

Announcements

1. Speed/memory problems: note that if you only need to project into K dimensions, you don't need to compute all eigenvectors, but just the top K ; consider `eigs` for Matlab, `numpy.linalg.eigh` in Python. If you decide to use the SVD instead, as has been alluded to in class and on Piazza, make sure you understand what matrix you should apply the SVD to. (Data = rows or columns? Center the data first? etc.) (Piazza @45 followup, "Numpy very slow")
2. A PCA example in C++ has been posted to the lecture 3 materials.
3. Homework updates (will be propagated to HW posted online some time today)
 - (a) A1 Q1.2 Y_I and Y_{II} should be equal *up to sign*, as opposed to "strictly equal", as indicated by the subsequent assignment question.
 - (b) A1 Q1.3: you may, for simplicity, assume that the \mathbf{x}_t s are centered; however, this condition is not strictly necessary. (Piazza @52)

Selected clustering optimization functions Assume we have n data points $\mathbf{x}_1, \dots, \mathbf{x}_n$. (When possible, we'll avoid using indices and refer to an arbitrary member of this set as \mathbf{x} .) Assume we have a partitioning of the data points into K clusters C_1, \dots, C_K , which we'll index by j .¹ For each cluster C_j , we write n_j for the number of \mathbf{x} s in C_j .

Some of these should be maximized and some of these should be minimized. Can you convince yourself which is which?

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|-------------------------------|--|--|
| (1) Within-cluster scatter | $\sum_j \sum_{\mathbf{x}_t, \mathbf{x}_s \in C_j, t < s} \ \mathbf{x}_t - \mathbf{x}_s\ _2^2$ | |
| (2) Within-cluster variation | $\sum_j n_j \sum_{\mathbf{x} \in C_j} \ \mathbf{x} - \mathbf{r}_j\ _2^2$ | centroid $\mathbf{r}_j \stackrel{def}{=} \frac{1}{n_j} \sum_{\mathbf{x} \in C_j} \mathbf{x}$ |
| (3) Between-cluster scatter | $\sum_j \sum_{\mathbf{x}_t, \mathbf{x}_s \text{ in different clusters, } t < s} \ \mathbf{x}_t - \mathbf{x}_s\ _2^2$ | |
| (4) Between-cluster variation | $\sum_j n_j (\mathbf{r}_j - \mu)(\mathbf{r}_j - \mu)^T$ | $\mu = \frac{1}{n} \sum_{\mathbf{x}} \mathbf{x}$ |
| (5) Trace | $\sum_j n_j \text{tr}(\Sigma_j)$ | Σ_j : covariance for C_j
$\text{tr}(M) \stackrel{def}{=} \sum_i M[i, i]$ |
| (6) "best-friend" | $\sum_j \max_{\mathbf{x} \in C_j} \min_{\mathbf{x}' \neq \mathbf{x} \in C_j} \{\ \mathbf{x} - \mathbf{x}'\ _2^2\}$ | |

Post-lecture update: Actually, the "best-friend" criterion has to be modified to handle the case of clusters containing a single element. More on this next lecture.

¹Using k as index variable might seem like a good idea, but my k s and K s are indistinguishable on the board.

Clicker question For any set of points $\mathbf{x}_1, \dots, \mathbf{x}_N$, let $\mathbf{r} = \frac{1}{N} \sum_t \mathbf{x}_t$ be the *centroid* of the points. Consider the following two assertions: **For any point \mathbf{z} ,**

$$(7) \quad \sum_t \|\mathbf{x}_t - \mathbf{z}\|_2^2 = \left(\sum_t \|\mathbf{x}_t - \mathbf{r}\|_2^2 \right) + \|\mathbf{r} - \mathbf{z}\|_2^2$$

$$(8) \quad \sum_t \|\mathbf{x}_t - \mathbf{z}\|_2^2 = \left(\sum_t \|\mathbf{x}_t - \mathbf{r}\|_2^2 \right) + N\|\mathbf{r} - \mathbf{z}\|_2^2$$

- A. Only (7) is true
- B. Only (8) is true
- C. Both are true
- D. Neither are true, by triangle inequality
- E. I really don't know

k-means algorithm Start with some initialization $\mathbf{r}_j^0, j \in 1, \dots, K$ (superscripts = iteration number, we start with $i = 0$). Repeat until “convergence”:

1. Assign each \mathbf{x} to its nearest *representative* \mathbf{r}_j^i .
2. Set \mathbf{r}_j^{i+1} to be the centroid of the \mathbf{x} s now assigned to it.
3. Increment i