

Machine Learning Basics

Wen Sun



Cornell University Artificial Intelligence (CUAI)

👍 CUAU is a unique club at Cornell that promotes undergraduate-led ML research

👍 We've published 4 NeurIPS, 1 ICML, 1 ICLR, and 1 ICCV paper since 2018

Our Mission

- ❑ Prepare our members to tackle cutting-edge research topics
- ❑ Connect undergraduates with Cornell faculty to explore shared interests
- ❑ Provide research credit and financial support for compute resources and conference travel

We are recruiting! 🙋



Announcement:

Outline for Today:

1. Supervised Learning (Classification / Regression) and Unsupervised learning

2. Generalization

3. Training / validation / testing

Classification

Dataset \mathcal{D}



,cat



,cat



,dog

Classification

Dataset \mathcal{D}



,cat



,cat



,dog



ML model

Classification

Dataset \mathcal{D}



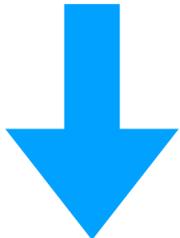
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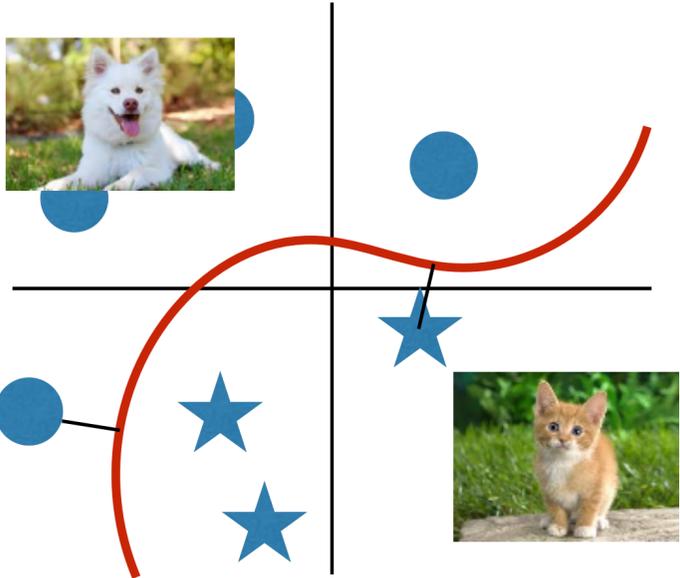
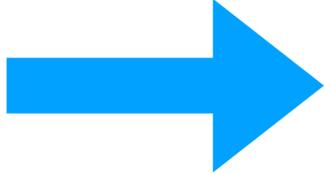
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ML model



Mathematical formulation of the pipeline

Dataset:

$$\mathcal{D} = \{(x_1, y_1), \dots, (x_n, y_n)\}, x_i \in \mathbb{R}^d, y_i \in \mathcal{C} \text{ (e.g., } \mathcal{C} = \{-1, 1\}\text{)}, (x_i, y_i) \sim \mathcal{P}$$

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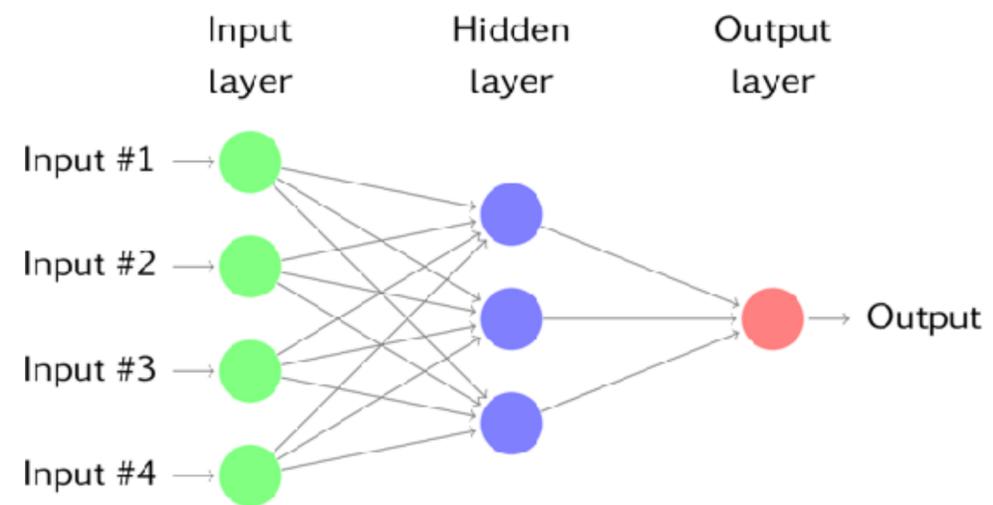
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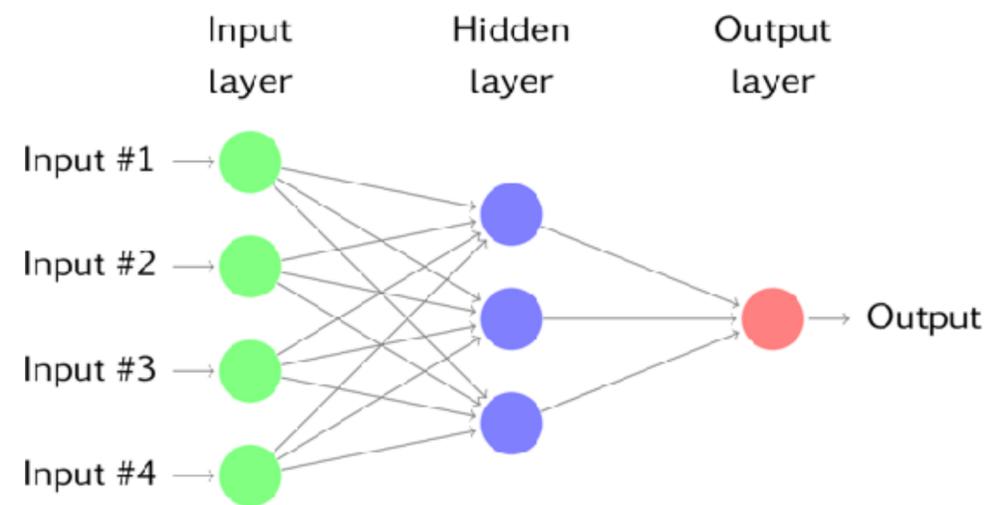
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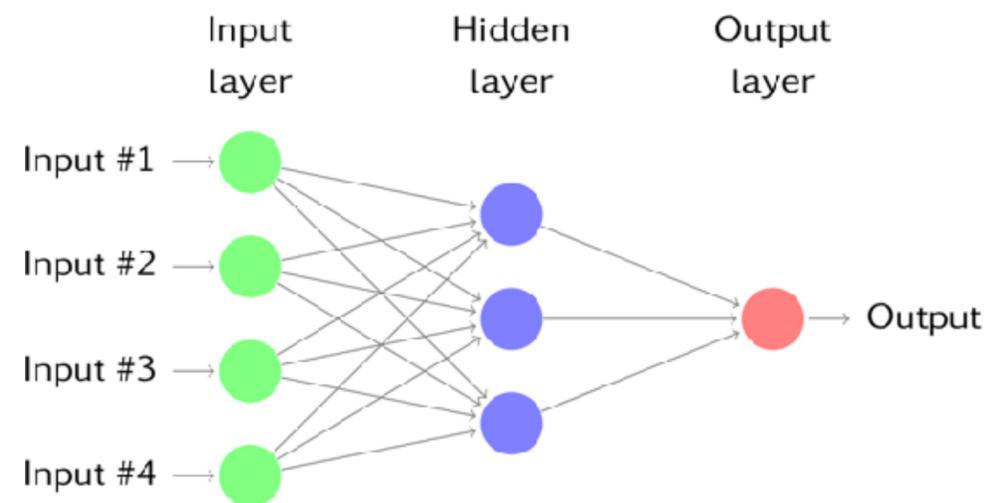
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i.e., a large family of NNs with different parameters

