

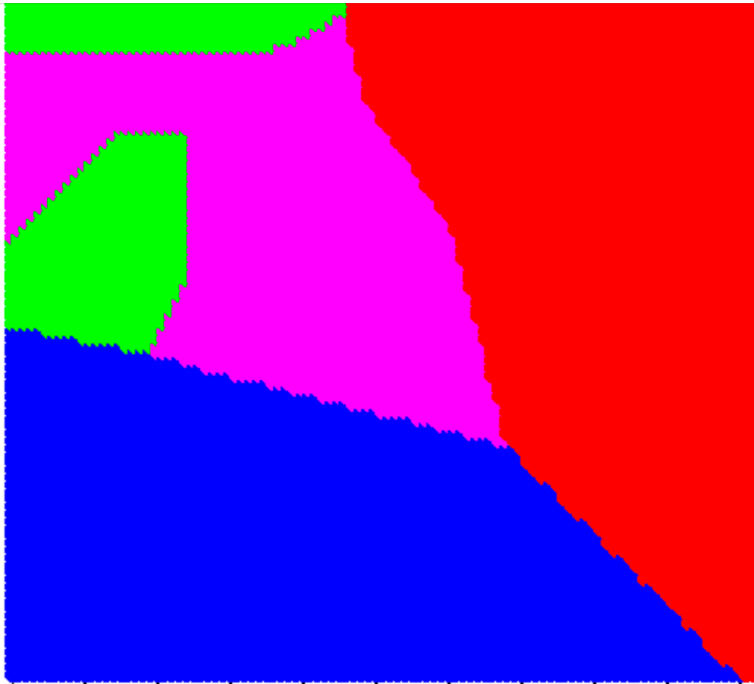
# Decision Trees

# **Announcements**

HW6 and P6 will be released soon

# Recap on the K-NN algorithm

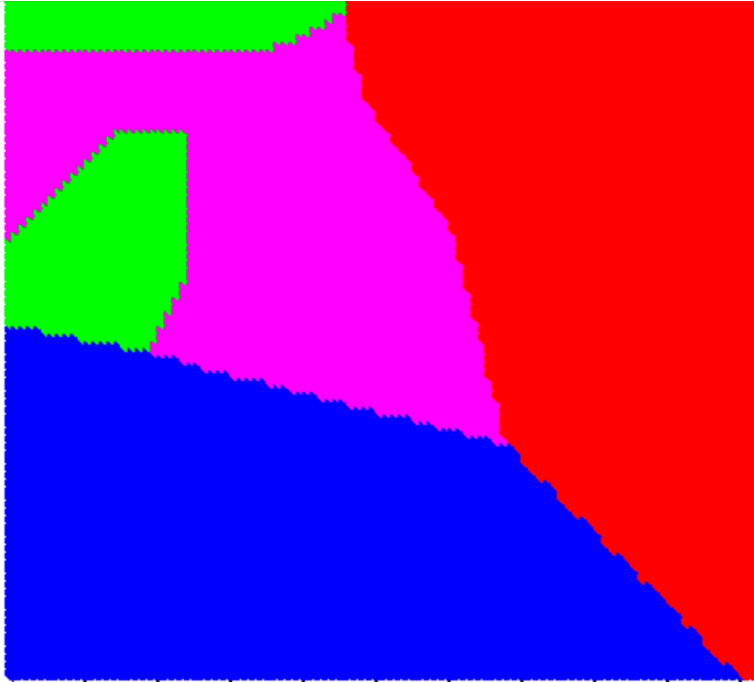
K-NN can have complicated nonlinear decision boundaries



[1-NN decision boundary in prelim]

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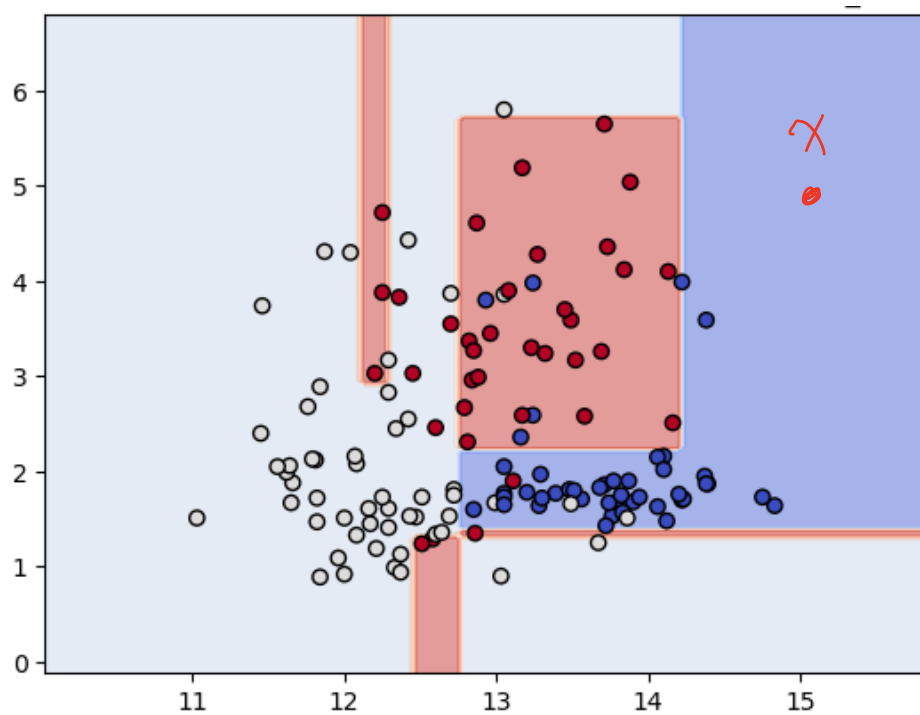
k-NN is expensive in computation  
and memory

# Objective today

Decision tree — more efficient algorithm that  
(1) splits space into regions with the same label, (2) is very fast in test time

