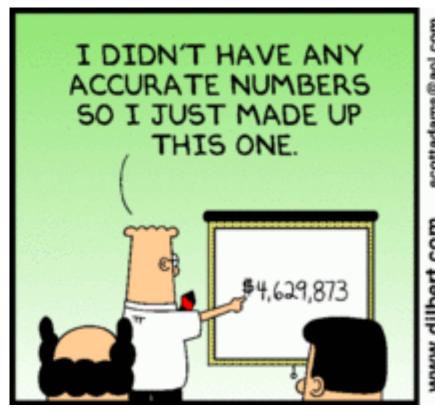
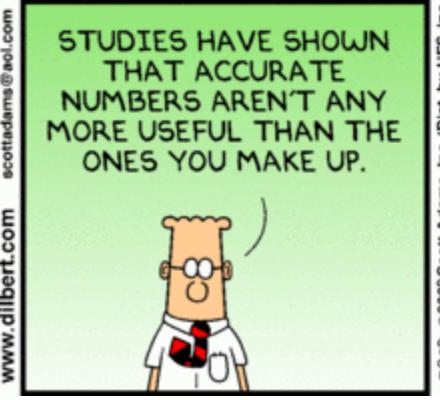
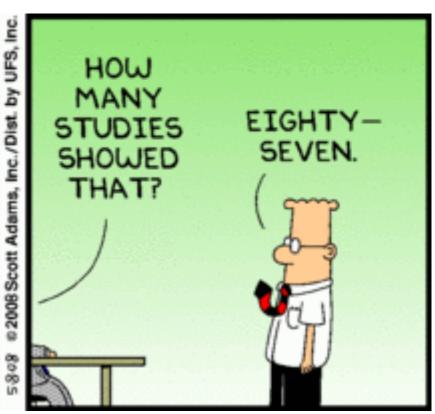
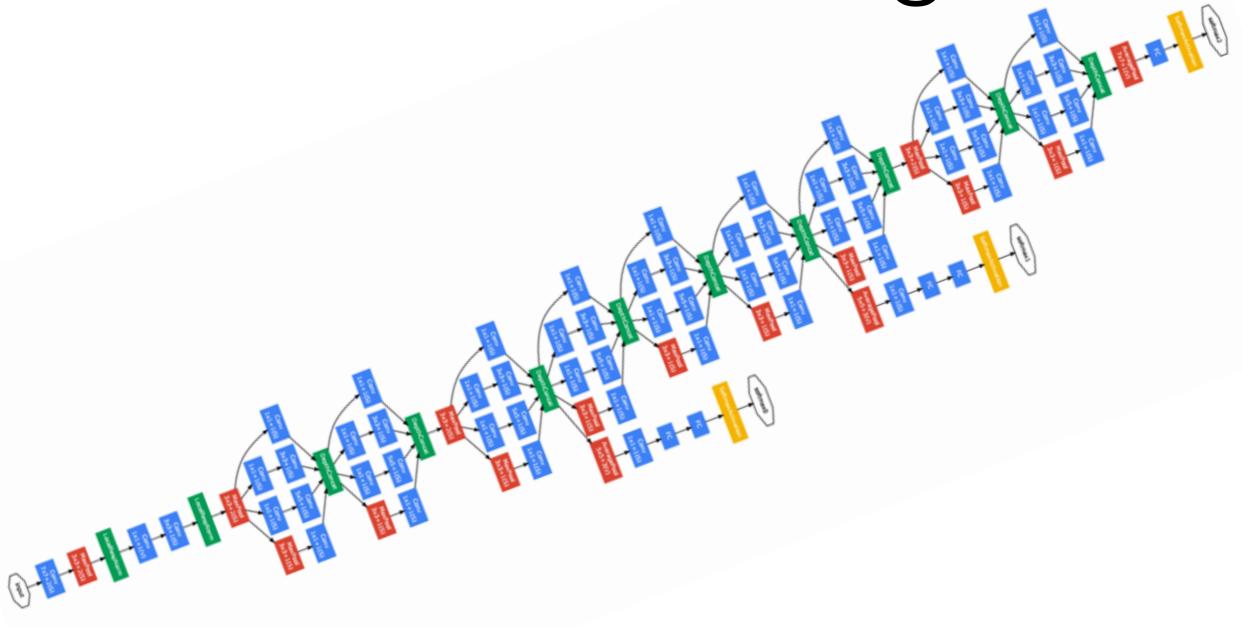
Convolutional Neural Networks

CS 4670/5670 Sean Bell

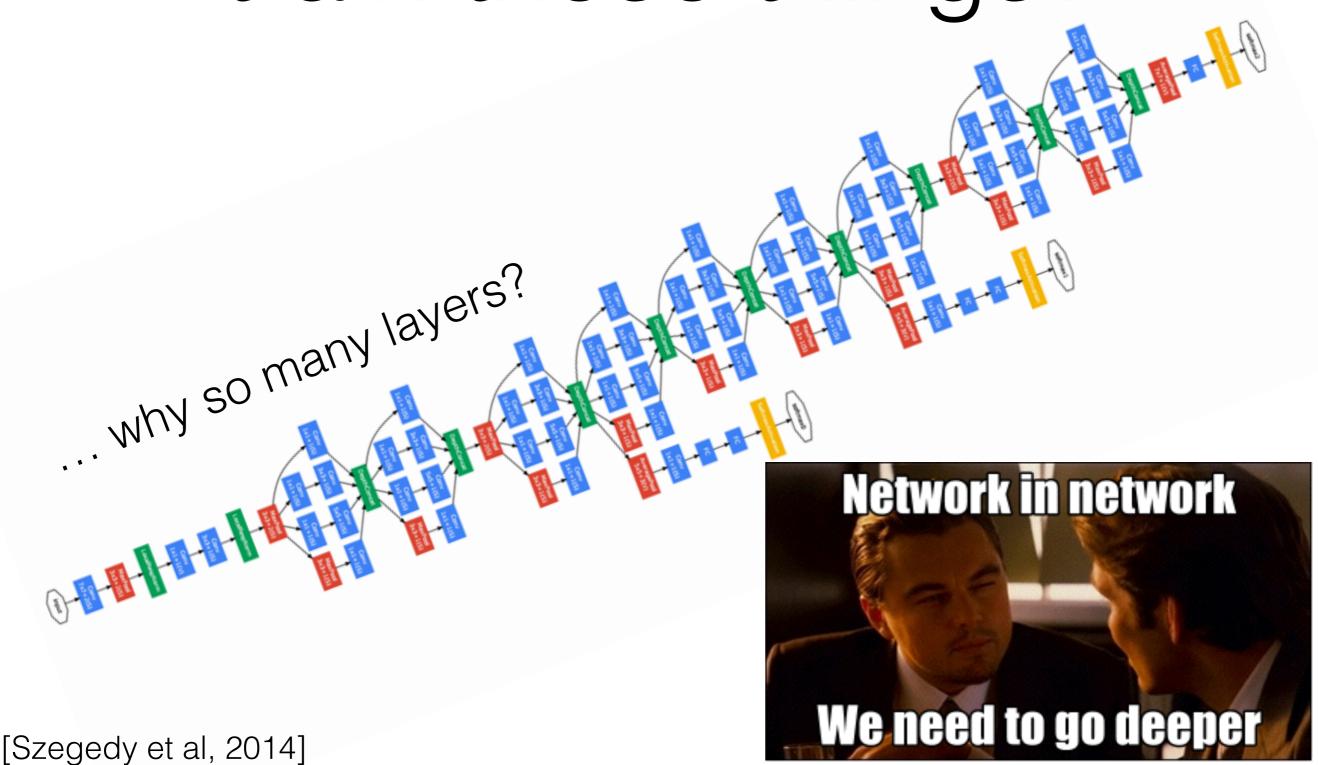












Roughly speaking:

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Gather labeled data

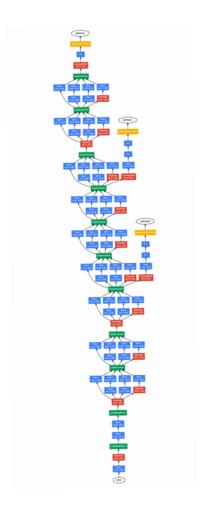


Roughly speaking:

Gather labeled data



Find a CNN architecture



Roughly speaking:

Gather labeled data

Aquatic

Gallinaceous

Bird

Archaeorni

Archaeorni

Archaeopte

Archaeopte

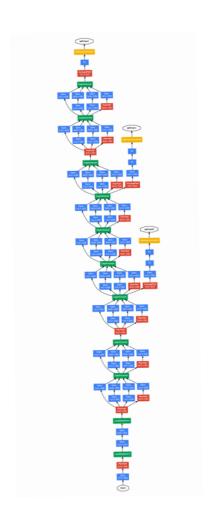
Archaeopte

Nester

Nester

Ratite

Find a CNN architecture



Minimize the loss



Split and preprocess your data

- Split and preprocess your data
- Choose your network architecture

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- Initialize the weights
- Find a learning rate and regularization strength
- Minimize the loss and monitor progress
- Fiddle with knobs

Loop:

1. Sample a batch of training data (~100 images)

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- 4. Update all parameters

Loop:

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- 2. Forwards pass: compute loss (avg. over batch)
- 3. Backwards pass: compute gradient
- 4. Update all parameters

Note: usually called "stochastic gradient descent" even though SGD has a batch size of 1

Regularization reduces overfitting:

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$$L = L_{\text{data}} + L_{\text{reg}}$$

$$L_{\text{reg}} = \lambda \frac{1}{2} ||W||_2^2$$

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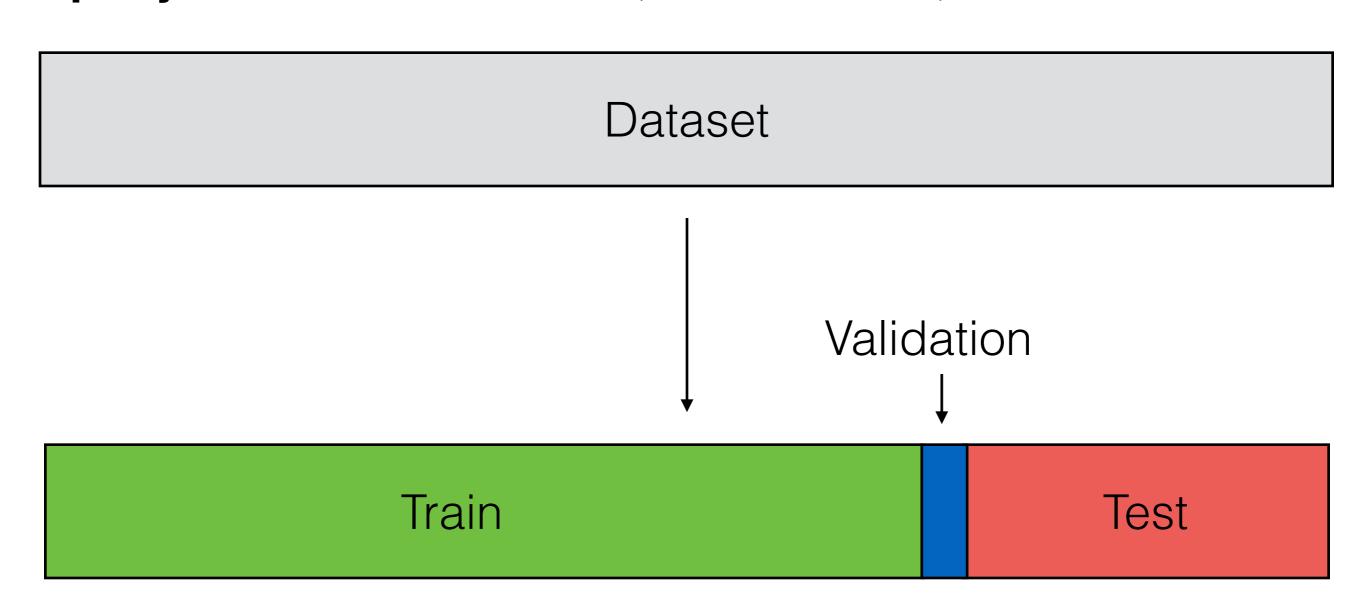
$$\lambda = 0.001 \qquad \qquad \lambda = 0.1$$

[Andrej Karpathy http://cs.stanford.edu/people/karpathy/convnetjs/demo/classify2d.html]

Split your data into "train", "validation", and "test":

Dataset

Split your data into "train", "validation", and "test":



Validation
Train

Test



Train: gradient descent and fine-tuning of parameters

Validation

Train

Test

Train: gradient descent and fine-tuning of parameters

Validation: determining hyper-parameters (learning rate, regularization strength, etc) and picking an architecture



Train: gradient descent and fine-tuning of parameters

Validation: determining hyper-parameters (learning rate, regularization strength, etc) and picking an architecture

Test: estimate real-world performance (e.g. accuracy = fraction correctly classified)



Be careful with false discovery:

Validation

Train

Test

Be careful with false discovery:

To avoid false discovery, once we have used a test set once, we should *not use it again* (but nobody follows this rule, since it's expensive to collect datasets)

Validation
Train
Test

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To avoid false discovery, once we have used a test set once, we should *not use it again* (but nobody follows this rule, since it's expensive to collect datasets)

