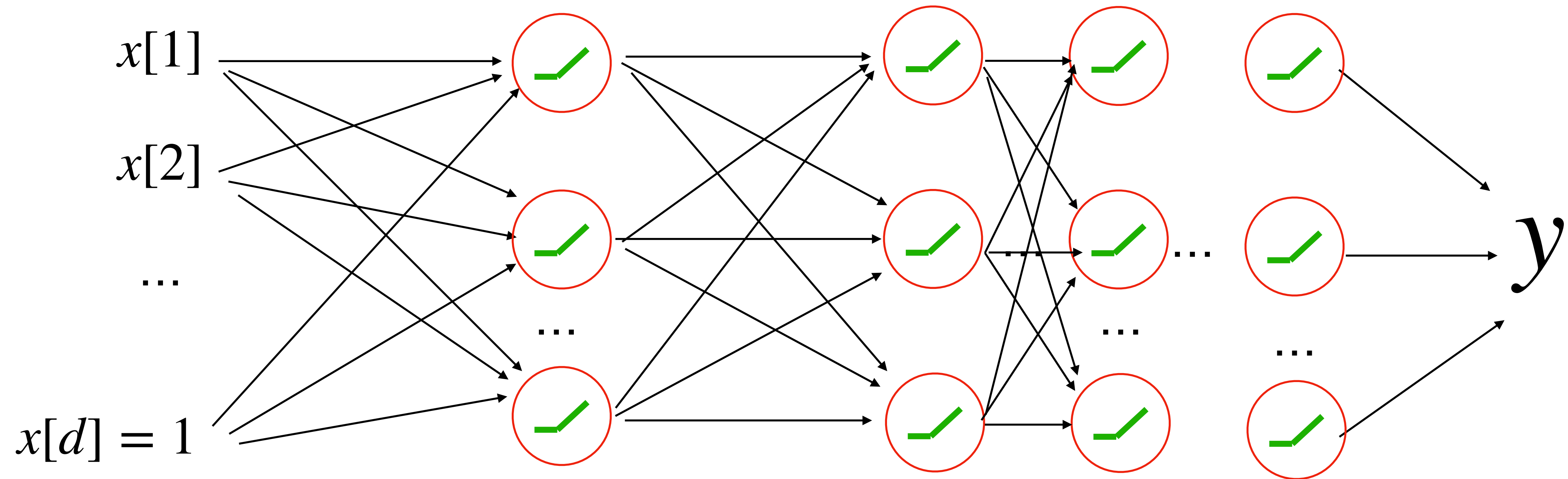


# Convolutional Neural Network

# **Announcements**

1. Releasing past semesters' final exams
2. Email for makeup final should be out today

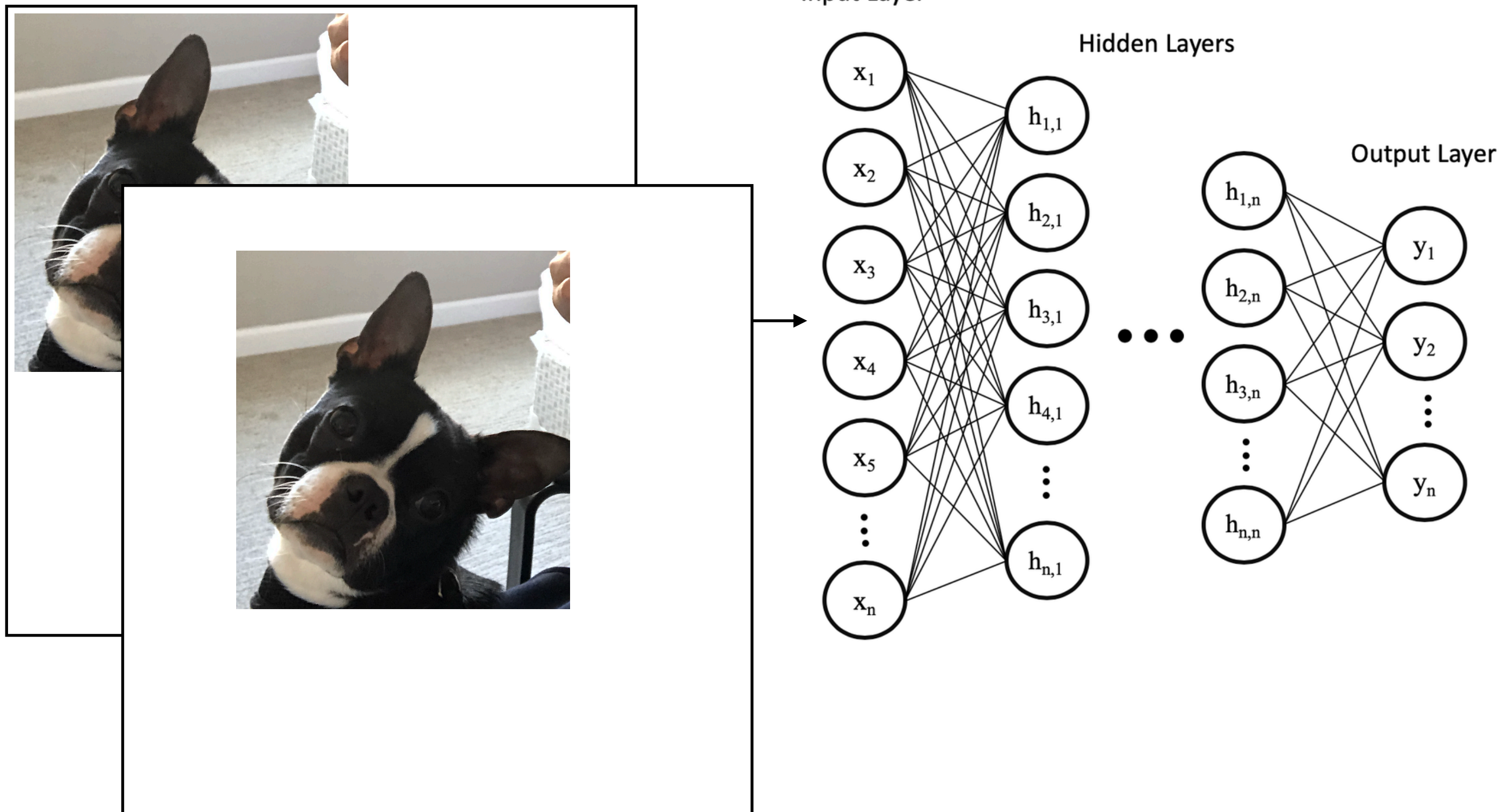
# Recap on fully connected NN



Not very scalable when  $d$  is large (e.g., when  $d$  is a million)