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# Outline of Today

1. Decision tree in classification

2. Decision tree in regression

3. Demos of decision tree



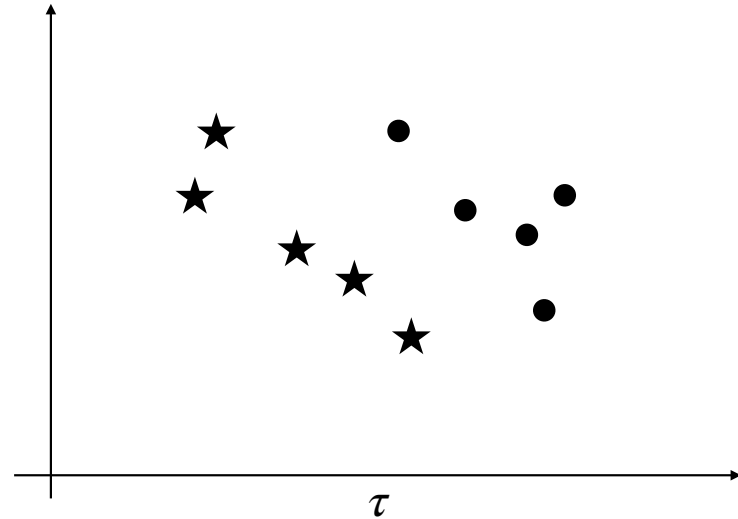


# How to split a tree node

Consider k-class classification, i.e.,  $y \in \{1, 2, \dots, k\}$

$x \in \mathbb{R}$

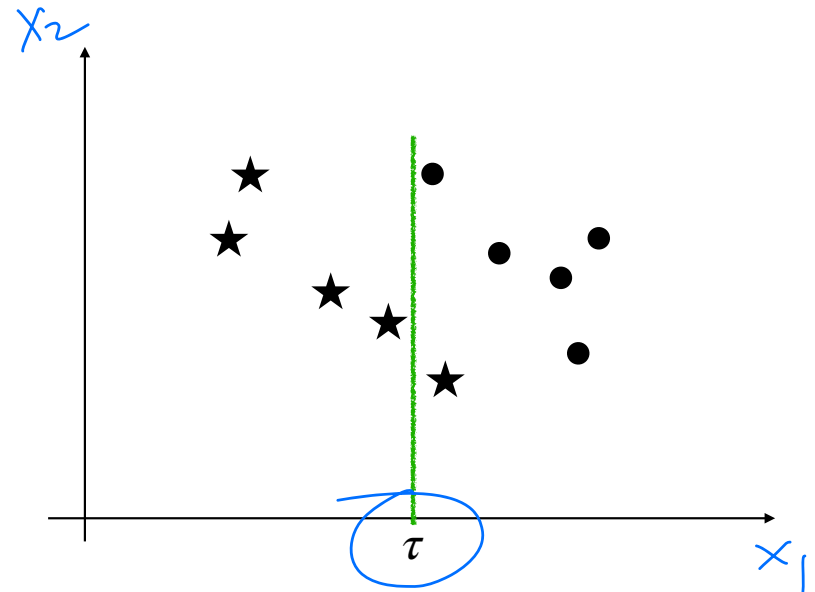
$$S = \{x, y\}$$



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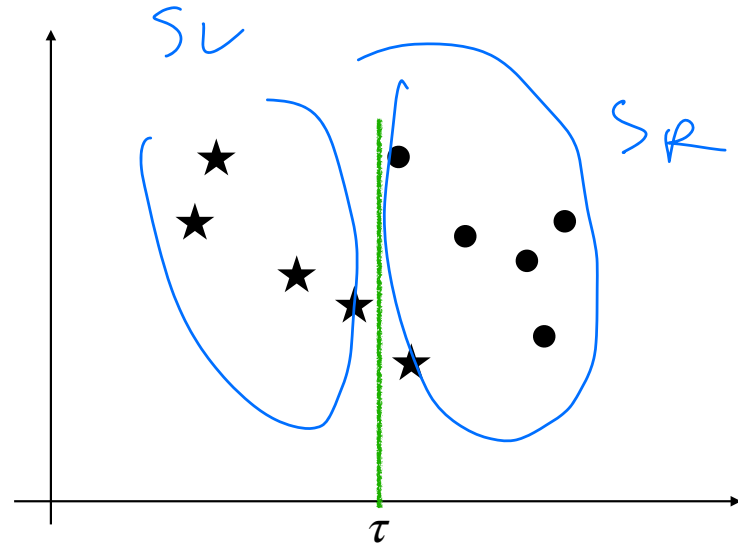
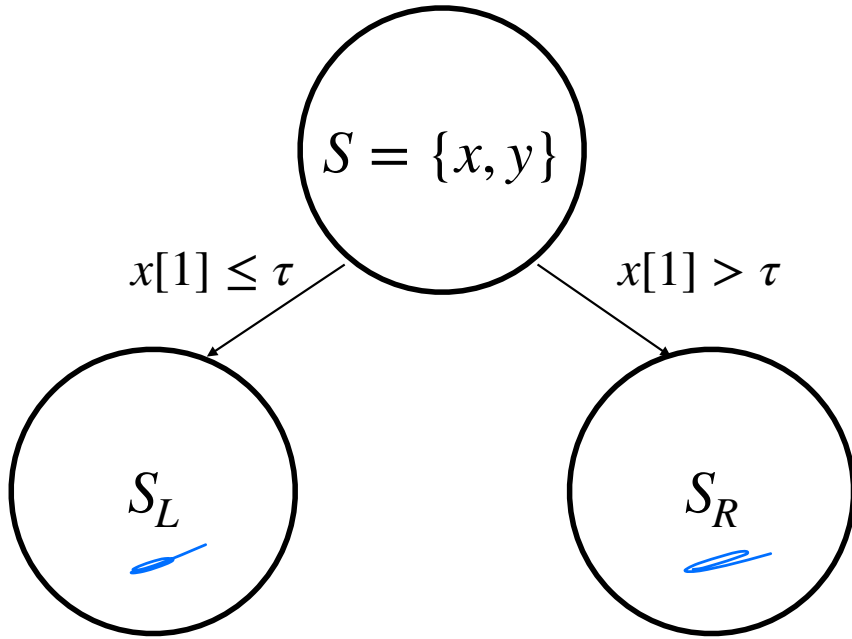
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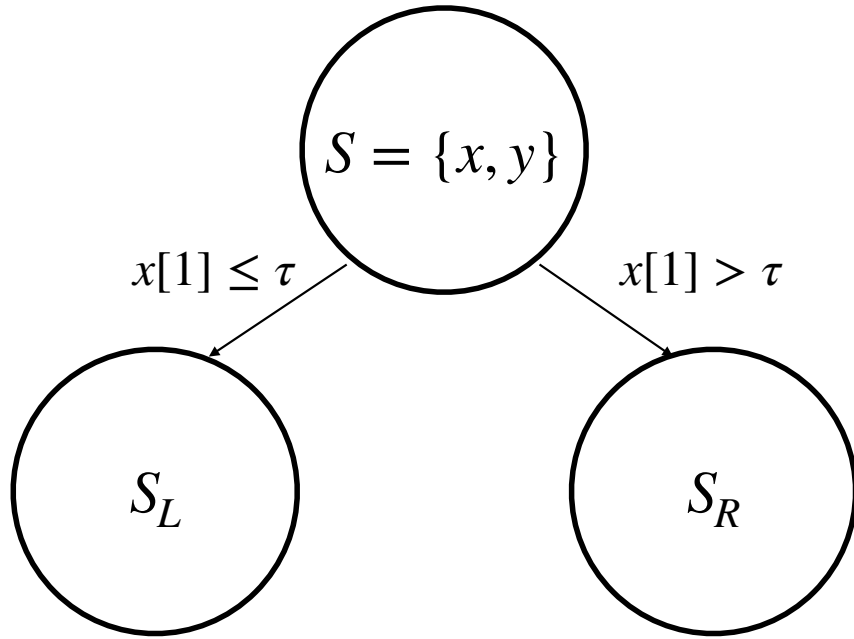
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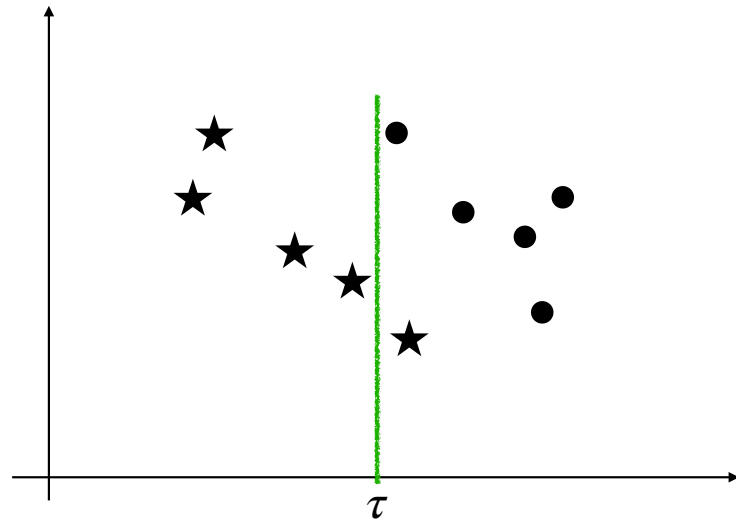


