

CS5412: CONSENSUS AND THE FLP IMPOSSIBILITY RESULT

Generalizing Ron and Hermione's challenge

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- Recall from last time: Ron and Hermione had difficulty agreeing where to meet for lunch
 - ▣ The central issue was that Ron wanted to reason in a perfectly logical way. They never knew for sure if email was delivered... and always ended up in the “default” case
- In general we often see cases in which N processes must agree upon something
 - ▣ Often reduced to “agreeing on a bit” (0/1)
 - ▣ To make this non-trivial, we assume that processes have an input and must pick some legitimate input value
- Can we implement a fault-tolerant agreement protocol?

Connection to consistency

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- A system behaves consistently if users can't distinguish it from a non-distributed system that supports the same functionality
 - ▣ Many notions of consistency reduce to agreement on the events that occurred and their order
 - ▣ Could imagine that our “bit” represents
 - Whether or not a particular event took place
 - Whether event A is the “next” event
- Thus fault-tolerant consensus is deeply related to fault-tolerant consistency

Consensus \equiv Agreement?

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- For CS5412 we treat these as synonyms
- The theoretical distributed systems community has detailed definitions and for that group, the terms refer to very similar but not identical problems
- Today we're “really” focused on Consensus, but don't worry about the distinctions

Fischer, Lynch and Patterson

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- A surprising result
 - ▣ Impossibility of Asynchronous Distributed Consensus with a Single Faulty Process
- They prove that no asynchronous algorithm for agreeing on a one-bit value can guarantee that it will terminate in the presence of crash faults
 - ▣ And this is true even if no crash actually occurs!
 - ▣ Proof constructs infinite non-terminating runs

Core of FLP result

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- They start by looking at an asynchronous system of N processes with inputs that are all the same
 - ▣ All 0's must decide 0, all 1's decides 1
- They are assume we are given a correct consensus protocol that will “vote” (somehow) to pick one of the inputs, e.g. perhaps the majority value
 - ▣ Now they focus on an initial set of inputs with an uncertain (“bivalent”) outcome (nearly a tie)
 - ▣ For example: $N=5$ and with a majority of 0's the protocol picks 0, but with a tie, it picks 1. Thus if one of process with a 0 happens to fail, the outcome is different than if all vote

Core of FLP result

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- Now they will show that from this bivalent state we can force the system to do some work and yet still end up in an equivalent bivalent state
- Then they repeat this procedure
- Effect is to force the system into an infinite loop!
 - ▣ And it works no matter what correct consensus protocol you started with. This makes the result very general

Bivalent state

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S_* denotes bivalent state
 S_0 denotes a decision 0 state
 S_1 denotes a decision 1 state

