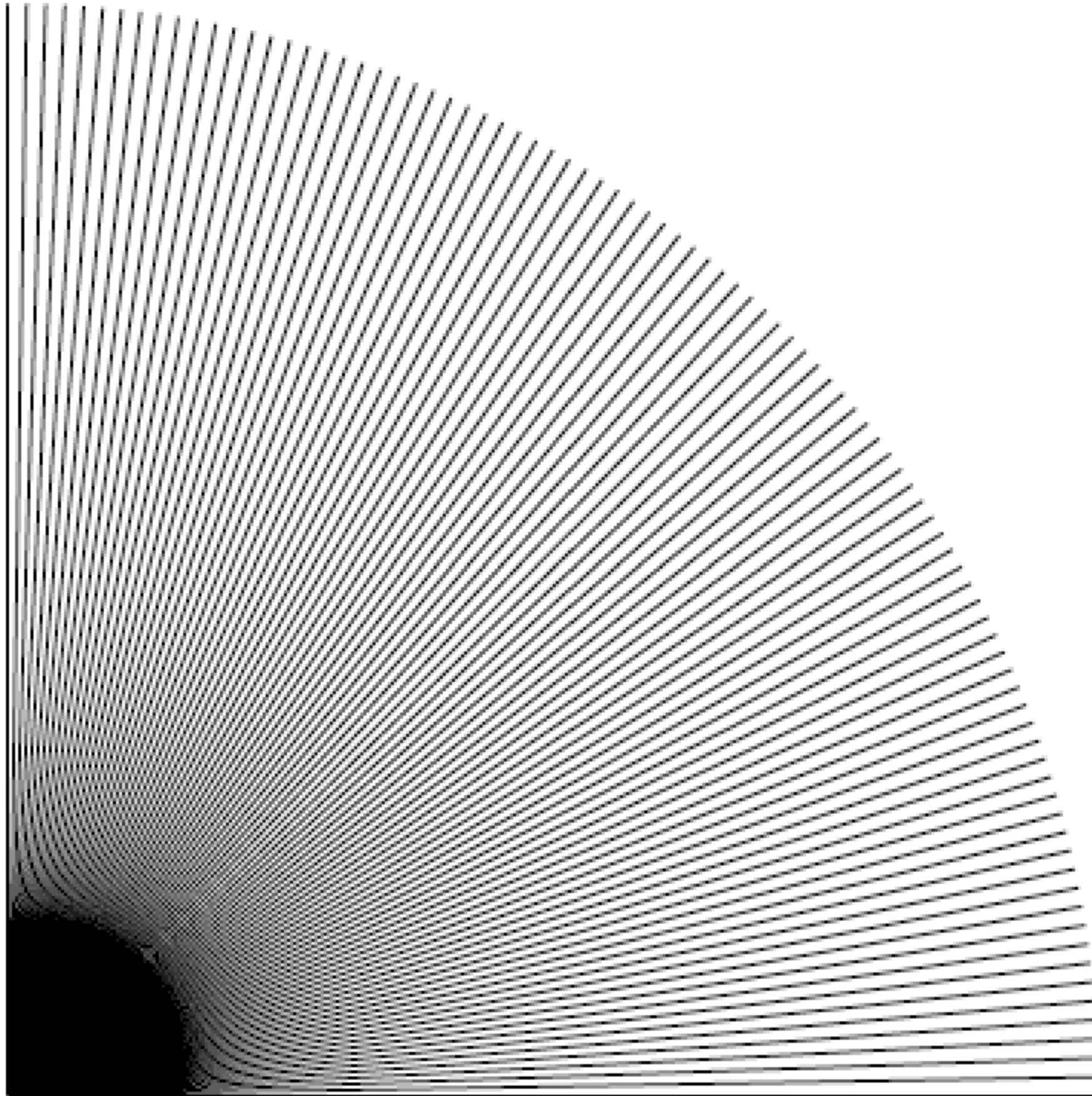
Signal processing view



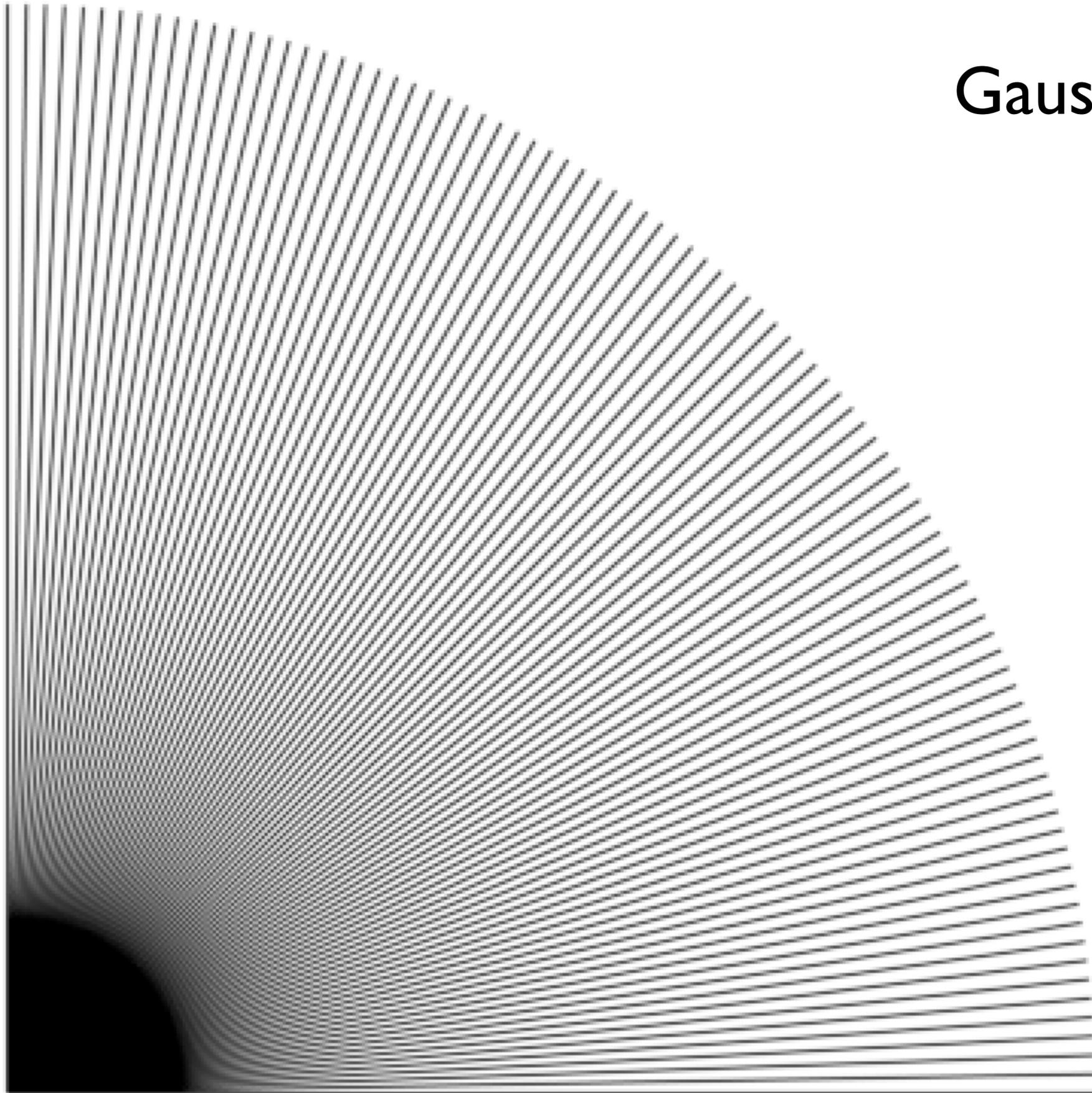
Point sampling in action



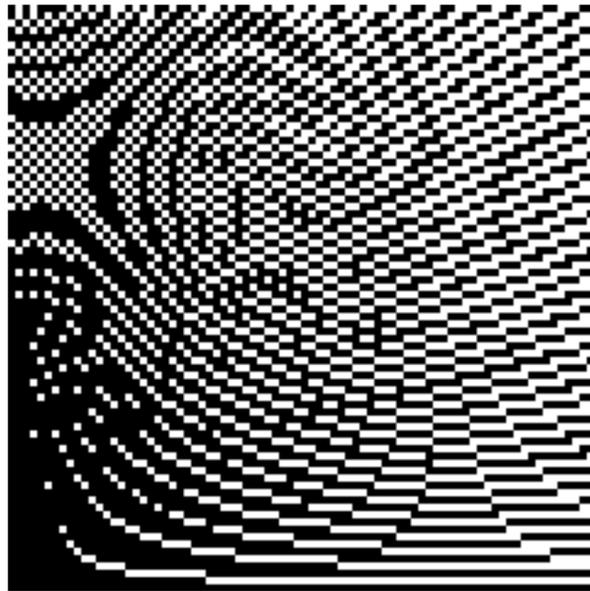
Box filtering in action