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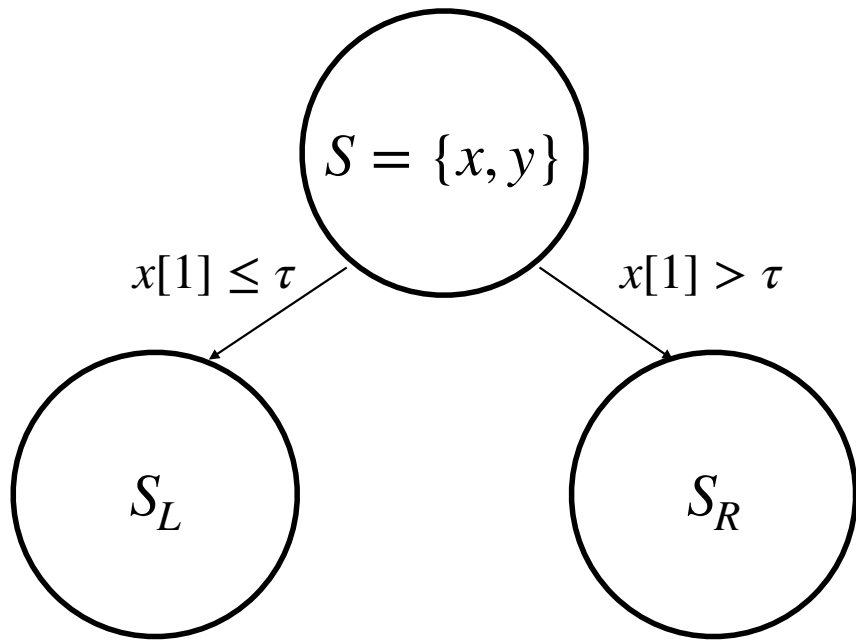


$$S_L + S_R = S, S_L \cap S_R = \emptyset$$



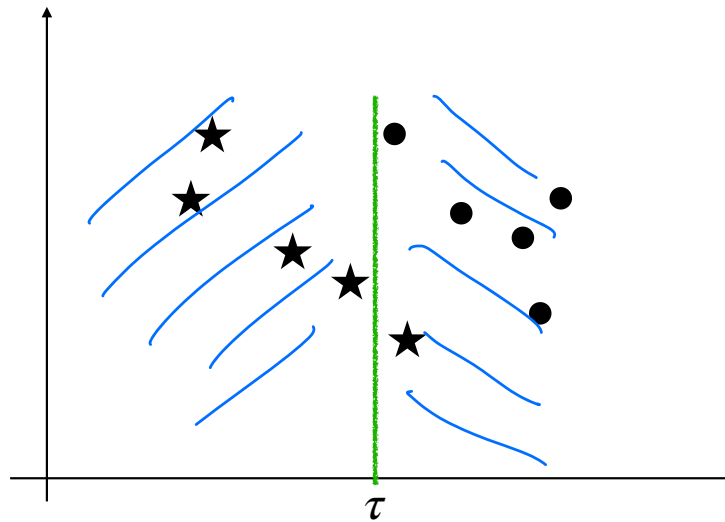
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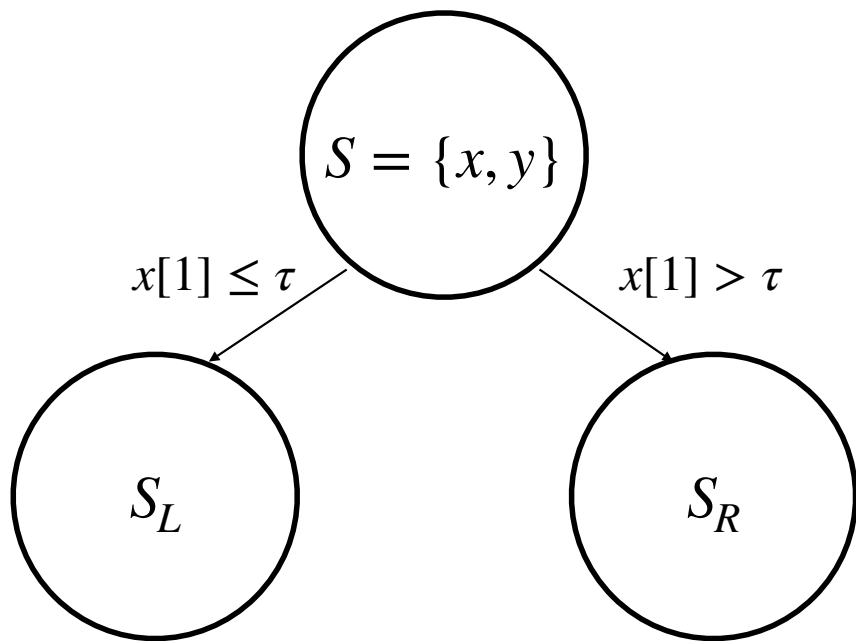
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Goal: do an axis aligned split such that diversity of labels in leafs are reduced