Instead, try and avoid looking at the test score until the end

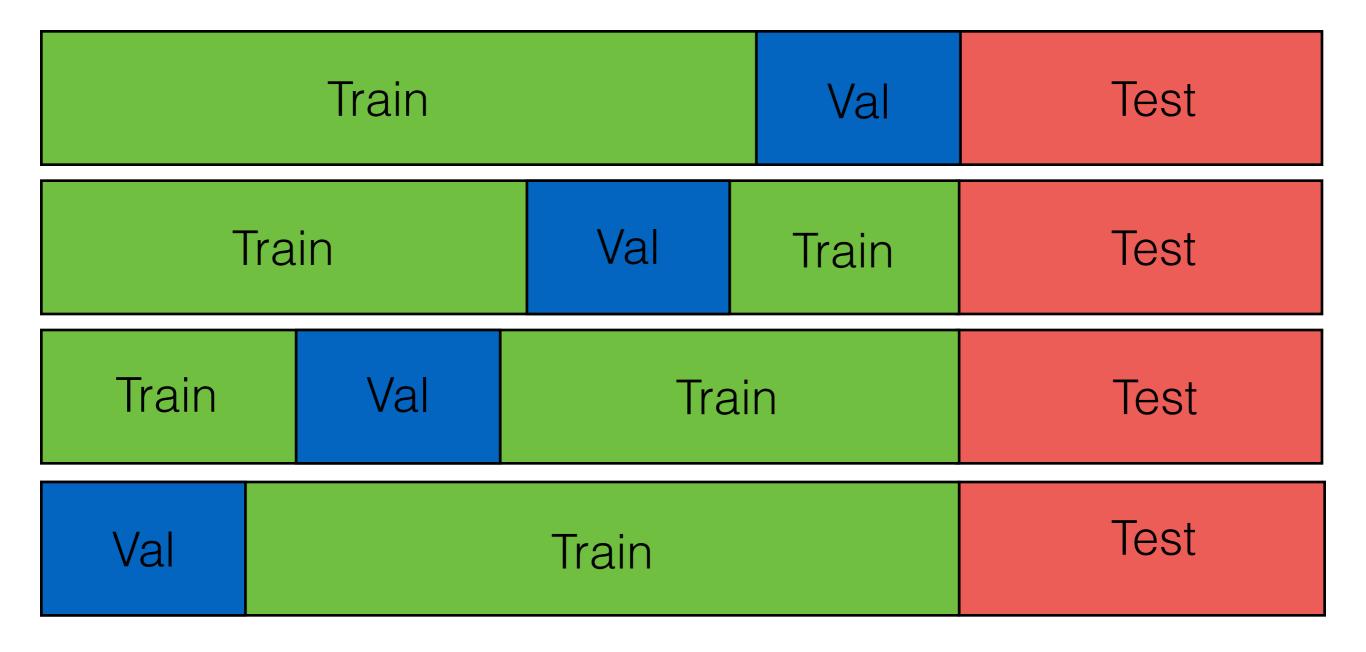
Train	Val	Test
-------	-----	------

Train		Val	Test
Train	Val	Train	Test

	Train		Val	Test
Train		Train	Test	
Train	Val	Train		Test

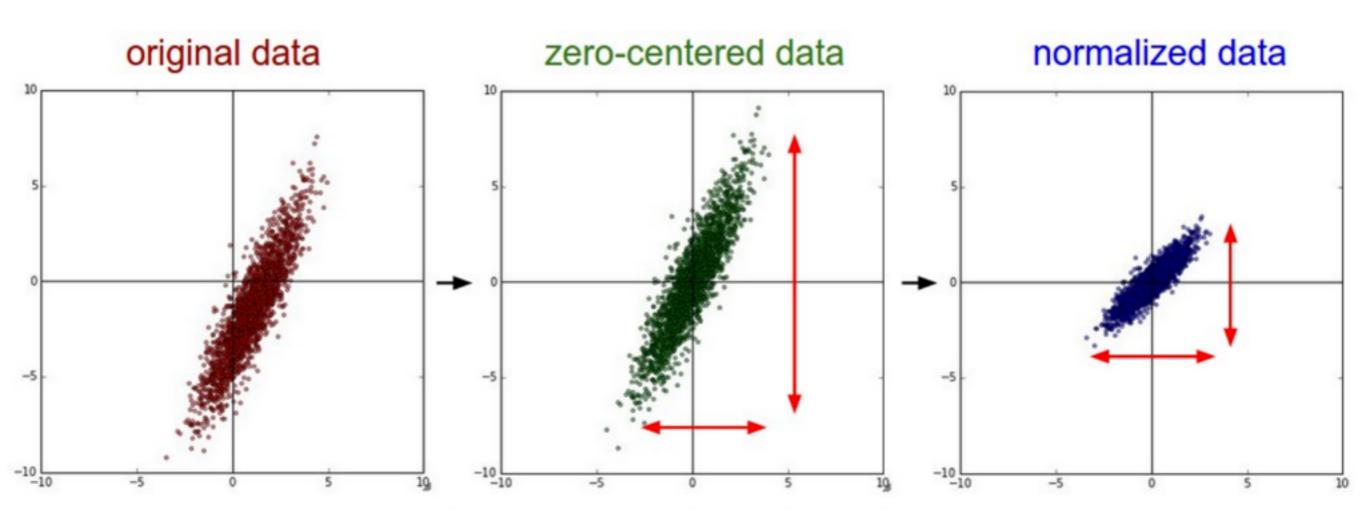
	Train		Val	Test
Tr	ain	Val	Train	Test
Train	Val	Train		Test
Val Train		Test		

Cross-validation: cycle which data is used as validation



Average scores across validation splits

Preprocess the data so that learning is better conditioned:



Preprocess the data so that learning is better conditioned:

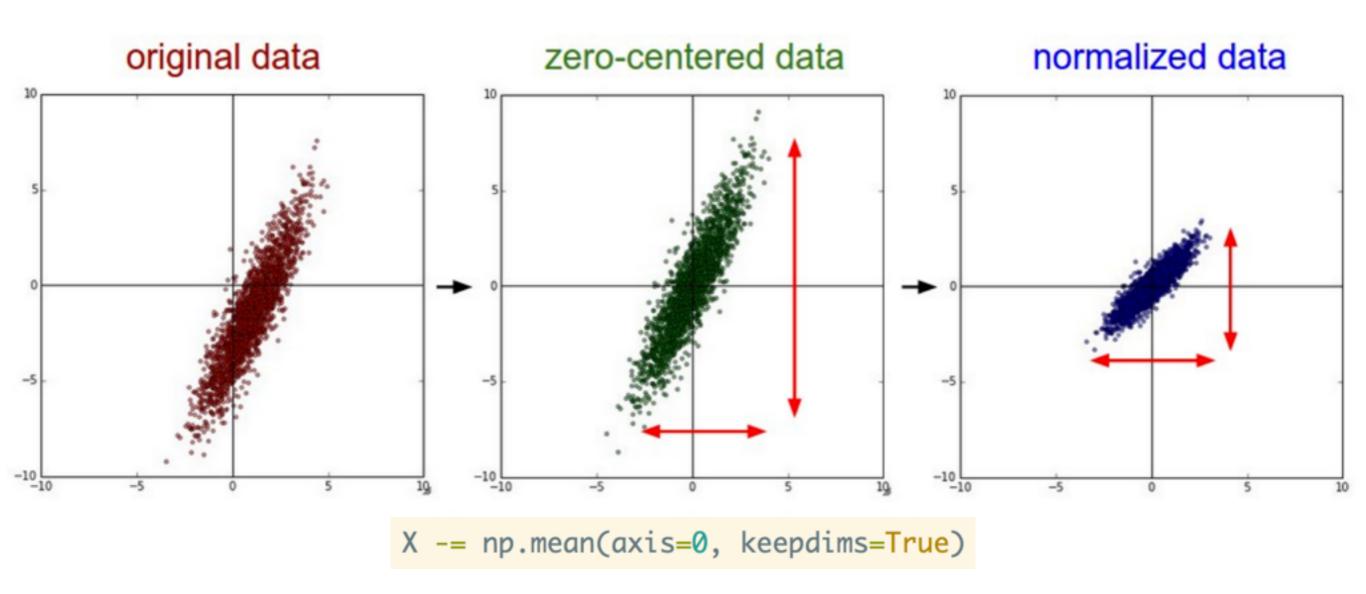
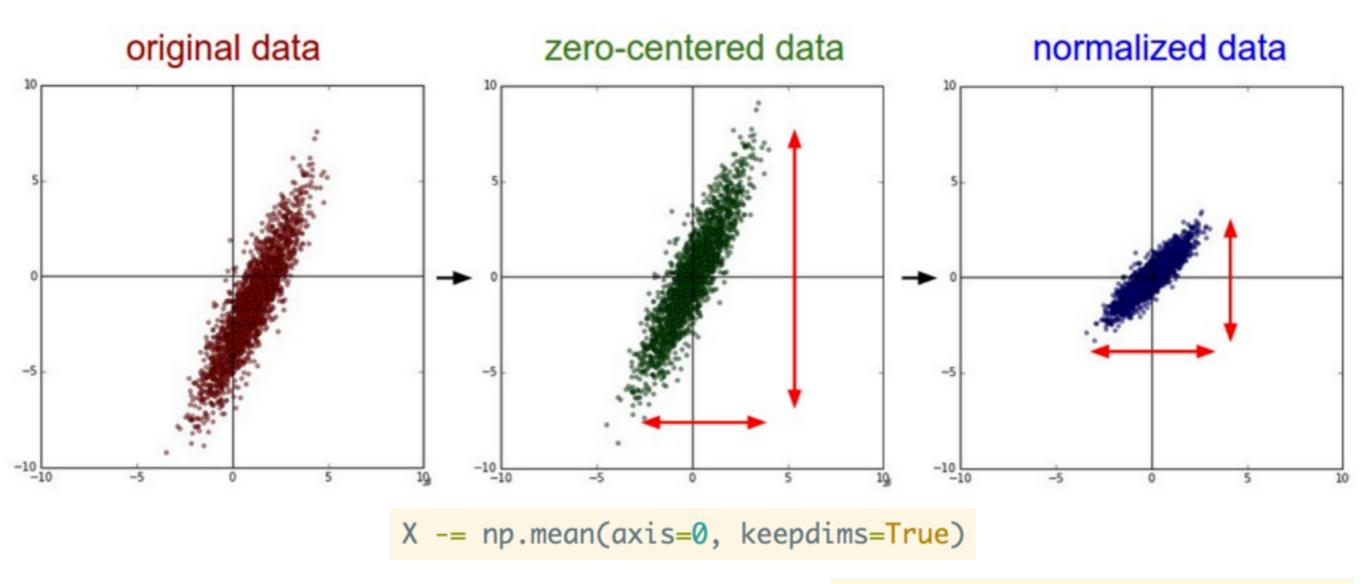


Figure: Andrej Karpathy

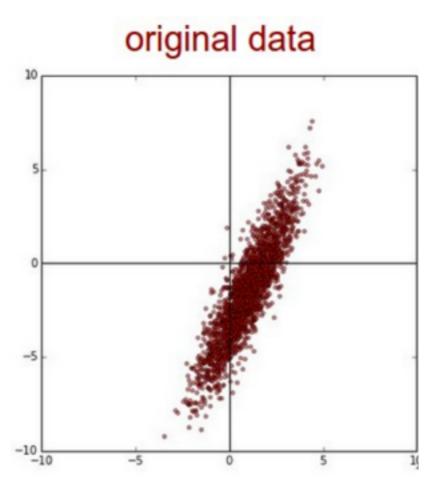
Preprocess the data so that learning is better conditioned:



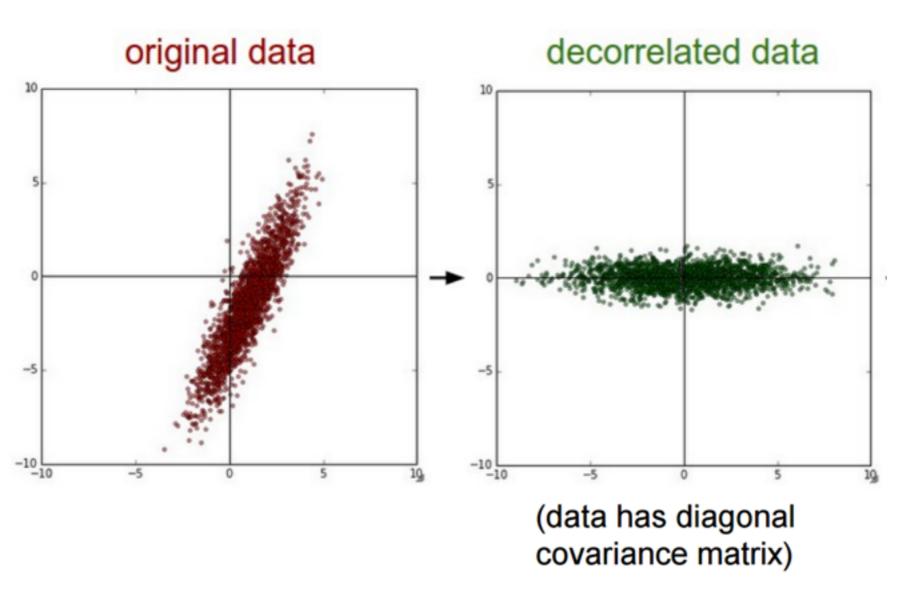
X /= np.std(axis=0, keepdims=True)

Figure: Andrej Karpathy

In practice, you may also see PCA and Whitening of the data:

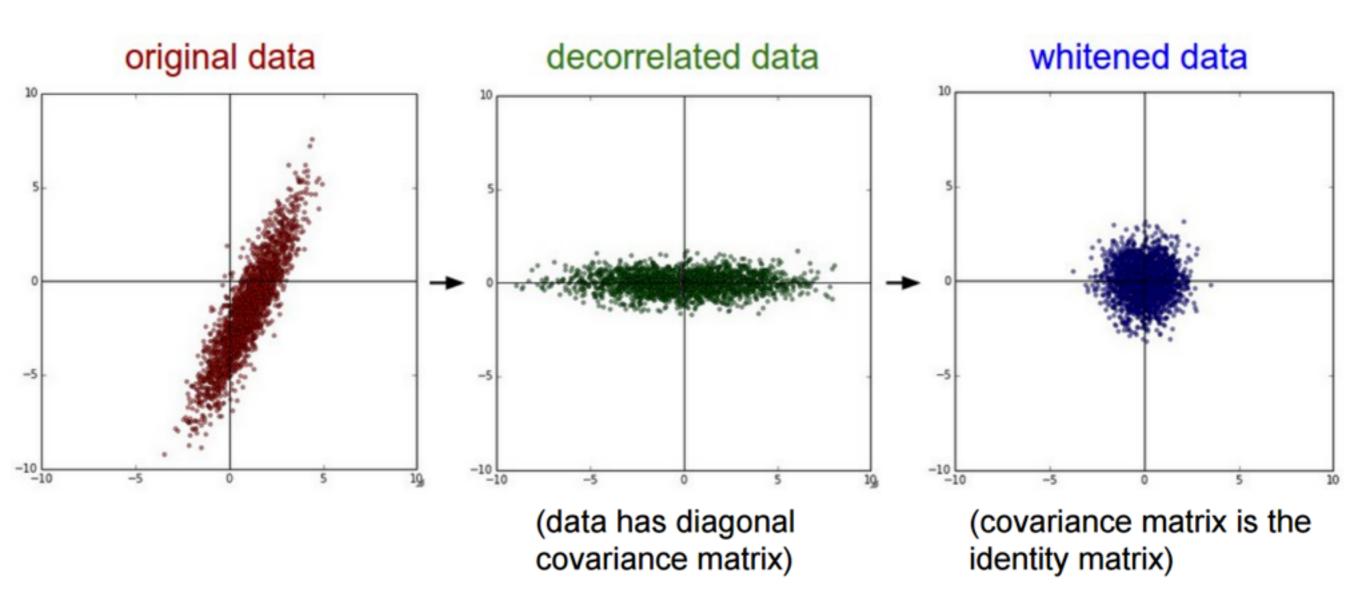


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Slide: Andrej Karpathy

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Slide: Andrej Karpathy

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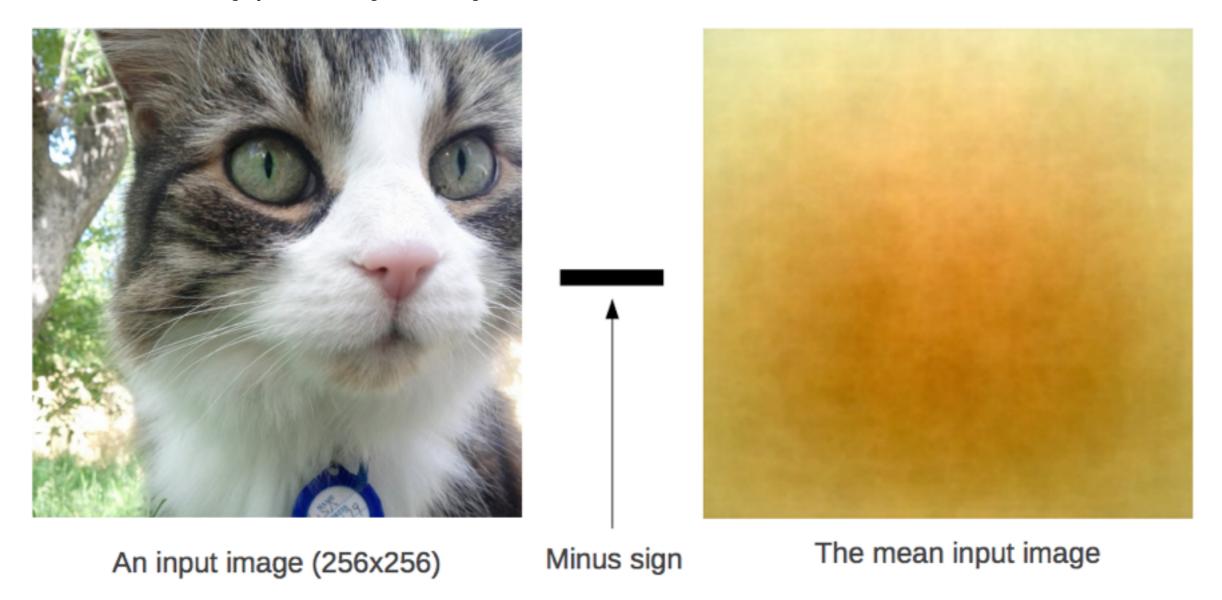
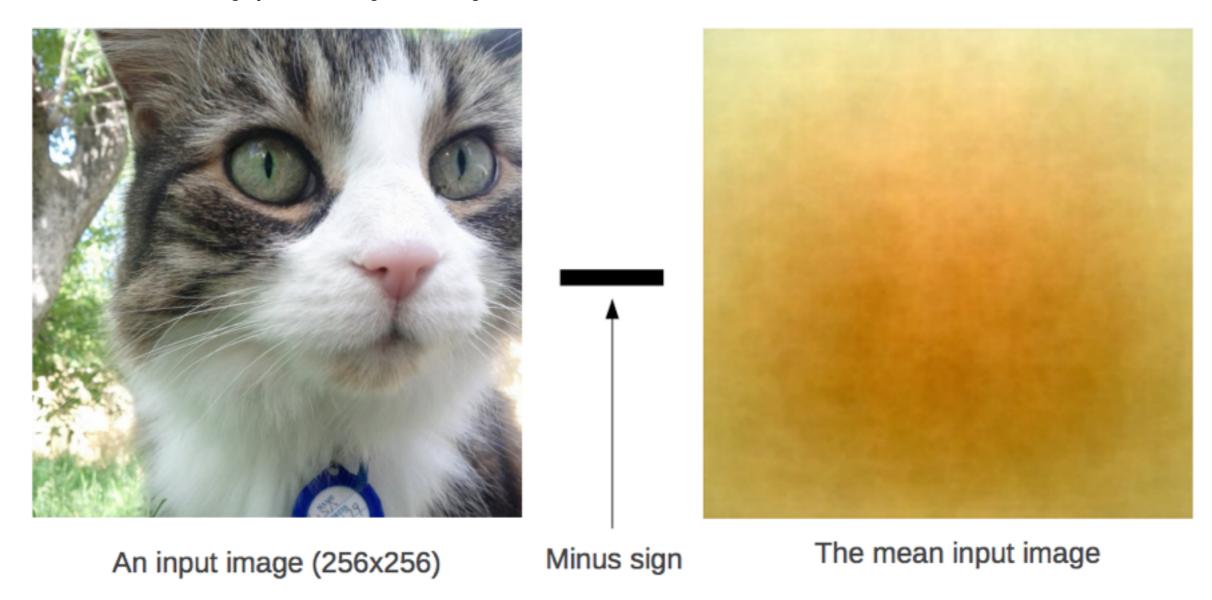