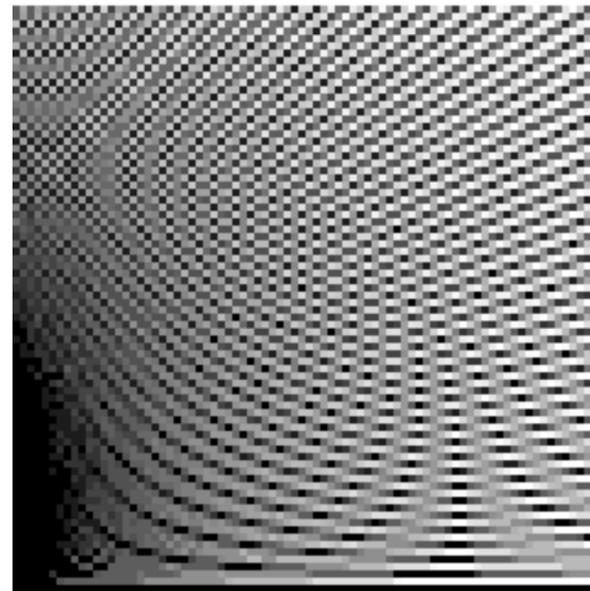
Gaussian filtering in action



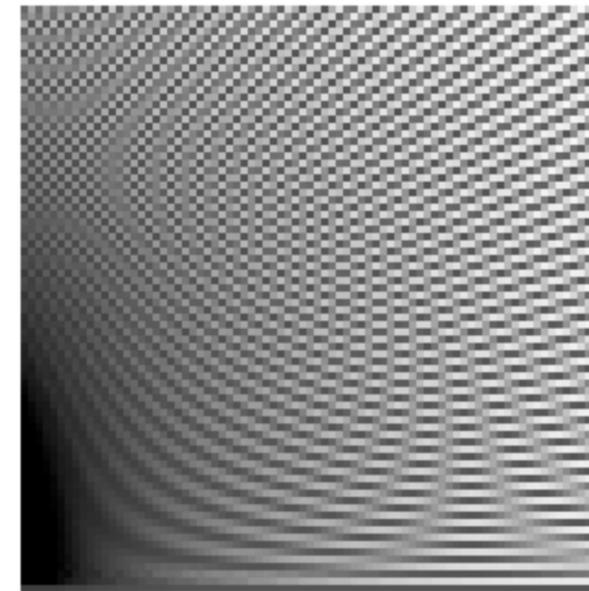
Filter comparison



Point sampling

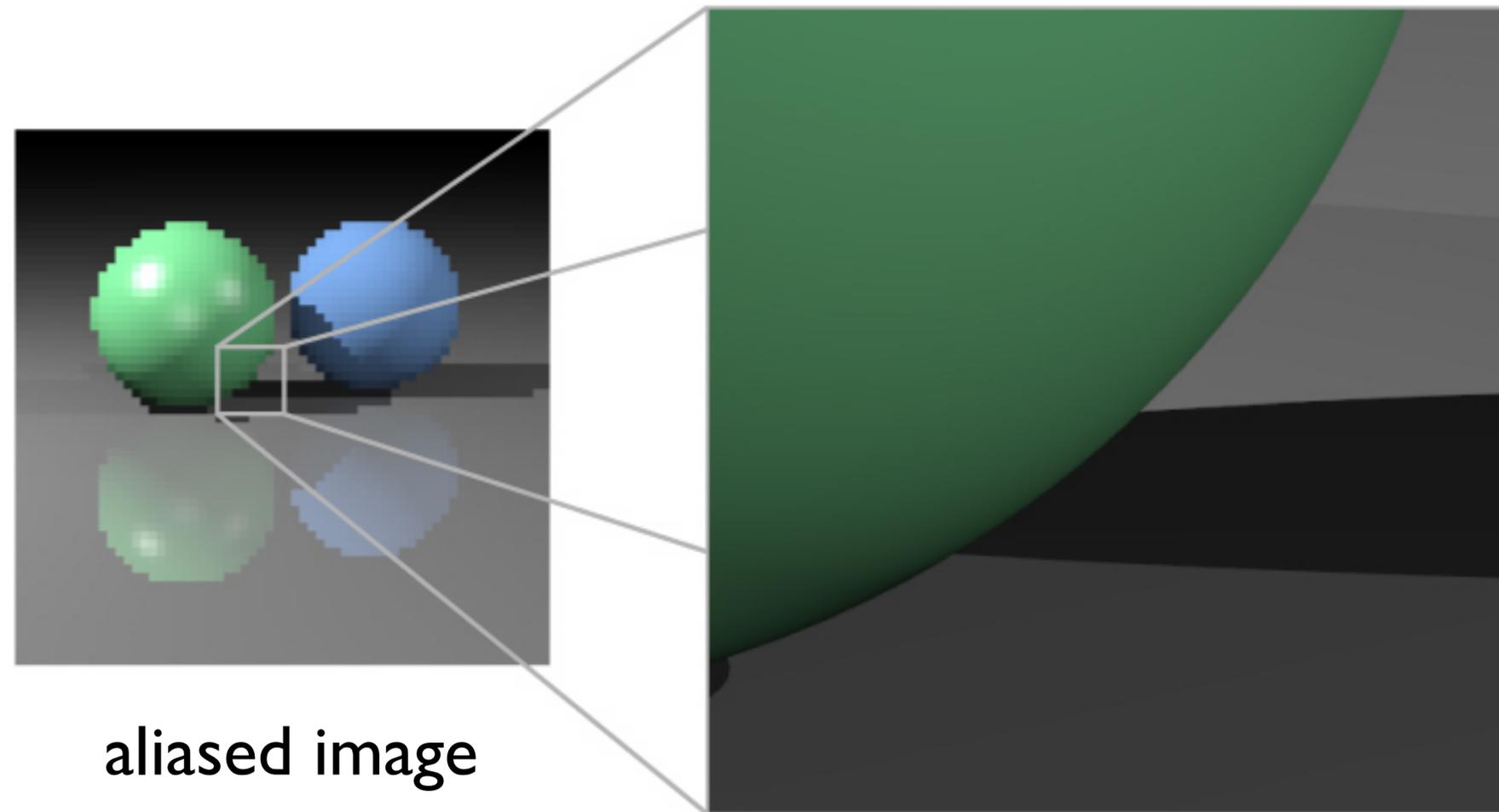


Box filtering

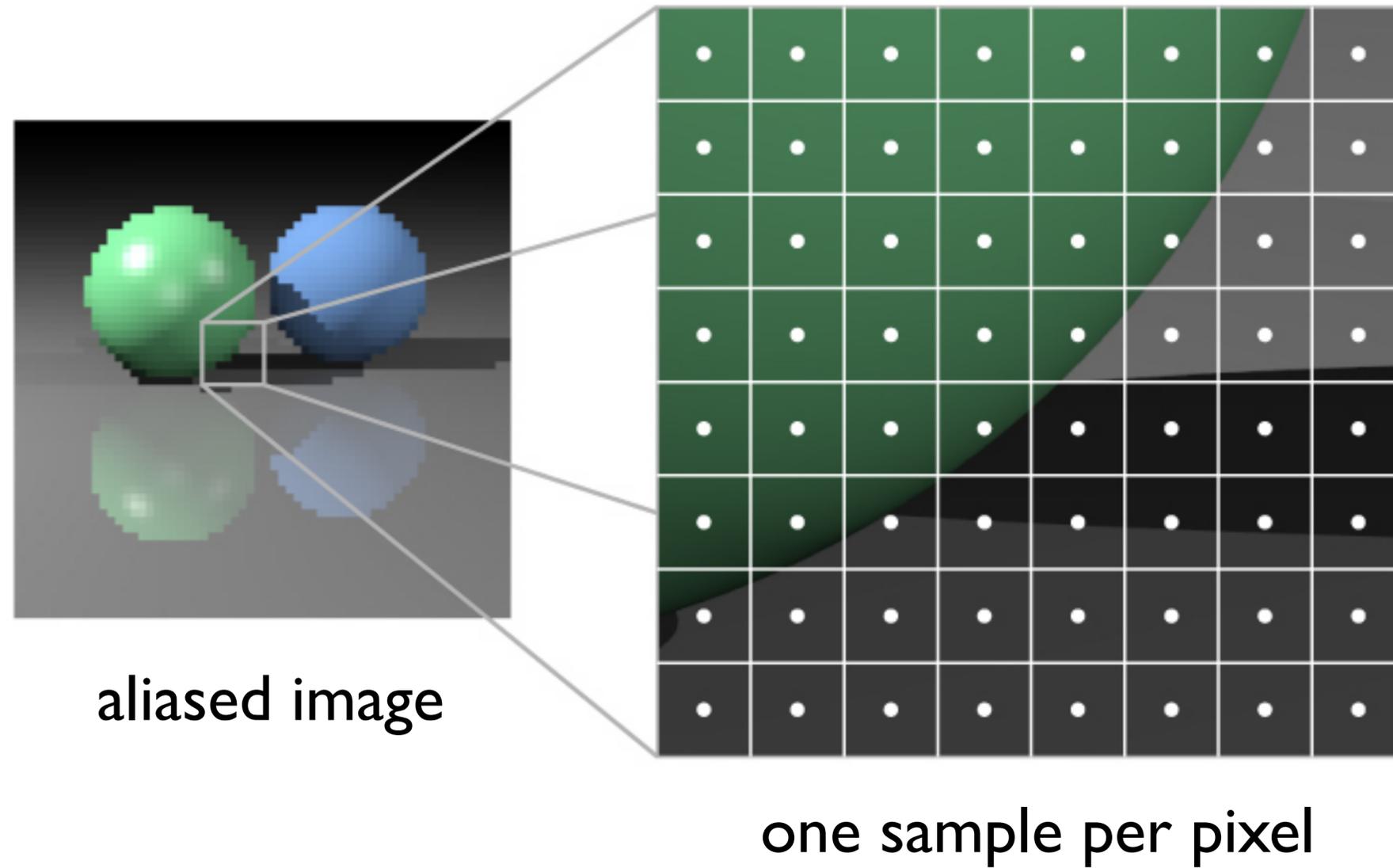


