

**Announcements**

1. Speed/memory problems: note that if you only need to project into  $K$  dimensions, you don't need to compute all eigenvectors, but just the top  $K$ ; consider `eigs` for Matlab, `numpy.linalg.eigh` in Python. If you decide to use the SVD instead, as has been alluded to in class and on Piazza, make sure you understand what matrix you should apply the SVD to. (Data = rows or columns? Center the data first? etc.) (Piazza @45 followup, "Numpy very slow")
2. A PCA example in C++ has been posted to the lecture 3 materials.
3. Homework updates (will be propagated to HW posted online some time today)
  - (a) A1 Q1.2  $Y_I$  and  $Y_{II}$  should be equal *up to sign*, as opposed to "strictly equal", as indicated by the subsequent assignment question.
  - (b) A1 Q1.3: you may, for simplicity, assume that the  $\mathbf{x}_t$ s are centered; however, this condition is not strictly necessary. (Piazza @52)

**Selected clustering optimization functions** Assume we have  $n$  data points  $\mathbf{x}_1, \dots, \mathbf{x}_n$ . (When possible, we'll avoid using indices and refer to an arbitrary member of this set as  $\mathbf{x}$ .) Assume we have a partitioning of the data points into  $K$  clusters  $C_1, \dots, C_K$ , which we'll index by  $j$ .<sup>1</sup> For each cluster  $C_j$ , we write  $n_j$  for the number of  $\mathbf{x}$ s in  $C_j$ .

Some of these should be maximized and some of these should be minimized. Can you convince yourself which is which?

- |                               |  |  |
|-------------------------------|--|--|
| (1) Within-cluster scatter    | $\sum_j \sum_{\mathbf{x}_t, \mathbf{x}_s \in C_j, t < s} \ \mathbf{x}_t - \mathbf{x}_s\ _2^2$                        |  |
| (2) Within-cluster variation  | $\sum_j n_j \sum_{\mathbf{x} \in C_j} \ \mathbf{x} - \mathbf{r}_j\ _2^2$   | centroid $\mathbf{r}_j \stackrel{def}{=} \frac{1}{n_j} \sum_{\mathbf{x} \in C_j} \mathbf{x}$ |
| (3) Between-cluster scatter   | $\sum_j \sum_{\mathbf{x}_t, \mathbf{x}_s \text{ in different clusters, } t < s} \ \mathbf{x}_t - \mathbf{x}_s\ _2^2$ |  |
| (4) Between-cluster variation | $\sum_j n_j (\mathbf{r}_j - \mu)(\mathbf{r}_j - \mu)^T$  | $\mu = \frac{1}{n} \sum_{\mathbf{x}} \mathbf{x}$   |
| (5) Trace                     | $\sum_j n_j \text{tr}(\Sigma_j)$   | $\Sigma_j$ : covariance for $C_j$<br>$\text{tr}(M) \stackrel{def}{=} \sum_i M[i, i]$         |
| (6) "best-friend"             | $\sum_j \max_{\mathbf{x} \in C_j} \min_{\mathbf{x}' \neq \mathbf{x} \in C_j} \{\ \mathbf{x} - \mathbf{x}'\ _2^2\}$   |  |

Post-lecture update: Actually, the "best-friend" criterion has to be modified to handle the case of clusters containing a single element. More on this next lecture.

<sup>1</sup>Using  $k$  as index variable might seem like a good idea, but my  $k$ s and  $K$ s are indistinguishable on the board.

**Clicker question** For any set of points  $\mathbf{x}_1, \dots, \mathbf{x}_N$ , let  $\mathbf{r} = \frac{1}{N} \sum_t \mathbf{x}_t$  be the *centroid* of the points. Consider the following two assertions: **For any point  $\mathbf{z}$ ,**

$$(7) \quad \sum_t \|\mathbf{x}_t - \mathbf{z}\|_2^2 = \left( \sum_t \|\mathbf{x}_t - \mathbf{r}\|_2^2 \right) + \|\mathbf{r} - \mathbf{z}\|_2^2$$

$$(8) \quad \sum_t \|\mathbf{x}_t - \mathbf{z}\|_2^2 = \left( \sum_t \|\mathbf{x}_t - \mathbf{r}\|_2^2 \right) + N\|\mathbf{r} - \mathbf{z}\|_2^2$$

- A. Only (7) is true
- B. Only (8) is true
- C. Both are true
- D. Neither are true, by triangle inequality
- E. I really don't know

**k-means algorithm** Start with some initialization  $\mathbf{r}_j^0, j \in 1, \dots, K$  (superscripts = iteration number, we start with  $i = 0$ ). Repeat until “convergence”:

1. Assign each  $\mathbf{x}$  to its nearest *representative*  $\mathbf{r}_j^i$ .
2. Set  $\mathbf{r}_j^{i+1}$  to be the centroid of the  $\mathbf{x}$ s now assigned to it.
3. Increment  $i$