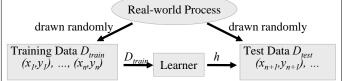
# Machine Learning Experiments and Overfitting

CS472/CS473 - Fall 2005

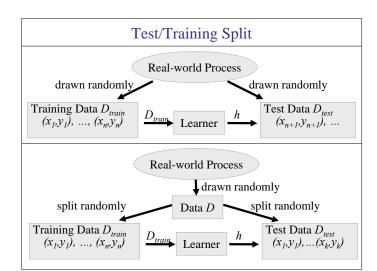
# Inductive Learning Setting Real-World Process New examples Learning as Prediction: Learner induces a general rule h from a set of observed examples that classifies new examples accurately.

# Testing Machine Learning Algorithms



### • Machine Learning Experiment:

- Gather training examples  $D_{train}$
- Run learning algorithm on  $D_{train}$  to produce h
- Gather Test Examples  $D_{test}$
- Apply h to D<sub>test</sub> and measure how many test examples are predicted correctly by h



# Measuring Prediction Performance

**Definition:** The training error  $Err_{D_{train}}(h)$  on training data  $D_{train} = ((\vec{x}_1, y_1), ..., (\vec{x}_n, y_n))$  of a hypothesis h is  $Err_{D_{train}}(h) = \frac{1}{n} \sum_{i=1}^{n} \Delta(h(\vec{x}_i), y_i)$ .

**Definition:** The **test error**  $Err_{D_{test}}(h)$  on test data  $D_{test} = ((\vec{x}_1, y_1), ..., (\vec{x}_k, y_k))$  of a hypothesis h is  $Err_{D_{test}}(h) = \frac{1}{n} \sum_{i=1}^k \Delta(h(\vec{x}_i), y_i)$ .

**Definition:** The prediction/generalization/true error  $Err_P(h)$  of a hypothesis h for a learning task P(X,Y) is

$$Err_P(h) = \sum_{\vec{x} \in X, y \in Y} \Delta(h(\vec{x}), y) P(X = \vec{x}, Y = y).$$

**Definition:** The zero/one-loss function  $\Delta(a,b)$  returns 1 if  $a \neq b$  and 0 otherwise.

# Performance Measures

#### Error Rate

- Fraction (or percentage) of false predictions

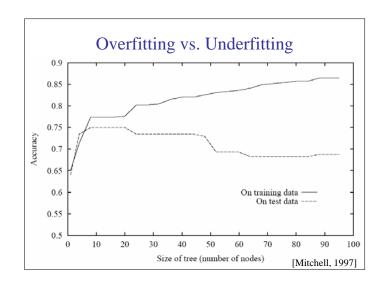
#### Accuracy

Fraction (or percentage) of correct predictions

### • Precision/Recall

- Applies only to binary classification problems (classes pos/neg)
- Precision: Fraction (or percentage) of correct predictions among all examples predicted to be positive
- Recall: Fraction (or percentage) of correct predictions among all positive examples

# Learning as Prediction Task Real-world Process drawn randomly. rawn randomly Training Data $D_{train}$ Test Data $D_{test}$ $(x_1,y_1), ..., (x_n,y_n)$ $(x_{n+1},y_{n+1}), ...$ Learner • Goal: Find h with small prediction error $Err_p(h)$ . • Strategy: Find (any?) h with small error $Err_{D_{train}}(h)$ on $D_{train}$ . **Inductive Learning Hypothesis:** Any hypothesis found to approximate the target function well over a sufficiently large set of training examples will also approximate the target function well over any other unobserved examples. → Is Inductive Learning Hypothesis really true?



# **Example: Text Classification**

- · Task: Learn rule that classifies Reuters Business News
  - Class +: "Corporate Acquisitions"
  - Class -: Other articles
  - 2000 training instances
- Representation:
  - Boolean attributes, indicating presence of a keyword in article
  - 9947 such keywords (more accurately, word "stems")

# LAROCHE STARTS BID FOR NECO SHARES Investor David F. La Roche of North Kingstown, R.I.,

said he is offering to purchase 170,000 common shares of NECO Enterprises Inc at 26 dIrs each. He said the successful completion of the offer, plus shares he already owns, would give him 50.5 pct of NECO's 962,016 common shares. La Roche said he may buy more, and possible all NECO shares. He said the offer and withdrawal rights will expire at 1630 EST/2130 gmt, March 30, 1987.

SALANT CORP 1ST QTR FEB 28 NET

Oper shr profit seven cts vs loss 12 cts. Oper net profit 216,000 vs loss 401,000. Sales 21.4 mln vs 24.9 mln. NOTE: Current year net excludes 142,000 dlr tax credit. Company operating in Chapter 11 bankruptcy.

# Text Classification Example: Results

- Data
  - Training Sample: 2000 examples
  - Test Sample: 600 examples
- Full Decision Tree:
  - Size: 437 nodes Training Error: 0.0% Test Error: 11.0%
- Early Stopping Tree:
  - Size: 299 nodes Training Error: 2.6% Test Error: 9.8%

# **Example: Smart Investing**

# Task: Pick stock analyst based on past performance. Experiment:

- Have analyst predict "next day up/down" for 10 days.
- Pick analyst that makes the fewest errors.

#### Situation 1:

- 1 stock analyst {A1}, A1 makes 5 errors

#### Situation 2:

- 3 stock analysts {A1,B1,B2}, B2 best with 1 error

#### **Situation 3:**

1003 stock analysts {A1,B1,B2,C1,...,C1000}, C543 best with 0 errors

Which analysts are you most confident in, A1, B2, or C543?

# Selecting Algorithm Parameters Optimal choice of algorithm parameters depends on learning task: • k in k-nearest neighbor, splitting criterion in decision trees Real-world Process drawn randomly Data Dsplit randomly (50% split randomly (30%) split randomly (20%) Test Data $D_{test}$ Train Data $D_{train}$ Validation Data $D_{ya}$ $(x_1, y_1), ..., (x_n, y_n)$ $(x_1,y_1), ..., (x_l,y_l)$ $(x_1,y_1),...(x_k,y_k)$ argmin, {Err, Learner p

# K-fold Cross Validation

#### • Given

- Sample of labeled instances D (after putting aside  $D_{test}$ )
- Learning Algorithms  $A_1 \dots A_p$  (e.g. k-NN with different k)

## • Compute

- Randomly partition D into k equally sized subsets  $D_1 \dots D_k$
- For i from l to k
  - Train  $A_1 \dots A_p$  on  $\{D_1 \dots D_{i-1} D_{i+1} \dots D_k\}$  and get  $h_1 \dots h_p$ .
  - Apply  $h_1 \dots h_p$  to  $D_i$  and compute  $Err_{D_i}(h_1) \dots Err_{D_i}(h_p)$ .

#### • Estimate

- $Err_{CV}(A_i)$   $\leftarrow$   $1/k \sum_{i \in \{1..k\}} Err_{D_i}(h_i)$  is estimate of the prediction error of  $A_i$
- Pick algorithm  $A_{best}$  with lowest  $Err_{CV}(A_i)$
- Train  $A_{best}$  on D and output resulting h