Figure: Alex Krizhevsky

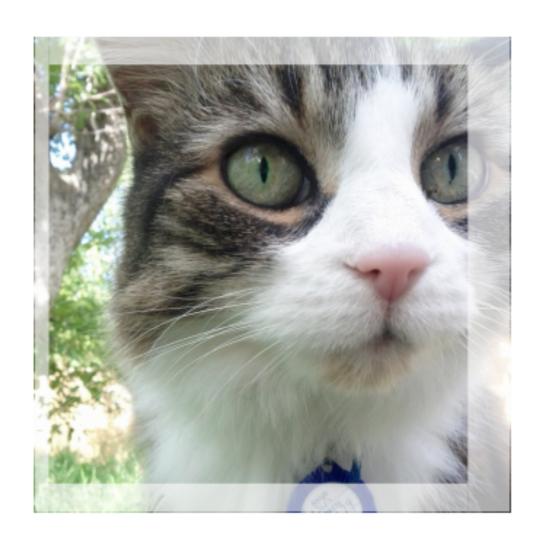
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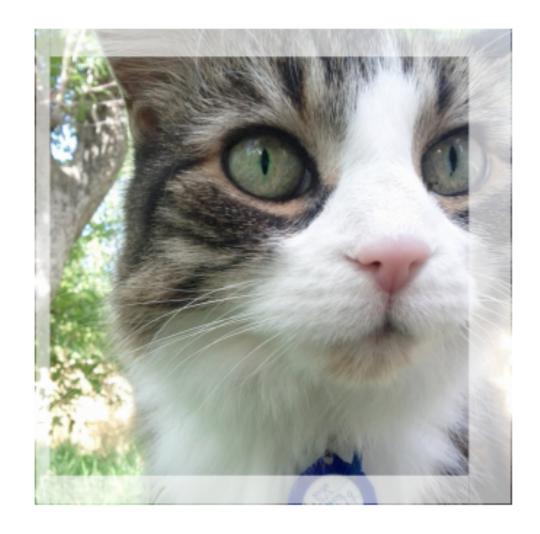
A per-channel mean also works (one value per R,G,B).

Figure: Alex Krizhevsky

Augment the data — extract random crops from the input, with slightly jittered offsets. Without this, typical CNNs (e.g. [Krizhevsky 2012]) overfit the data.

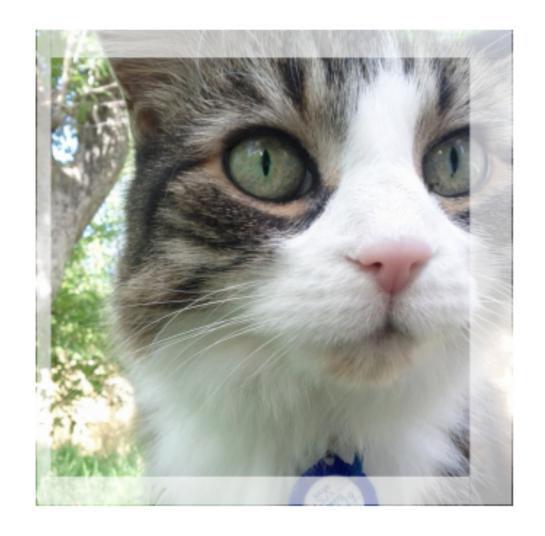


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E.g. 224x224 patches extracted from 256x256 images

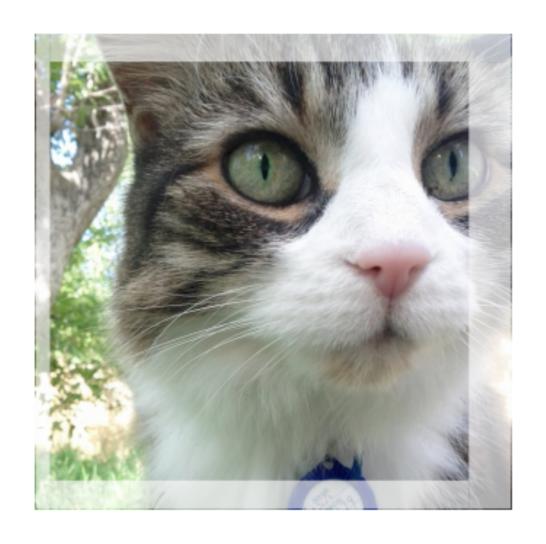
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Randomly reflect horizontally

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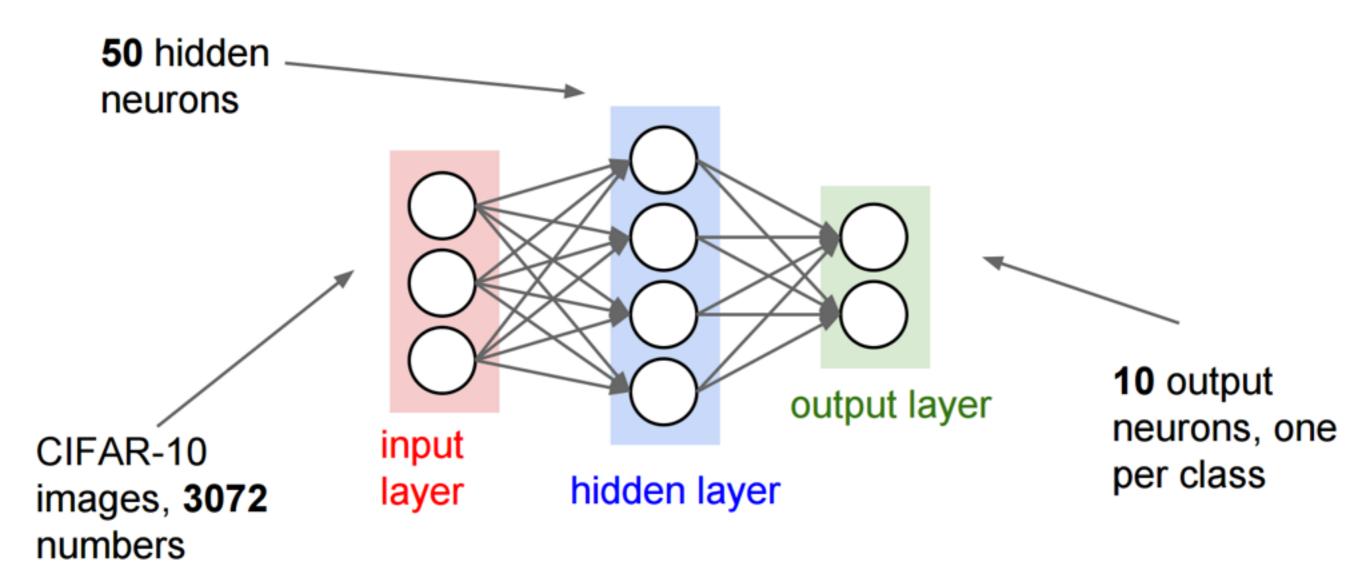
Perform the augmentation live during training

(2) Choose your architecture

Toy example: one hidden layer of size 50

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Slide: Andrej Karpathy

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Set the bias to zero (or small nonzero):

$$b = np.zeros(H)$$

```
def init_two_layer_model(input_size, hidden_size, output_size):
    # initialize a model
    model = {}
    model['W1'] = 0.0001 * np.random.randn(input_size, hidden_size)
    model['b1'] = np.zeros(hidden_size)
    model['W2'] = 0.0001 * np.random.randn(hidden_size, output_size)
    model['b2'] = np.zeros(output_size)
    return model
```

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```
model = init_two_layer_model(32*32*3, 50, 10) # input size, hidden size, number of classes loss, grad = two_layer_net(X_train, model, y_train, 0.0) disable regularization
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returns the loss and the gradient for all parameters

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2.30261216167

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loss, grad = two layer net(X train, model, y train, 0.0
                                                disable regularization
print loss
2.30261216167
                     loss ~2.3.
                                        returns the loss and the
                     "correct " for
                                        gradient for all parameters
                     10 classes
```

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3.06859716482

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    return model
```

3.06859716482

loss went up, good. (sanity check)

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'sgd': vanilla gradient descent (no momentum etc)

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learning_rate_decay = 1: constant learning rate
sample_batches = False (full gradient descent, no batches)
epochs = 200: number of passes through the data

Slide: Andrej Karpathy

```
Finished epoch 1 / 200: cost 2.302603, train: 0.400000, val 0.400000, lr 1.000000e-03
Finished epoch 2 / 200: cost 2.302258, train: 0.450000, val 0.450000, lr 1.000000e-03
Finished epoch 3 / 200: cost 2.301849, train: 0.600000, val 0.600000, lr 1.000000e-03
Finished epoch 4 / 200: cost 2.301196, train: 0.650000, val 0.650000, lr 1.000000e-03
Finished epoch 5 / 200: cost 2.300044, train: 0.650000, val 0.650000, lr 1.000000e-03
Finished epoch 6 / 200: cost 2.297864, train: 0.550000, val 0.550000, lr 1.000000e-03
Finished epoch 7 / 200: cost 2.293595, train: 0.600000, val 0.600000, lr 1.000000e-03
Finished epoch 8 / 200: cost 2.285096, train: 0.550000, val 0.550000, lr 1.000000e-03
Finished epoch 9 / 200: cost 2.268094, train: 0.550000, val 0.550000, lr 1.000000e-03
Finished epoch 10 / 200: cost 2.234787, train: 0.500000, val 0.500000, lr 1.000000e-03
Finished epoch 11 / 200: cost 2.173187, train: 0.500000, val 0.500000, lr 1.000000e-03
Finished epoch 12 / 200: cost 2.076862, train: 0.500000, val 0.500000, lr 1.000000e-03
Finished epoch 13 / 200: cost 1.974090, train: 0.400000, val 0.400000, lr 1.000000e-03
Finished epoch 14 / 200: cost 1.895885, train: 0.400000, val 0.400000, lr 1.000000e-03
Finished epoch 15 / 200: cost 1.820876, train: 0.450000, val 0.450000, lr 1.000000e-03
Finished epoch 16 / 200: cost 1.737430, train: 0.450000, val 0.450000, lr 1.000000e-03
Finished epoch 17 / 200: cost 1.642356, train: 0.500000, val 0.500000, lr 1.000000e-03
Finished epoch 18 / 200: cost 1.535239, train: 0.600000, val 0.600000, lr 1.000000e-03
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 Finished epoch 19 / 200: cost 1.421527, train: 0.600000, val 0.600000, lr 1.000000e-03
Finished epoch 195 / 200: cost 0.002694, train: 1.0000000, val 1.0000000, lr 1.000000e-03
Finished epoch 196 / 200: cost 0.002674, train: 1.0000000, val 1.0000000, lr 1.000000e-03
Finished epoch 197 / 200: cost 0.002655, train: 1.000000, val 1.000000, lr 1.000000e-03
Finished epoch 198 / 200: cost 0.002635, train: 1.0000000, val 1.0000000, lr 1.000000e-03
Finished epoch 199 / 200: cost 0.002617, train: 1.0000000, val 1.0000000, lr 1.000000e-03
Finished epoch 200 / 200: cost 0.002597, train: 1.0000000, val 1.0000000, lr 1.000000e-03
finished optimization. best validation accuracy: 1.000000
```

100% accuracy on the training set (good)

```
Finished epoch 1 / 200: cost 2.302603, train: 0.400000, val 0.400000, lr 1.000000e-03
 Finished epoch 2 / 200: cost 2.302258, train: 0.450000, val 0.450000, lr 1.000000e-03
 Finished epoch 3 / 200: cost 2.301849, train: 0.600000, val 0.600000, lr 1.000000e-03
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 Finished epoch 19 / 200: cost 1.421527, train: 0.600000, val 0.600000, lr 1.000000e-03
Finished epoch 195 / 200: cost 0.002694, train: 1.000000
                                                               val 1.000000, lr 1.000000e-03
Finished epoch 196 / 200: cost 0.002674, train: 1.000000
                                                                val 1.000000, lr 1.000000e-03
Finished epoch 197 / 200: cost 0.002655, train: 1.000000
                                                                val 1.000000, lr 1.000000e-03
Finished epoch 198 / 200: cost 0.002635, train: 1.000000,
                                                               val 1.000000, lr 1.000000e-03
Finished epoch 199 / 200: cost 0.002617, train: 1.000000,
                                                               val 1.000000, lr 1.000000e-03
Finished epoch 200 / 200: cost 0.002597, train: 1.000000,
                                                               val 1.000000, lr 1.000000e-03
finished optimization. best validation accuracy: 1.000000
```

Let's start with small regularization and find the learning rate that makes the loss decrease:

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```
model = init two layer model(32*32*3, 50, 10) # input size, hidden size, number of classes
trainer = ClassifierTrainer()
best model, stats = trainer.train(X train, y train, X val, y val,
                                  model, two layer net,
                                  num epochs=10, reg=0.000001,
                                  update='sgd', tearning rate decay=1,
                                  sample batches - True,
                                  learning rate=le-6, verbose=True)
Finished epoch 1 / 10: cost 2.302576, train: 0.080000, val 0.103000, lr 1.000000e-06
Finished epoch 2 / 10: cost 2.302582, train: 0.121000, val 0.124000, lr 1.000000e-06
Finished epoch 3 / 10: cost 2.302558, train: 0.119000, val 0.138000, lr 1.000000e-06
Finished epoch 4 / 10: cost 2.302519, train: 0.127000, val 0.151000, lr 1.000000e-06
Finished epoch 5 / 10: cost 2.302517, train: 0.158000, val 0.171000, lr 1.000000e-06
Finished epoch 6 / 10: cost 2.302518, train: 0.179000, val 0.172000, lr 1.000000e-06
Finished epoch 7 / 10: cost 2.302466, train: 0.180000, val 0.176000, lr 1.000000e-06
Finished epoch 8 / 10: cost 2.302452, train: 0.175000, val 0.185000, lr 1.000000e-06
Finished epoch 9 / 10: cost 2.302459, train: 0.206000, val 0.192000, lr 1.000000e-06
Finished epoch 10 / 10 cost 2.302420 train: 0.190000, val 0.192000, lr 1.000000e-06
finished optimization. best validation accuracy: 0.192000
```