System
starts in S_*

Events can
take it to
state S_0



Sooner or later all executions
decide 0

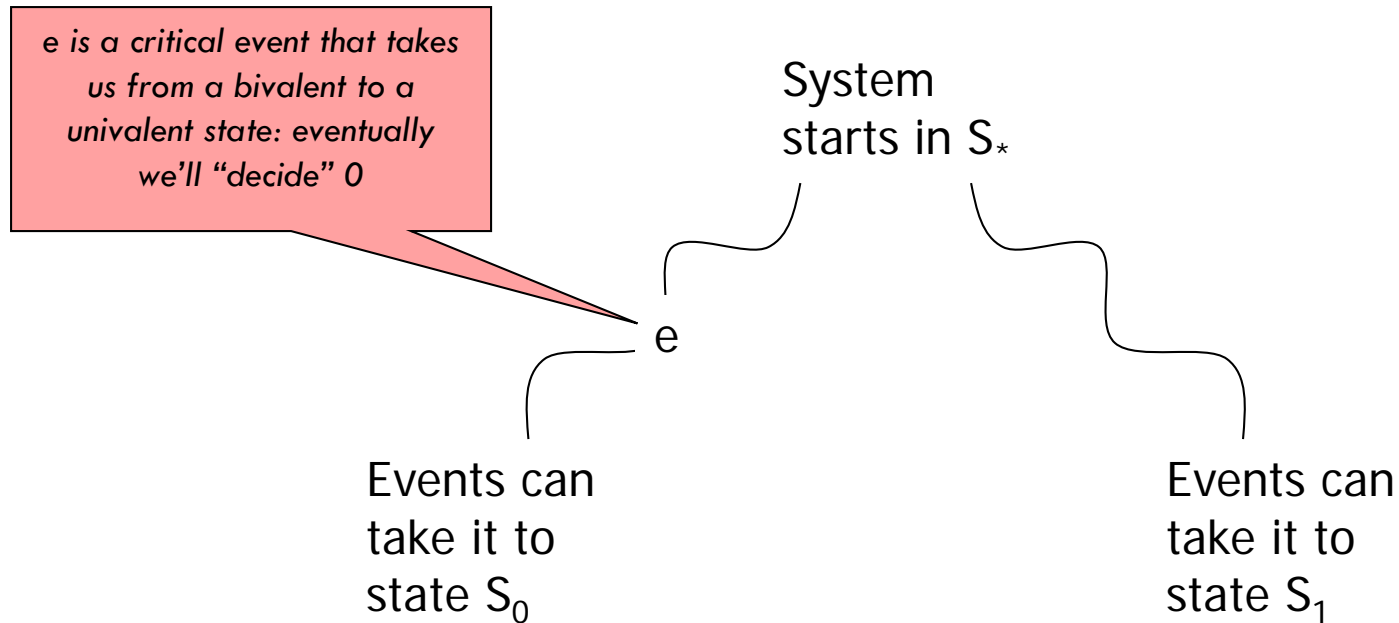
Events can
take it to
state S_1



Sooner or later all executions
decide 1

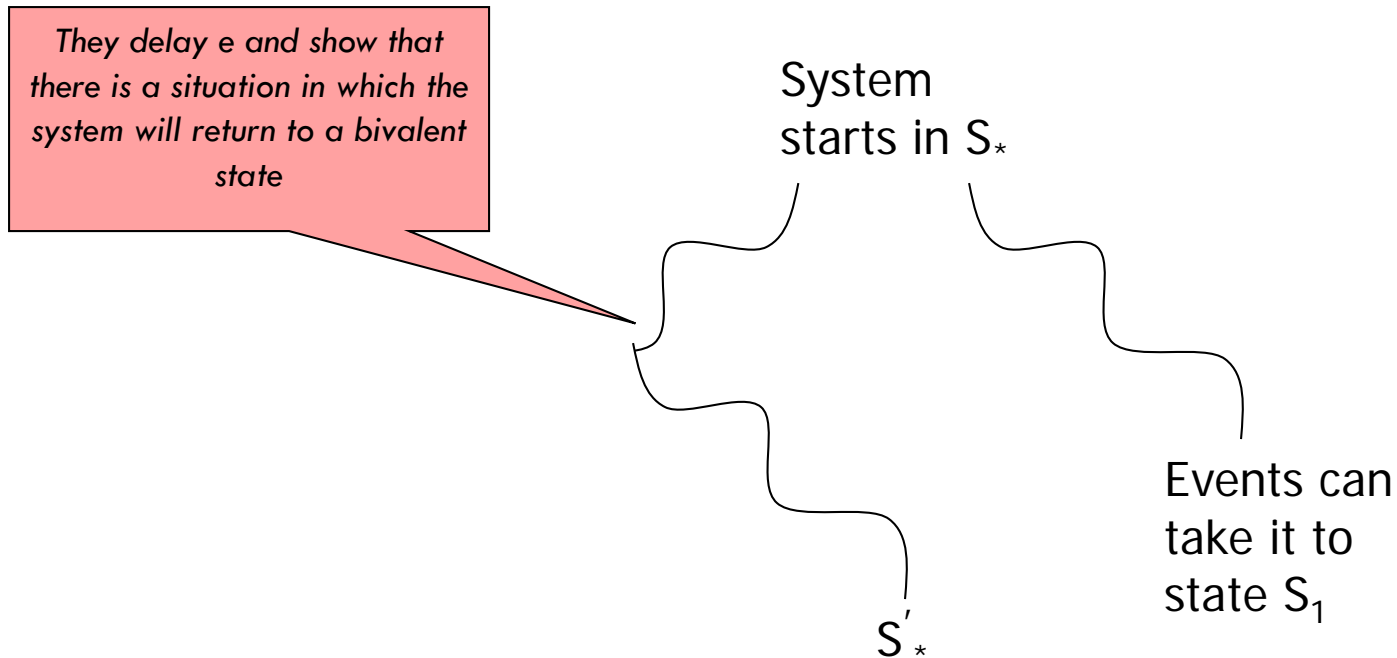