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Hypothesis class

$$\mathcal{H} = \{h\}$$

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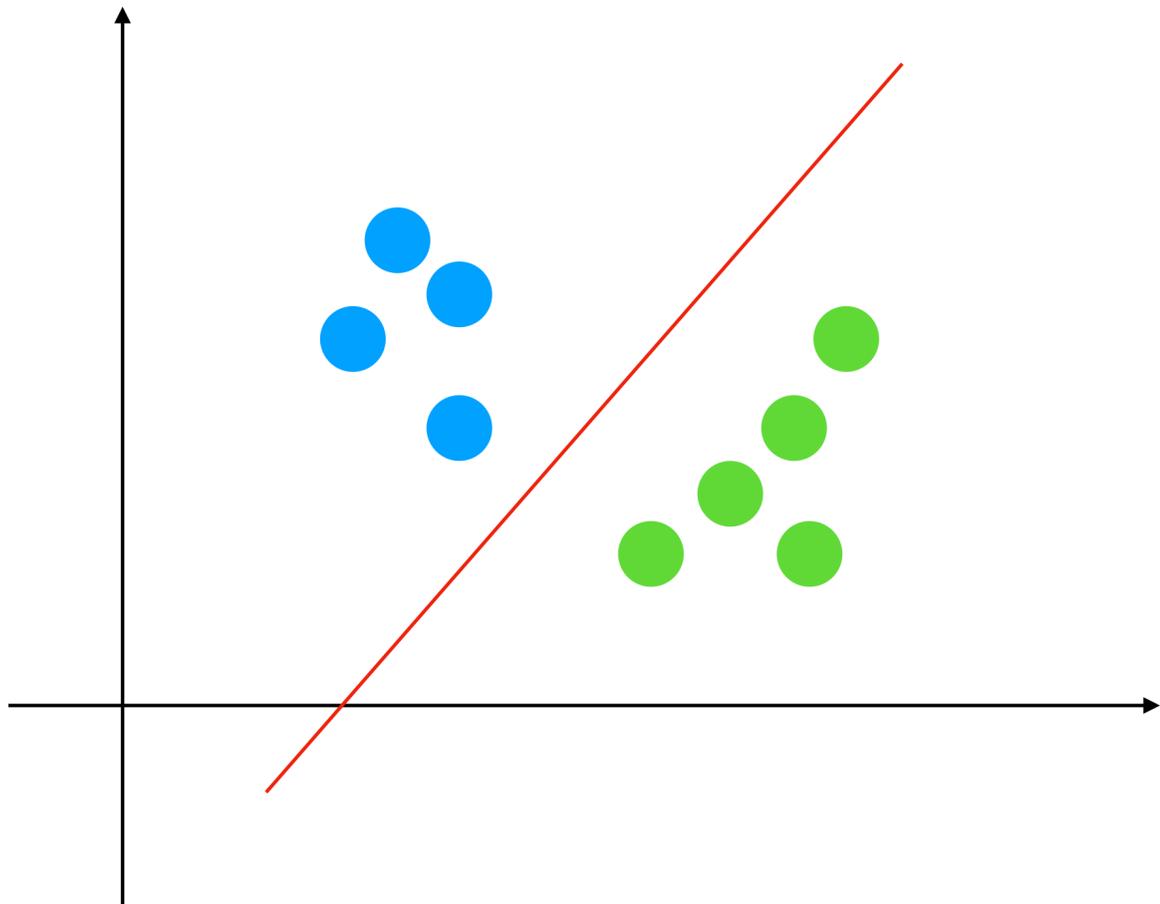
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Inductive bias (i.e., assumptions) encoded in the hypothesis class

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 \mathcal{H} contains all possible linear functions

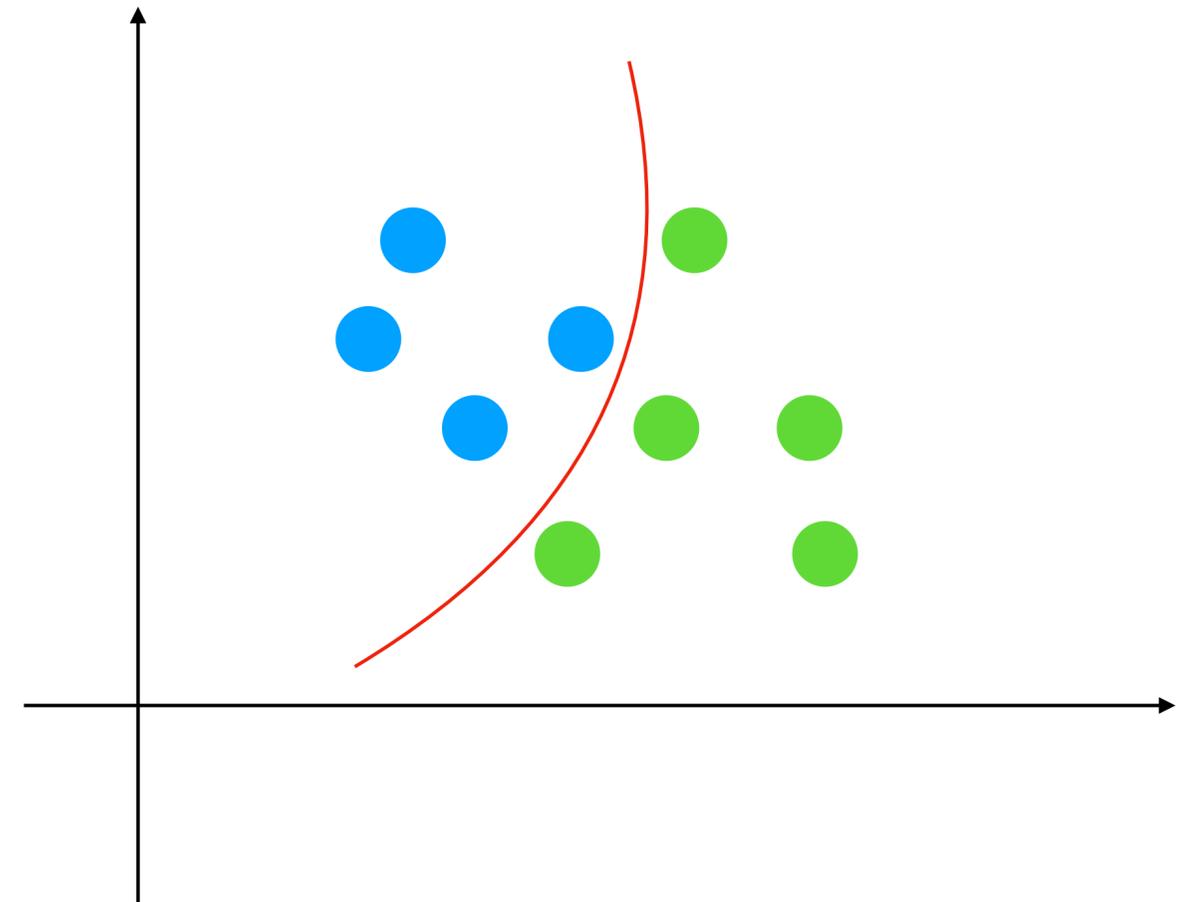
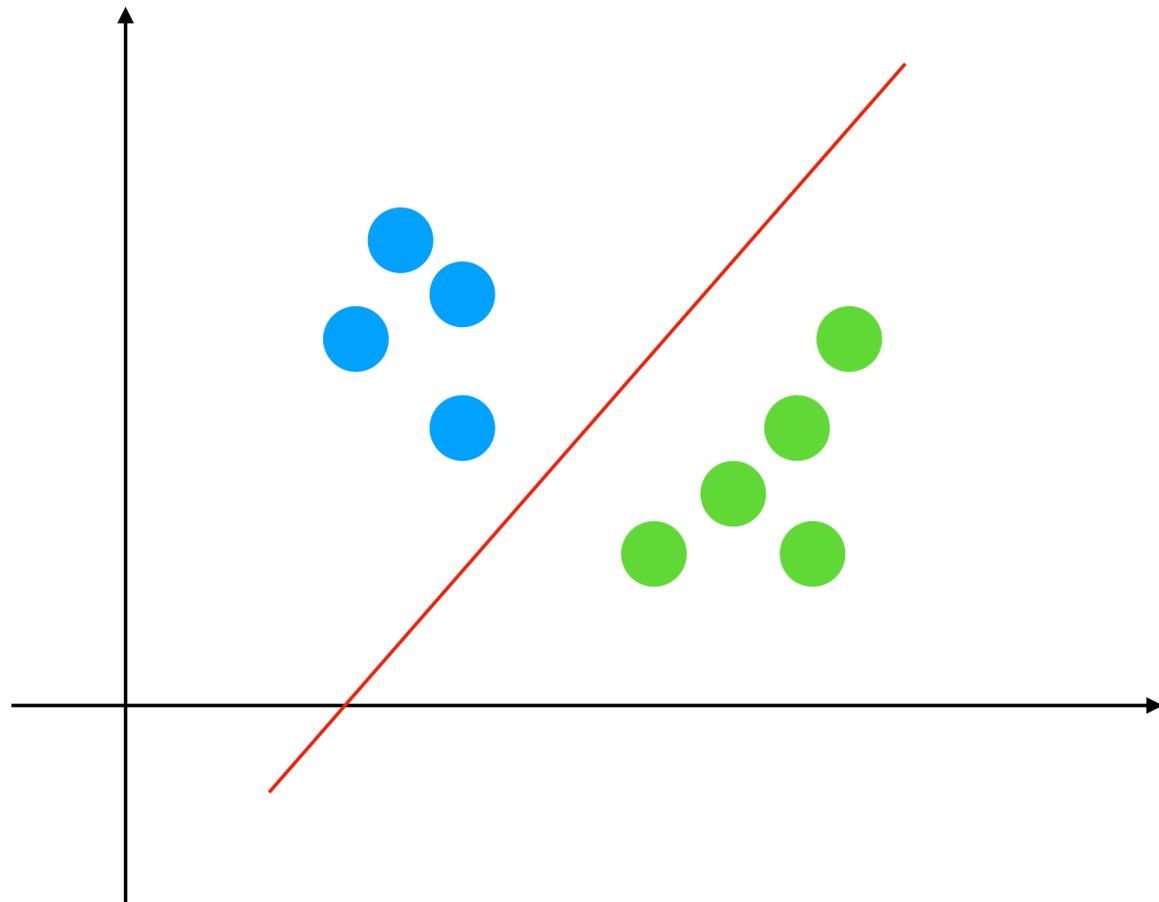