```
model = init two layer model(32*32*3, 50, 10) # input size, hidden size, number of classes
trainer = ClassifierTrainer()
best model, stats = trainer.train(X train, y train, X val, y val,
                                  model, two layer net,
                                  num_epochs=10, reg=0.000001,
                                  update='sgd', tearning rate decay=1,
                                  sample batches - True,
                                  learning rate=le-6, verbose=True)
Finished epoch 1 / 10: cost 2.302576, train: 0.080000, val 0.103000, lr 1.000000e-06
Finished epoch 2 / 10: cost 2.302582, train: 0.121000, val 0.124000, lr 1.000000e-06
Finished epoch 3 / 10: cost 2.302558, train: 0.119000, val 0.138000, lr 1.000000e-06
Finished epoch 4 / 10: cost 2.302519, train: 0.127000, val 0.151000, lr 1.000000e-06
Finished epoch 5 / 10: cost 2.302517, train: 0.158000, val 0.171000, lr 1.000000e-06
Finished epoch 6 / 10: cost 2.302518, train: 0.179000, val 0.172000, lr 1.000000e-06
Finished epoch 7 / 10: cost 2.302466, train: 0.180000, val 0.176000, lr 1.000000e-06
Finished epoch 8 / 10: cost 2.302452, train: 0.175000, val 0.185000, lr 1.000000e-06
Finished epoch 9 / 10: cost 2.302459, train: 0.206000, val 0.192000, lr 1.000000e-06
Finished epoch 10 / 10 cost 2.302420 train: 0.190000, val 0.192000, lr 1.000000e-06
finished optimization. best validation accuracy: 0.192000
```

Loss barely changes

(learning rate is too low or regularization too high)

Slide: Andrej Karpathy

```
model = init two layer model(32*32*3, 50, 10) # input size, hidden size, number of classes
trainer = ClassifierTrainer()
best model, stats = trainer.train(X train, y train, X val, y val,
                                  model, two_layer_net,
                                  num_epochs=10, reg=0.000001,
                                  update='sgd', learning rate decay=1,
                                  sample batches - True,
                                  learning rate=le-6, verbose=True)
Finished epoch 1 / 10: cost 2.302576, train: 0.080000, val 0.103000, lr 1.000000e-06
Finished epoch 2 / 10: cost 2.302582, train: 0.121000, val 0.124000, lr 1.000000e-06
Finished epoch 3 / 10: cost 2.302558, train: 0.119000, val 0.138000, lr 1.000000e-06
Finished epoch 4 / 10: cost 2.302519, train: 0.127000, val 0.151000, lr 1.000000e-06
Finished epoch 5 / 10: cost 2.302517, train: 0.158000, val 0.171000, lr 1.000000e-06
Finished epoch 6 / 10: cost 2.302518, train: 0.179000, val 0.172000, lr 1.000000e-06
Finished epoch 7 / 10: cost 2.302466, train: 0.180000, val 0.176000, lr 1.000000e-06
Finished epoch 8 / 10: cost 2.302452, train: 0.175000, val 0.185000, lr 1.000000e-06
Finished epoch 9 / 10: cost 2.302459, train: 0.206000, val 0.192000, lr 1.000000e-06
Finished epoch 10 / 10 cost 2.302420 train: 0.190000, val 0.192000, lr 1.000000e-06
finished optimization. best validation accuracy: 0.192000
```

Loss barely changes

Why is the accuracy 20%?

(learning rate is too low or regularization too high)

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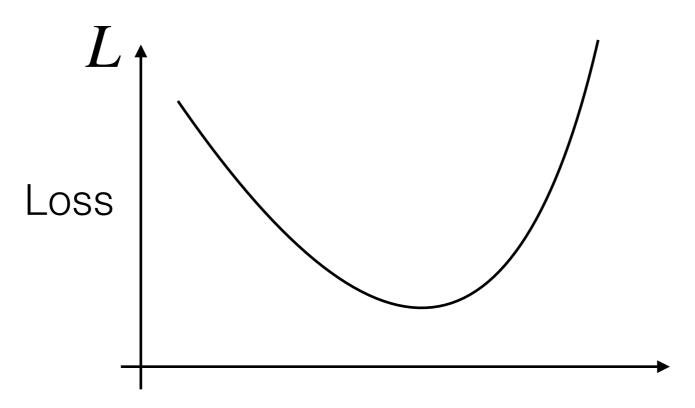
Learning rate: 1e6 — what could go wrong?

/home/karpathy/cs231n/code/cs231n/classifiers/neural_net.py:50: RuntimeWarning: divide by zero en countered in log

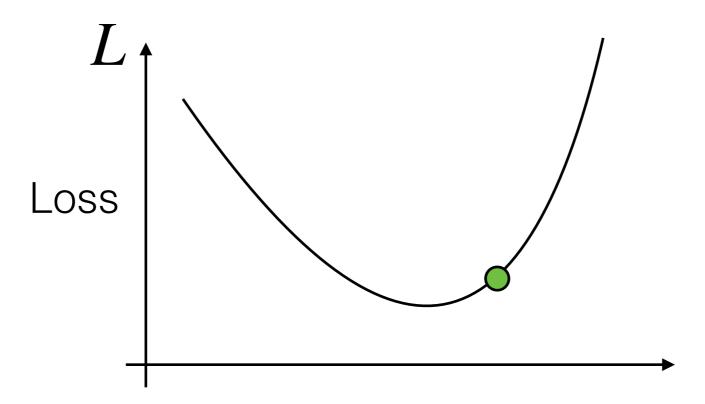
Learning rate: 1e6 — what could go wrong?

/home/karpathy/cs231n/code/cs231n/classifiers/neural_net.py:50: RuntimeWarning: divide by zero en countered in log

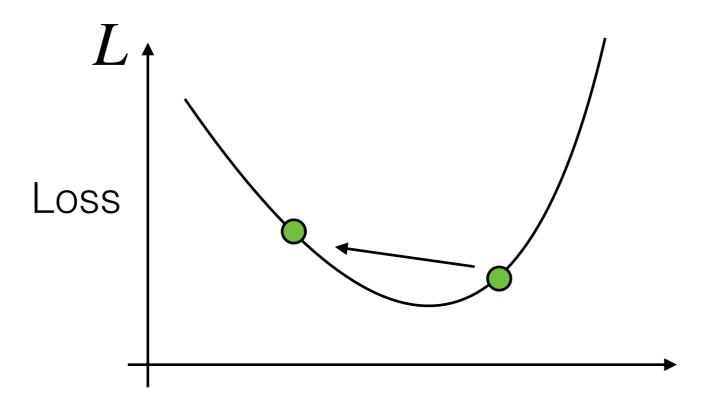
Loss is NaN —> learning rate is too high



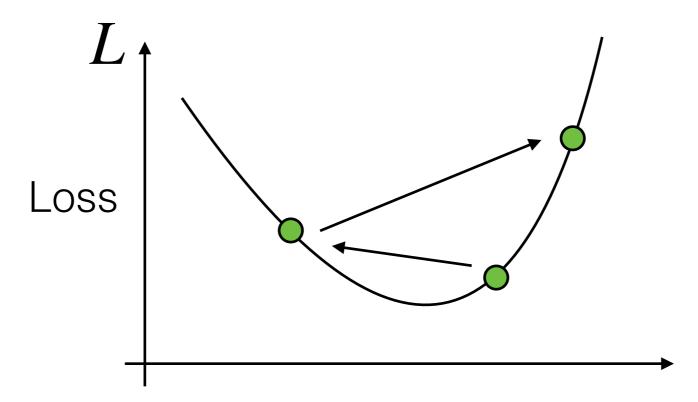
A weight somewhere in the network



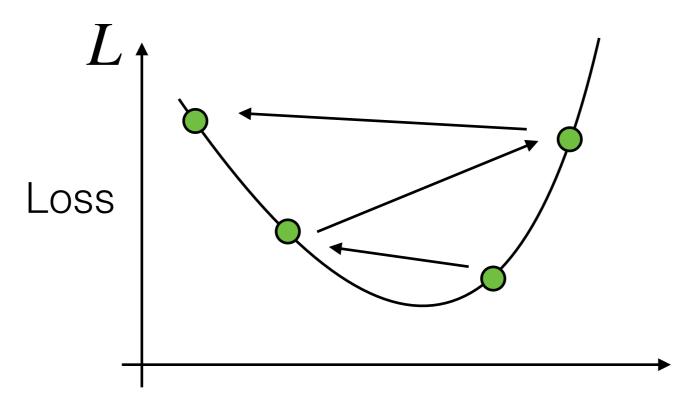
A weight somewhere in the network



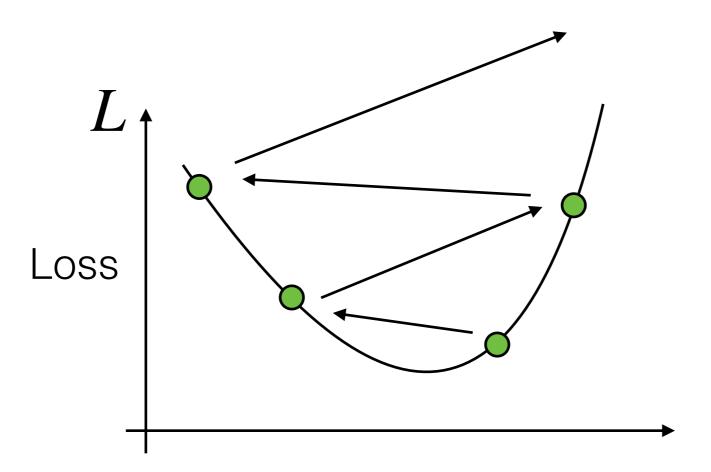
A weight somewhere in the network



A weight somewhere in the network



A weight somewhere in the network



A weight somewhere in the network

Learning rate: 3e-3

Learning rate: 3e-3

Learning rate: 3e-3

Loss is inf —> still too high

Learning rate: 3e-3

Loss is inf —> still too high

But now we know we should be searching the range [1e-3 ... 1e-5]

Coarse to fine search

First stage: only a few epochs (passes through the data) to get a rough idea

Coarse to fine search

First stage: only a few epochs (passes through the data) to get a rough idea

Second stage: longer running time, finer search

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Coarse to fine search

First stage: only a few epochs (passes through the data) to get a rough idea

Second stage: longer running time, finer search

Tip: if loss > 3 * original loss, quit early (learning rate too high)

```
max_count = 100

for count in xrange(max_count):
    reg = 10**uniform(-5, 5)
    lr = 10**uniform(-3, -6)

note it's best to optimize in log space
```

```
val_acc: 0.412000, lr: 1.405206e-04, reg: 4.793564e-01, (1 / 100)
val_acc: 0.214000, lr: 7.231888e-06, reg: 2.321281e-04, (2 / 100)
val_acc: 0.208000, lr: 2.119571e-06, reg: 8.011857e+01, (3 / 100)
val_acc: 0.196000, lr: 1.551131e-05, reg: 4.374936e-05, (4 / 100)
val_acc: 0.079000, lr: 1.753300e-05, reg: 1.200424e+03, (5 / 100)
val_acc: 0.223000, lr: 4.215128e-05, reg: 4.196174e+01, (6 / 100)
val_acc: 0.441000, lr: 1.750259e-04, reg: 2.110807e-04, (7 / 100)
val_acc: 0.241000, lr: 6.749231e-05, reg: 4.226413e+01, (8 / 100)
val_acc: 0.482000, lr: 4.296863e-04, reg: 6.642555e-01, (9 / 100)
val_acc: 0.079000, lr: 5.401602e-06, reg: 1.599828e+04, (10 / 100)
val_acc: 0.154000, lr: 1.618508e-06, reg: 4.925252e-01, (11 / 100)
```

Coarse to fine search

```
max count = 100
for count in xrange(max count):
                                                           note it's best to optimize in log space
     reg = 10**uniform(-5, 5)
     lr = 10**uniform(-3, -6)
     trainer = ClassifierTrainer()
     model = init two layer model(32*32*3, 50, 10) # input size, hidden size, number of classes
     trainer = ClassifierTrainer()
     best model local, stats = trainer.train(X train, y train, X val, y val,
                                      model, two layer net,
                                      num epochs=5, reg=reg,
                                      update='momentum', learning rate decay=0.9,
                                      sample batches = True, batch size = 100,
                                      learning rate=lr, verbose=False)
                   val acc: 0.412000, lr: 1.405206e-04, reg: 4.793564e-01, (1 / 100)
                   val acc: 0.214000, lr: 7.231888e-06, reg: 2.321281e-04, (2 / 100)
                   val acc: 0.208000, lr: 2.119571e-06, reg: 8.011857e+01, (3 / 100)
                   val acc: 0.196000, lr: 1.551131e-05, reg: 4.374936e-05, (4 / 100)
                   val acc: 0.079000, lr: 1.753300e-05, reg: 1.200424e+03, (5 / 100)
                   val acc: 0.223000, lr: 4.215128e-05, reg: 4.196174e+01, (6 / 100)
                   val acc: 0.441000, lr: 1.750259e-04, reg: 2.110807e-04, (7 / 100)
                   val acc: 0.241000, lr: 6.749231e-05, reg: 4.226413e+01, (8 / 100)
                   val acc: 0.482000, lr: 4.296863e-04, reg: 6.642555e-01, (9 / 100)
                   val acc: 0.079000, lr: 5.401602e-06, reg: 1.599828e+04, (10 / 100)
                   val acc: 0.154000, lr: 1.618508e-06, reg: 4.925252e-01, (11 / 100)
```

Slide: Andrej Karpathy

```
max_count = 100
for count in xrange(max_count):
    reg = 10**uniform(-5, 5)
    lr = 10**uniform(-3, -6)
```

```
max_count = 100
for count in xrange(max_count):
    reg = 10**uniform(-5, 5)
    lr = 10**uniform(-3, -6)
adjust range
```

```
max_count = 100
for count in xrange(max_count):
    reg = 10**uniform(-5, 5)
    lr = 10**uniform(-3, -6)
```

```
adjust range
```

```
max_count = 100
for count in xrange(max_count):
    reg = 10**uniform(-4, 0)
    lr = 10**uniform(-3, -4)
```

Coarse to fine search

max count = 100

```
adjust range
for count in xrange(max count):
      reg = 10**uniform(-5, 5)
      lr = 10**uniform(-3, -6)
   val acc: 0.527000, lr: 5.340517e-04, reg: 4.097824e-01, (0 / 100)
   val acc: 0.492000, lr: 2.279484e-04, reg: 9.991345e-04, (1 / 100)
   val acc: 0.512000, lr: 8.680827e-04, reg: 1.349727e-02, (2 / 100)
   val acc: 0.461000, lr: 1.028377e-04, reg: 1.220193e-02, (3 / 100)
   val acc: 0.460000, lr: 1.113730e-04, reg: 5.244309e-02, (4 / 100)
   val acc: 0.498000, lr: 9.477776e-04, reg: 2.001293e-03, (5 / 100)
   val acc: 0.469000, lr: 1.484369e-04, reg: 4.328313e-01, (6 / 100)
   val acc: 0.522000, lr: 5.586261e-04, reg: 2.312685e-04, (7 / 100)
   val acc: 0.530000, lr: 5.808183e-04, reg: 8.259964e-02, (8 / 100)
   val acc: 0.489000, lr: 1.979168e-04, reg: 1.010889e-04, (9 / 100)
   val acc: 0.490000, lr: 2.036031e-04, reg: 2.406271e-03, (10 / 100)
   val acc: 0.475000, lr: 2.021162e-04, reg: 2.287807e-01, (11 / 100)
   val acc: 0.460000, lr: 1.135527e-04, reg: 3.905040e-02, (12 / 100)
   val acc: 0.515000, lr: 6.947668e-04, reg: 1.562808e-02, (13 / 100)
   val acc: 0.531000, lr: 9.471549e-04, reg: 1.433895e-03, (14 / 100)
   val acc: 0.509000, lr: 3.140888e-04, reg: 2.857518e-01, (15 / 100)
   val acc: 0.514000, lr: 6.438349e-04, reg: 3.033781e-01, (16 / 100)
   val acc: 0.502000, lr: 3.921784e-04, reg: 2.707126e-04, (17 / 100)
   val acc: 0.509000, lr: 9.752279e-04, reg: 2.850865e-03, (18 / 100)
   val acc: 0.500000, lr: 2.412048e-04, reg: 4.997821e-04, (19 / 100)
   val acc: 0.466000, lr: 1.319314e-04, reg: 1.189915e-02, (20 / 100)
   val acc: 0.516000, lr: 8.039527e-04, reg: 1.528291e-02, (21 / 100)
```