# Recap on fully connected NN

Also not translation invariant



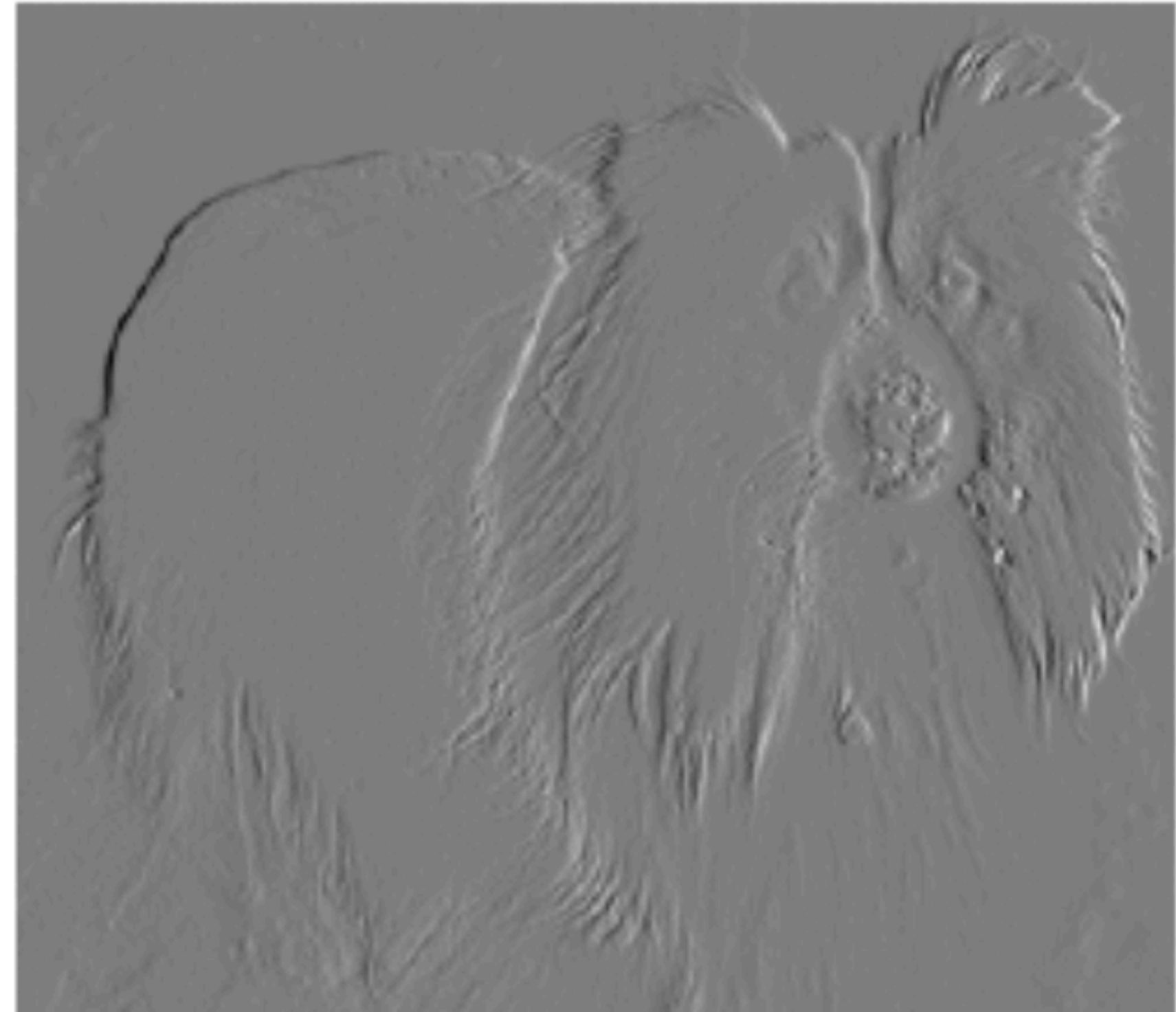
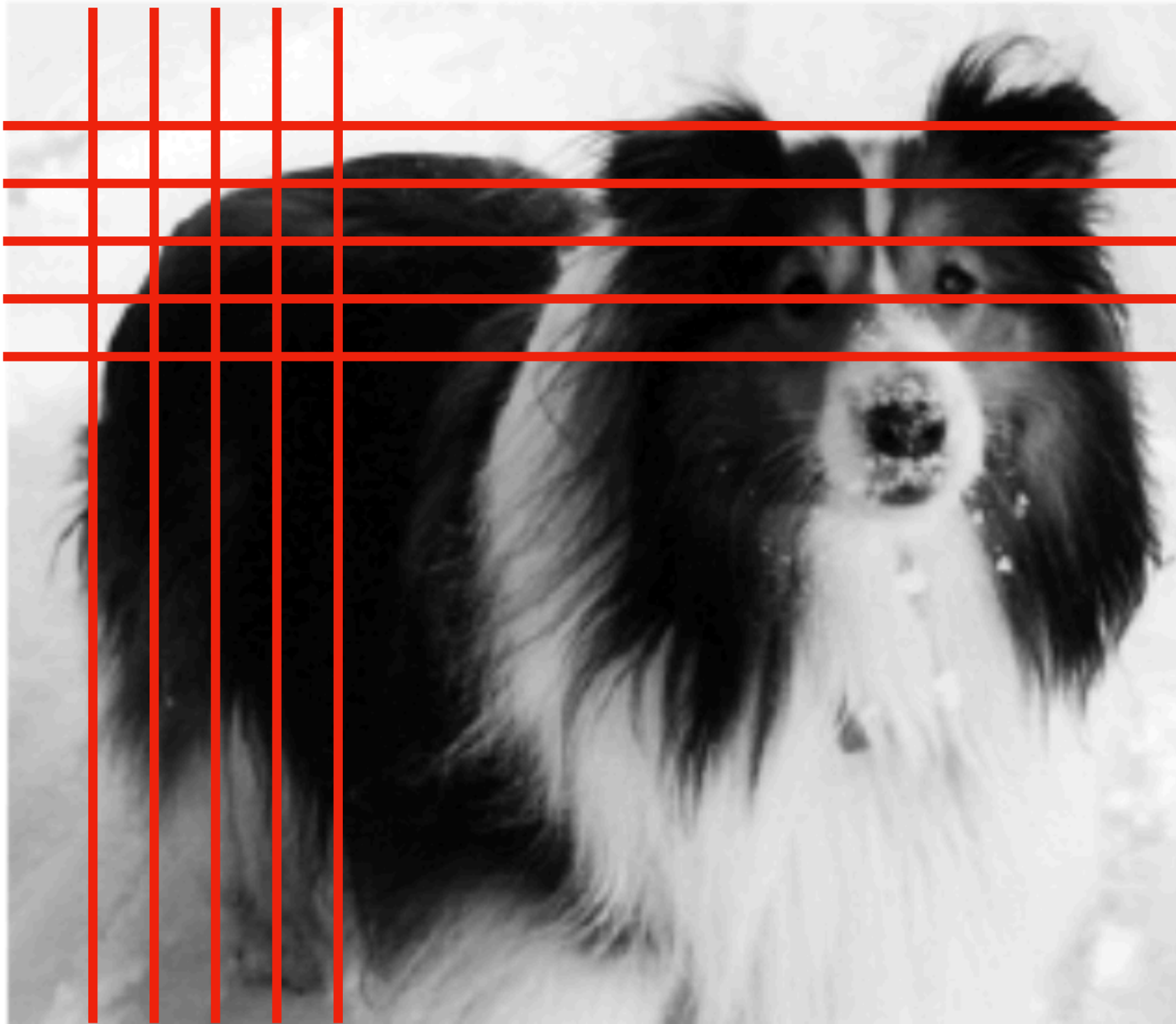
# Objective today