Examples of hypothesis

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 \mathcal{H} contains all possible linear functions

Ex: h is nonlinear $h(x) = \text{sign}(w^\top (\text{relu}(Ax)))$;
 \mathcal{H} contains all possible one-layer NN



Examples of hypothesis

No free lunch theorem says that we must make such assumptions

Examples of hypothesis

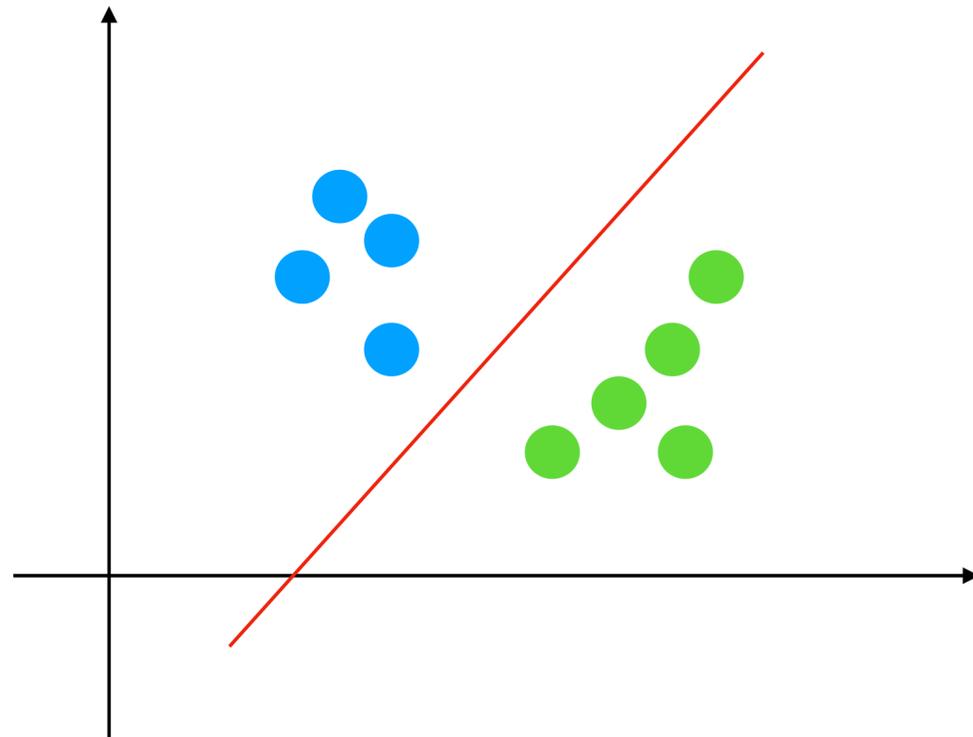
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Informal theorem: for any machine learning algorithm \mathcal{A} , there must exist a task \mathcal{P} on which it will fail

Examples of hypothesis

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Informal theorem: for any machine learning algorithm \mathcal{A} , there must exist a task \mathcal{P} on which it will fail



We use prior knowledge (i.e., we believe linear function is enough) to design an ML algorithm here

The Loss Function

Q: how to select the best hypothesis \hat{h} from \mathcal{H} ?

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Examples:

Zero-one loss:

$$\ell(h, x, y) = \begin{cases} 0 & h(x) = y \\ 1 & h(x) \neq y \end{cases}$$

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$$\ell(h, x, y) = \begin{cases} 0 & h(x) = y \\ 1 & h(x) \neq y \end{cases}$$

Squared loss:

$$\ell(h, x, y) = (h(x) - y)^2$$

Learning/Training

Q: how to select the best hypothesis \hat{h} from \mathcal{H} ?

With loss ℓ being defined, we can perform **training/learning**:

$$\hat{h} = \arg \min_{h \in \mathcal{H}} \sum_{i=1}^n \ell(h, x_i, y_i)$$

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e.g., total number of mistakes h makes on n
training samples (training error)