Bivalent state

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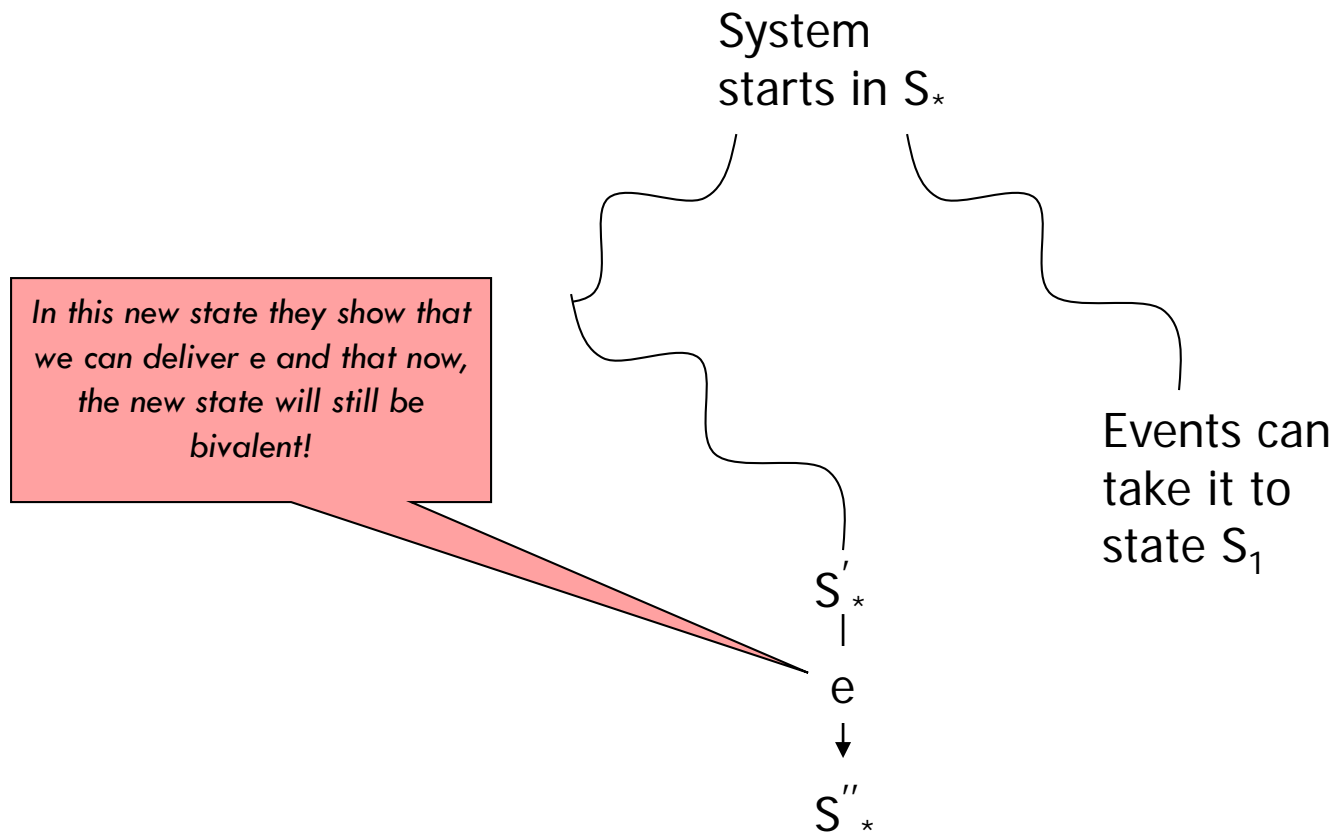
Bivalent state

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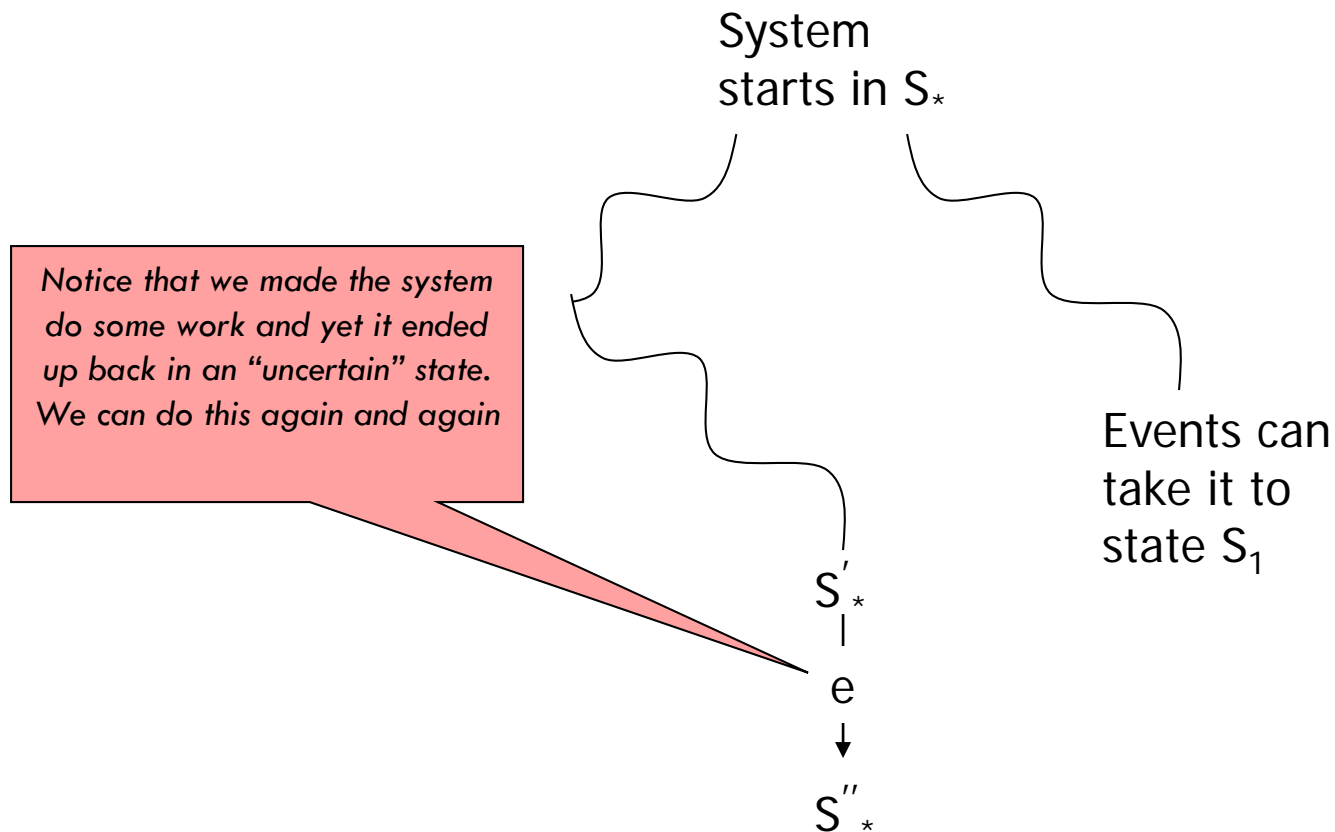
Bivalent state