Understand the convolution operator and the Convolution network  
(designed for dealing w/ image inputs)

# Outline today

1. Edge detector and convolution
2. Convolution layer and a pooling layer
3. Case study on LeNet (ResNet)

# Edge detector





# Implementing vertical Edge detector w/ convolution

Kernel 1x2 matrix

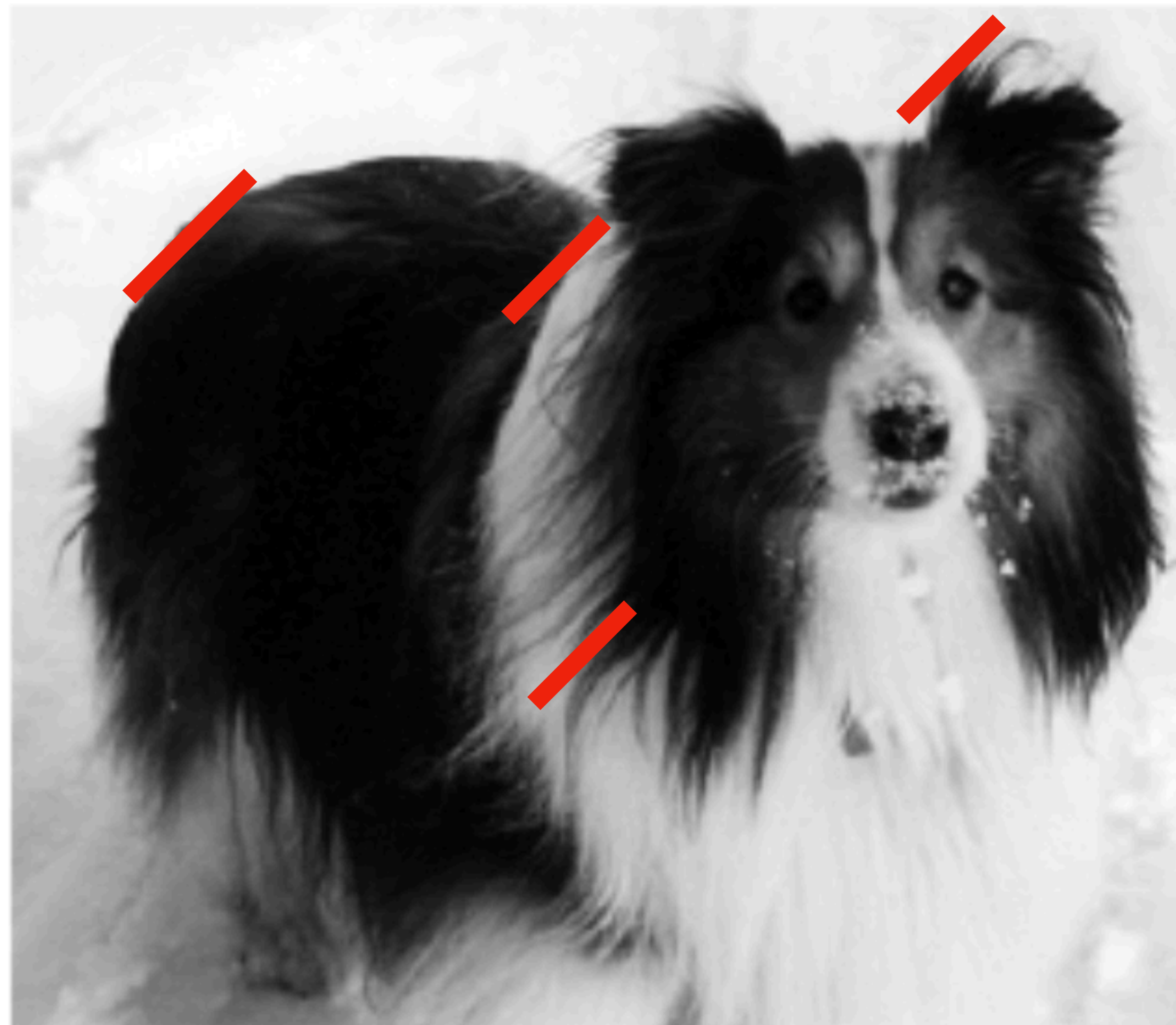


<b>-1</b>	<b>1</b>
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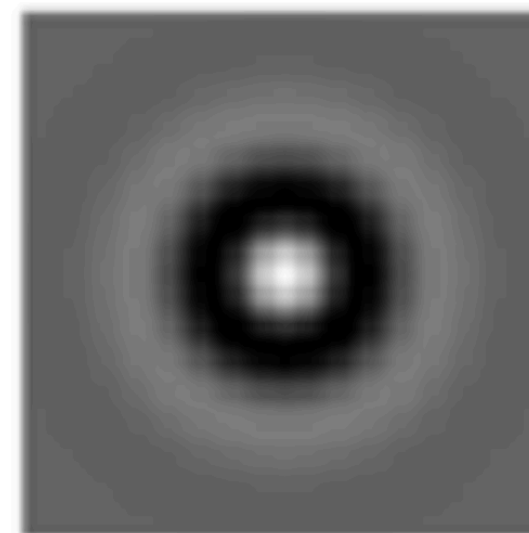
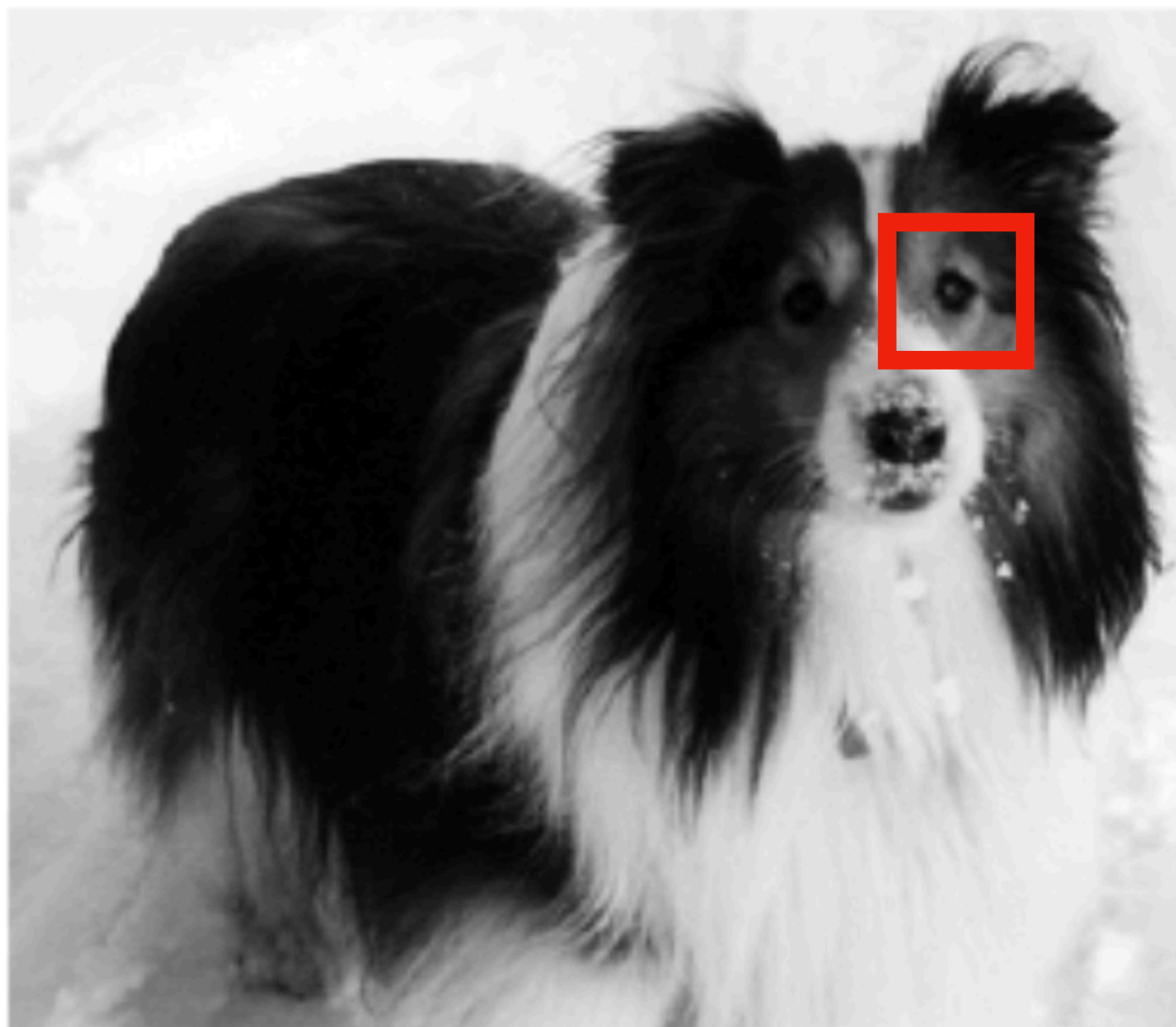
# Other Edge detector