Putting things together: Binary classification

Dataset \mathcal{D}



,cat

x_1, y_1



,cat

x_2, y_2

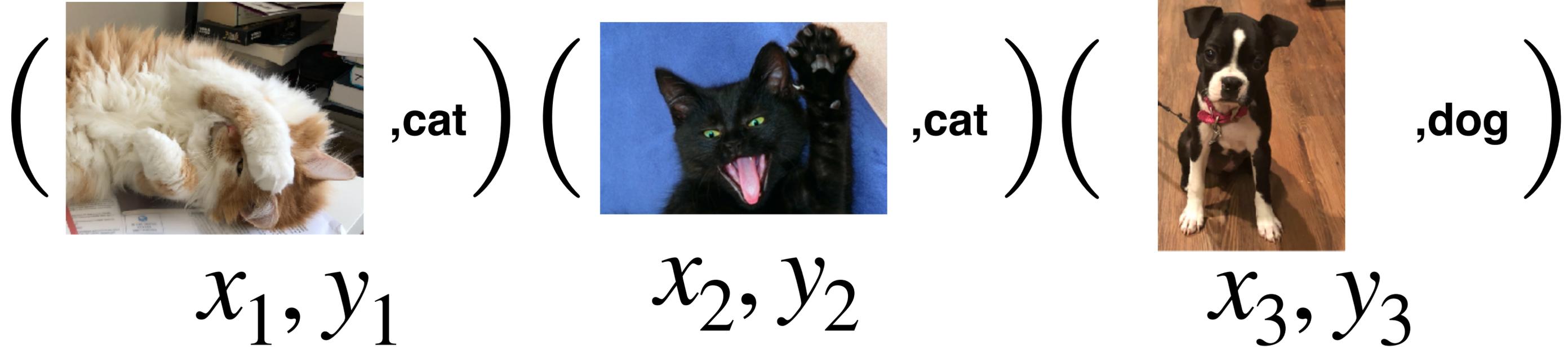


,dog

x_3, y_3

Putting things together: Binary classification

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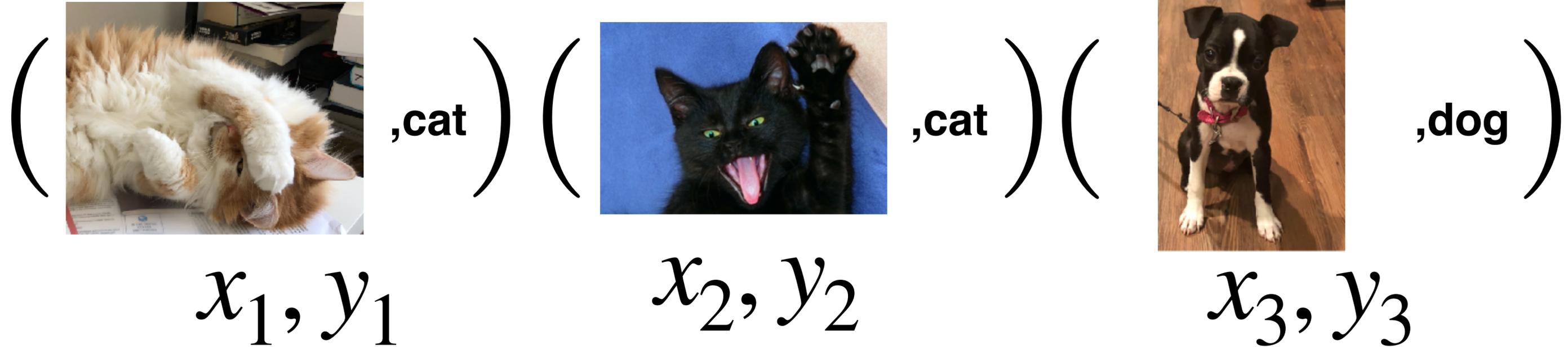


ML model, e.g., neural network w/ 0-1 loss

$$\hat{h}_{nn} = \arg \min_{h_{nn} \in \mathcal{H}} \sum_{i=1}^n \ell_{0-1}(h_{nn}, x_i, y_i)$$

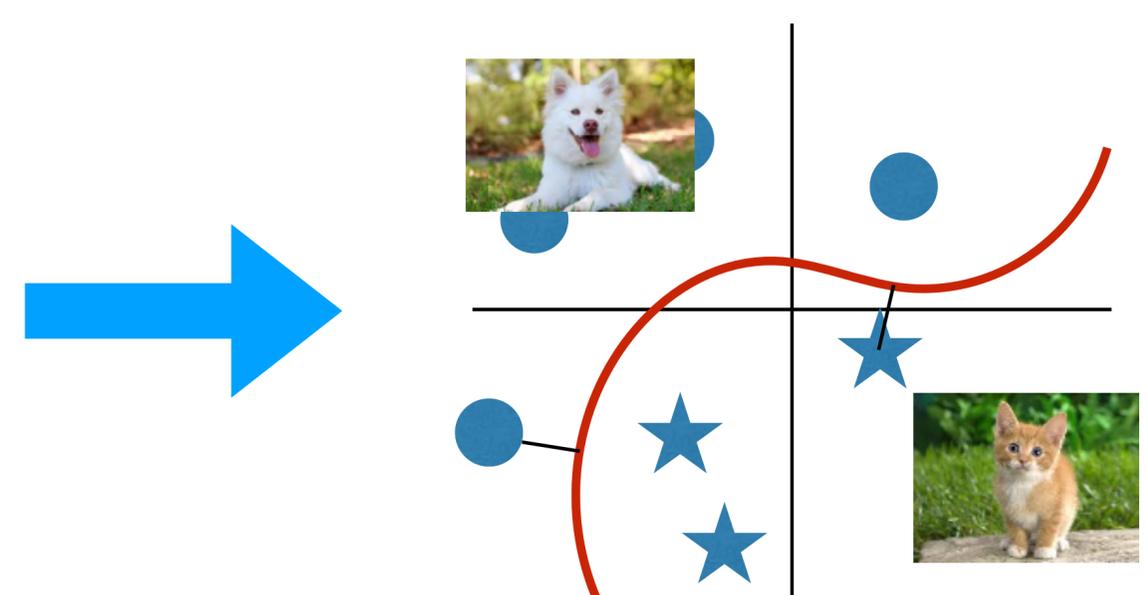
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Regression

**Example: learning to drive
from expert**



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Feature x



Expert steering
angle y

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$$\mathcal{D} = \{(x_1, y_1), \dots, (x_n, y_n)\}$$

collected by human expert

Regression

Example: learning to drive from expert



Feature x



Expert steering angle y

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Continuous variable $(-\pi, \pi)$

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Loss function: square loss

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Training: minimizing mean squared error (MSE)