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Bivalent state

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Core of FLP result in words

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- In an initially bivalent state, they look at some execution that would lead to a decision state, say “0”
 - ▣ At some step this run switches from bivalent to univalent, when some process receives some message m
 - ▣ They now explore executions in which m is delayed

Core of FLP result

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- So:
 - ▣ Initially in a bivalent state
 - ▣ Delivery of m would make us univalent but we delay m
 - ▣ They show that if the protocol is fault-tolerant there must be a run that leads to the other univalent state
 - ▣ And they show that you can deliver m in this run without a decision being made
- This proves the result: they show that a bivalent system can be forced to do some work and yet remain in a bivalent state.
 - ▣ If this is true once, it is true as often as we like
 - ▣ In effect: we can delay decisions indefinitely

But how did they “really” do it?

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- Our picture just gives the basic idea
- Their proof actually proves that there is a way to force the execution to follow this tortured path
- But the result is very theoretical...
 - ▣ ... to much so for us in CS5412
 - ▣ So we'll skip the real details

Intuition behind this result?

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- Think of a real system trying to agree on something in which process p plays a key role
- But the system is fault-tolerant: if p crashes it adapts and moves on
- Their proof “tricks” the system into thinking p failed
 - ▣ Then they allow p to resume execution, but make the system believe that perhaps q has failed
 - ▣ The original protocol can only tolerate 1 failure, not 2, so it needs to somehow let p rejoin in order to achieve progress
- This takes time... and no real progress occurs

But what did “impossibility” mean?

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- In formal proofs, an algorithm is totally correct if
 - ▣ It computes the right thing
 - ▣ And it *always* terminates
- When we say something is possible, we mean “there is a totally correct algorithm” solving the problem
- FLP proves that any fault-tolerant algorithm solving consensus has runs that never terminate
 - ▣ These runs are extremely unlikely (“probability zero”)
 - ▣ Yet they imply that we can’t find a totally correct solution
 - ▣ And so “consensus is impossible” (“not always possible”)

How did they pull this off?

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- A very clever adversarial attack
 - ▣ They assume they have perfect control over which messages the system delivers, and when
 - ▣ They can pick the exact state in which a message arrives in the protocol
- They use this ultra-precise control to force the protocol to loop in the manner we've described
- In practice, no adversary ever has this much control

In the real world?

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- The FLP scenario “could happen”
 - ▣ After all, it is a valid scenario.
 - ▣ ... And any valid scenario can happen

- But step by step they take actions that are incredibly unlikely. For many to happen in a row is just impossible in practice
 - ▣ A “probability zero” sequence of events
 - ▣ Yet in a temporal logic sense, FLP shows that if we can prove correctness for a consensus protocol, we’ll be unable to prove it live in a realistic network setting, like a cloud system

So...

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- Fault-tolerant consensus is...
 - ▣ Definitely possible (not even all that hard). Just vote!
 - ▣ And we can prove protocols of this kind correct.

- But we can't prove that they will terminate
 - ▣ If our goal is just a probability-one guarantee, we actually *can* offer a proof of progress
 - ▣ But in temporal logic settings we want perfect guarantees and we can't achieve that goal

Recap

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- We have an asynchronous model with crash failures
 - ▣ A bit like the real world!
- In this model we know how to do some things
 - ▣ Tracking “happens before” & making a consistent snapshot
 - ▣ Later we’ll find ways to do ordered multicast and implement replicated data and even solve consensus
- But now we also know that there will always be scenarios in which our solutions can’t make progress
 - ▣ Often can engineer system to make them extremely unlikely
 - ▣ Impossibility doesn’t mean these solutions are wrong – only that they live within this limit

Tougher failure models

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- We've focused on crash failures
 - ▣ In the synchronous model these look like a “farewell cruel world” message
 - ▣ Some call it the “failstop model”. A faulty process is viewed as first saying goodbye, then crashing
- What about tougher kinds of failures?
 - ▣ Corrupted messages
 - ▣ Processes that don't follow the algorithm
 - ▣ Malicious processes out to cause havoc?

Here the situation is much harder

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- Generally we need at least $3f+1$ processes in a system to tolerate f Byzantine failures
 - ▣ For example, to tolerate 1 failure we need 4 or more processes
- We also need $f+1$ “rounds”
- Let’s see why this happens