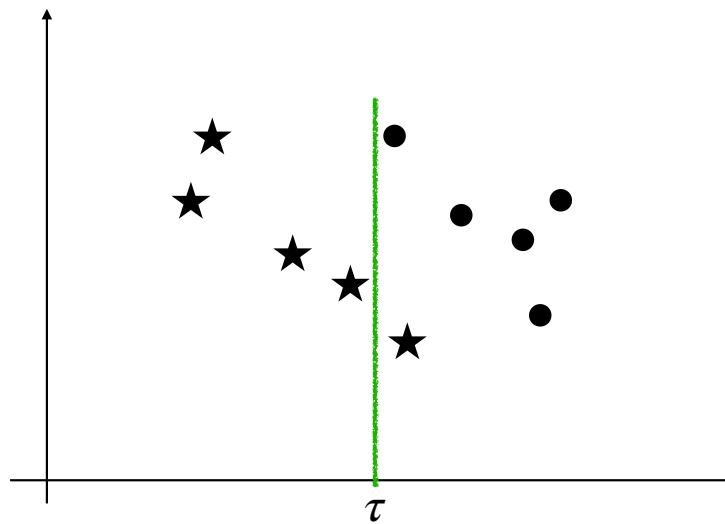
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How to mathematically quantify “diversity”?

## Detour: Entropy

Given a set  $S = \{x_i, y_i\}_{i=1}^n$ ,  $y_i \in \{1, 2, \dots, k\}$ , measure the diversity of labels via entropy

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High entropy means “diverse, chaos, uncertain”

# Entropy

Consider a Bernoulli distribution

$$P(y = 1) = p, P(y = 0) = 1 - p$$

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$$-P(y = 1) \cdot \ln P(y = 1) - P(y = 0) \cdot \ln P(y = 0)$$

*(Handwritten annotations: a blue circle around  $P(y = 1)$  with  $p$  written below it, and a blue circle around  $P(y = 0)$  with  $1-p$  written below it.)*

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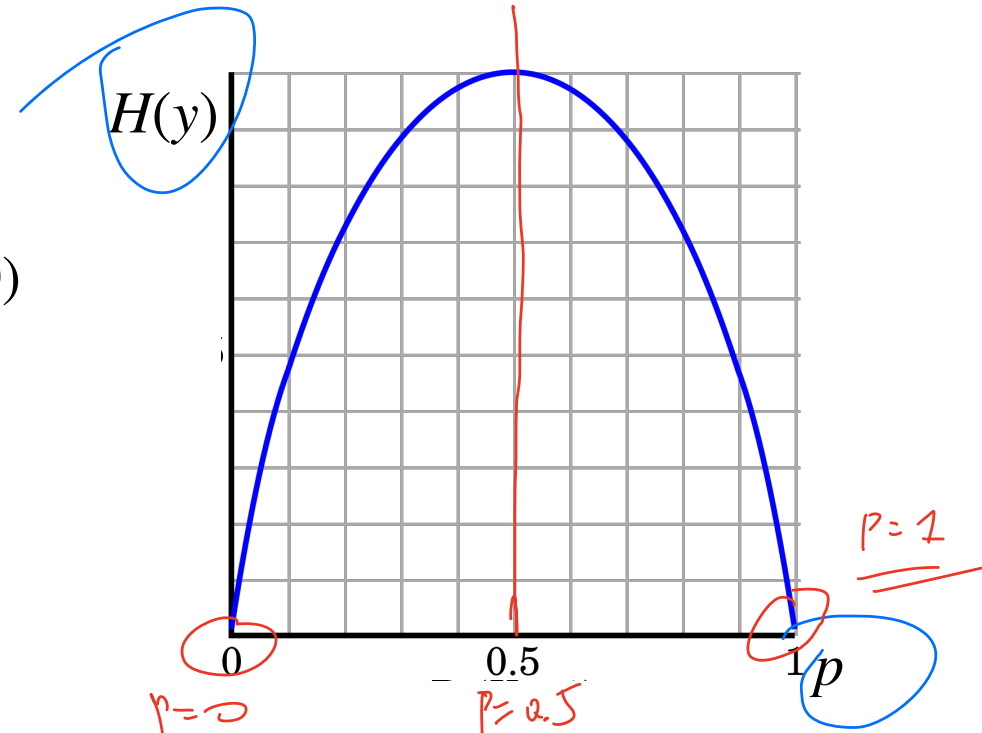
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# Entropy

Consider a categorical distribution

$$y \in \{1, 2, \dots, k\}, P(y = i) = p_i \geq 0, \sum_{i=1}^k p_i = 1$$

Q: when is entropy maximized?

