## The Perceptron Algorithm

## Announcements

1. P2 (Perceptron) will be out tmr

## Recap on PCA

T/F: we need to center the dataset before we run PCA

Recap on PCA

T/F: we need to center the dataset before we run PCA

Q: How to pick the parameter K in PCA?

$$
X_{x}^{\top}=U \wedge U^{\top}
$$




Frank Rosenblatt
@ Cornell!


## Perceptron, 1957

Predecessor of deep networks.

Separating two classes of objects using a linear threshold classifier.



## Perceptron, 1957

New Navy Device Learns by Doing

- The New York Times (July 8, 1958)
"Later perceptrons will be able to recognize people and call out their names and instantly translate speech in one language to speech or writing in another language, it was predicted."
https://news.cornell.edu/stories/2019/09/professors-perceptron-paved-way-ai-60-years-too-soon


## Today

Objective: learn our first (binary) classification algorithm and understand why it works

## Outline

1. Linear binary Classifier
2. Algorithm
3. Proof of why it works

## Linear classifier

Binary classification setting: $x \in \mathbb{R}^{d}, y=\{-1,+1\}$


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$w$ : weight vector, wlog assume $\|w\|_{2}=1$
$b: \notin$ bias term; $|b|$ determines the distance of the hyperplane to origin

## Linear classifier

Binary classification setting: $x \in \mathbb{R}^{d}, y=\{-1,+1\}$


## Setting

We often assume data $\left\{x_{i}, y_{i}\right\}_{i=1}^{n}$ is linearly separable,


$$
\begin{aligned}
& \text { i.e., } \exists w^{\star}, b^{\star} \text {, such that } \\
& \operatorname{sign}\left(\left(w^{\star}\right)^{\top} x_{i}+b^{\star}\right)=\operatorname{sign}\left(y_{i}\right), \forall i
\end{aligned}
$$

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We often assume data $\left\{x_{i}, y_{i}\right\}_{i=1}^{n}$ is linearly separable,


Linear classifier

Absorbing the bias term into the feature vector


## Linear classifier

## Absorbing the bias term into the feature vector

$$
w^{\top} x+b=\left[\begin{array}{l}
w \\
b
\end{array}\right]^{\top}\left[\begin{array}{l}
x \\
1
\end{array}\right]
$$

Throughout the semester, we will assume feature $x$ in/default contains the constant 1


## Outline

1. Linear binary Classifier
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For $t=0 \rightarrow \infty$

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For $t=0 \rightarrow \infty$ $10{ }^{\top} \times$

New feature $x_{t}$ shows up
Alg makes a prediction $\hat{y}_{t}=\operatorname{sign}\left(w_{t}^{\top} x_{t}\right)$

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Check if $\hat{y}_{t}=y_{t}$

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Goal: make \# of mistakes $\sum_{t=0}^{\infty} 1\left(\hat{y}_{t} \neq y_{t}\right)$ as small as possible

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Perceptron tells us how to do this update!

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## The Algorithm

## Initialize $w_{0}=\mathbf{0}$

For $t=0 \rightarrow \infty$
New feature $x_{t}$ shows up
Alg makes a prediction $\hat{y}_{t}=\operatorname{sign}\left(w_{t}^{\top} x_{t}\right)$
Check if $\hat{y}_{t}=y_{t}$

## The Algorithm

$$
\begin{aligned}
& \text { Initialize } w_{0}=0 \text { Initidiza the zero vector } \\
& \text { For } t=0 \rightarrow \infty
\end{aligned}
$$

New feature $x_{t}$ shows up
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Case 1: $\hat{y}_{t}=y_{t}, w_{t+1}=w_{t}$
Case 2: $\hat{y}_{t} \neq y_{t}$ (e.g., $\left.\hat{y}_{t}=-1, y_{t}=1\right)$

$$
W_{t+1}=W_{e}+y_{t} \cdot x_{t}
$$

$$
=w_{t}+x_{t}
$$


$\omega_{t}^{1} t_{t}$ was negative

## The Algorithm

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$$
w_{t+1}^{\top} x_{t}-w_{t}^{\top} x_{t}=\left(x_{t}^{\top} x_{t}\right)
$$

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w_{t+1}^{\top} x_{t}-w_{t}^{\top} x_{t}=\left(x_{t}^{\top} x_{t}\right)
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Value of $w_{t+1}^{\top} x_{t}$ is increased (the correct progress)

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$$
w_{t+1}^{\top} x_{t}-w_{t}^{\top} x_{t}=\left(x_{t}^{\top} x_{t}\right)
$$

Value of $w_{t+1}^{\top} x_{t}$ is increased (the correct progress)

Q: what happens when

$$
\hat{y}_{t}=1, y_{t}=-1
$$

$$
W_{t+1}=W_{e}-\chi_{t}
$$

## A Geometric explanation

$$
\text { When we make a mistake, i.e., } y_{t}\left(w_{t}^{\top} x_{t}\right)<0 \text { (e.g., } y_{t}=-1, w_{t}^{\top} x_{t}>0 \text { ) }
$$

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When we make a mistake, i.e., $y_{t}\left(w_{t}^{\top} x_{t}\right)<0$ (e.g., $y_{t}=-1, w_{t}^{\top} x_{t}>0$ )


Q: What does $w^{\star}$ look like?