Kernel 3x3 matrix

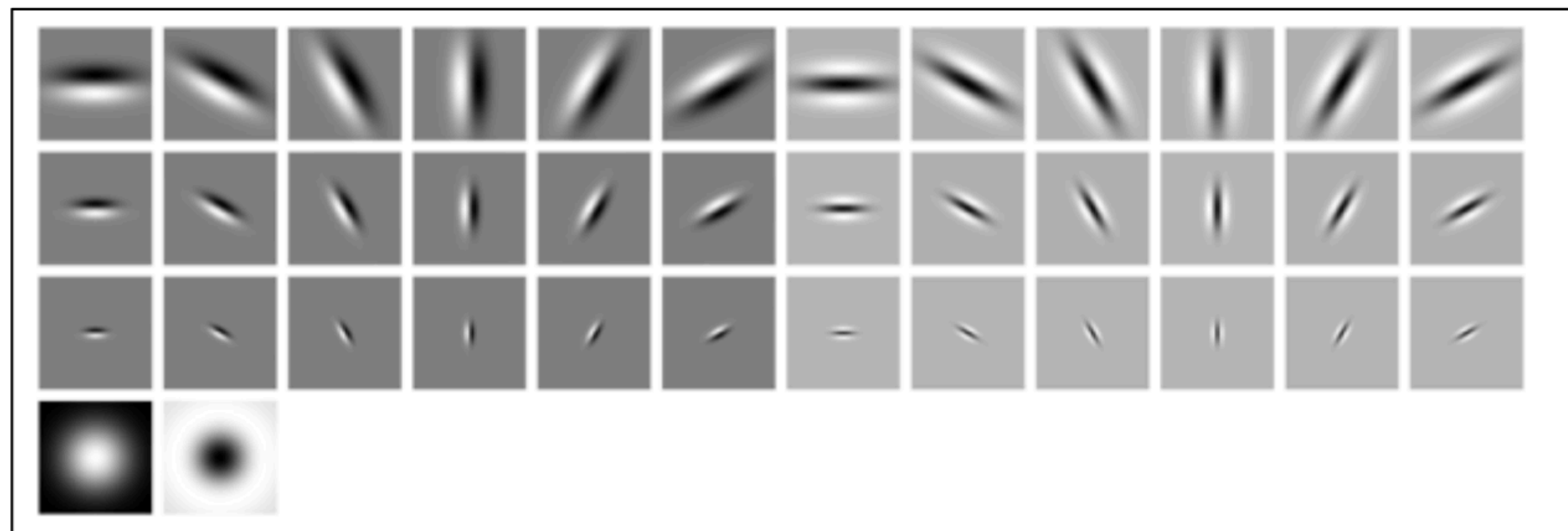
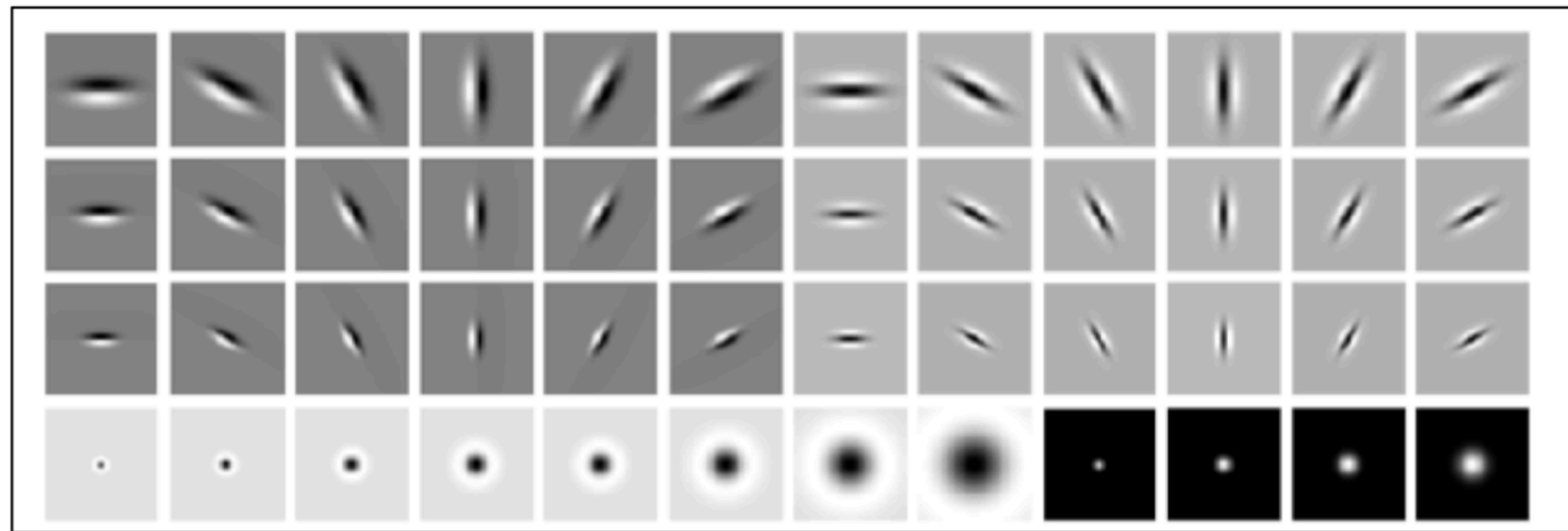
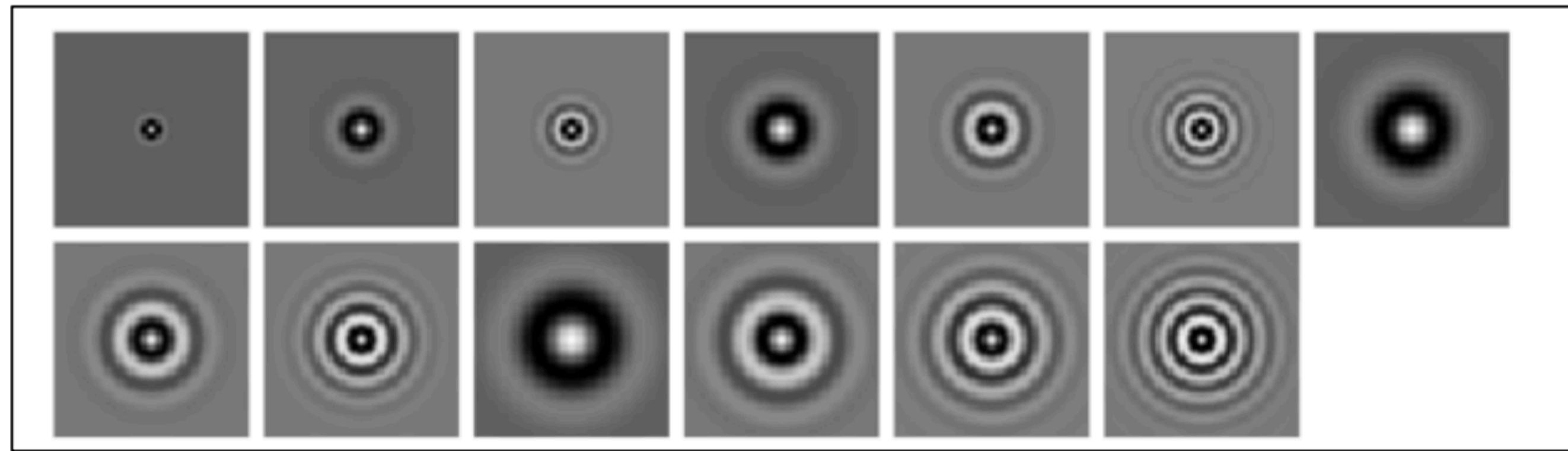