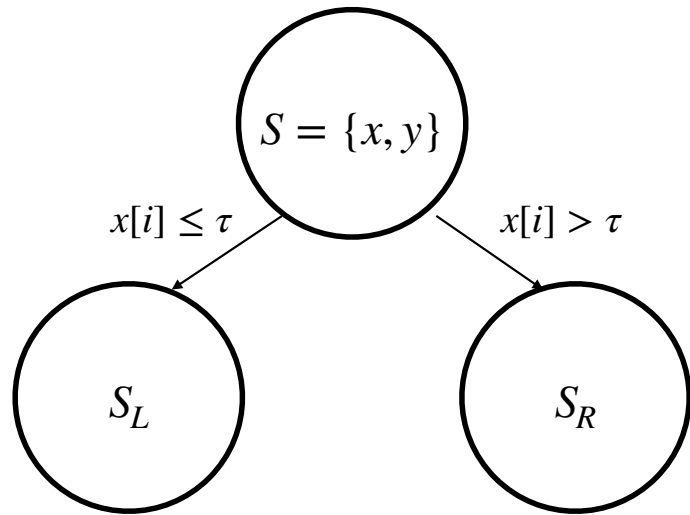
$$\sum_{i=1}^k - (p_i \ln p_i)$$

$$p_1 = p_2 = \dots = p_k = \frac{1}{k}$$



# Back to tree node split...

Consider a split, i.e, dim  $i$  and threshold  $\tau$ ,

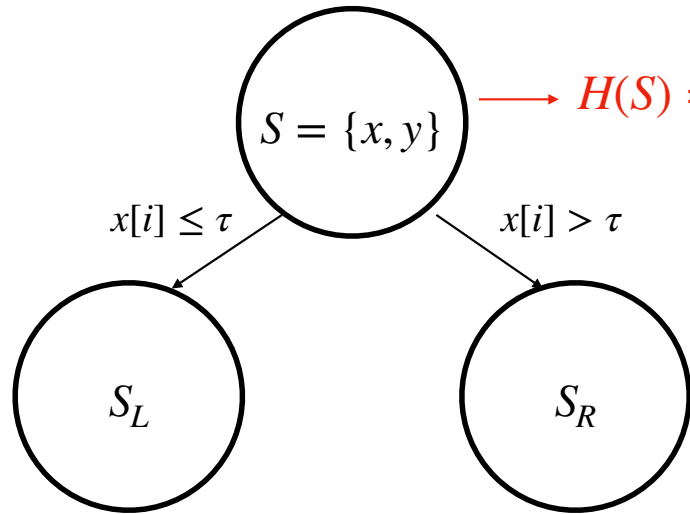


Optimization:

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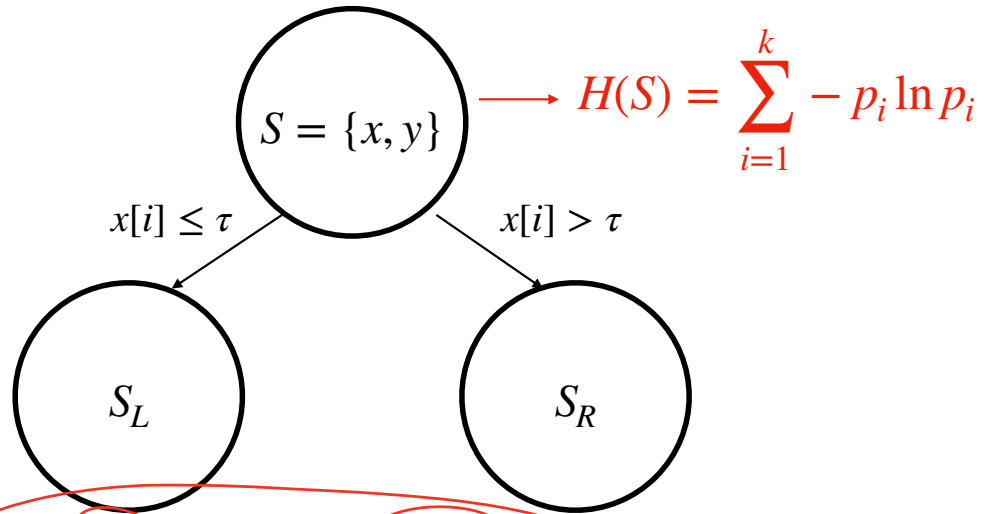


$$H(S) = \sum_{i=1}^k -p_i \ln p_i$$

$p_i = \frac{\text{\# of } x[i] \text{ in } S}{|S|}$

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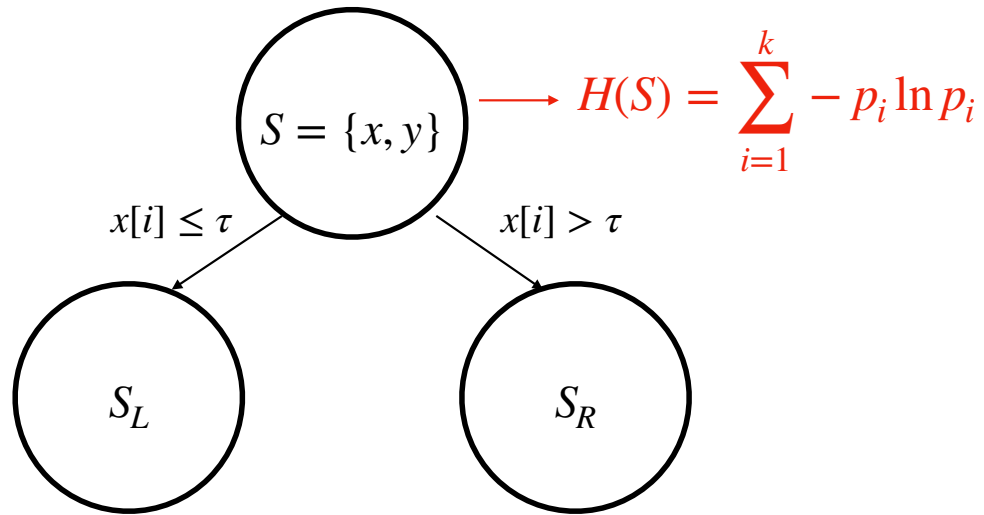


Optimization:

$$\left(\frac{|S_L|}{|S|}\right) H(S_L) + \left(\frac{|S_R|}{|S|}\right) H(S_R)$$