```
max count = 100
for count in xrange(max count):
      reg = 10**uniform(-4, 0)
      lr = 10**uniform(-3, -4)
```

Coarse to fine search

max count = 100

```
adjust range
                                                                            max count = 100
for count in xrange(max count):
                                                                            for count in xrange(max count):
      reg = 10**uniform(-5, 5)
                                                                                  reg = 10**uniform(-4, 0)
      lr = 10**uniform(-3, -6)
                                                                                  lr = 10**uniform(-3, -4)
   val acc: 0.527000, lr: 5.340517e-04, reg: 4.097824e-01, (0 / 100)
   val acc: 0.492000, lr: 2.279484e-04, reg: 9.991345e-04, (1 / 100)
   val acc: 0.512000, lr: 8.680827e-04, reg: 1.349727e-02, (2 / 100)
   val acc: 0.461000, lr: 1.028377e-04, reg: 1.220193e-02, (3 / 100)
   val acc: 0.460000, lr: 1.113730e-04, reg: 5.244309e-02, (4 / 100)
   val acc: 0.498000, lr: 9.477776e-04, reg: 2.001293e-03, (5 / 100)
   val acc: 0.469000, lr: 1.484369e-04, reg: 4.328313e-01, (6 / 100)
   val acc: 0.522000, lr: 5.586261e-04, reg: 2.312685e-04, (7 / 100)
   val acc: 0.530000, lr: 5.808183e-04, reg: 8.259964e-02, (8 / 100)
   val acc: 0.489000, lr: 1.979168e-04, reg: 1.010889e-04, (9 / 100)
   val acc: 0.490000, lr: 2.036031e-04, reg: 2.406271e-03, (10 / 100)
   val acc: 0.475000, lr: 2.021162e-04, reg: 2.287807e-01, (11 / 100)
   val acc: 0.460000, lr: 1.135527e-04, reg: 3.905040e-02, (12 / 100)
   val acc: 0.515000, lr: 6.947668e-04, reg: 1.562808e-02, (13 / 100)
                                                                                  53%
   val acc: 0.531000, lr: 9.471549e-04, reg: 1.433895e-03, (14 / 100)
   val acc: 0.509000, lr: 3.140888e-04, reg: 2.857518e-01, (15 / 100)
   val acc: 0.514000, lr: 6.438349e-04, reg: 3.033781e-01, (16 / 100)
   val acc: 0.502000, lr: 3.921784e-04, reg: 2.707126e-04, (17 / 100)
   val acc: 0.509000, lr: 9.752279e-04, reg: 2.850865e-03, (18 / 100)
   val acc: 0.500000, lr: 2.412048e-04, reg: 4.997821e-04, (19 / 100)
   val acc: 0.466000, lr: 1.319314e-04, reg: 1.189915e-02, (20 / 100)
   val acc: 0.516000, lr: 8.039527e-04, reg: 1.528291e-02, (21 / 100)
```

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Coarse to fine search

max count = 100