0	0	1
0	1	0
1	0	0

# More examples



# The Filter bank



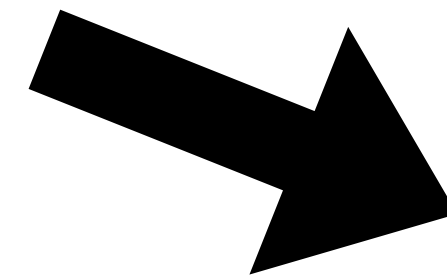
# Summary of Convolution operator

Image (2d matrix)

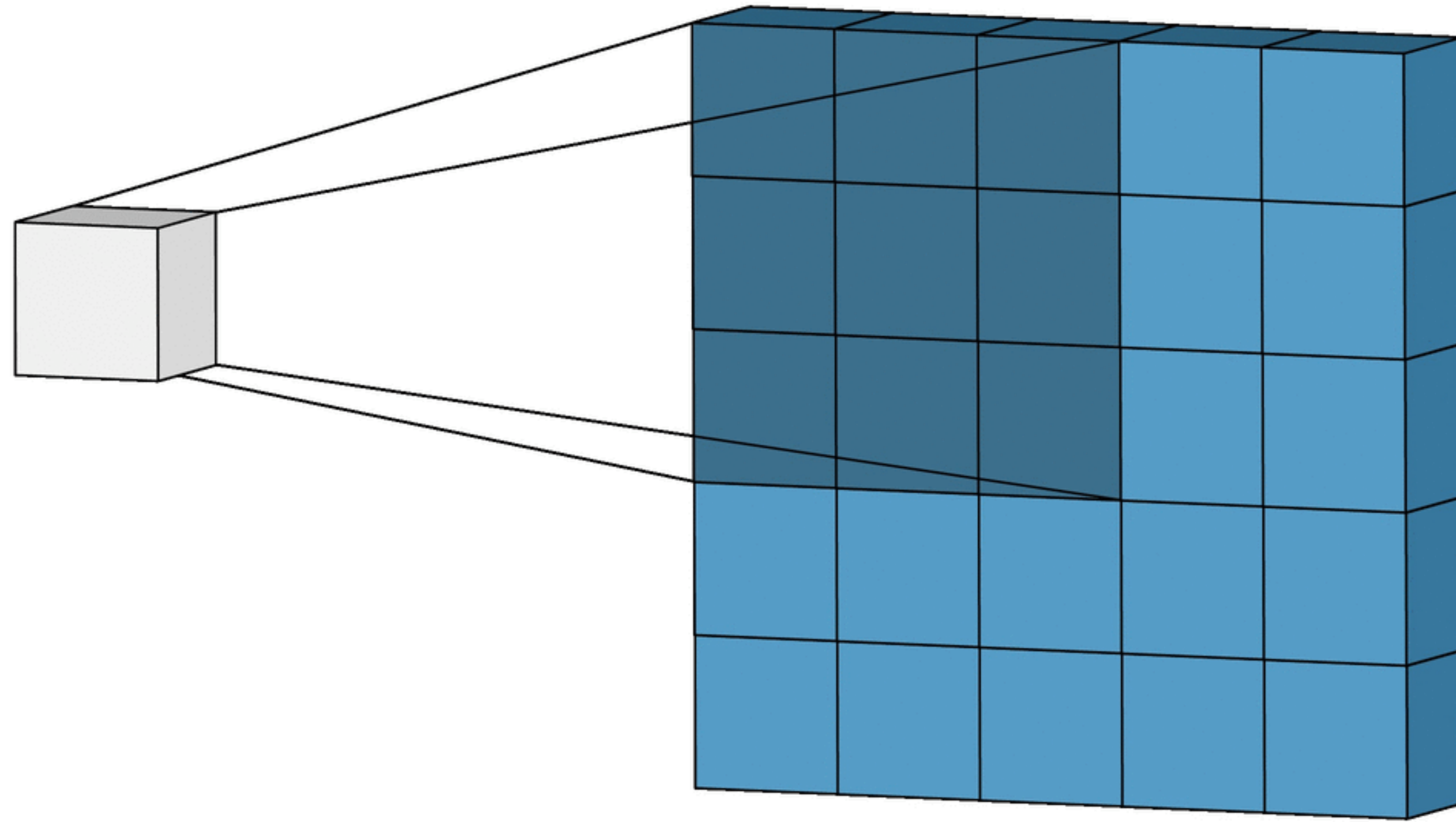
<b>a</b>	<b>b</b>	<b>c</b>	<b>d</b>
<b>e</b>	<b>f</b>	<b>g</b>	<b>h</b>
<b>i</b>	<b>j</b>	<b>k</b>	<b>l</b>

