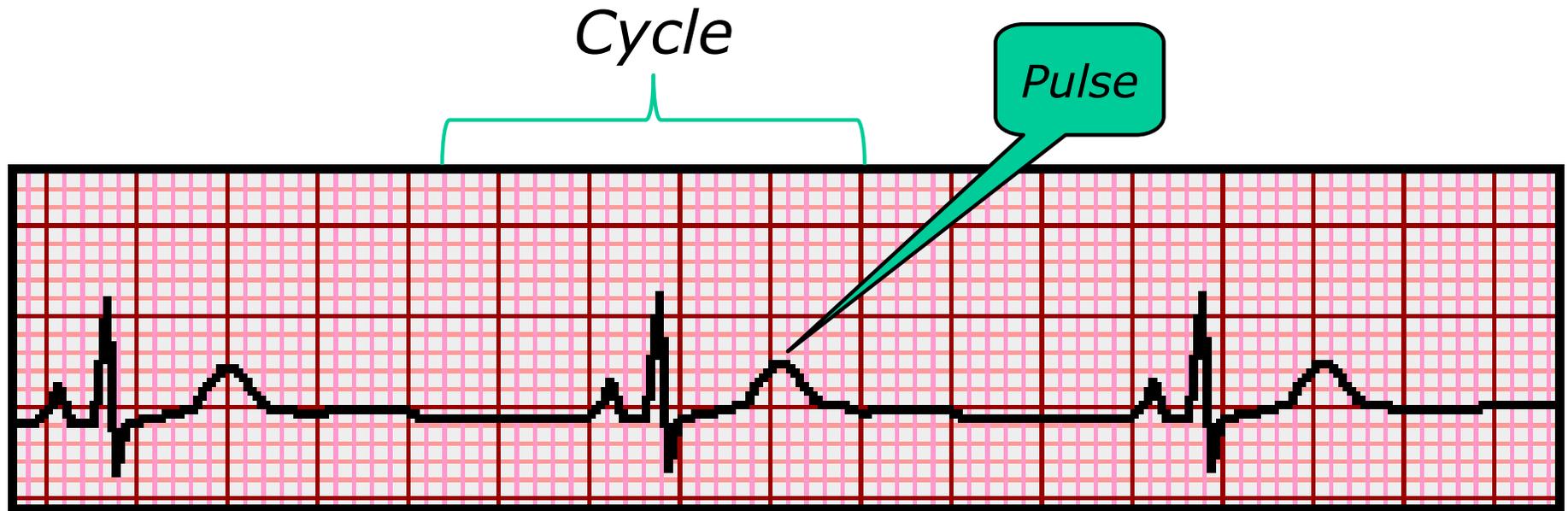


CS5540: Computational Techniques for Analyzing Clinical Data

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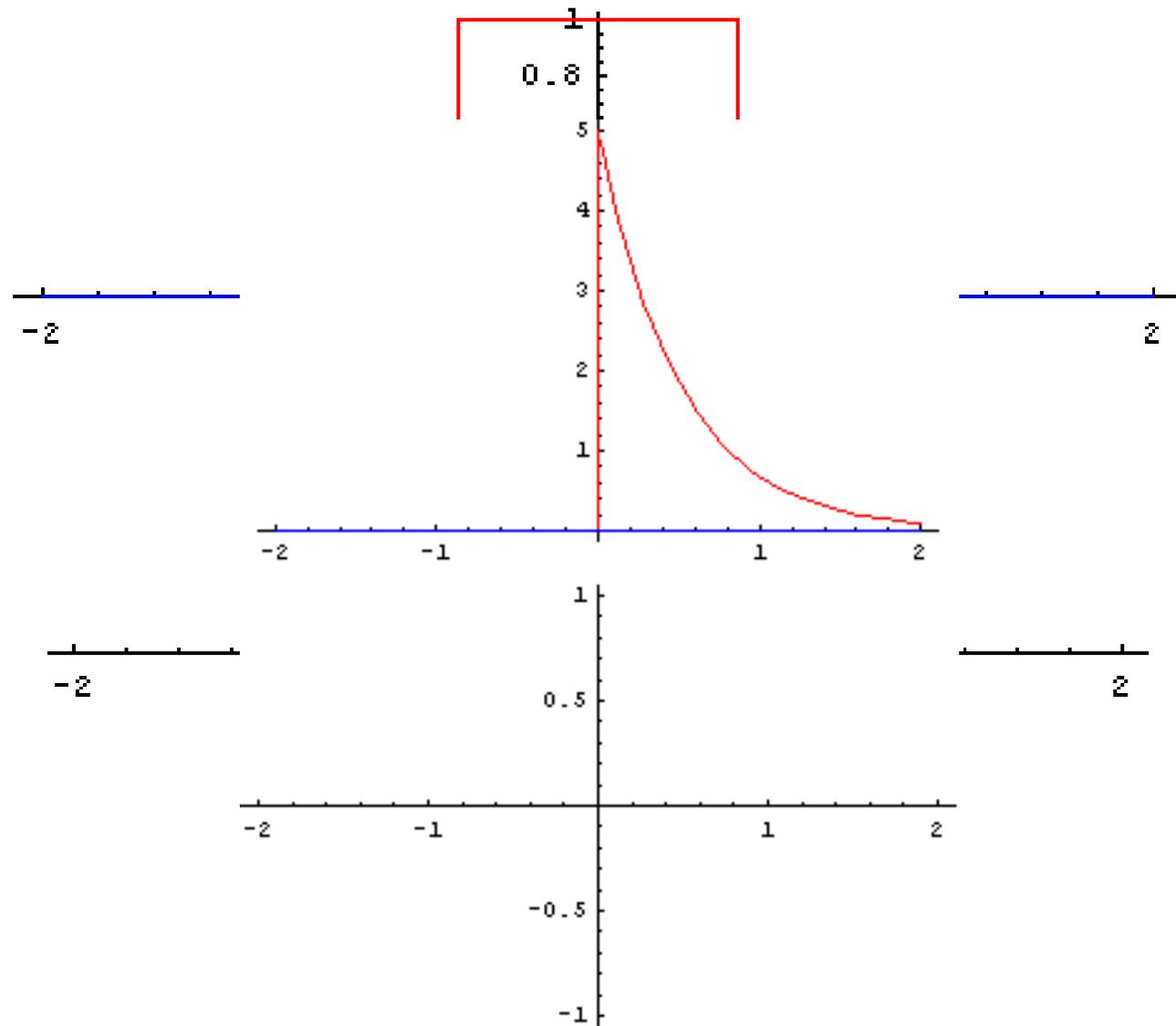
Cycles and pulses



www.uptodate.com

Note: cycle is standard terminology, but pulse is not. The ECG literature calls these “waves” but we want to be more general than just ECG.

Convolution in action



Convolution as a dot product

- Note: technically this is correlation
 - Same as convolution when symmetric

[... 19 20 -4 17 93 ...]

$$[1 \ -1] = 19 - 20 = -1$$

$$[1 \ -1] = 20 - (-4) = 24$$

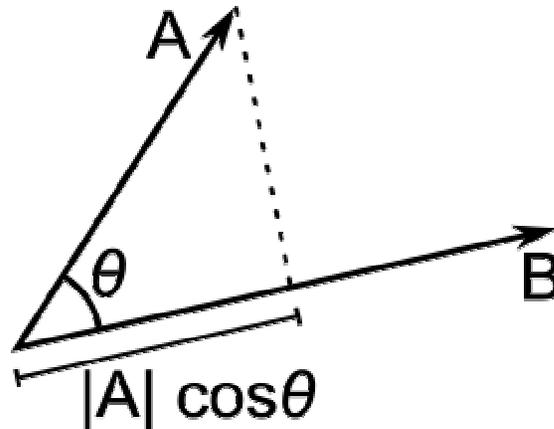
$$[1 \ -1] = -4 - 17 = -21$$

- This seems like a lot of mechanism to get somewhere totally obvious



Geometric intuition

- Taking the dot product of two vectors
 - Recall $[a \ b \ c] @ [e \ f \ g] = ae + bf + cg$
 - Basically the projection of a vector on another



- The normalized vector with the biggest projection on x is, of course: x !
 - Useful intuition for transforms, etc.



Normalization

- Matched filter must be normalized
 - Want to find our template in the ECG data
- What looks like $[1\ 2\ 6]$?
 - Obviously, $[\dots\ 1\ 2\ 6\ \dots]$ does (score = 41)
 - What about $[\dots\ 150\ 100\ 50\dots]$?
 - Subtract mean from both template and ECG
 - Ex: $[-1\ 1]$ template
 - Also need to normalize the “energy” to 1
 - Sum of squares



Convolution and edge detection

- Strategy: smooth (convolve with a Gaussian) then find zero crossings
- We can also look for inflection points (2nd derivative is zero) after smoothing
- Or we can look for big changes in the ECG
 - Sort of what we did with the matched filter
- Can do smoothing at the same time!



Convolution's properties

- Convolution is also popular because it is a surprisingly deep topic
 - With lots of connections to other areas
 - Central limit theorem
 - Multiplication of polynomials
 - Etc, etc.