```
adjust range
                                                                          max count = 100
for count in xrange(max count):
                                                                          for count in xrange(max count):
      reg = 10**uniform(-5, 5)
                                                                                reg = 10**uniform(-4, 0)
     lr = 10**uniform(-3, -6)
                                                                                lr = 10**uniform(-3, -4)
   val acc: 0.527000, lr: 5.340517e-04, reg: 4.097824e-01, (0 / 100)
   val acc: 0.492000, lr: 2.279484e-04, reg: 9.991345e-04, (1 / 100)
   val acc: 0.512000, lr: 8.680827e-04, reg: 1.349727e-02, (2 / 100)
                                                                            Remember this is
   val acc: 0.461000, lr: 1.028377e-04, reg: 1.220193e-02, (3 / 100)
   val acc: 0.460000, lr: 1.113730e-04, reg: 5.244309e-02, (4 / 100)
                                                                          just a 2 layer neural
   val acc: 0.498000, lr: 9.477776e-04, reg: 2.001293e-03, (5 / 100)
   val acc: 0.469000, lr: 1.484369e-04, reg: 4.328313e-01, (6 / 100)
                                                                          net with 50 neurons
   val acc: 0.522000, lr: 5.586261e-04, reg: 2.312685e-04, (7 / 100)
   val acc: 0.530000, lr: 5.808183e-04, reg: 8.259964e-02, (8 / 100)
   val acc: 0.489000, lr: 1.979168e-04, reg: 1.010889e-04, (9 / 100)
   val acc: 0.490000, lr: 2.036031e-04, reg: 2.406271e-03, (10 / 100)
   val acc: 0.475000, lr: 2.021162e-04, reg: 2.287807e-01, (11 / 100)
   val acc: 0.460000, lr: 1.135527e-04, reg: 3.905040e-02, (12 / 100)
   val acc: 0.515000, lr: 6.947668e-04, reg: 1.562808e-02, (13 / 100)
                                                                                 53%
   val acc: 0.531000, lr: 9.471549e-04, reg: 1.433895e-03, (14 / 100)
   val acc: 0.509000, lr: 3.140888e-04, reg: 2.857518e-01, (15 / 100)
   val acc: 0.514000, lr: 6.438349e-04, reg: 3.033781e-01, (16 / 100)
   val acc: 0.502000, lr: 3.921784e-04, reg: 2.707126e-04, (17 / 100)
   val acc: 0.509000, lr: 9.752279e-04, reg: 2.850865e-03, (18 / 100)
   val acc: 0.500000, lr: 2.412048e-04, reg: 4.997821e-04, (19 / 100)
   val acc: 0.466000, lr: 1.319314e-04, reg: 1.189915e-02, (20 / 100)
   val acc: 0.516000, lr: 8.039527e-04, reg: 1.528291e-02, (21 / 100)
```

Slide: Andrej Karpathy

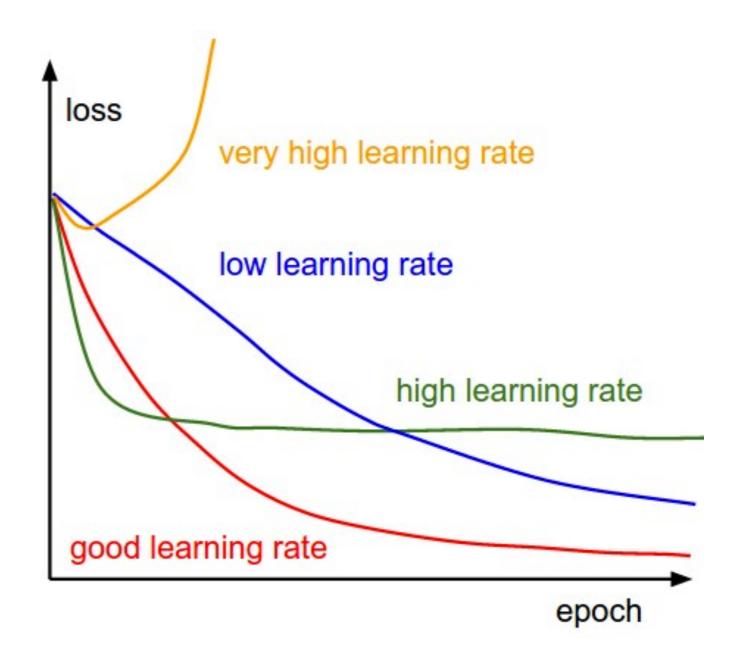
Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Plot the loss

Normally, you don't have the budget for lots of cross-validation —> visualize as you go

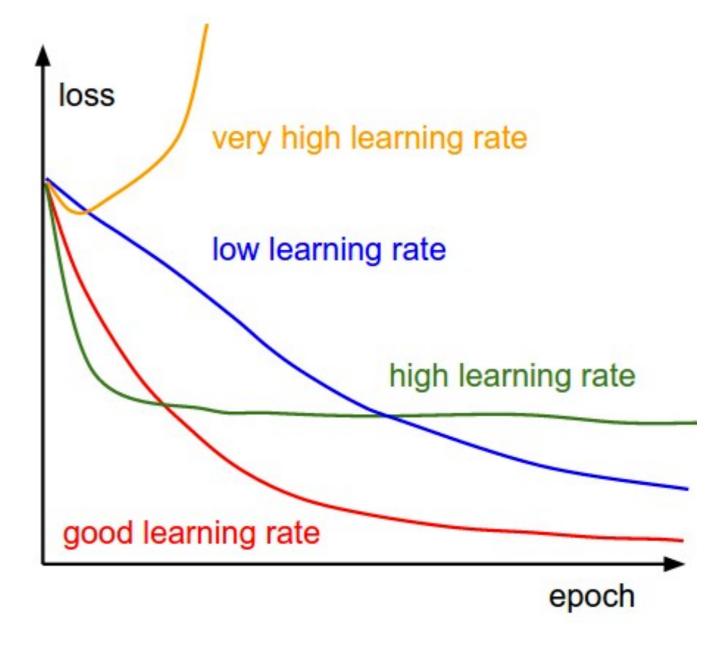
Plot the loss



Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Plot the loss

For very small learning rates, the loss decreases linearly and slowly

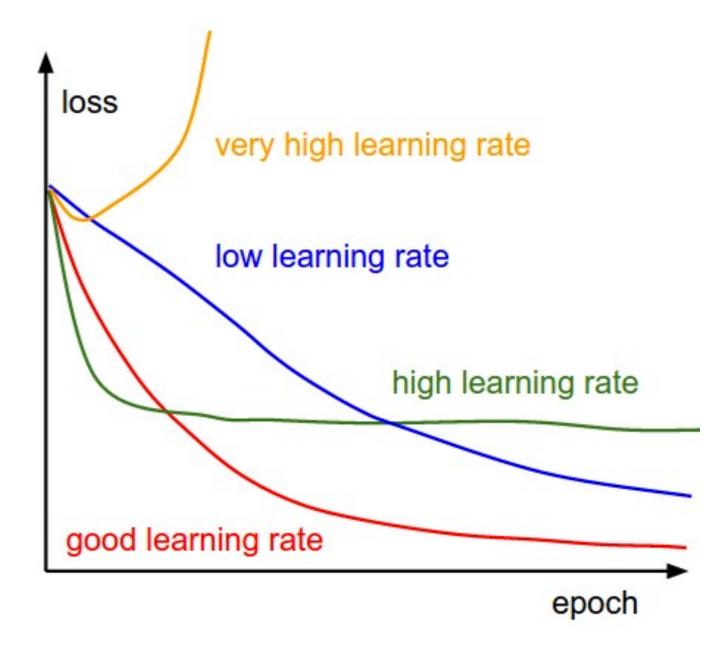


Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Plot the loss

For very small learning rates, the loss decreases linearly and slowly

(Why linearly?)



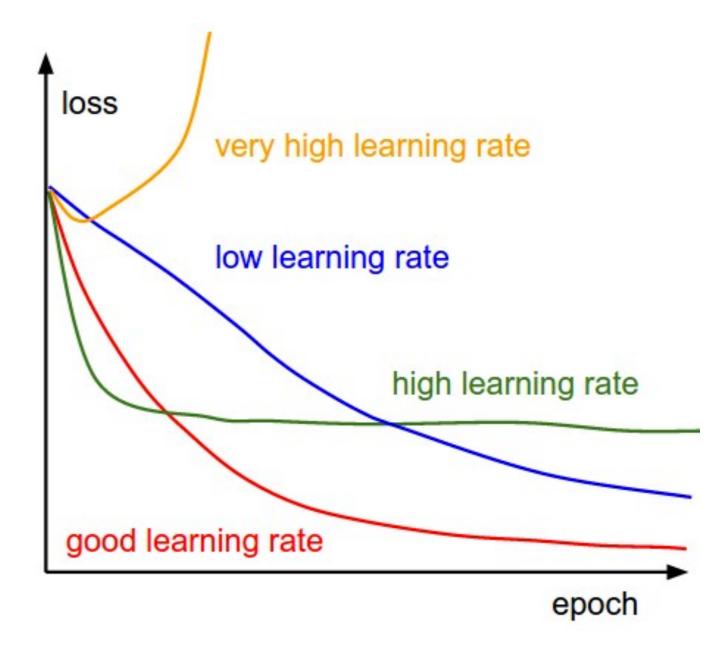
Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Plot the loss

For very small learning rates, the loss decreases linearly and slowly

(Why linearly?)

Larger learning rates tend to look more exponential



Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Typical training loss:

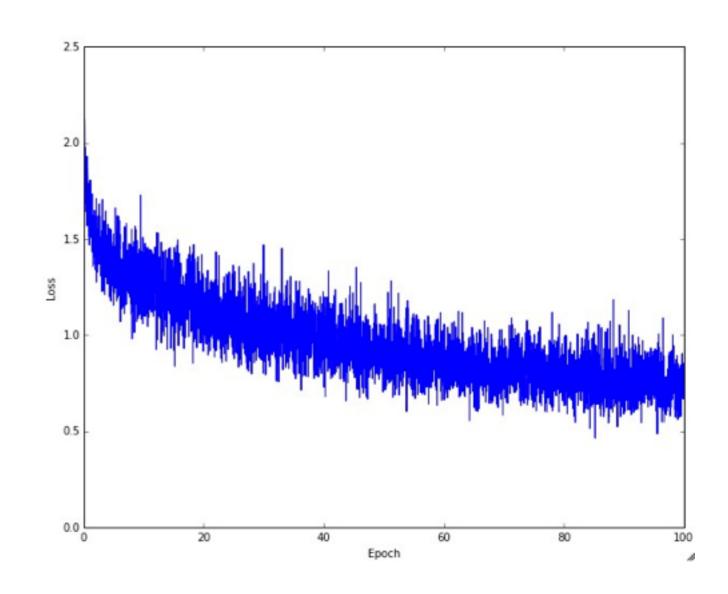


Figure: Andrej Karpathy

Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Typical training loss:

Why is it varying so rapidly?

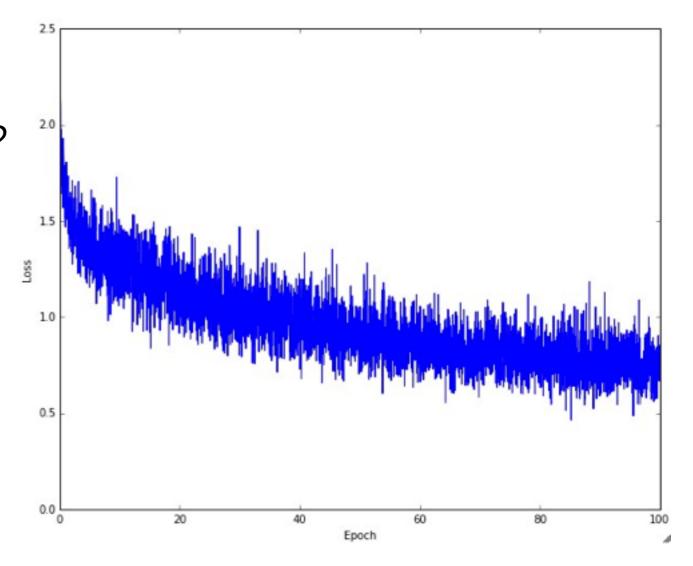


Figure: Andrej Karpathy

Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Typical training loss:

Why is it varying so rapidly?

The width of the curve is related to the batchsize — if too noisy, increase the batch size

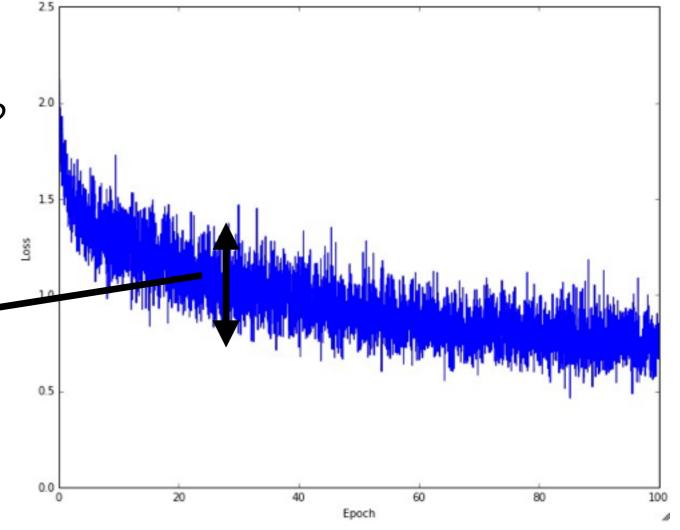


Figure: Andrej Karpathy

Normally, you don't have the budget for lots of cross-validation —> visualize as you go

Typical training loss:

Why is it varying so rapidly?

The width of the curve is related to the batchsize — if too noisy, increase the batch size

Possibly too linear (learning rate too small)

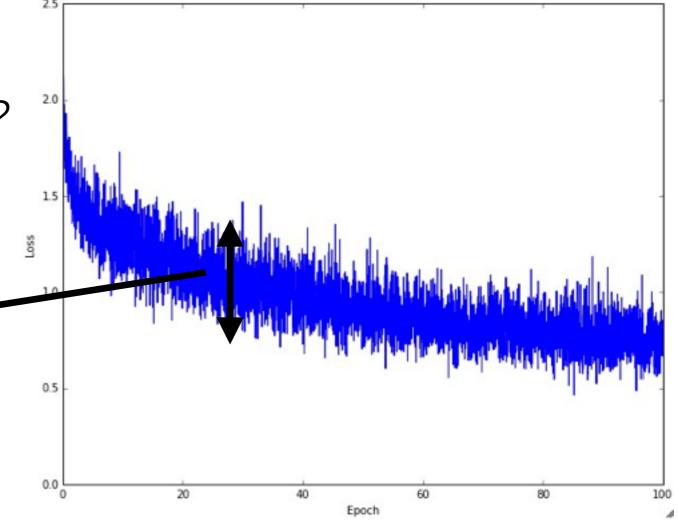
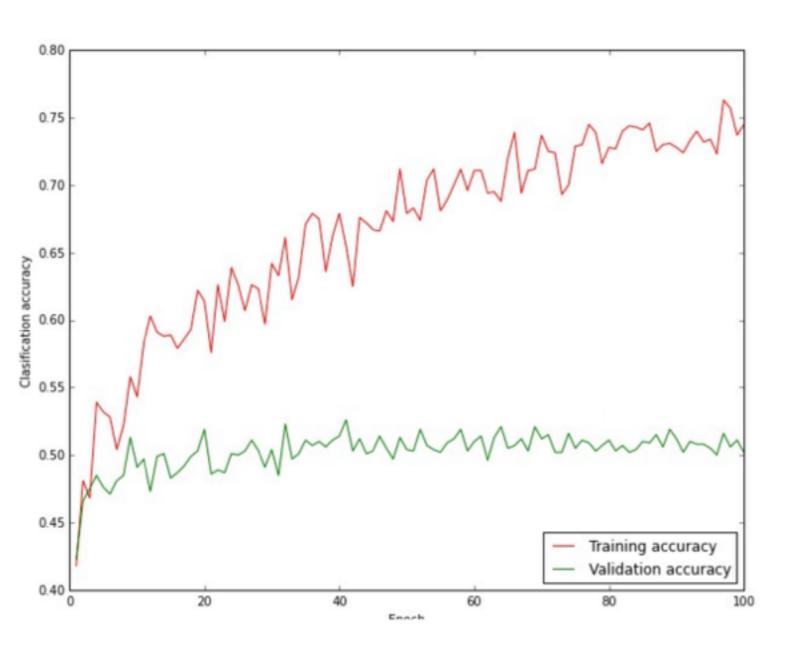
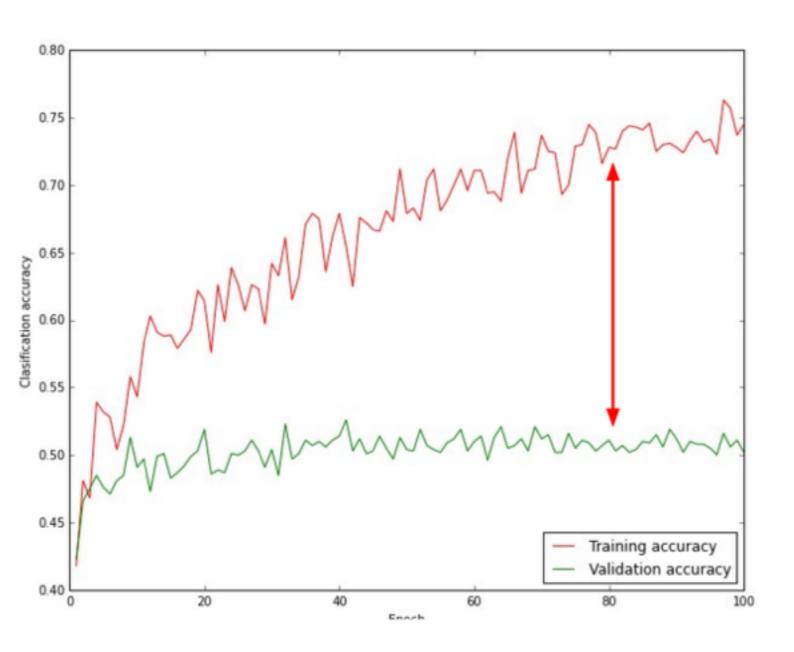


Figure: Andrej Karpathy

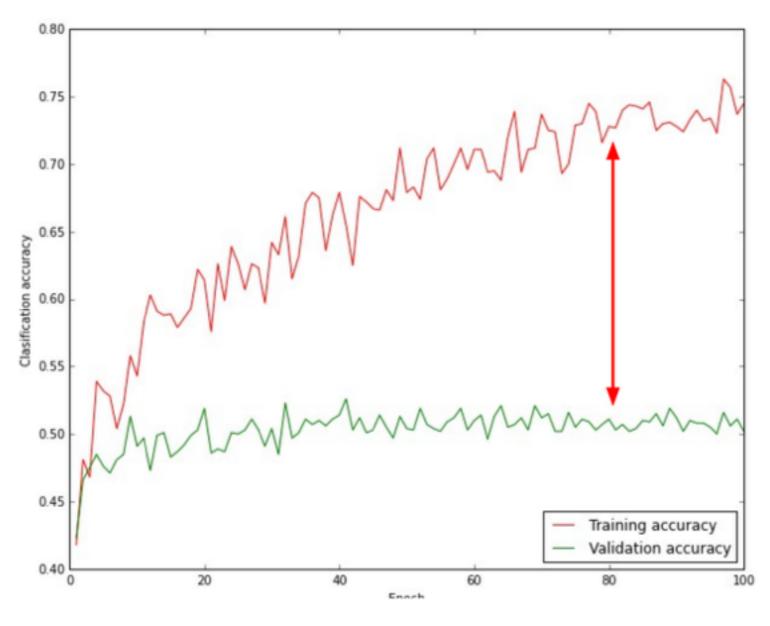
Visualize the accuracy



Visualize the accuracy

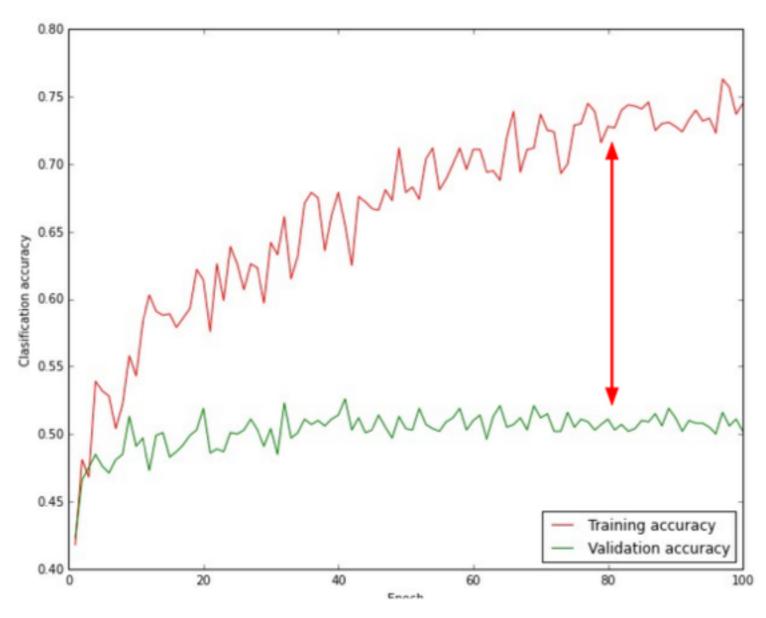


Visualize the accuracy



Big gap: overfitting (increase regularization)

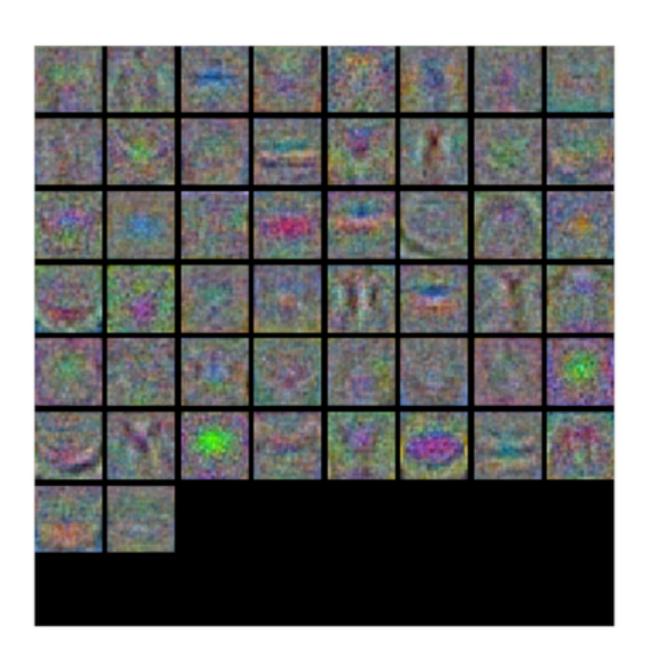
Visualize the accuracy



Big gap: overfitting (increase regularization)

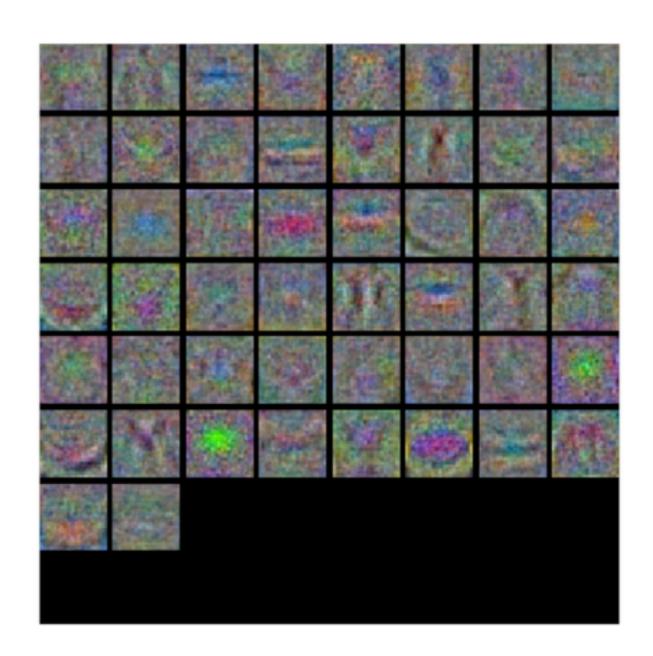
No gap: underfitting (increase model capacity, make layers bigger or decrease regularization)

Visualize the weights

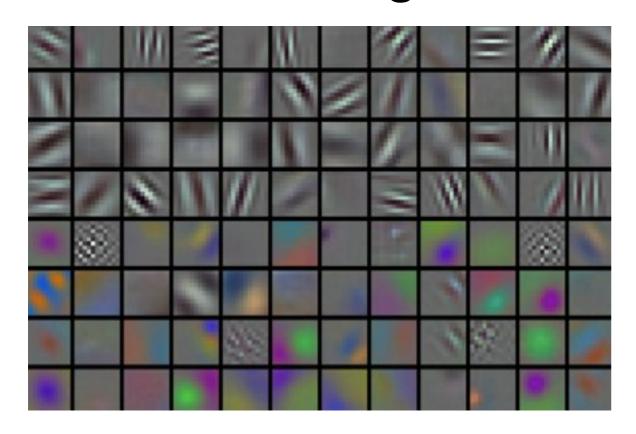


Visualize the weights

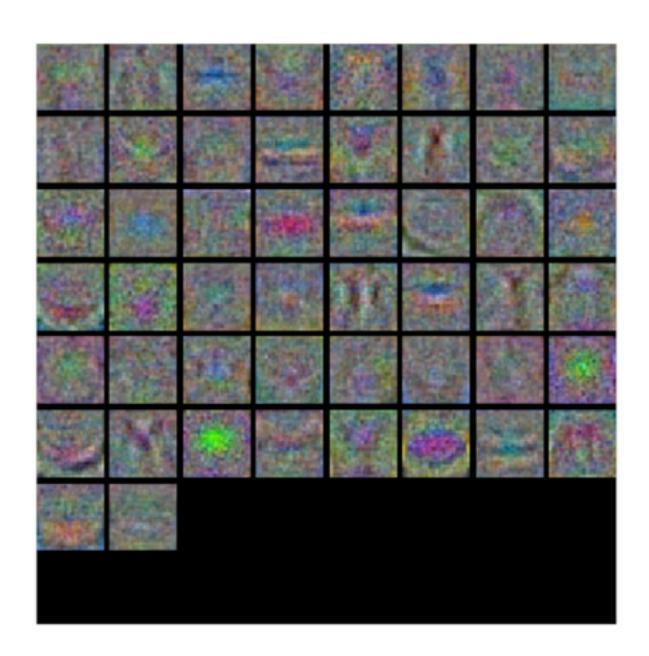
Noisy weights: possibly regularization not strong enough



Visualize the weights



Nice clean weights: training is proceeding well



Network architecture

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- Learning rate, decay schedule, update type

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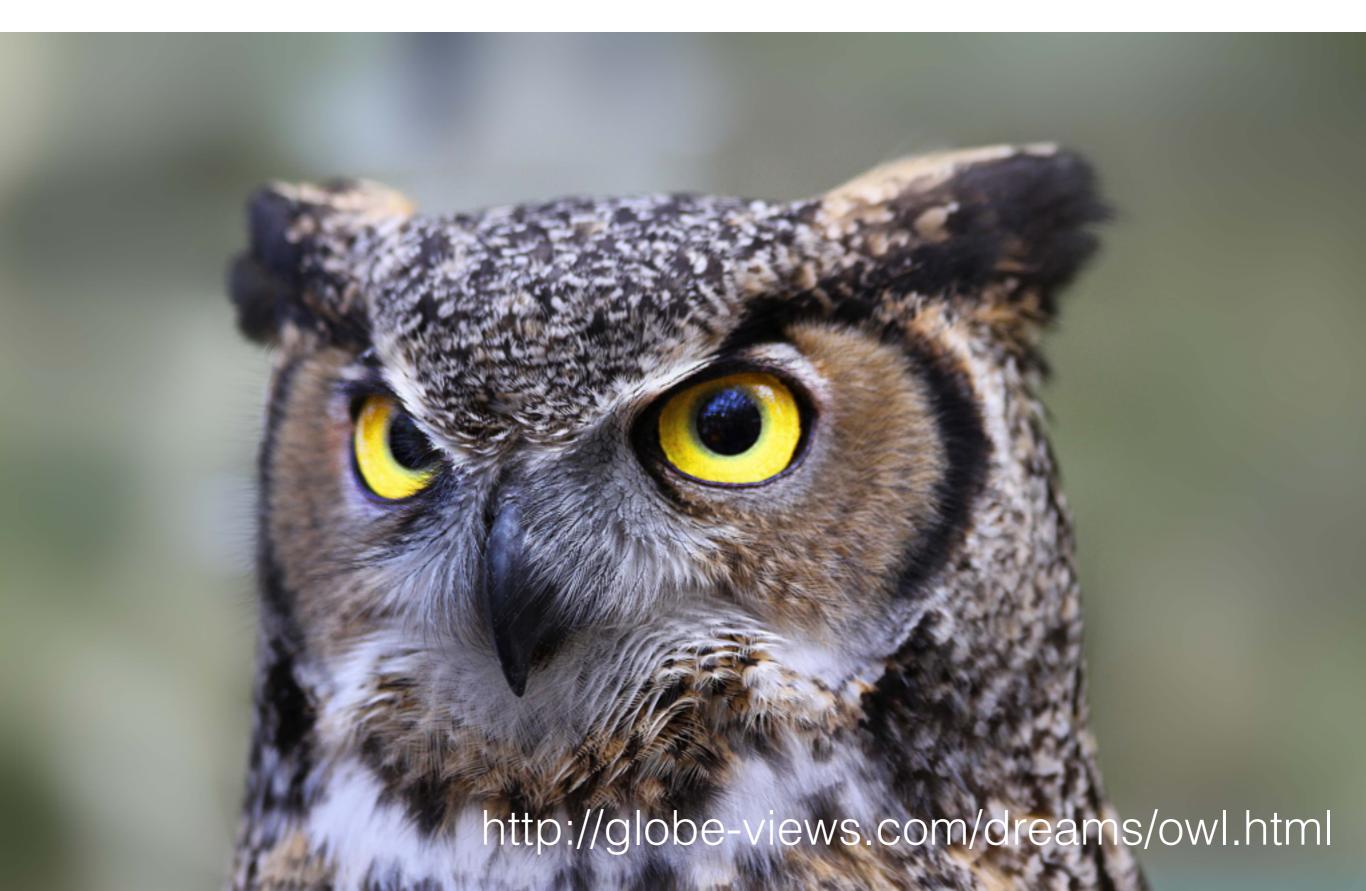
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Neural network parameters



Questions?

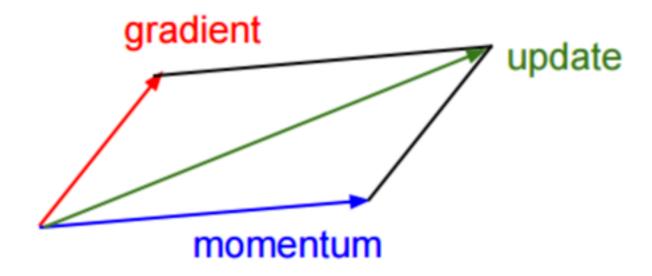
30s owl break



Tricks for making training work better

Simple but powerful improvement:

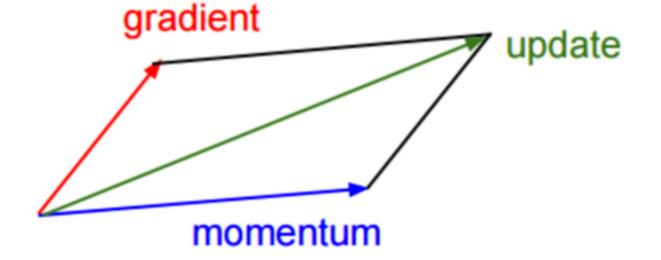
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$$v_{i+1} = 0.9v_i - \alpha \frac{\partial L}{\partial \theta} (\theta_i)$$

$$\theta_{i+1} = \theta_i + v_{i+1}$$

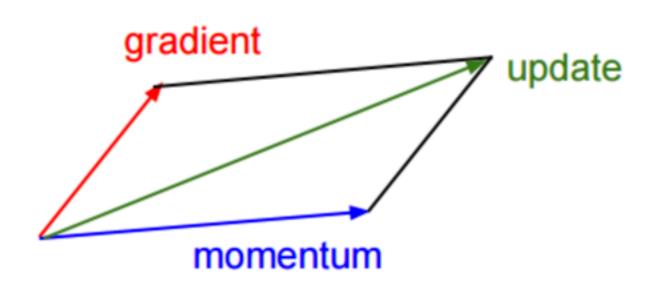


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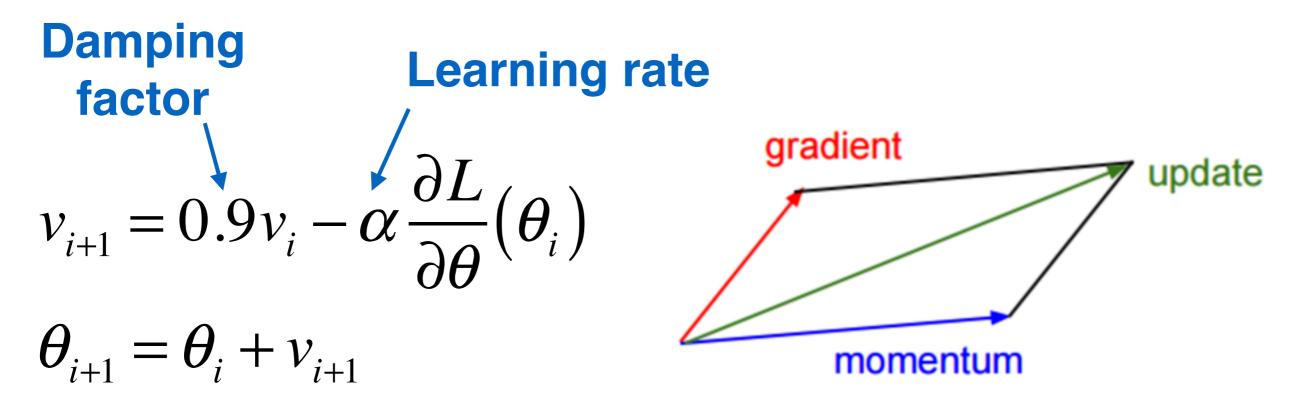
Give some "momentum" to the parameters

Damping factor $v_{i+1} = 0.9v_i - \alpha \frac{\partial L}{\partial \theta}(\theta_i)$

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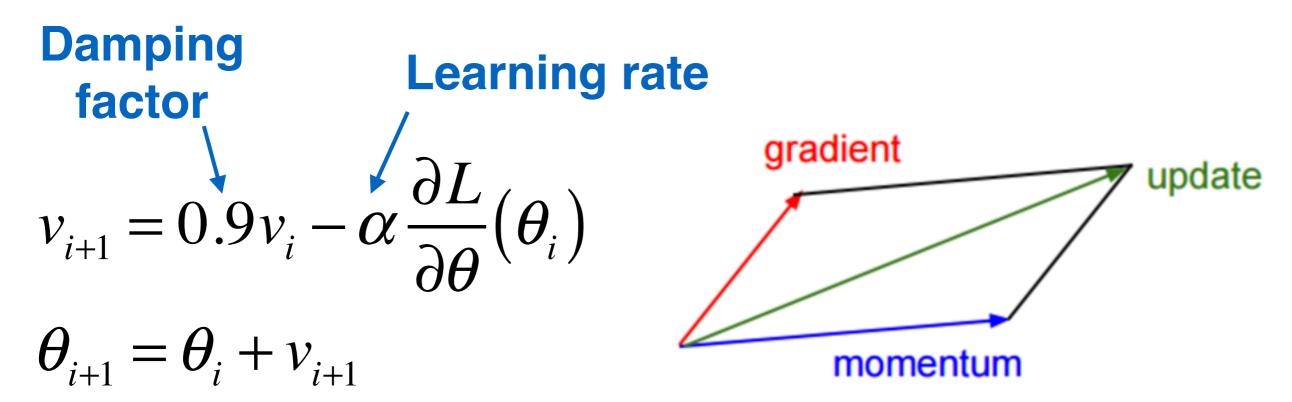


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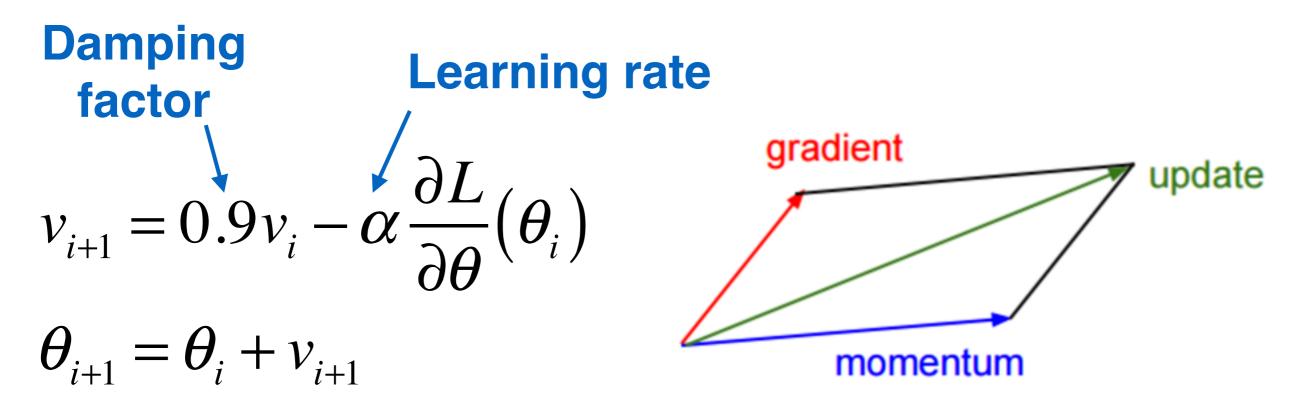
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Unfortunate nomenclature: the damping factor is called "momentum"

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Give some "momentum" to the parameters



Unfortunate nomenclature: the damping factor is called "momentum"

"Lesson from the trenches": well-tuned SGD with Momentum is very hard to beat for CNNs

Figure: Andrej Karpathy

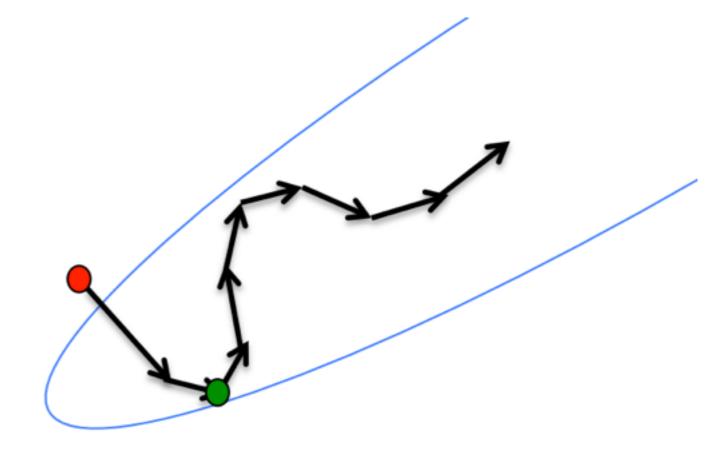