Kernel 2x2 matrix

<b>W</b>	<b>X</b>
<b>Y</b>	<b>Z</b>




# Visualization of convolution



**Q: if the image is  $d \times d$ , and kernel is  $k \times k$ , what is the dim of the output matrix?**

# Convolution over volumes (3d tensor)

RGB Image



$$d \times d \times 3$$

\*

Filter



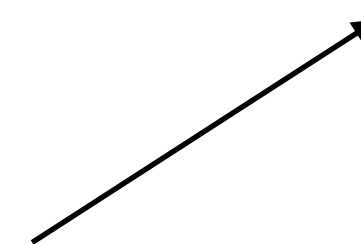
$$k \times k \times 3$$

\*

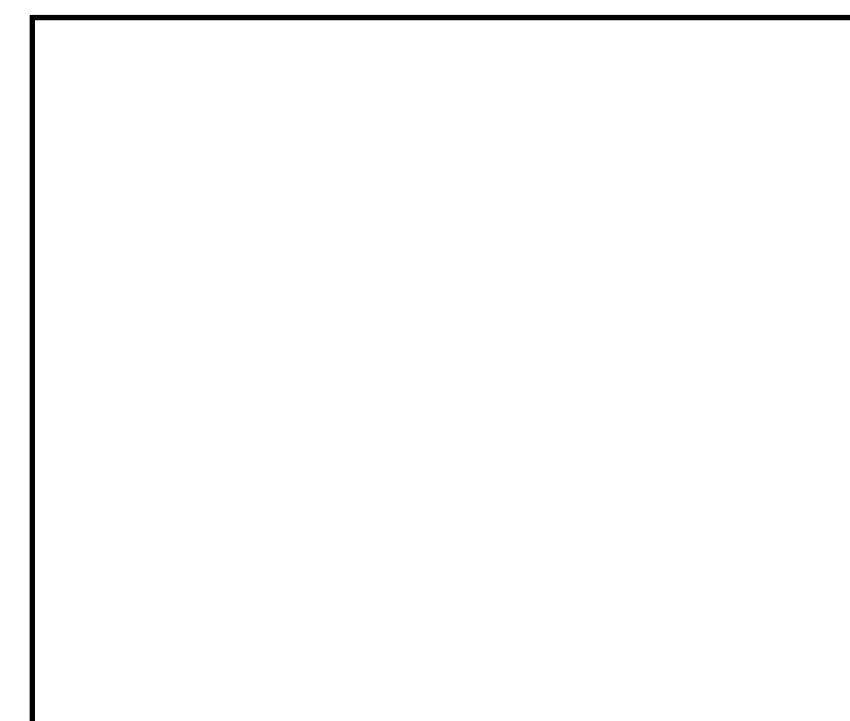
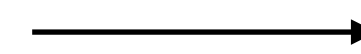
Filter 2



$$k \times k \times 3$$



$$(d - k + 1) \times (d - k + 1)$$



$$(d - k + 1) \times (d - k + 1)$$

## **Key question**

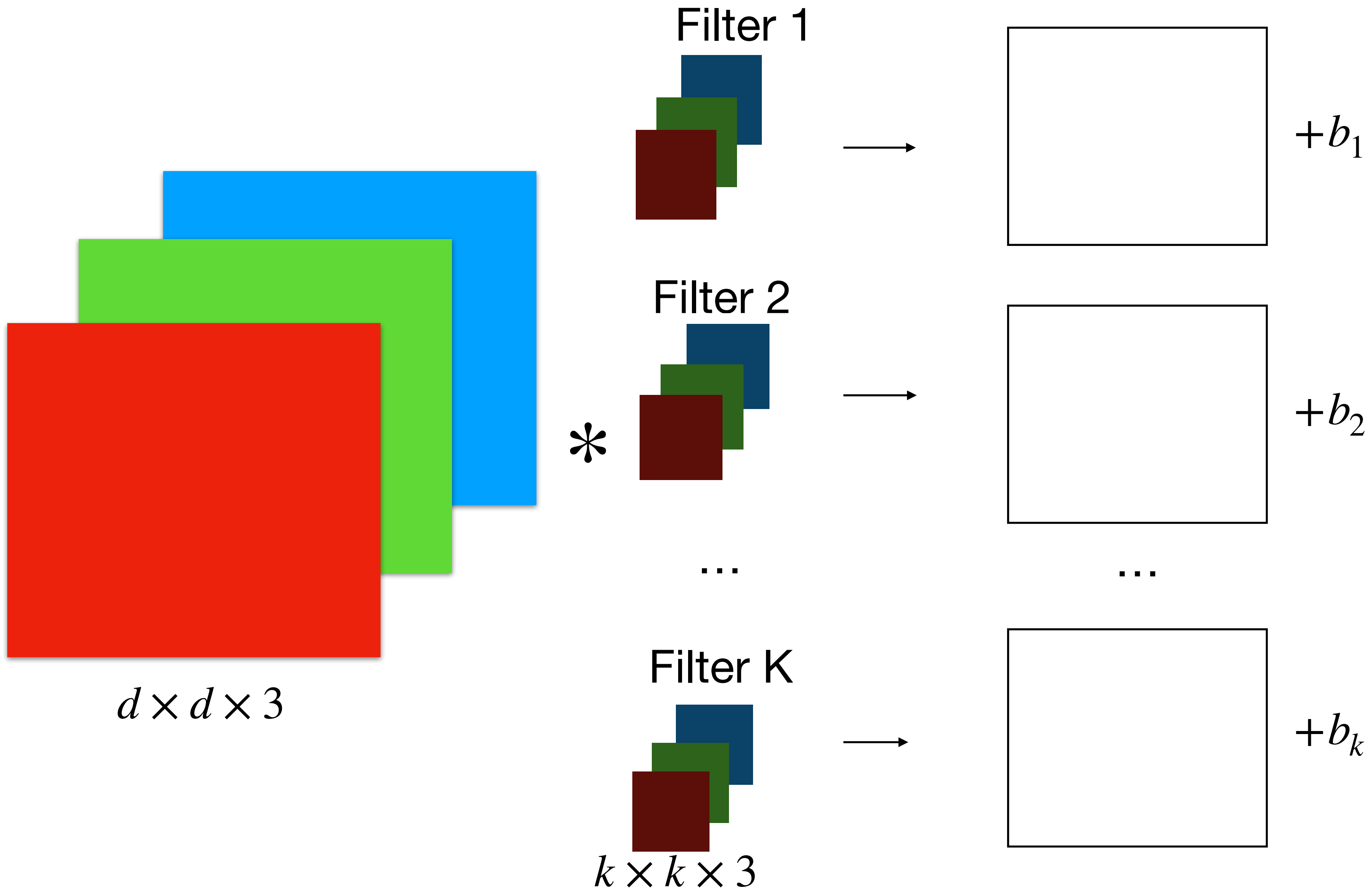
Can we learn these detectors / filters in an end-to-end fashion?