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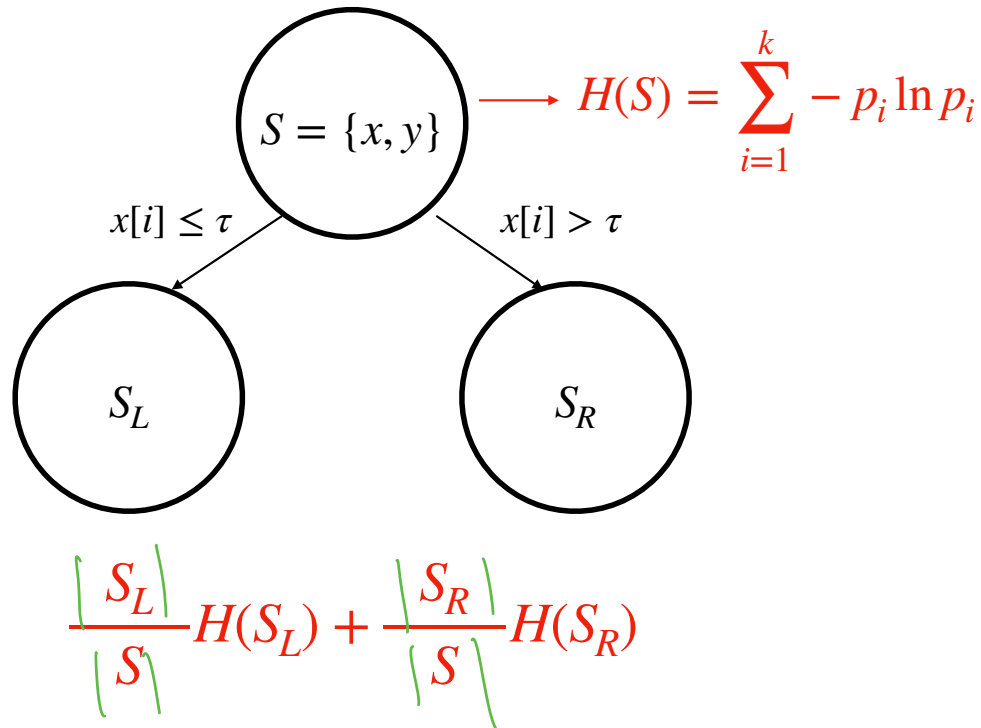
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Find a split  $(i, \tau)$  such that

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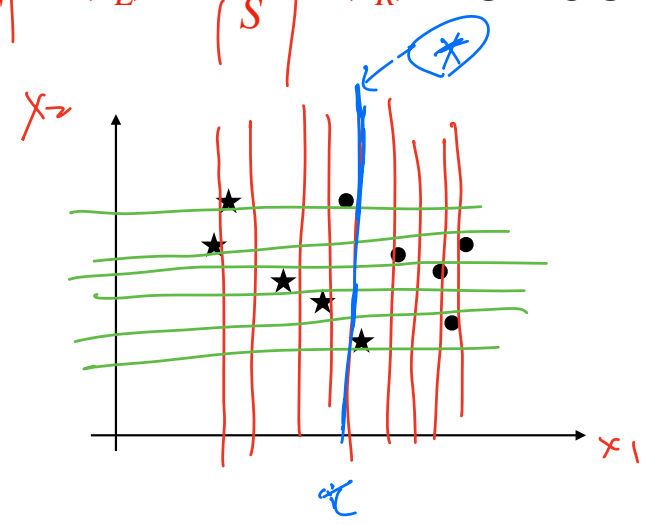


*dim from 1, 2, ..., d*

**Optimization:**  $\tau \in R$   
*threshold of d*

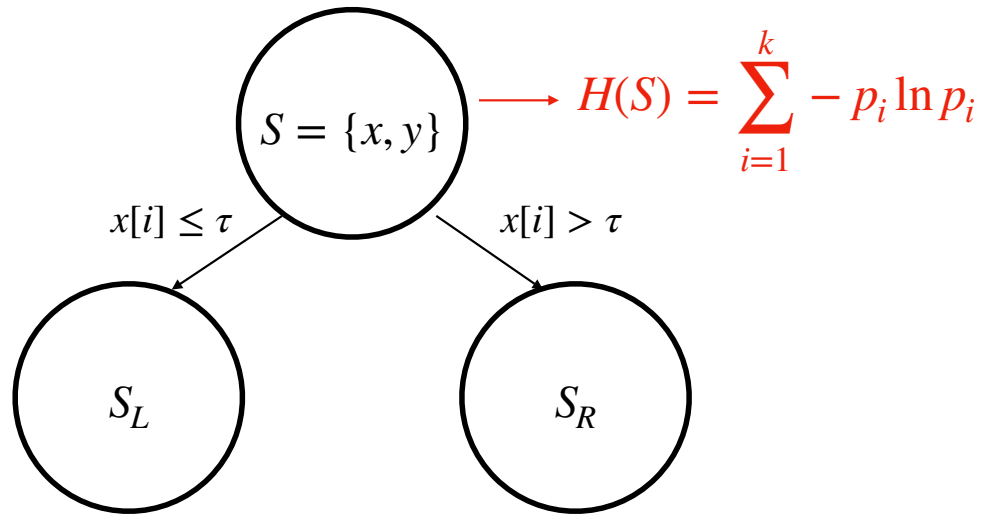
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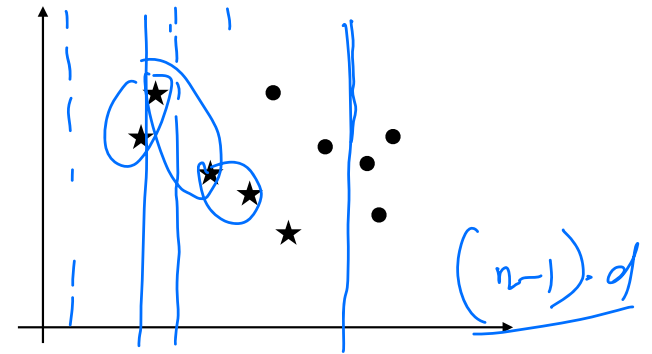


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Q: how many splits we need to check?

$n$  points

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Input: training set  $S = \{x, y\}$

