

The k-NN classifier

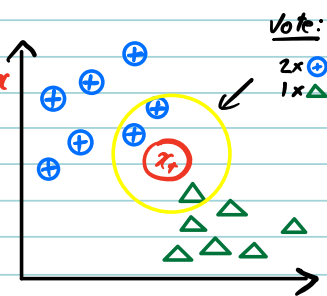
Assumption: Similar points share similar labels

Classification Rule: For a test input x_t assign the **most common** label among its **k most similar training inputs**.

Formally: $D = \{(x_1, y_1), \dots, (x_n, y_n)\}$ training data. Test point x

Let $S_x \subseteq D$ such that $|S_x| = k$
and $\forall (x', y') \in D \setminus S_x \quad \text{dist}(x', x) \geq \max_{(x'', y'') \in S_x} \text{dist}(x'', x)$

$h(x) = \text{mode} \{y : (x', y) \in S_x\}$



Protip: In case of a draw decide by reducing k by 1, until you reach a unique mode.

Training Error: Leave-One-Out (LOO) estimate: Take each training point out and estimate its label, pretending it was a test point. (i.e. a point cannot be its own neighbor)

What distance function should we use?

Common choice: Minkowski's distance:

$$\text{dist}(x, z) = \left(\sum_{\alpha} |x_{\alpha} - z_{\alpha}|^p \right)^{1/p} \quad \text{for } p > 0$$

special case: $p=2 \leftarrow$ Euclidean distance
 $p=1 \leftarrow$ Manhattan distance

Quiz: What if $p \rightarrow \infty$ or $p \rightarrow 0^+$?

How does k affect the outcome? How does the classifier behave as $k=1$, or $k=n$?

Bayes Optimal Classifier

Your data D is drawn from some distribution $(x, y) \sim P(x, y)$. Also: $P(x, y) = P(y|x)P(x)$

Assume you knew $P(y|x)$ (you never do, but just for the sake of the argument).

For some test x what label would you predict?

The most likely label: $h_{\text{opt}}(x) = \underset{y}{\text{argmax}} P(y|x)$

What is the expected error of the BOC? Let $y^* = h_{\text{opt}}(x)$ $\epsilon = 1 - P(y^*|x)$

The probability that x does not have the most likely label.

You can never do better than the BOC!

Asymptotic error bound for 1-NN (Cover and Hart 1967)

Quiz 1: You have a coin that shows head with probability p .
If you throw it twice, what is the probability q that both throws lead to **different** outcomes?

2. Show that $q \leq 2(1-p)$.

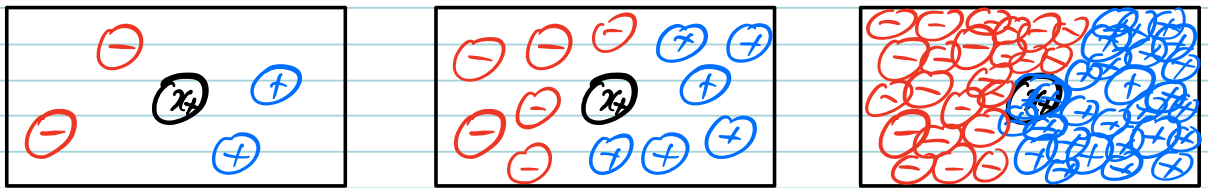
Back to 1-NN. We want to prove that the expected 1-NN test error is less than $2 \times$ the BOC error, as $n \rightarrow \infty$. (for binary classification.)

Argument: Let x be the test point and \hat{x} be its nearest neighbor.

Claim 1: As $n \rightarrow \infty$, $\text{dist}(x, \hat{x}) \rightarrow 0$ ← i.e. The nearest neighbor becomes infinitely close.

Claim 2: As $\text{dist}(x, \hat{x}) \rightarrow 0$, $\hat{x} \rightarrow x$ ← i.e. In fact, the nearest neighbor becomes identical to x .

(see Cover & Hart for proof.)



Assume for x_t the label y^* is most likely. Let $p = P(y^* | x_t)$

The BOC would predict y^* , and be wrong with probability $\underline{\underline{\epsilon_{BOC} = 1-p}}$.

What is the error of 1-NN as $n \rightarrow \infty$?

1-NN is wrong if the labels of x and \hat{x} are **different**.

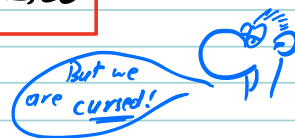
By claim 2 we have $\hat{x} \rightarrow x$. And $p(y^* | \hat{x}) = p(y^* | x) = p$

Both points x and \hat{x} could take on label y^* with prob. p , and not with $(1-p)$.

Remember Quiz 2. regard both points as the same coin tossed twice.

They disagree with probability $2p(1-p) \leq 2(1-p) = \underline{\underline{2\epsilon_{BOC}}}$

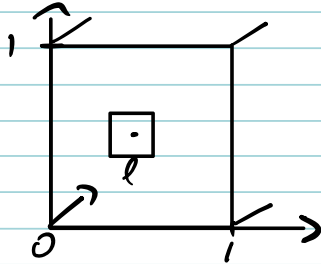
$\Rightarrow \epsilon_{1-NN} \leq 2\epsilon_{BOC}$ as $n \rightarrow \infty$



Curse of Dimensionality

Assume $x_i \in [0,1]^d$ (i.e. the d dimensional unit hypercube).
 All data is drawn uniformly at random.
 Let $k=10$.

Let l be the edge length of the smallest hypercube that contains all k nearest neighbors of a test point x .



$$l^d \approx \frac{k}{n} \Rightarrow l \approx \left(\frac{k}{n}\right)^{1/d}$$

↑ volume of mini cube containing the k neighbors
 ↑ Total volume of hypercube $[0,1]^d$ is $1^d=1$
 $\frac{k}{n}$ is the fraction that k points take up. (because points are uniformly sampled)

If $n=1000$ how big is l ?

d	2	10	100	1000
l	0.1	0.63	0.955	0.9954

Almost the entire space is needed to fit 10 nearest neighbors.

This means nearest neighbors are not similar, violating the k -NN assumption!

How many points would we need for l to be small?
 Fix $l=0.1$

$$l^d = \frac{k}{n} \Rightarrow n = k \left(\frac{1}{l}\right)^d = k 10^d \leftarrow \text{grows exponentially with } d!$$

Rescue to the curse:

Data can have structure:

- Data can lie on intrinsically low dimensional subspaces or sub-manifolds.

- Data can be clustered (very non-uniform).