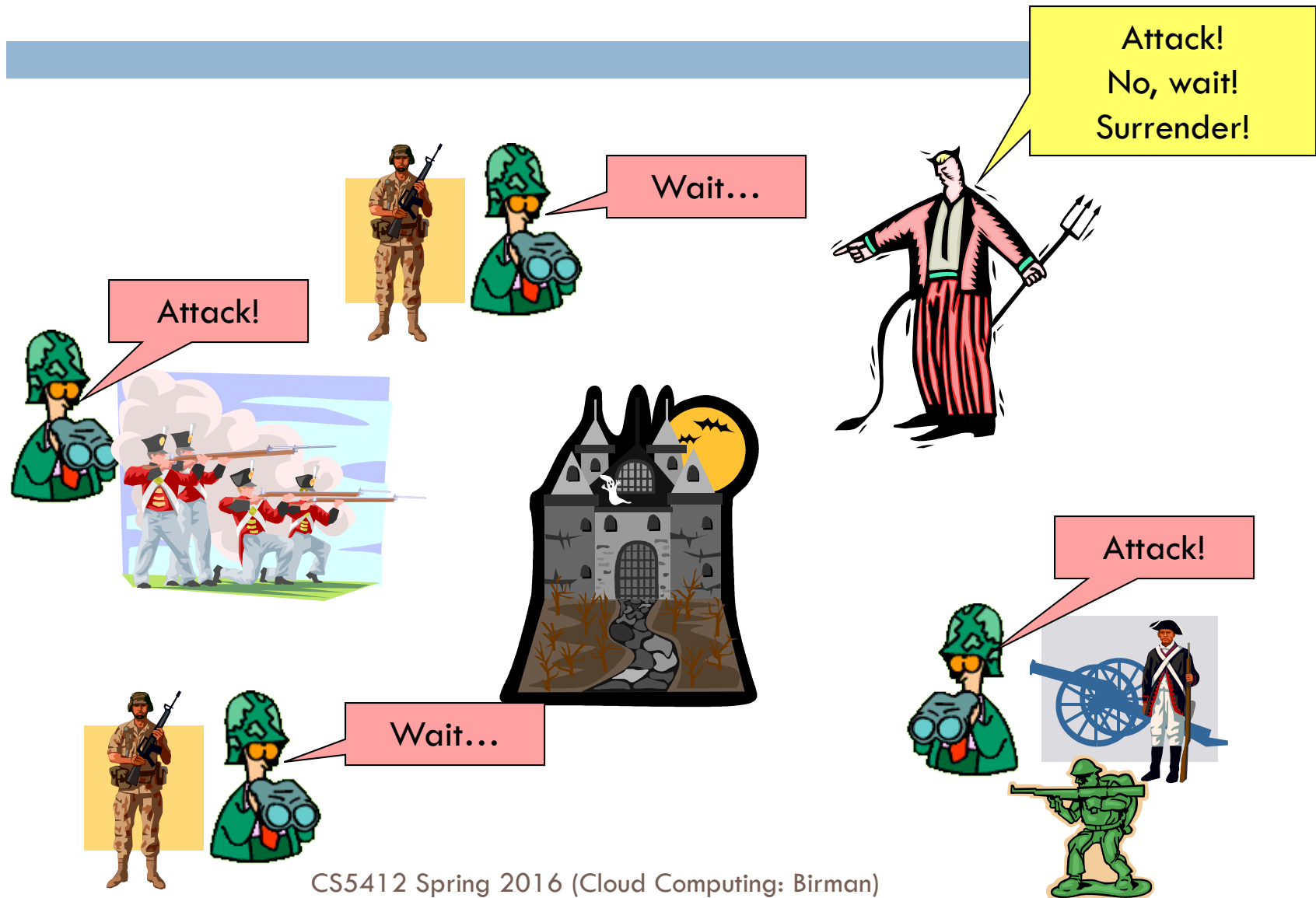
Byzantine scenario

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- Generals (N of them) surround a city
 - ▣ They communicate by courier
- Each has an opinion: “attack” or “wait”
 - ▣ In fact, an attack would succeed: the city will fall.
 - ▣ Waiting will succeed too: the city will surrender.
 - ▣ But if some attack and some wait, disaster ensues
- Some Generals (f of them) are traitors... it doesn't matter if they attack or wait, but we must prevent them from disrupting the battle
 - ▣ Traitor can't forge messages from other Generals