$$\arg \min_{\theta} \sum_i (\theta^\top x_i - y_i)^2 / n$$

An Autonomous Land Vehicle In A Neural Network *[Pomerleau, NIPS '88]*

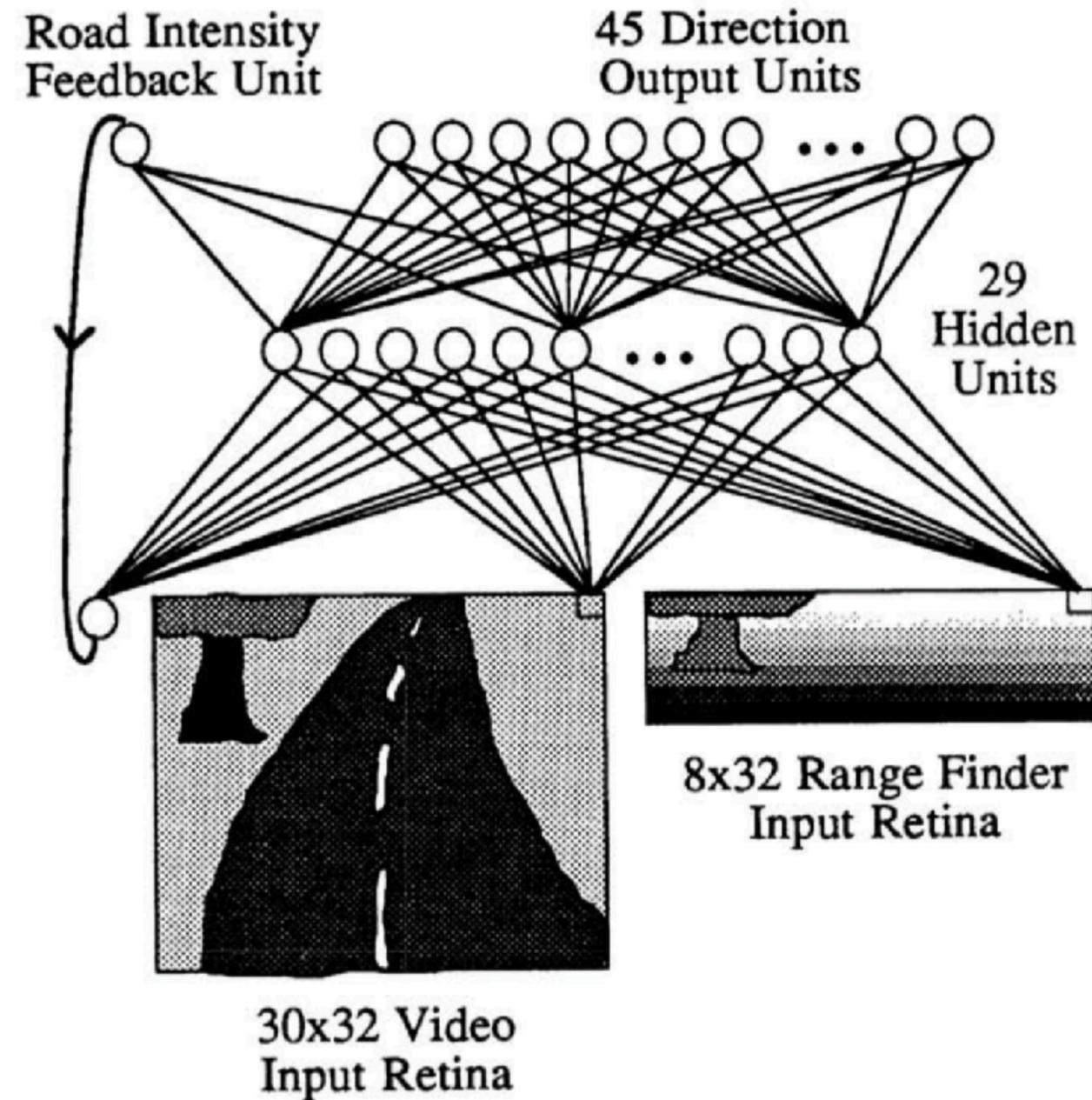


Figure 1: ALVINN Architecture

Unsupervised Learning

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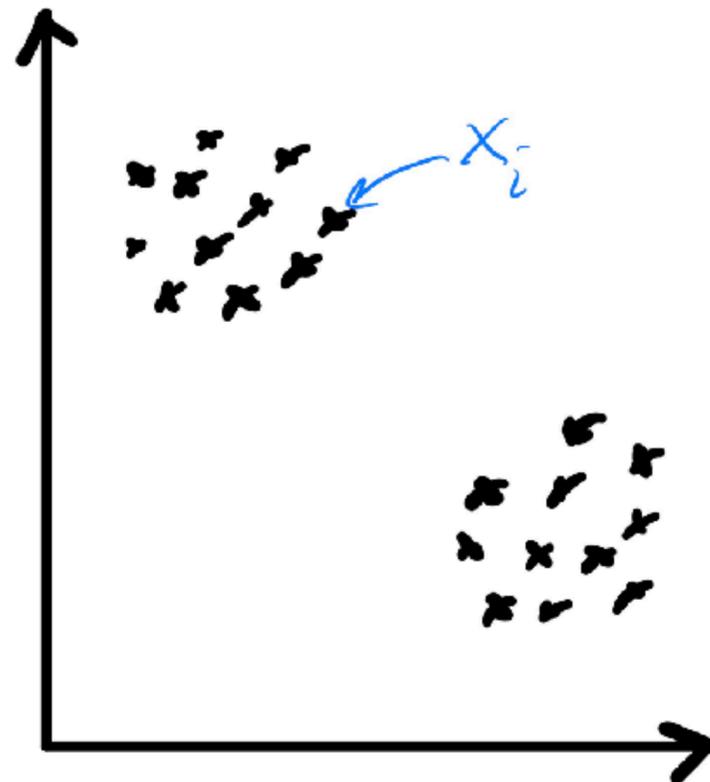
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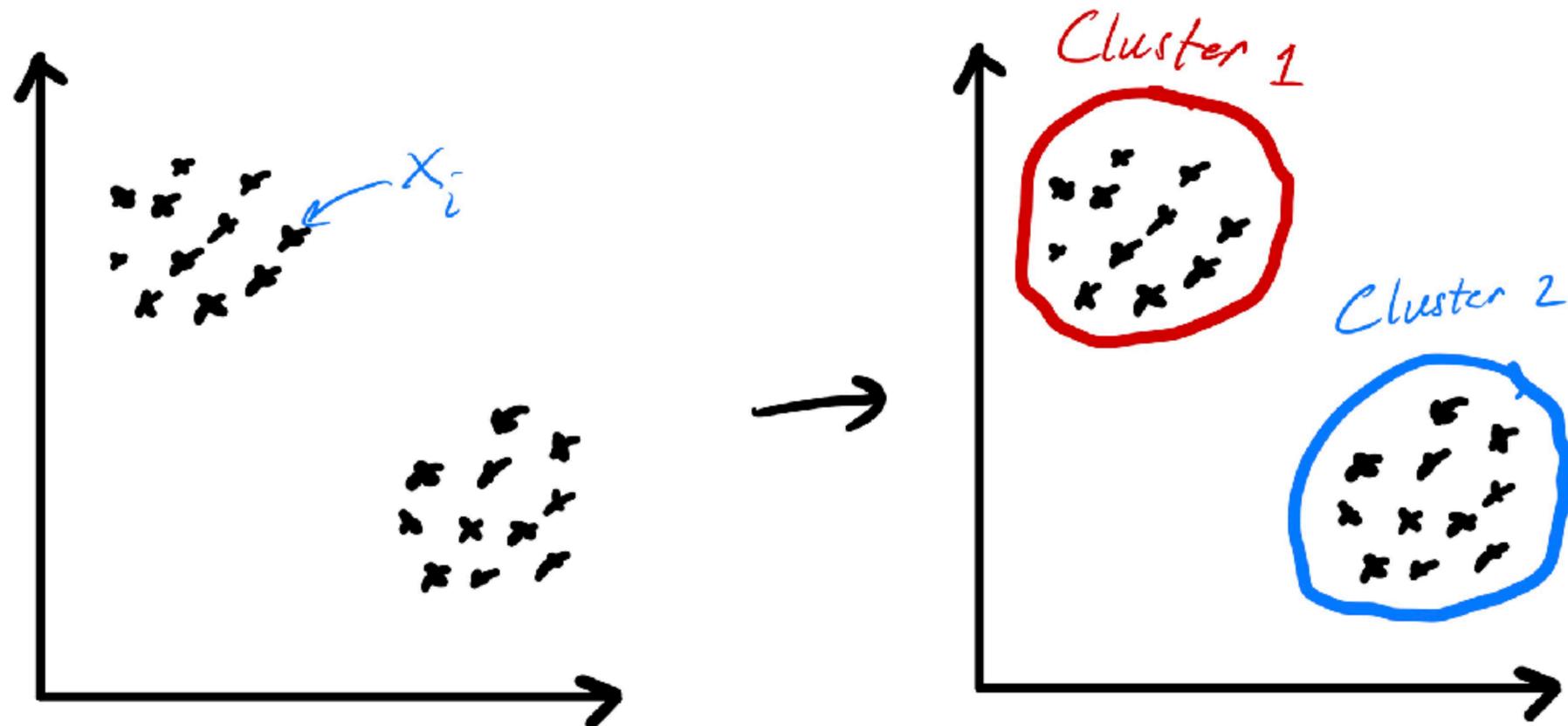