Gaussian convolution

- The standard way to smooth data is to convolve with a Gaussian
 - Related to Gaussian noise assumption
- Gaussian noise assumption itself comes from one of the Gaussian's many amazing properties, the Central Limit Theorem



Random variables

- A discrete random variable assigns each integer a probability
 - Ex: a perfect coin or a die
 - The assignment function is the density
- What happens when we toss a two dice and add them up?
 - This is another random variable
 - Q: What is the density?
 - A: Convolution of the dice density with itself



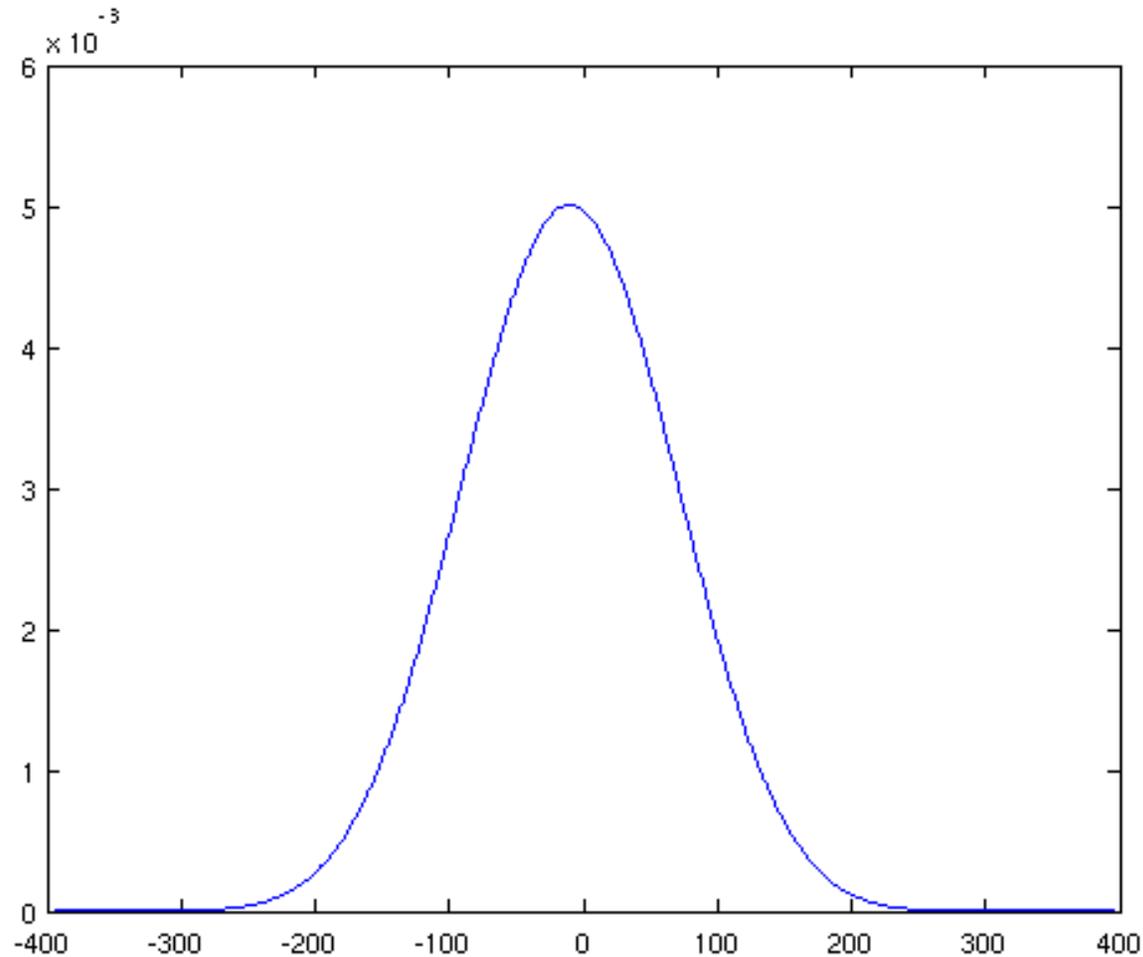
Limit theorems

- Let's throw more and more dice, adding up their totals
 - Ex: 1000 dice
 - Sum is from 1000 to 6000
 - If the dice density is uniform, we'll typically get around 3500
 - What about an arbitrary density?
- Central limit theorem: we will end up with a Gaussian



Illustration

- How fast does this become Gaussian?