Gaussian filtering

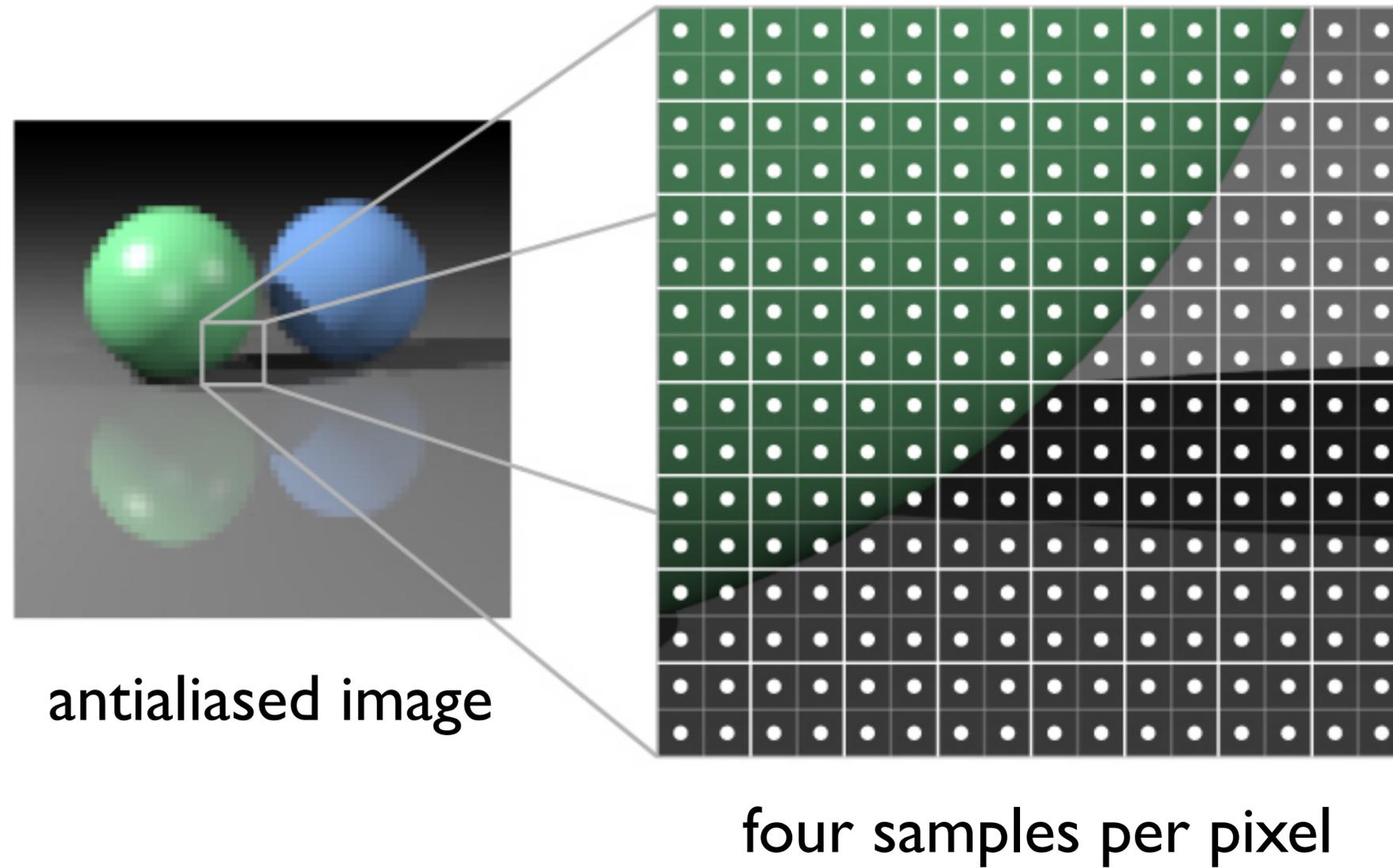
Antialiasing in ray tracing



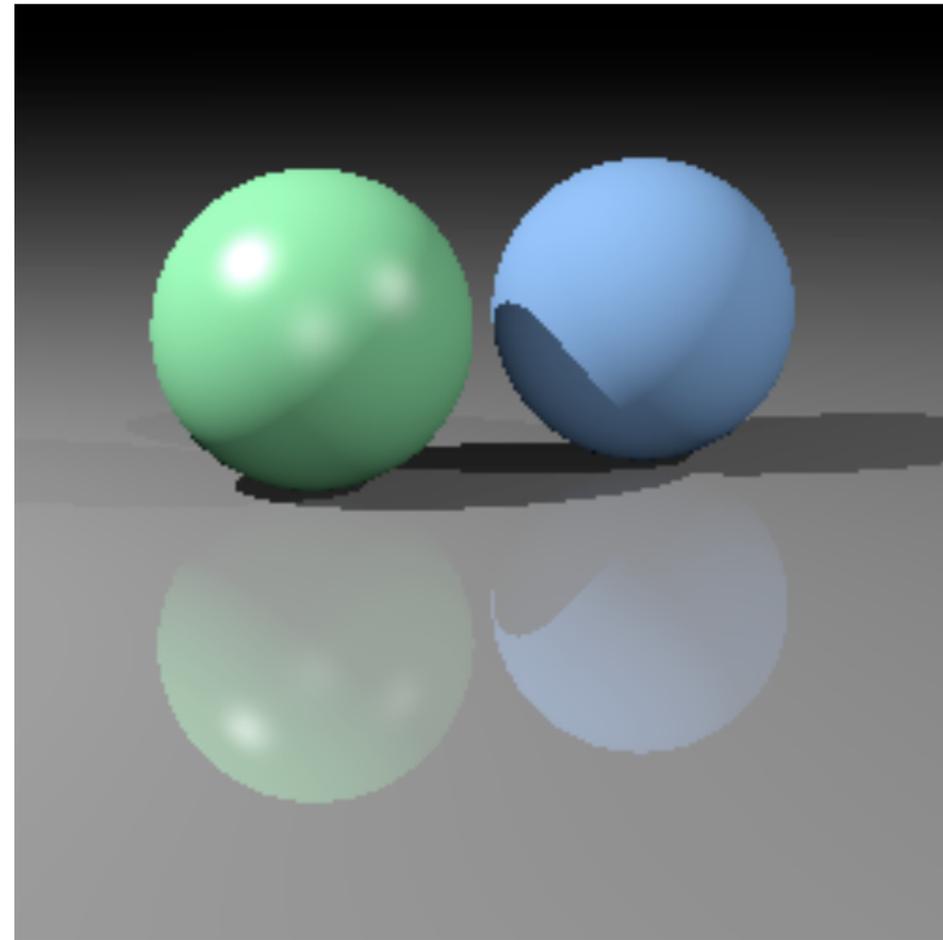
Antialiasing in ray tracing



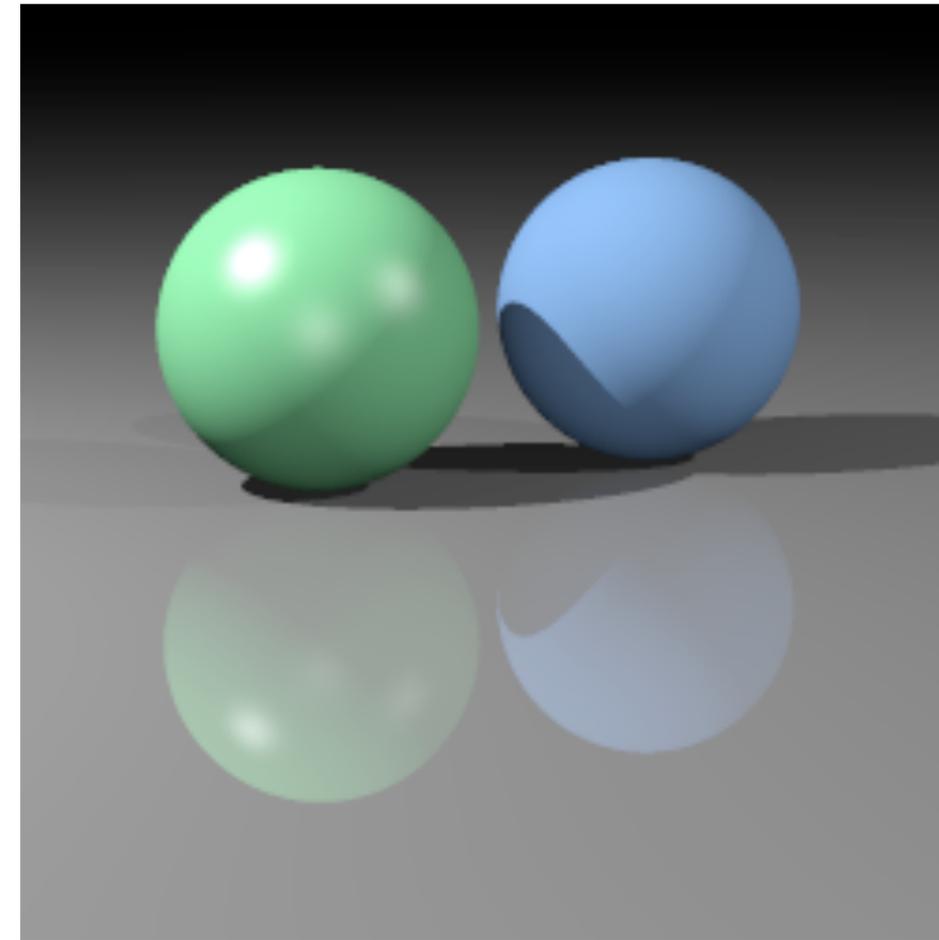