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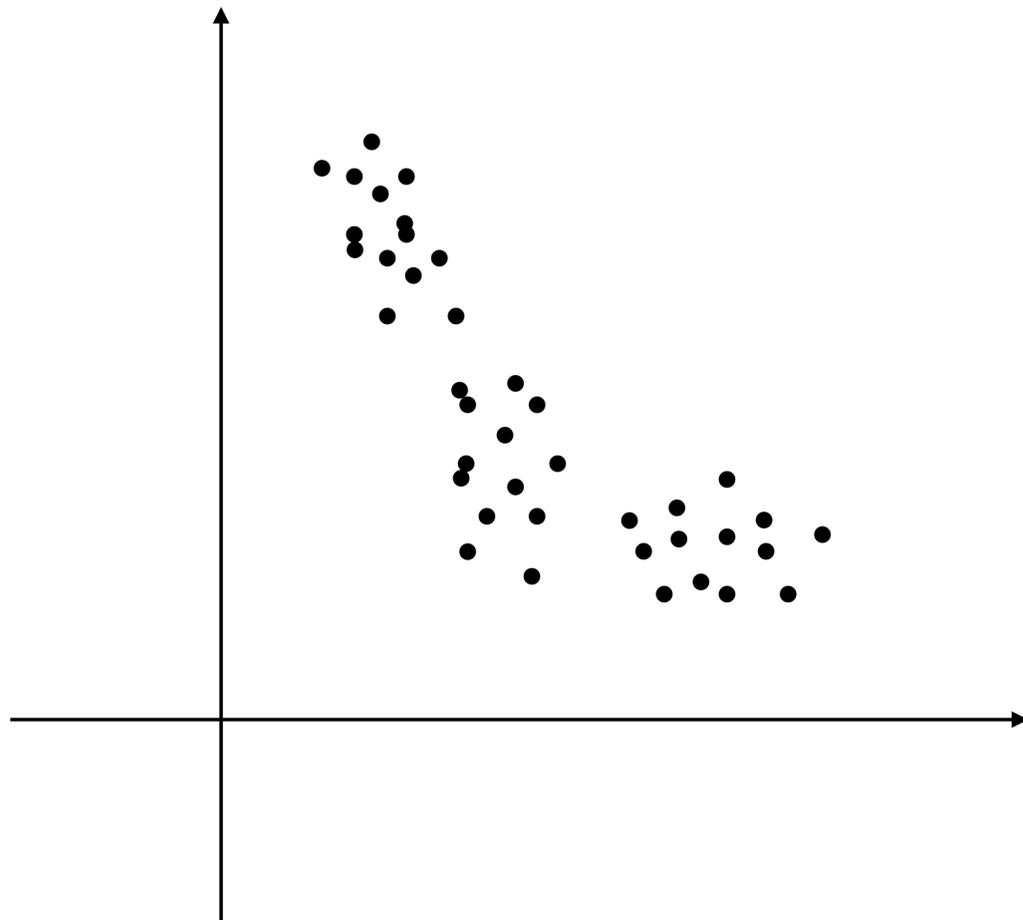


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Example: Density estimation / Anomaly detection

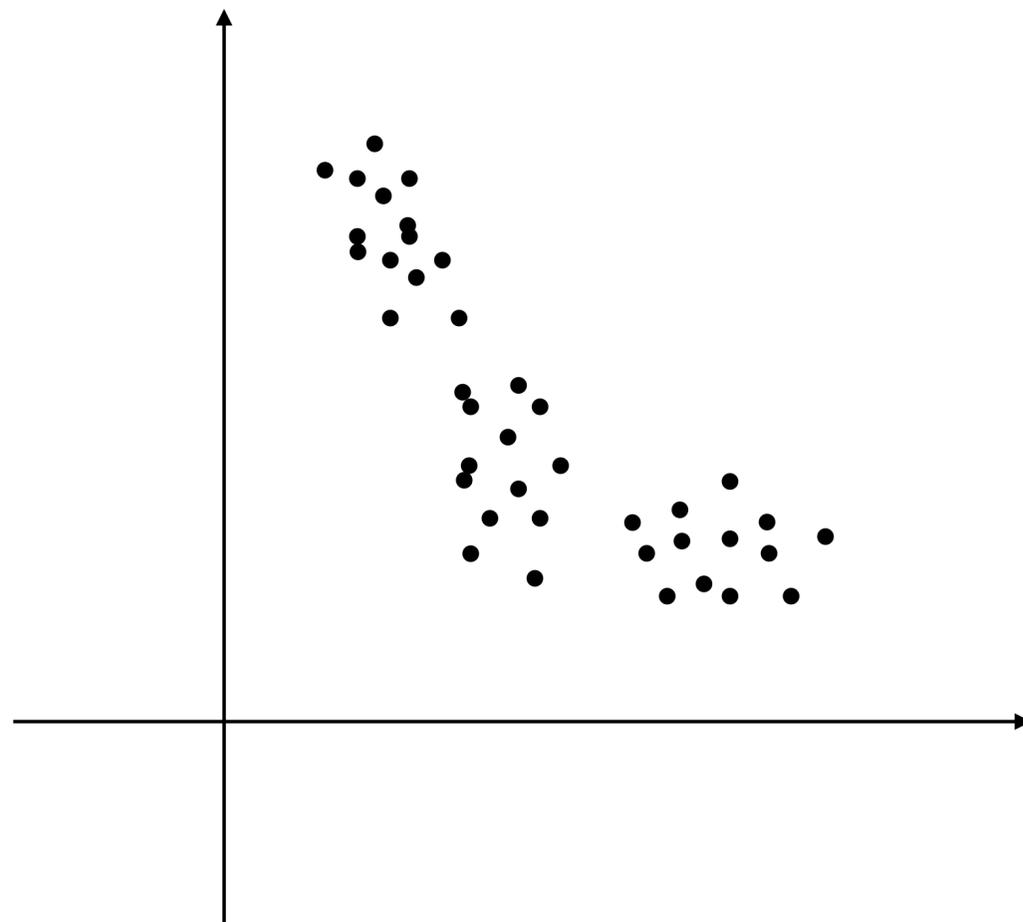


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Can we construct a distribution $\hat{\mathcal{P}}$ to approximate \mathcal{P} ?

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Generalization

Dataset \mathcal{D}



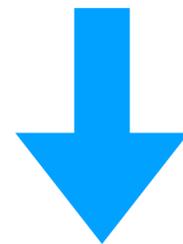
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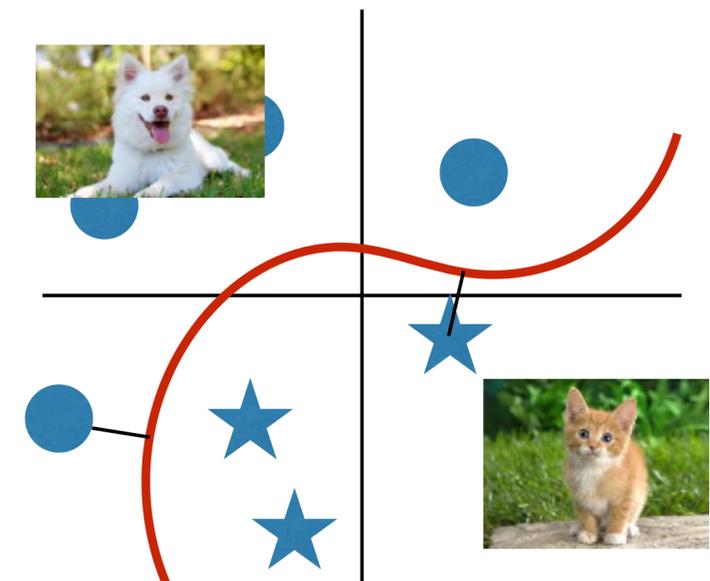
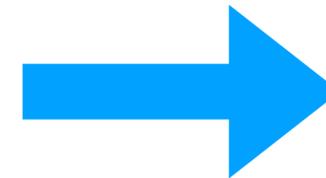
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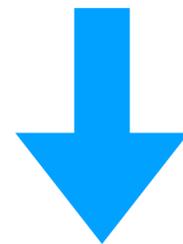
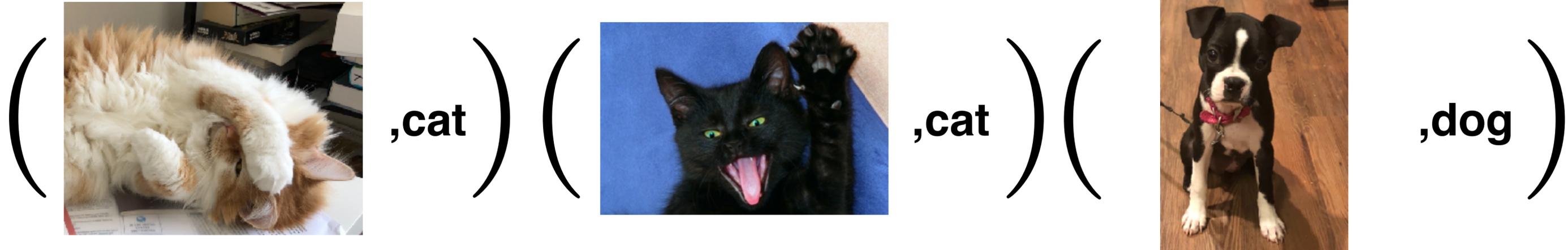