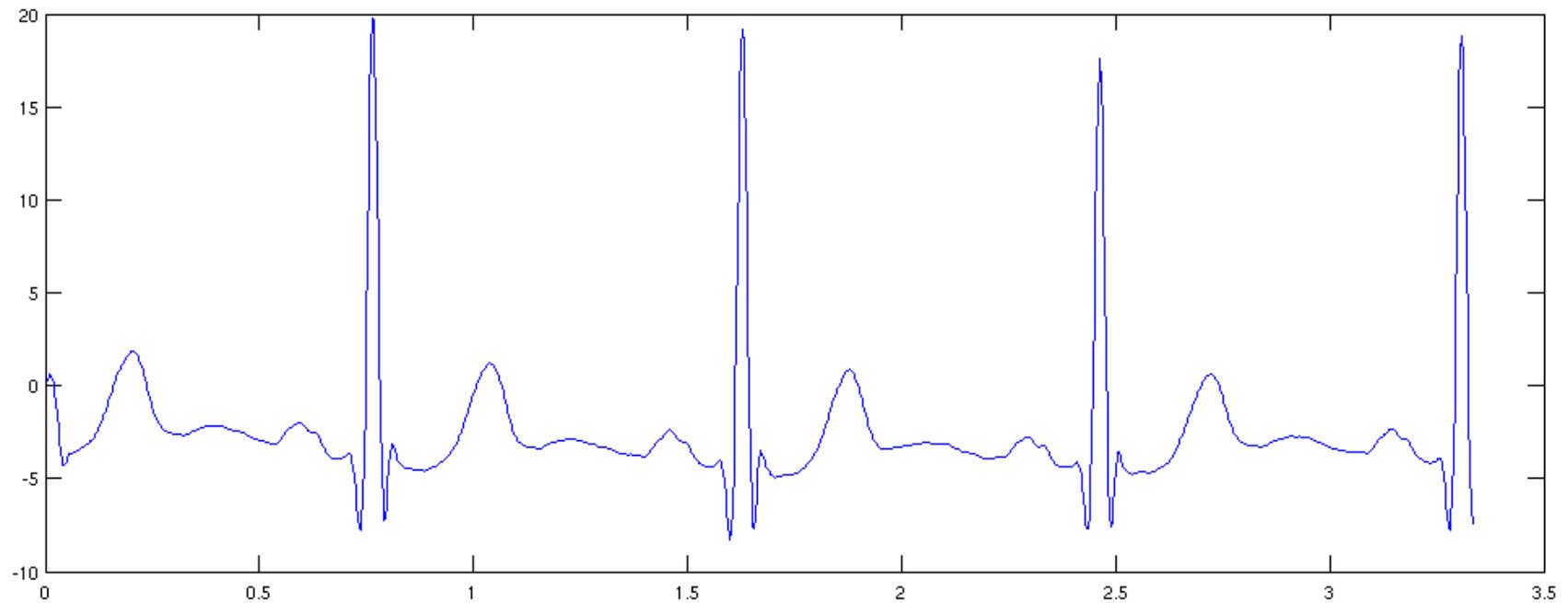
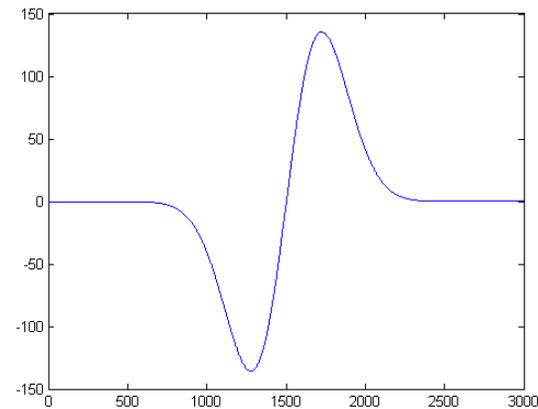


Convolution and edges

- We want to smooth then find zero crossings or big increases/decreases
- There is some nice math that tells us we can do this in a single step
 - It was actually illustrated in the matched filter



Pulse finding example



Linearity

- Scalars don't matter
 - Scalars in Y, not T (the latter is scale invariance, which is much harder)
- Addition doesn't matter
- Formally, for any two ECG's X,Y and scalars a,b we have
$$H(aX + bY) = a H(x) + b H(y)$$
- Many devices/systems are linear when they are well behaved



Shift invariance

- Shift the input, shift the output
- Or: starting point doesn't matter
- Note that fixed shift itself is a convolution



LSI systems

- Many important systems have both of these properties
 - Linear Shift Invariant
 - Aka Linear Time Invariant



LSI and convolution

- Convolution is an LSI operation
 - Pretty obvious (think about local averaging)
- But any LSI is actually convolution with something, which is easy to find
 - Why would this be true??



Unit impulse response

- Unit impulse: [... 0 1 0 ...]
- Any input is the sum of scaled and shifted unit impulses
 - Example: to get [1 6 -10] we:
 - Take the unit impulse shifted once left: [1 0 0]
 - Add 6 times the unit impulse, no shift: [1 6 0]
 - Subtract 10 times the unit impulse, shifted right