# Outline today

1. Edge detector and convolution
2. Convolution layer and a pooling layer
3. Case study on LeNet (ResNet)

# Building a convolution layer



# Pooling layer

We use a pooling layer to downsize the inputs

**e.g., Max pooling (2x2 filter and stride 2)**

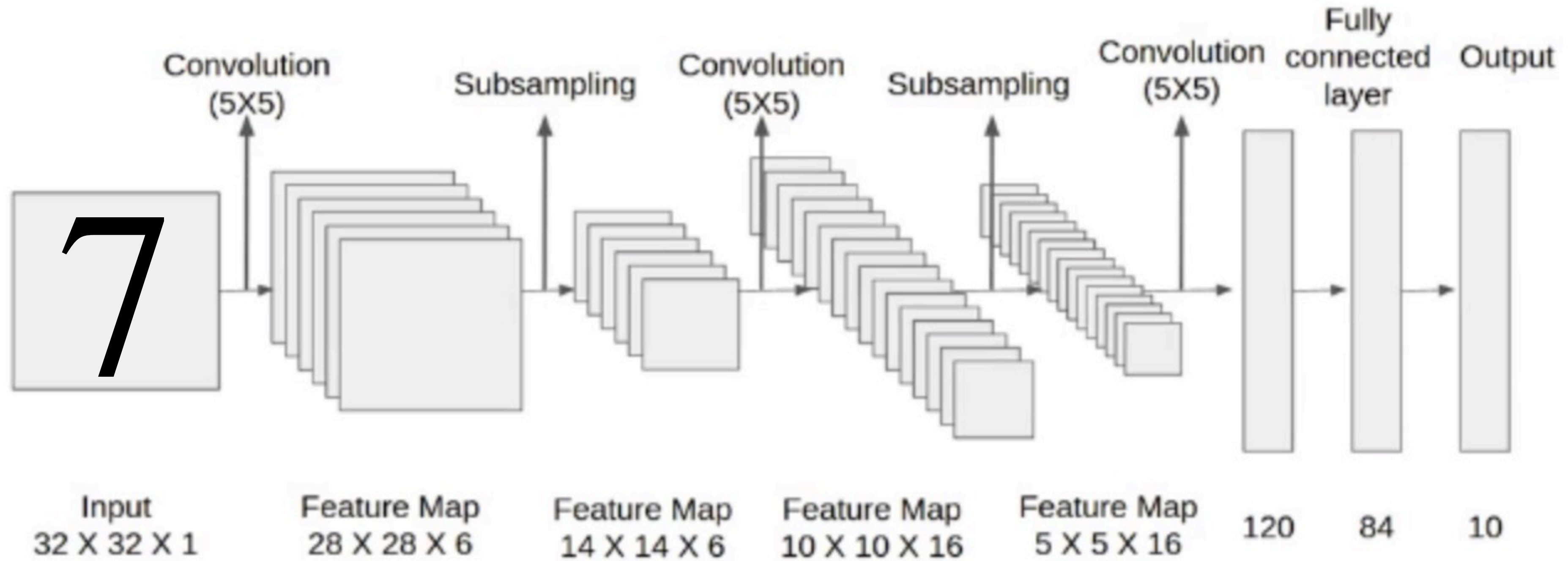
e.g., some Output of a convolution layer

<b>1</b>	<b>3</b>	<b>0</b>	<b>6</b>
<b>5</b>	<b>4</b>	<b>12</b>	<b>2</b>
<b>7</b>	<b>1</b>	<b>9</b>	<b>0</b>
<b>4</b>	<b>3</b>	<b>1</b>	<b>8</b>


# Outline today

1. Edge detector and convolution
2. Convolution layer and a pooling layer
3. Case study on LeNet

# LeNet 5



# ResNet

(The last reading quiz in on the classic ResNet paper!)

# Summary for today

Convolutional neural network works well for images where pixels have strong local spatial correlations

## **Limitations:**

convolution cannot capture global information (correlation among very distant pixels);  
Fine-grained details may lost during pooling.