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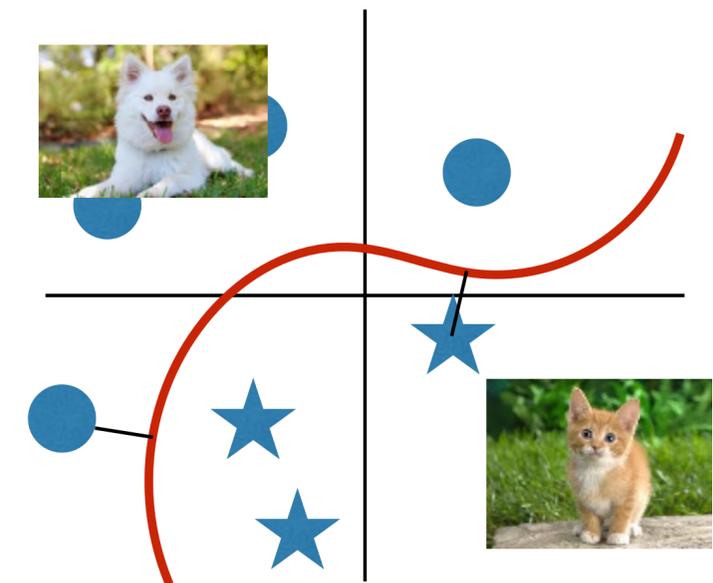
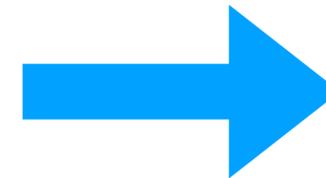


Generalization

Dataset \mathcal{D}



ML model



Generalization: how well can our trained model do on unseen test examples?

Let's formalize this using distribution

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e.g., expected classification error of \hat{h}

Overfitting

Overfitting: we have a small training error but large generalization error

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Example

Hypothesis \tilde{h} that memorizes the whole training set

$$\tilde{h}(x) = \begin{cases} y_i & \exists (x_i, y_i) \in \mathcal{D} \text{ w/ } x_i = x \\ 0 & \text{else} \end{cases}$$

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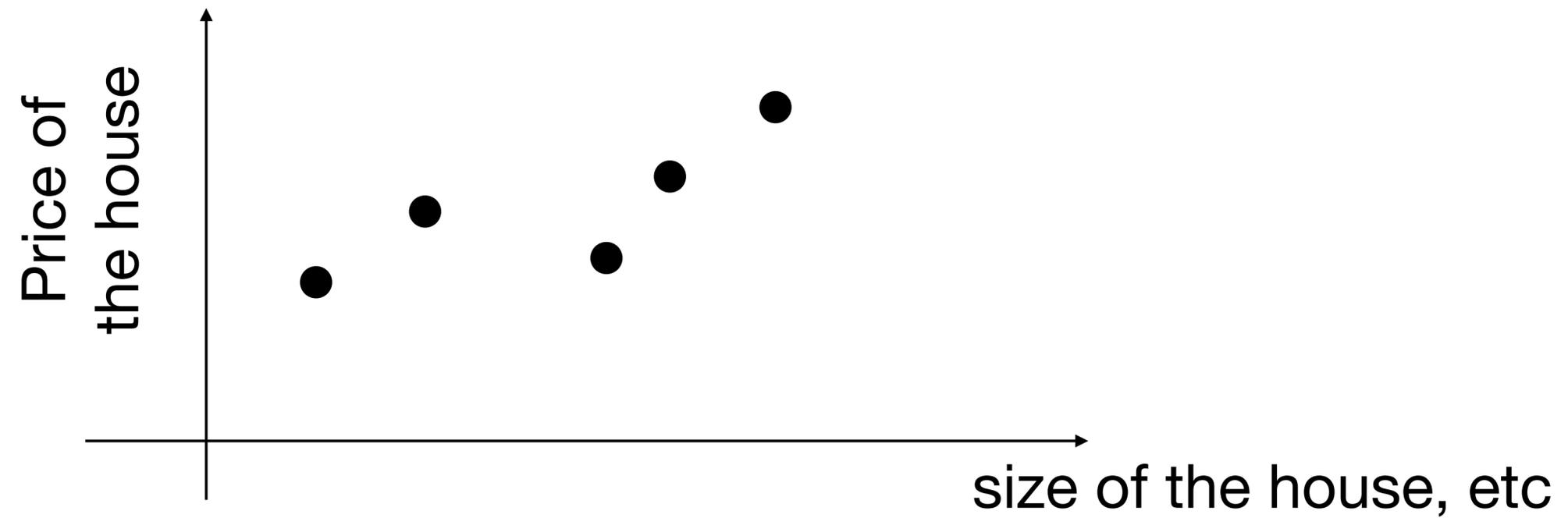
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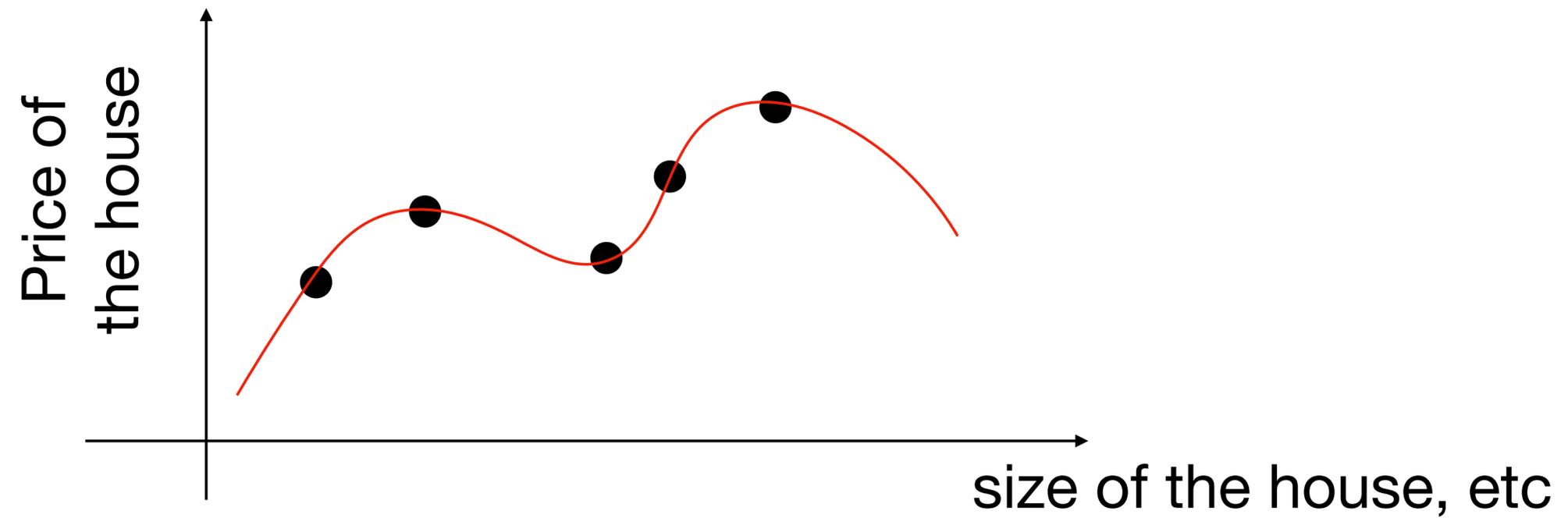
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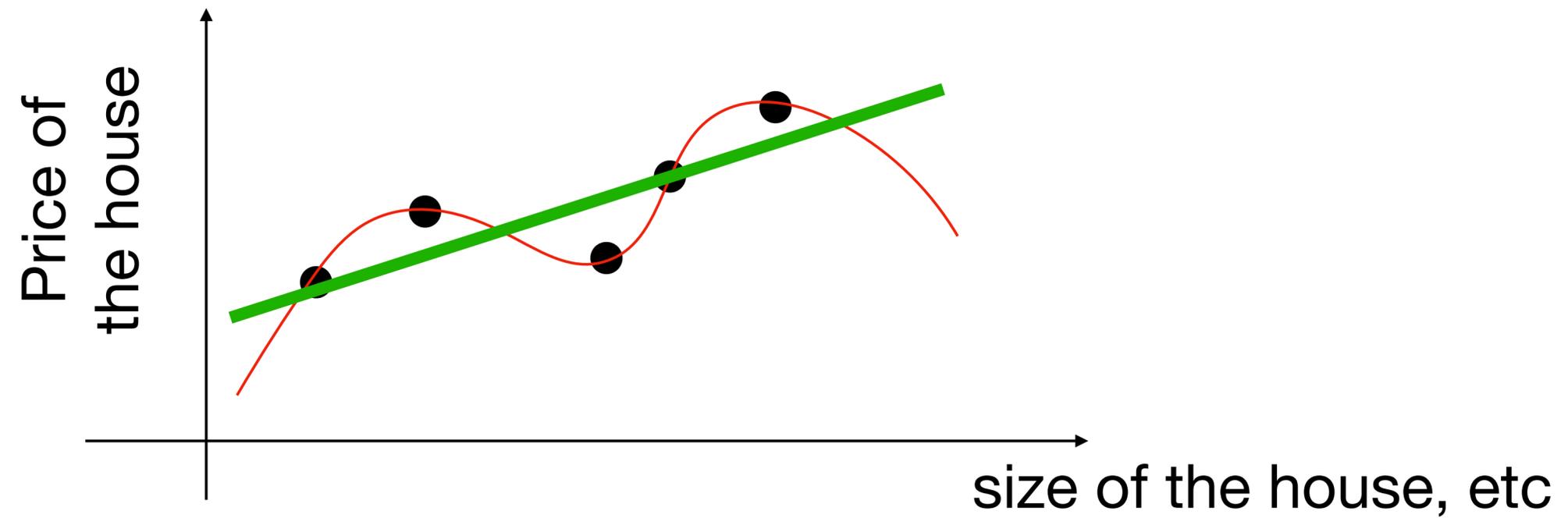
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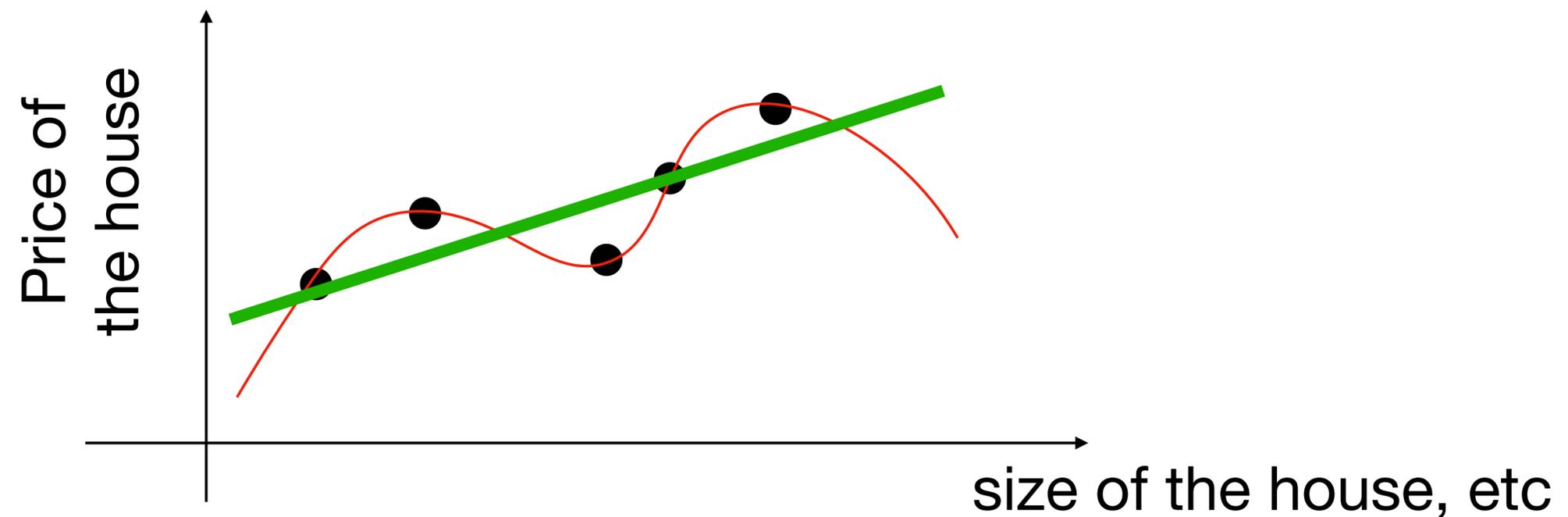
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Overfitting: we have a small training error but large generalization/test error