**Decision\_tree( $S$ ):**



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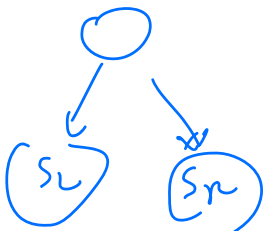
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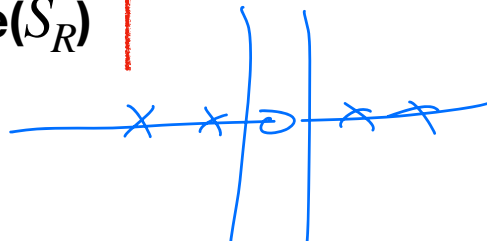
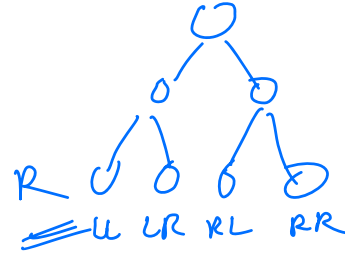
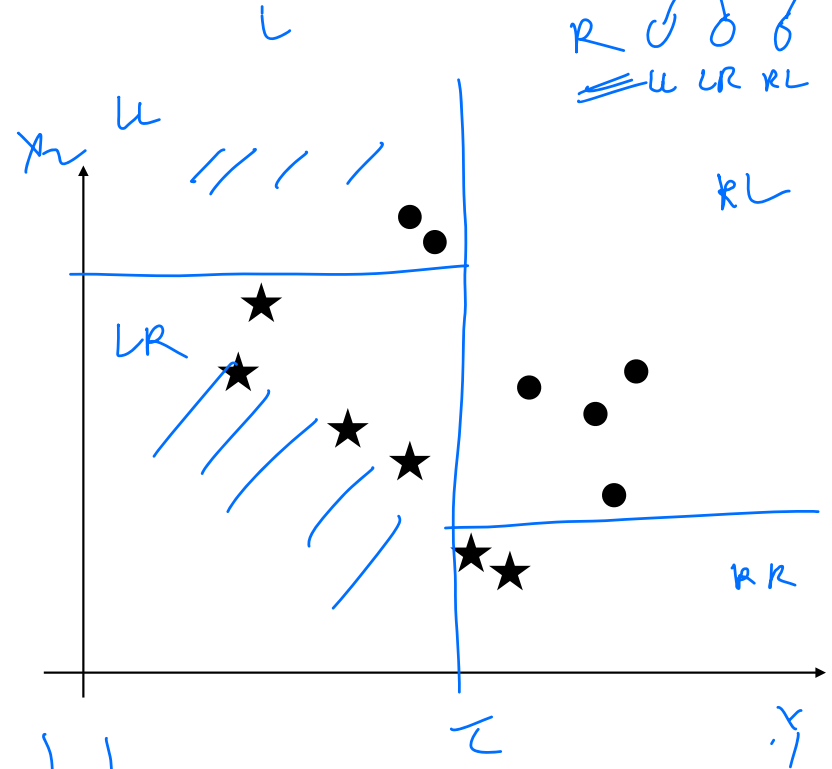
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$$\begin{matrix} x_i & x_j \\ \left( \begin{array}{l} x_i = x_j \\ y_i \neq y_j \end{array} \right) \end{matrix}$$



# Outline of Today

1. Decision tree in classification
2. Decision tree in regression
3. Demos of decision tree

# Regression

How to split the note, i.e., what is the diversity measure?

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P.2

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Consider a set of training points  $S = \{x_i, y_i\}_{i=1}^m, y_i \in \mathbb{R}$

Define the sample mean  $\hat{y}_S = \sum_{i=1}^m y_i / m$



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Define the sample mean  $\hat{y}_S = \sum_{i=1}^m y_i / m$

Impurity: sample variance  $\widehat{Var}(S) = \sum_{i=1}^m (y_i - \bar{y}_S)^2 / m$

$\Rightarrow \text{Var}(y)$  when  $m \rightarrow \infty$

# Regression Tree



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- IF  $|S| \leq k$ :

Set leaf value to be  $\bar{y}_S$

Threshold  $k \in \mathbb{N}^+$   
(e.g.  $k=3$ )

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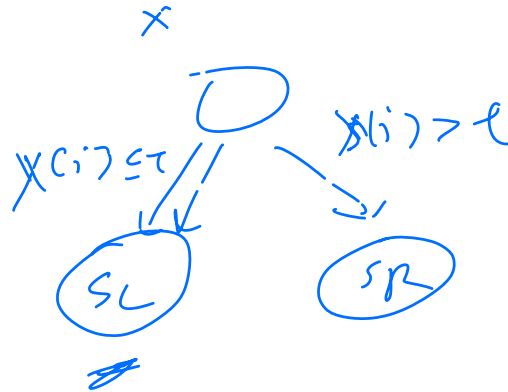
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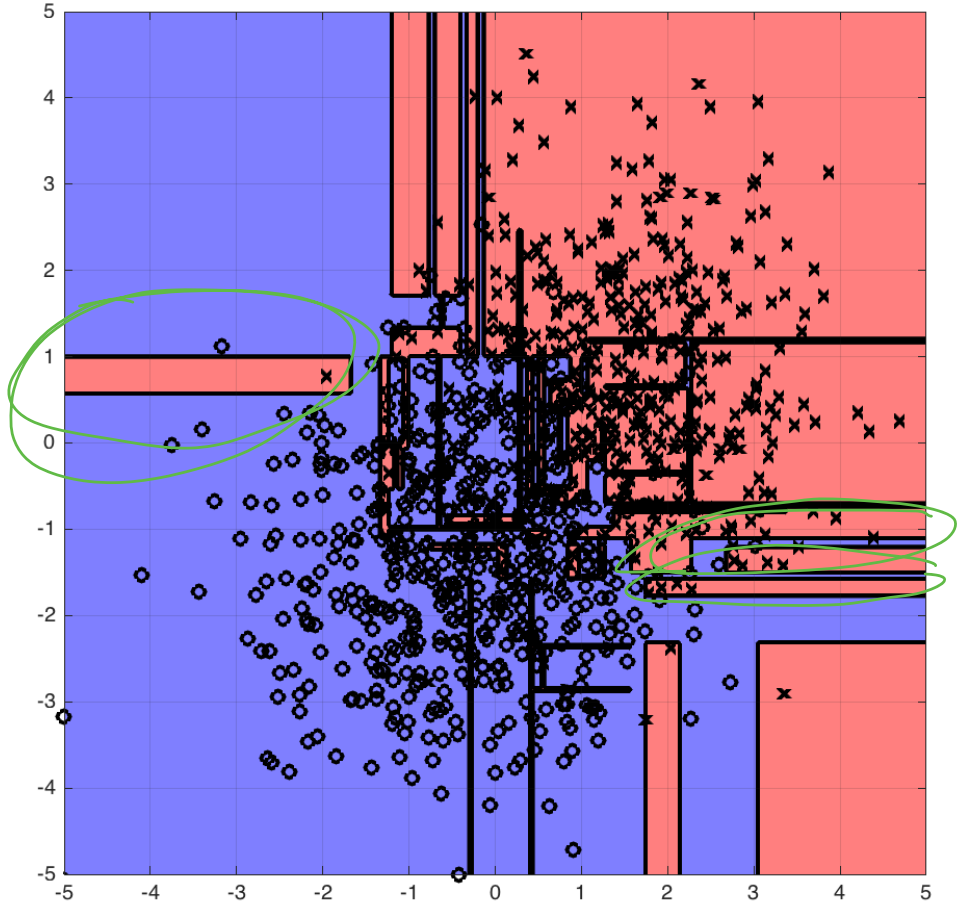
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# Issue of Decision Trees

Decision Tree  
can have high  
variance, i.e.,  
overfitting!