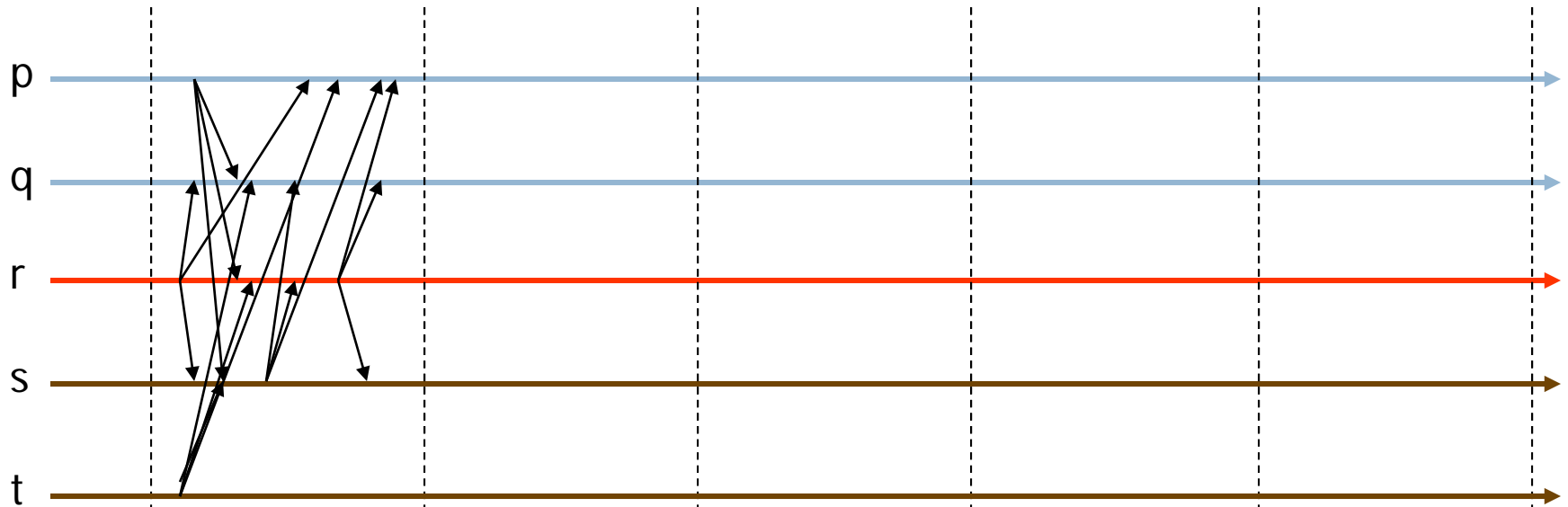
Byzantine scenario

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A timeline perspective

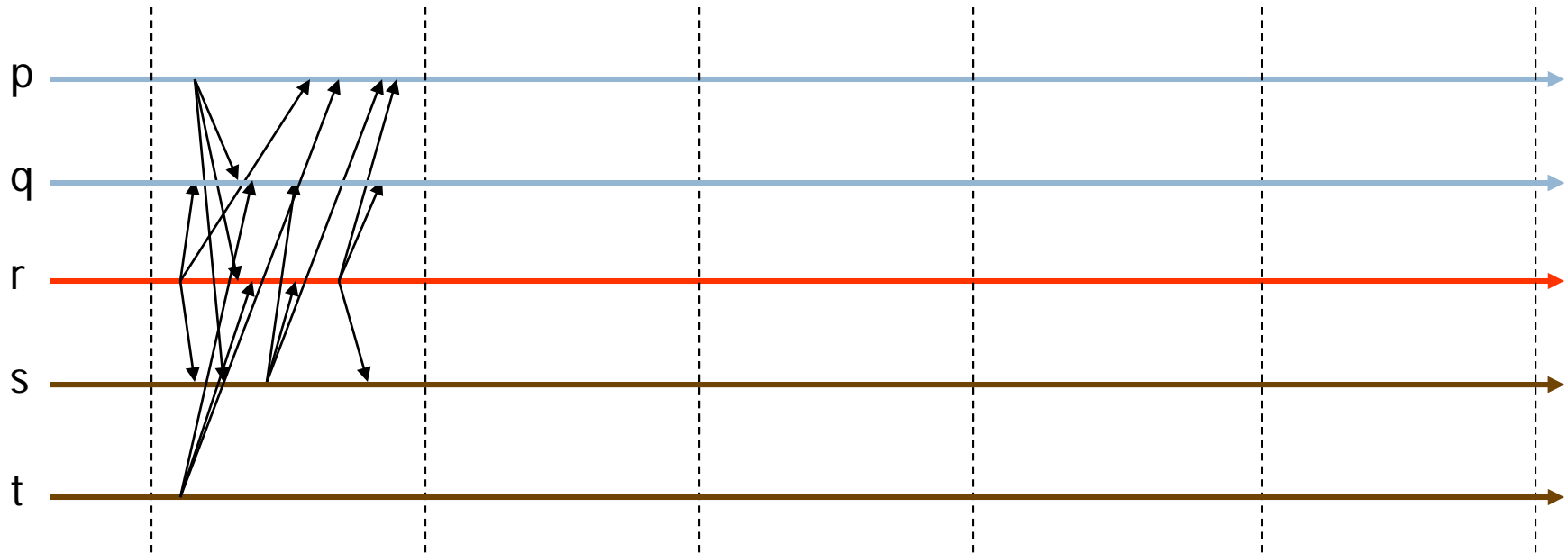
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- Suppose that p and q favor attack, r is a traitor and s and t favor waiting... assume that in a tie vote, we attack

A timeline perspective

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- After first round collected votes are:
 - ▣ {attack, attack, wait, wait, traitor's-vote}

What can the traitor do?

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- Add a legitimate vote of “attack”
 - ▣ Anyone with 3 votes to attack knows the outcome
- Add a legitimate vote of “wait”
 - ▣ Vote now favors “wait”
- Or send different votes to different folks
- Or don't send a vote, at all, to some

Outcomes?

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- Traitor simply votes:
 - ▣ Either all see $\{a, a, a, w, w\}$
 - ▣ Or all see $\{a, a, w, w, w\}$
- Traitor double-votes
 - ▣ Some see $\{a, a, a, w, w\}$ and some $\{a, a, w, w, w\}$
- Traitor withholds some vote(s)
 - ▣ Some see $\{a, a, w, w\}$, perhaps others see $\{a, a, a, w, w\}$ and still others see $\{a, a, w, w, w\}$
- Notice that traitor can't manipulate votes of loyal Generals!

What can we do?