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## A Geometric explanation

When we make a mistake, i.e., $y_{t}\left(w_{t}^{\top} x_{t}\right)<0$ (e.g., $y_{t}=-1, w_{t}^{\top} x_{t}>0$ )


We should track how the $\cos \left(\theta_{t}\right)$ is changing:

$$
\cos \left(\theta_{t}\right)=\frac{w_{t}^{\top} w^{\star}}{\left\|w_{t}\right\|_{2}}
$$



Q: What does $w^{\star}$ look like?

## Outline

1. Linear binary Classifier
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## Main theorem



## Main theorem

## Theorem of Perceptron:



## Main theorem

## Theorem of Perceptron:

Assume $\left\|x_{t}\right\|_{2} \leq 1, \forall t$. If there exists $w^{\star}$ with $\left\|w^{\star}\right\|_{2}=1$, such that

$$
y_{t}\left(x_{t}^{\top} w^{\star}\right) \geq \gamma>0, \forall t
$$


then:

$$
\sum_{t=0}^{\infty} \mathbb{1}\left(\hat{y}_{t} \neq y_{t}\right) \leq 1 / \gamma^{2}
$$

## Proof of the theorem



$$
\cos \left(\theta_{t}\right)=\frac{w_{t}^{\top} w^{\star}}{\left\|w_{t}\right\|_{2}}
$$

## Proof of the theorem




Assume we make a mistake at $x_{t}$, track how the denominator and numerator change

## Proof of the theorem



1. $\operatorname{Track} w_{t}^{\top} w^{\star}$

## Proof of the theorem



## Proof of the theorem



$$
\text { 1. Track } w_{t}^{\top} w^{\star}
$$

$$
w_{t+1}^{\top} w^{\star}=\left(w_{t}+y_{t} x_{t}\right)^{\top} w^{\star}
$$

$$
=w_{t}^{\top} w^{\star}+y_{t} x_{t}^{\top} w^{\star}
$$

## Proof of the theorem




## Proof of the theorem



1. $\operatorname{Track} w_{t}^{\top} w^{\star}$
$w_{t+1}^{\top} w^{\star}=\left(w_{t}+y_{t} x_{t}\right)^{\top} w^{\star}$
$=w_{t}^{\top} w^{\star}+y_{t} x_{t}^{\top} w^{\star}$
$\geq w_{t}^{\top} w^{\star}+\gamma$
Whenever we make a mistake, $w_{t}^{\top} w^{\star}$ at least increased by $\gamma$


## Proof of the theorem

$$
\begin{aligned}
& \text { 2. Track } w_{t}^{\top} w_{t} \\
& w_{t+1}^{\top} w_{t+1}=\left(w_{t}+y_{t} x_{t}\right)^{\top}\left(w_{t}+y_{t} x_{t}\right)=1 \\
& =w_{t}^{\top} w_{t}+2 w_{t}^{\top}\left(x_{t} y_{t}\right)+x_{t}^{\top} x_{t}
\end{aligned}
$$

Discuss this derivation in small group for 5 minutes!

## Proof of the theorem



## Proof of the theorem



## Proof of the theorem



## Proof of the theorem


3. What is $\cos \left(\theta_{t}\right)=w_{t}^{\top} w^{\star} / \sqrt{w_{t}^{\top} w_{t}}$ if we have made M mistakes?

After make M mistakes:

$$
\begin{gathered}
w_{t}^{\top} w^{\star} \geq M \gamma \\
w_{t}^{\top} w_{t} \leq M
\end{gathered}
$$

$$
1 \geq \cos \left(\theta_{t}\right) \geq(M \gamma) / \sqrt{M}=\sqrt{M} \gamma
$$

## Proof of the theorem


3. What is $\cos \left(\theta_{t}\right)=w_{t}^{\top} w^{\star} / \sqrt{w_{t}^{\top} w_{t}}$ if we have
made $\mathbf{M}$ mistakes?

After make M mistakes:

$$
\begin{gathered}
w_{t}^{\top} w^{\star} \geq M \gamma \\
w_{t}^{\top} w_{t} \leq M \\
1 \geq \cos \left(\theta_{t}\right) \geq(M \gamma) / \sqrt{M}=\sqrt{M} \gamma \\
\Rightarrow M \leq 1 / \gamma^{2}
\end{gathered}
$$



## Summary



## The Perceptron algorithm:

1. Binary classification algorithm, runs in online mode, makes update when makes a mistake (See lecture note for how to apply Perceptron on a static dataset)
2. Total \# of mistakes is bounded by a constant $\left(1 / \gamma^{2}\right)$