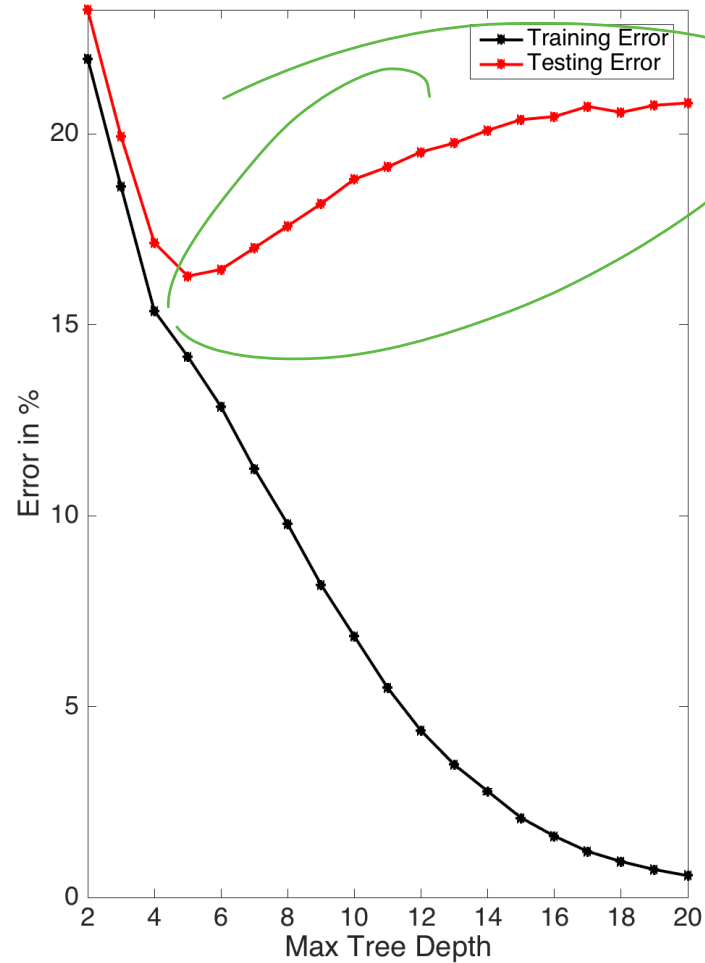
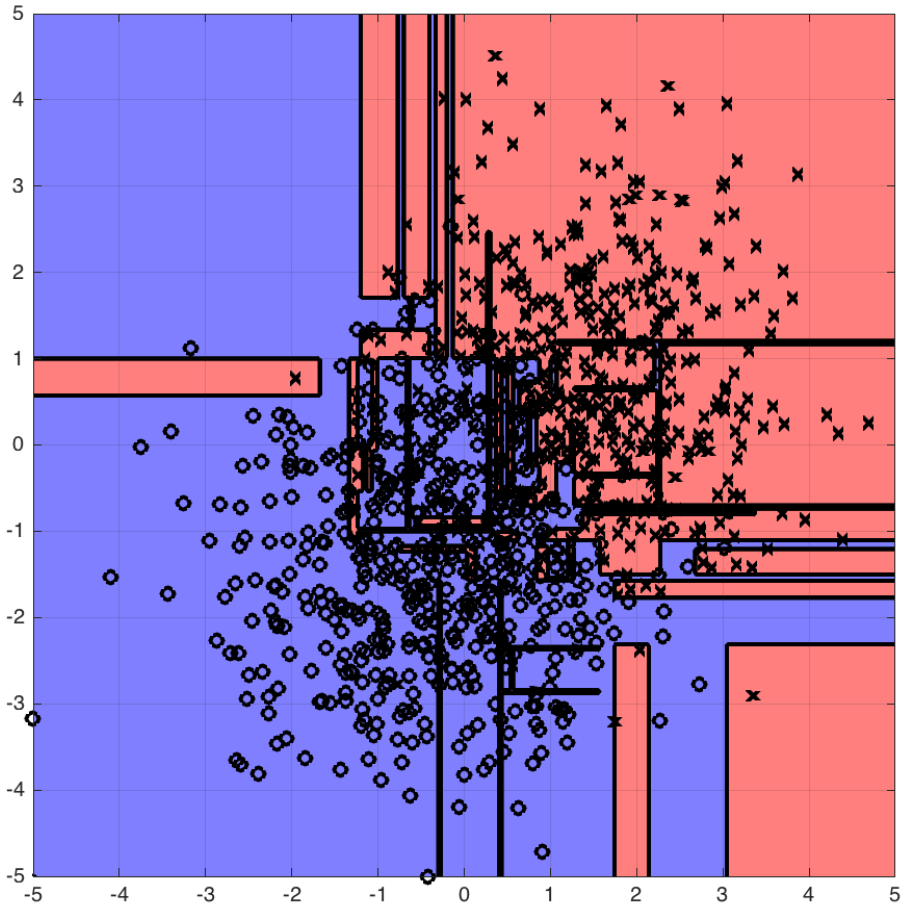


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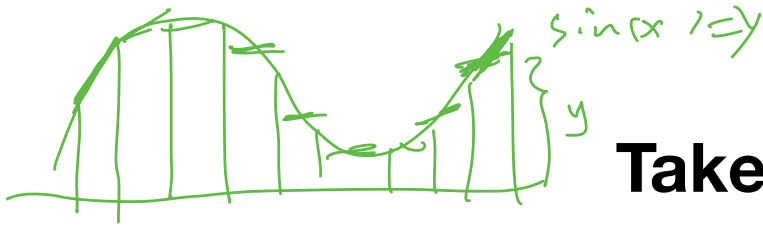


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## Take-home messages

1 Decision tree algorithms splits space into axis-aligned regions

Each region ideally should only contain one unique label

2: Split a node such that the entropy of labels in the leafs are minimized

3: Can easily overfit as the depth of the tree increases  
(limiting the depth of the tree is a good regularization)