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- Clearly we can't decide yet; some loyal Generals might have contradictory data
 - ▣ In fact if anyone has 3 votes to attack, they can already “decide”.
 - ▣ Similarly, anyone with just 4 votes can decide
 - ▣ But with 3 votes to “wait” a General isn't sure (one could be a traitor...)
- So: in round 2, each sends out “witness” messages: here's what I saw in round 1
 - ▣ General Smith send me: “attack_{(signed) Smith}”

Digital signatures

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- These require a cryptographic system
 - ▣ For example, RSA
 - ▣ Each player has a secret (private) key K^{-1} and a public key K .
 - She can publish her public key
 - ▣ RSA gives us a single “encrypt” function:
 - $\text{Encrypt}(\text{Encrypt}(M, K), K^{-1}) = \text{Encrypt}(\text{Encrypt}(M, K^{-1}), K) = M$
 - Encrypt a hash of the message to “sign” it

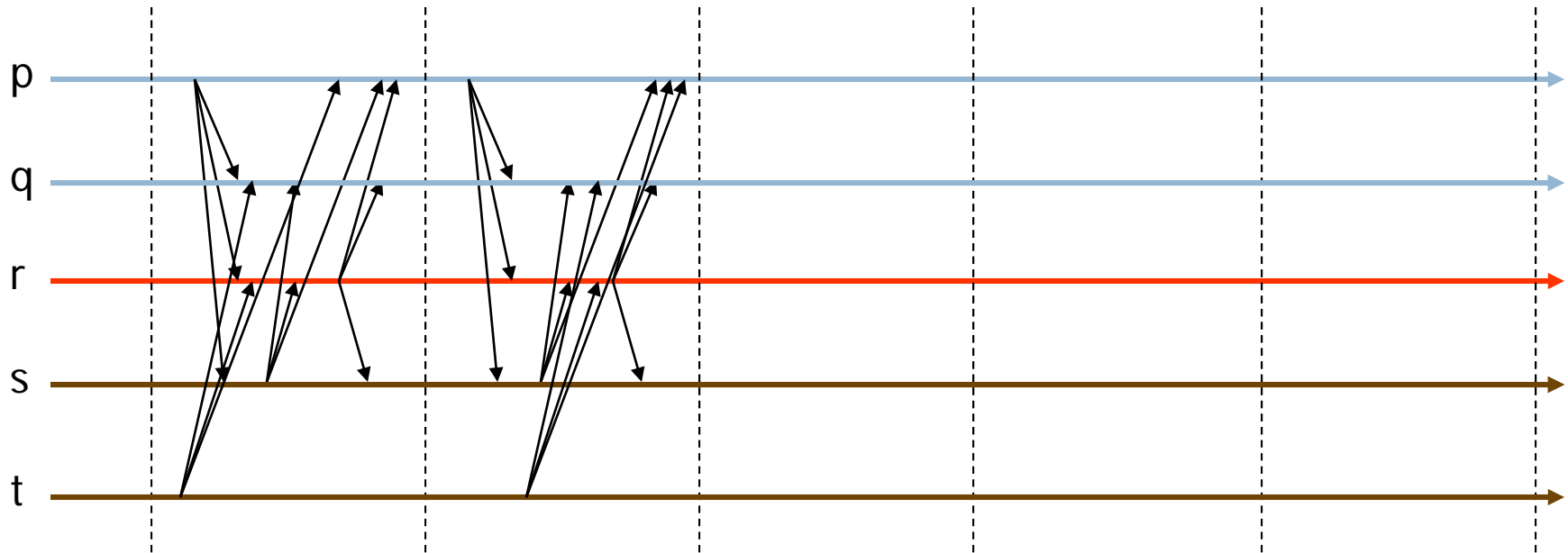
With such a system

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- A can send a message to B that only A could have sent
 - ▣ A just encrypts the body with her private key
- ... or one that only B can read
 - ▣ A encrypts it with B's public key
- Or can sign it as proof she sent it
 - ▣ B can recompute the signature and decrypt A's hashed signature to see if they match
- These capabilities limit what our traitor can do: he can't forge or modify a message