Antialiasing in ray tracing



Antialiasing in ray tracing



one sample/pixel

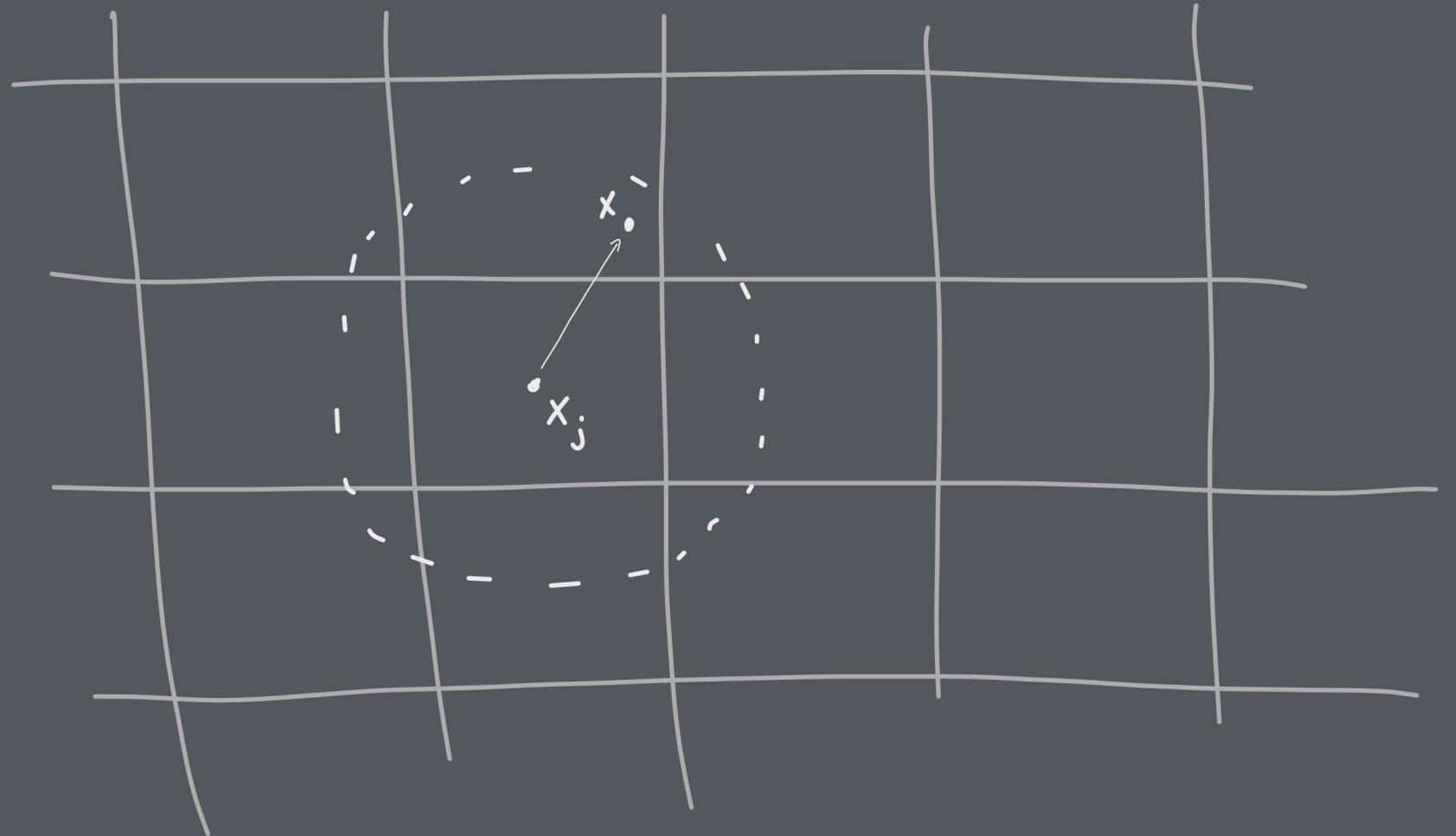


9 samples/pixel

Pixel filtering

For antialiasing, each pixel is a weighted integral

$$\Phi_j = \int E(\mathbf{x})h(\mathbf{x} - \mathbf{x}_j) d\mathbf{x}$$



The Measurement Equation

Pixel value is a measurement of energy

- integrate radiance over aperture solid angle: irradiance
- integrate irradiance over pixel area: power
- integrate power over shutter time: energy

$$J_j = \int_{\Delta t} \int_{R^2} \int_{\Omega_A} L_i(\mathbf{x}, \omega_i) h(\mathbf{x} - \mathbf{x}_j) \cos \theta d\omega d\mathbf{x} dt$$

- change variable to aperture to integrate over scene rays

$$J_j = \frac{1}{f^2} \int_{\Delta t} \int_{R^2} \int_A L_i(\mathbf{y}, \omega(\mathbf{x}, \mathbf{y})) h(\mathbf{x} - \mathbf{x}_j) \cos^4 \theta d\omega d\mathbf{y} dt$$

- follow rays to surface to connect to rendering equation

$$J_j = \frac{1}{f^2} \int_{\Delta t} \int_{R^2} \int_A L(\psi(\mathbf{y}, \omega), -\omega) h(\mathbf{x} - \mathbf{x}_j) \cos^4 \theta d\omega d\mathbf{y} dt$$