Example



Training error = 0 (e.g., we probably overfit to noises), but could do terribly on test examples

Overfitting

How to tell that our models overfit?

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Training, validation, and testing

Given a training dataset \mathcal{D} , we can split it into three sets:

\mathcal{D}_{TR} : training set

\mathcal{D}_{VA} : validation set

\mathcal{D}_{TE} : test set

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Before training/learning, we often **randomly** split it with size proportional to 80% / 10% / 10%

Selecting models using validation set

We can use validation set to select models, i.e., select hypothesis class, tune parameters, etc

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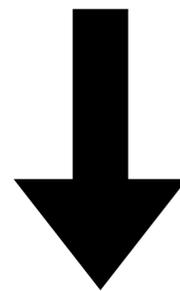
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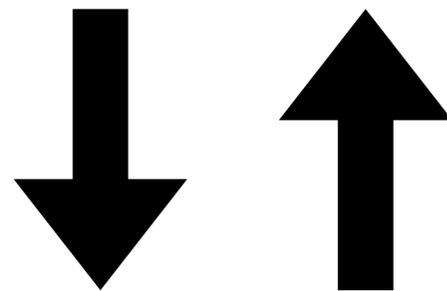


Revise model on \mathcal{D}_{TR} (e.g., add regularization, change neural network structures, etc)

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Such independence implies that:

$$\frac{1}{|\mathcal{D}_{TF}|} \sum_{x,y \in \mathcal{D}_{TE}} \ell(\hat{h}, x, y) \approx \mathbb{E}_{x,y \sim \mathcal{P}}[\ell(\hat{h}, x, y)]$$

(Due to law of large numbers)

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(very possible in medical applications!)



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For $i = 1 \rightarrow K$:

|

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(very possible in medical applications!)

K-fold cross validation

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For $i = 1 \rightarrow K$:

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When $K = n$, this is leave-one-out cross validation

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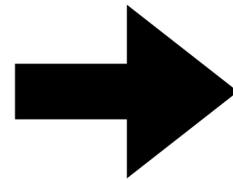
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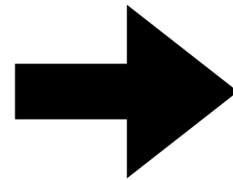
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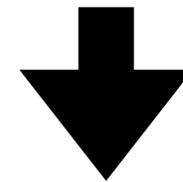
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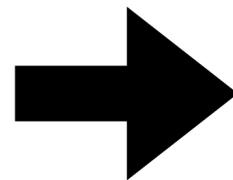
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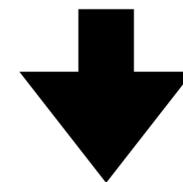
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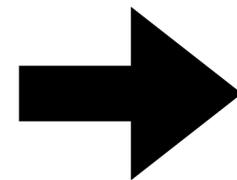


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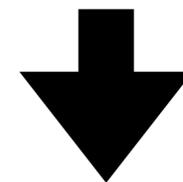
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Output: \hat{h} that has small generalization error
 $\mathbb{E}_{x,y \sim \mathcal{P}}[\ell(\hat{h}, x, y)]$

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