A timeline perspective

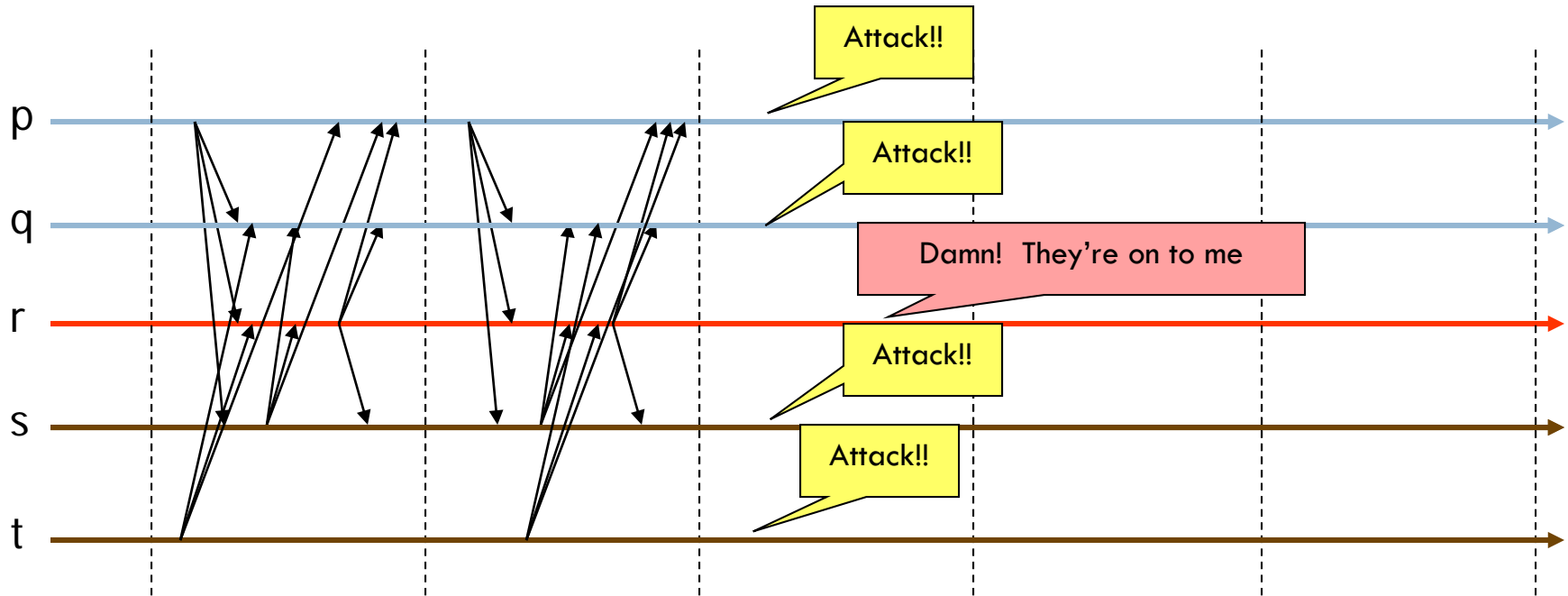
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- In second round if the traitor didn't behave identically for all Generals, we can weed out his faulty votes

A timeline perspective

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□ We attack!

Traitor is stymied

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- Our loyal generals can deduce that the decision was to attack
- Traitor can't disrupt this...
 - ▣ Either forced to vote legitimately, or is caught
 - ▣ But costs were steep!
 - $(f+1)*n^2$,messages!
 - Rounds can also be slow....
 - ▣ “Early stopping” protocols: $\min(t+2, f+1)$ rounds; t is true number of faults

Recent work with Byzantine model

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- Focus is typically on using it to secure particularly sensitive, ultra-critical services
 - ▣ For example the “certification authority” that hands out keys in a domain
 - ▣ Or a database maintaining top-secret data
- Researchers have suggested that for such purposes, a “Byzantine Quorum” approach can work well
- They are implementing this in real systems by simulating rounds using various tricks

Byzantine Quorums

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- Arrange servers into a $\sqrt{n} \times \sqrt{n}$ array
 - ▣ Idea is that any row or column is a quorum
 - ▣ Then use Byzantine Agreement to access that quorum, doing a read or a write
- Separately, Castro and Liskov have tackled a related problem, using BA to secure a file server
 - ▣ By keeping BA out of the critical path, can avoid most of the delay BA normally imposes

Split secrets

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- In fact BA algorithms are just the tip of a broader “coding theory” iceberg
- One exciting idea is called a “split secret”
 - ▣ Idea is to spread a secret among n servers so that any k can reconstruct the secret, but no individual actually has all the bits
 - ▣ Protocol lets the client obtain the “shares” without the servers seeing one-another’s messages
 - ▣ The servers keep but can’t read the secret!
- Question: In what ways is this better than just encrypting a secret?

How split secrets work

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- They build on a famous result
 - ▣ With $k+1$ distinct points you can uniquely identify an order- k polynomial
 - i.e 2 points determine a line
 - 3 points determine a unique quadratic
 - ▣ The polynomial is the “secret”
 - ▣ And the servers themselves have the points – the “shares”
 - ▣ With coding theory the shares are made just redundant enough to overcome $n-k$ faults

Byzantine Broadcast (BB)

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- Many classical research results use Byzantine Agreement to implement a form of fault-tolerant multicast
 - ▣ To send a message I initiate “agreement” on that message
 - ▣ We end up agreeing on content and ordering w.r.t. other messages
- Used as a primitive in many published papers

Pros and cons to BB

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- On the positive side, the primitive is very powerful
 - ▣ For example this is the core of the Castro and Liskov technique
- But on the negative side, BB is slow
 - ▣ We'll see ways of doing fault-tolerant multicast that run at 150,000 small messages per second
 - ▣ BB: more like 5 or 10 per second
- The right choice for infrequent, very sensitive actions... but wrong if performance matters

Take-aways?

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- Fault-tolerance matters in many systems
 - ▣ But we need to agree on what a “fault” is
 - ▣ Extreme models lead to high costs!
- Common to reduce fault-tolerance to some form of data or “state” replication
 - ▣ In this case fault-tolerance is often provided by some form of broadcast
 - ▣ Mechanism for *detecting* faults is also important in many systems.
 - Timeout is common... but can behave inconsistently
 - “View change” notification is used in some systems. They typically implement a fault agreement protocol.