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- Imagine a ball on the loss surface (its position is the current weight settings)

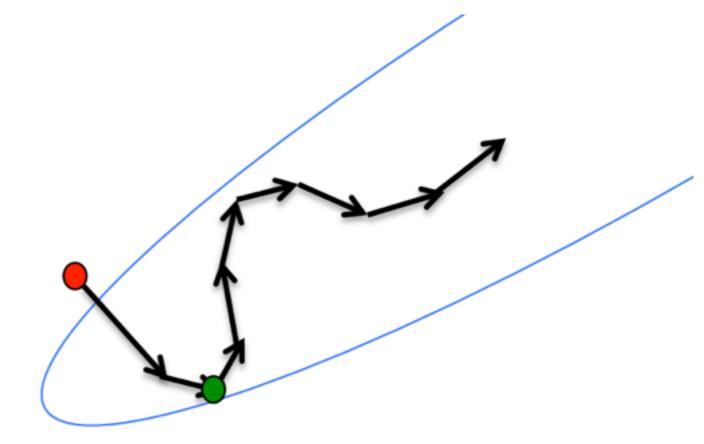
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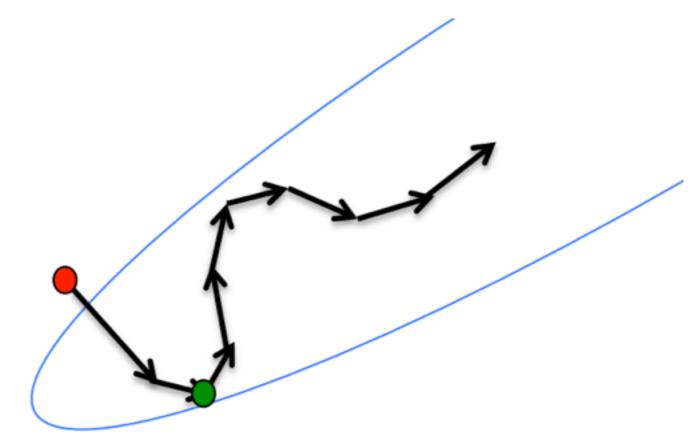
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Intuition behind momentum:

- Imagine a ball on the loss surface (its position is the current weight settings)
- Directions with lots of oscillations are damped
- Builds up speed in directions with a consistent gradient



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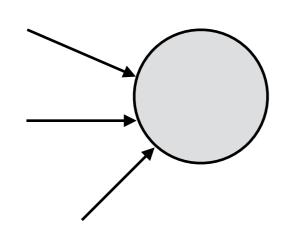
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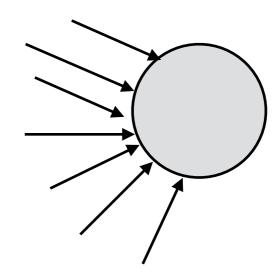
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decay_rate is a hyper-parameter (typically 0.9, 0.99, or 0.999)

Weight Initialization

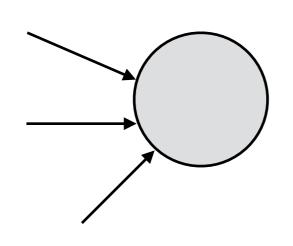
For deep nets, initialization is subtle and important:

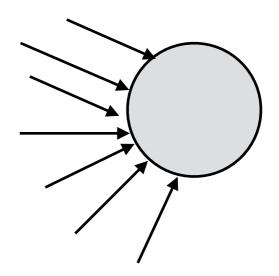




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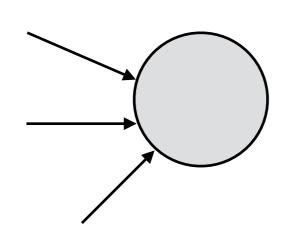


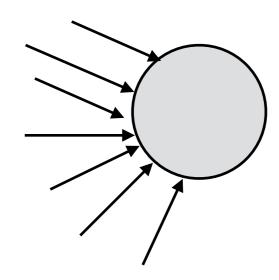
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```

For neural nets with ReLU, this will ensure all activations have the same variance

[He et al, "Delving Deep into Rectifiers:

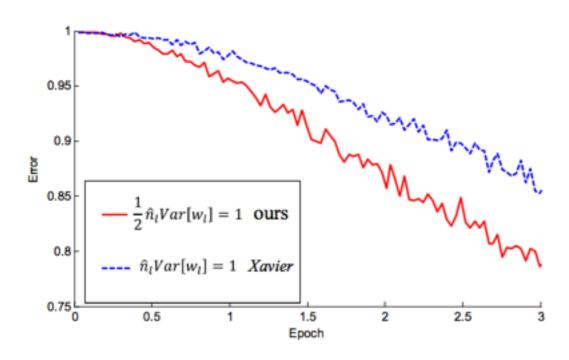
Surpassing Human-Level Performance on ImageNet Classification", arXiv 2015]

Initialization matters

Training can take much longer if not carefully initialized:

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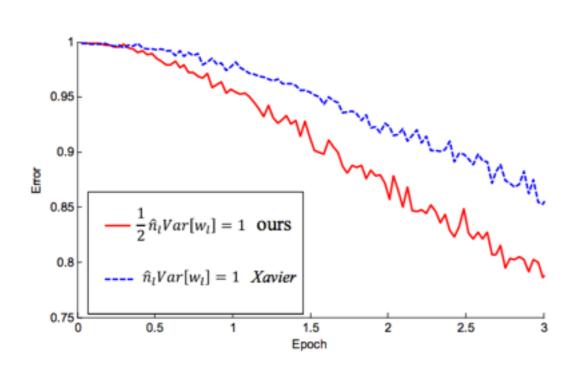
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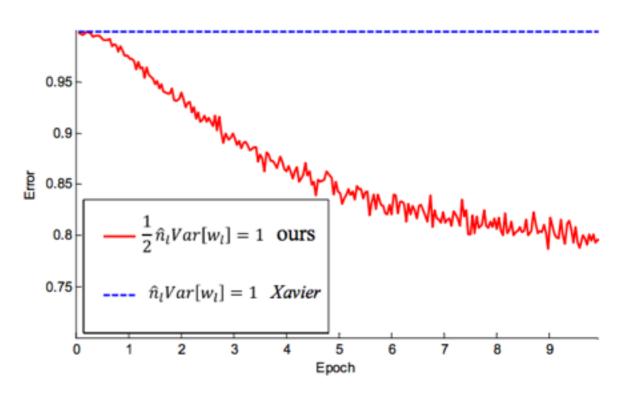
22 layer model

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22 layer model



30 layer model

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Max norm

Clamp weights to some max norm

$$||W||_2^2 \le c$$

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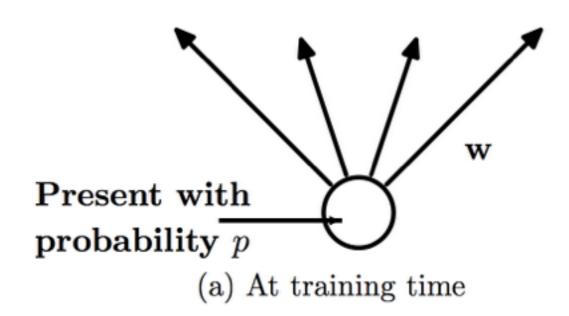
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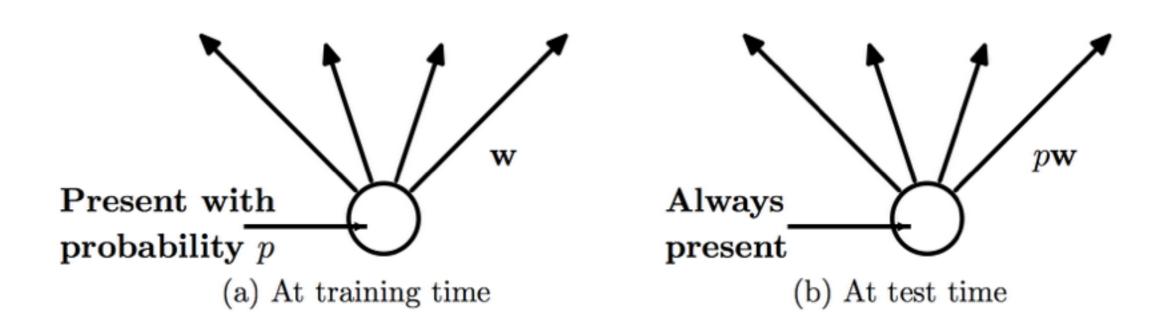
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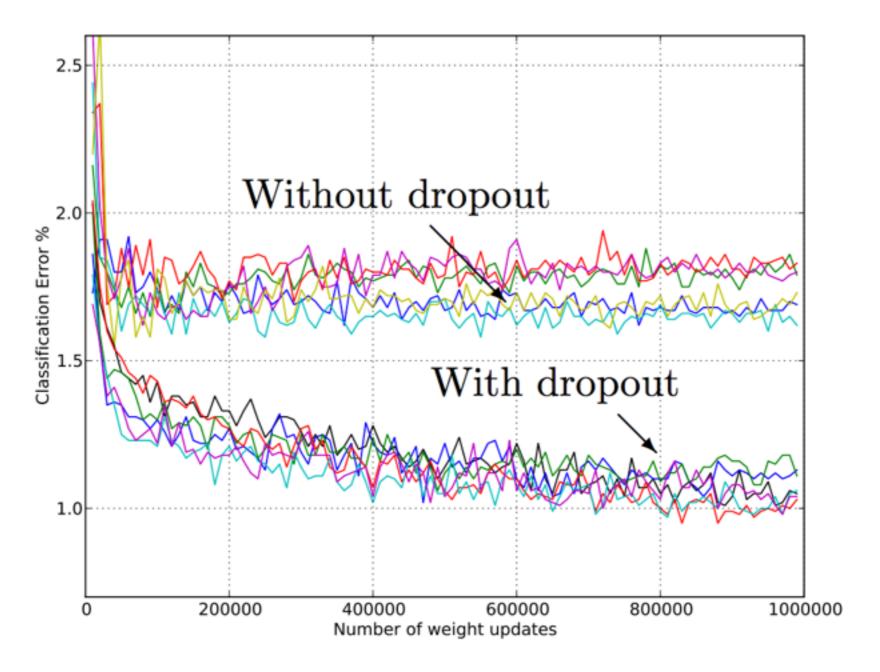
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Note: typically, biases are excluded from regularization

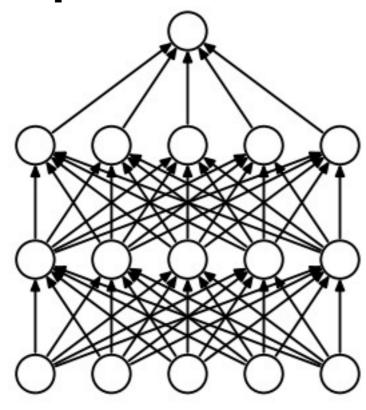
[Andrej Karpathy http://cs.stanford.edu/people/karpathy/convnetjs/demo/classify2d.html]



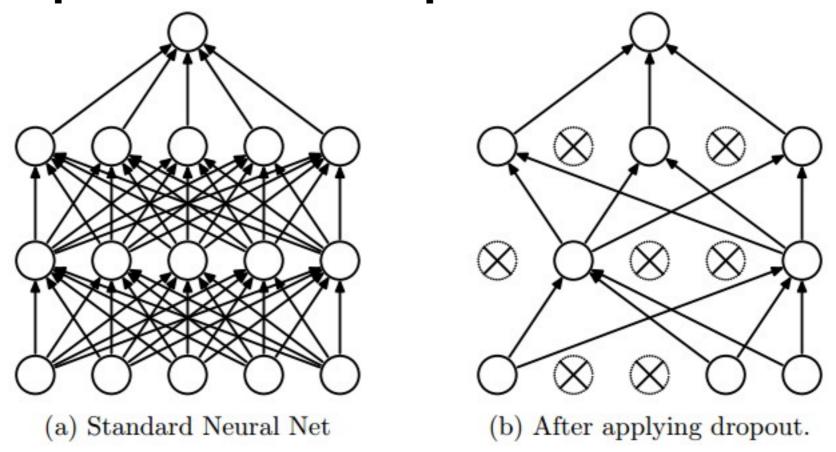




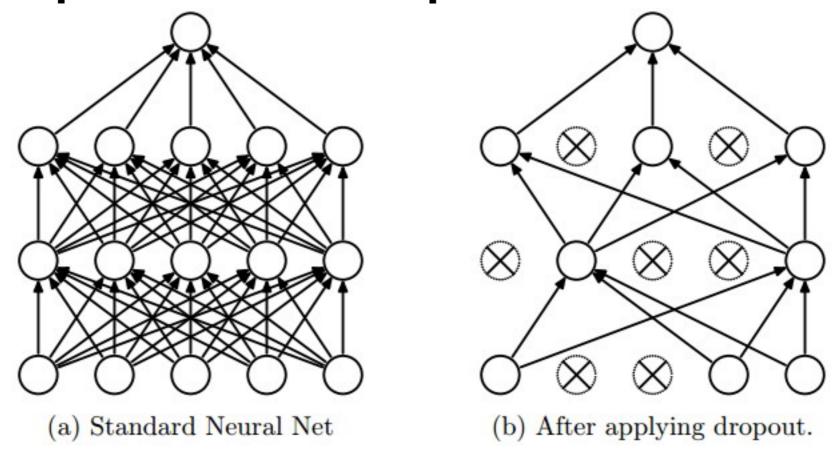
[Srivasta et al, "Dropout: A Simple Way to Prevent Neural Networks from Overfitting", JMLR 2014]



(a) Standard Neural Net



Simple but powerful technique to reduce overfitting:

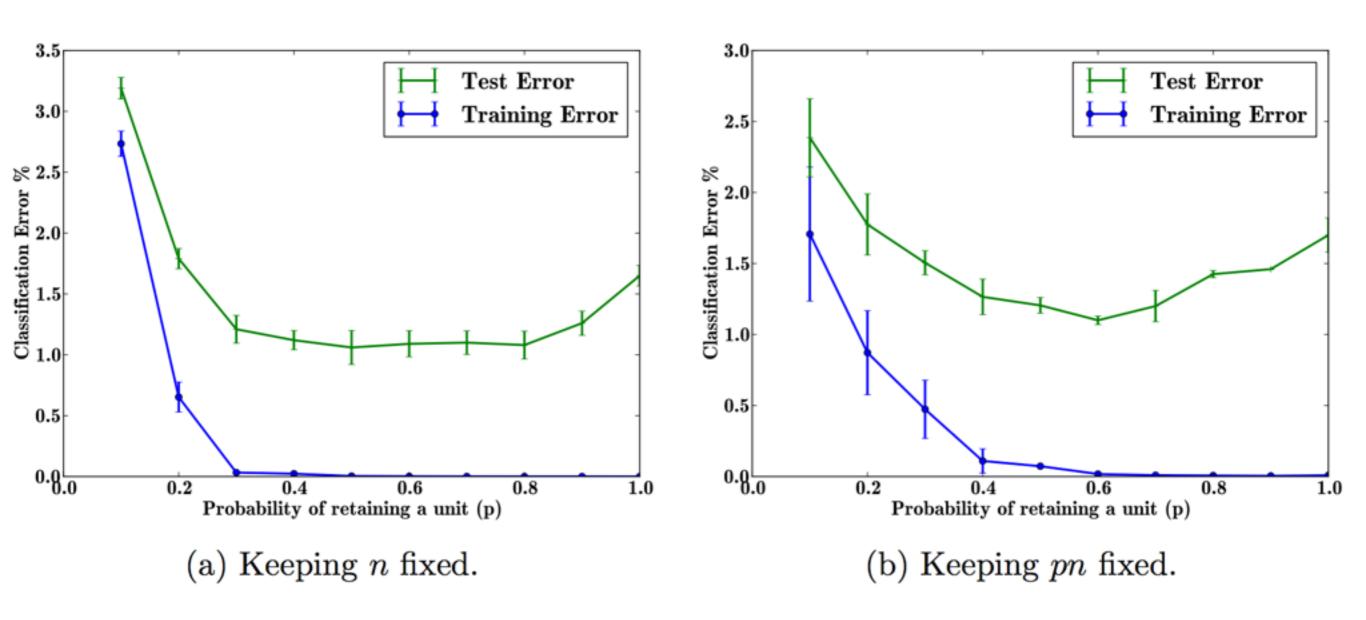


Note: Dropout can be interpreted as an approximation to taking the geometric mean of an ensemble of exponentially many models

[Srivasta et al, "Dropout: A Simple Way to Prevent Neural Networks from Overfitting", JMLR 2014]

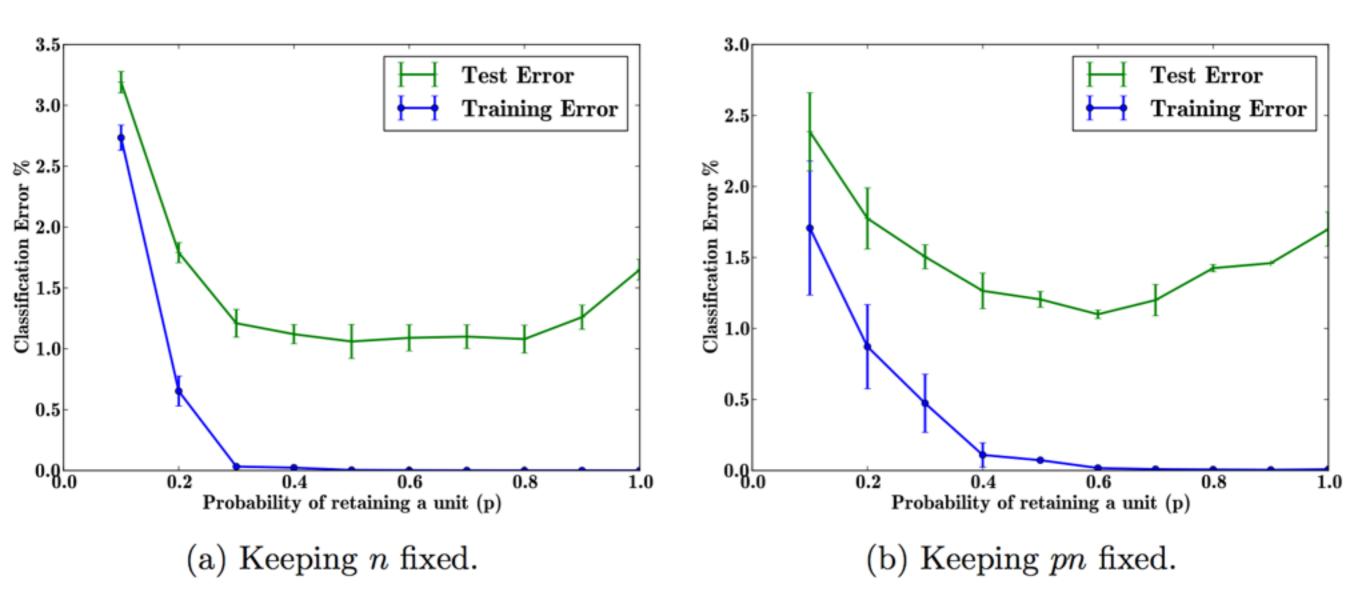
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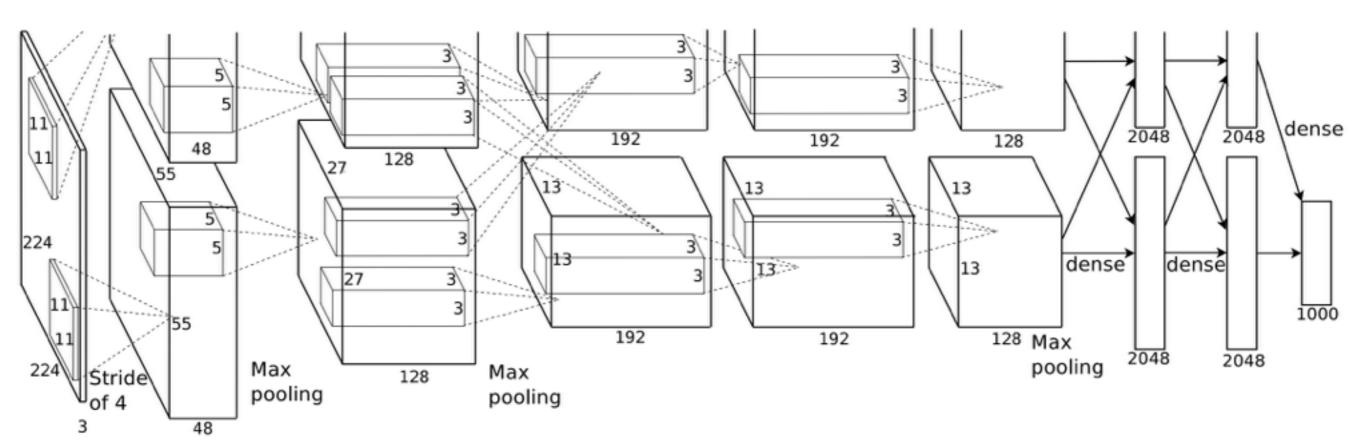
How much dropout? Around p = 0.5



[Srivasta et al, "Dropout: A Simple Way to Prevent Neural Networks from Overfitting", JMLR 2014]

Case study: [Krizhevsky 2012]

"Without dropout, our network exhibits substantial overfitting."

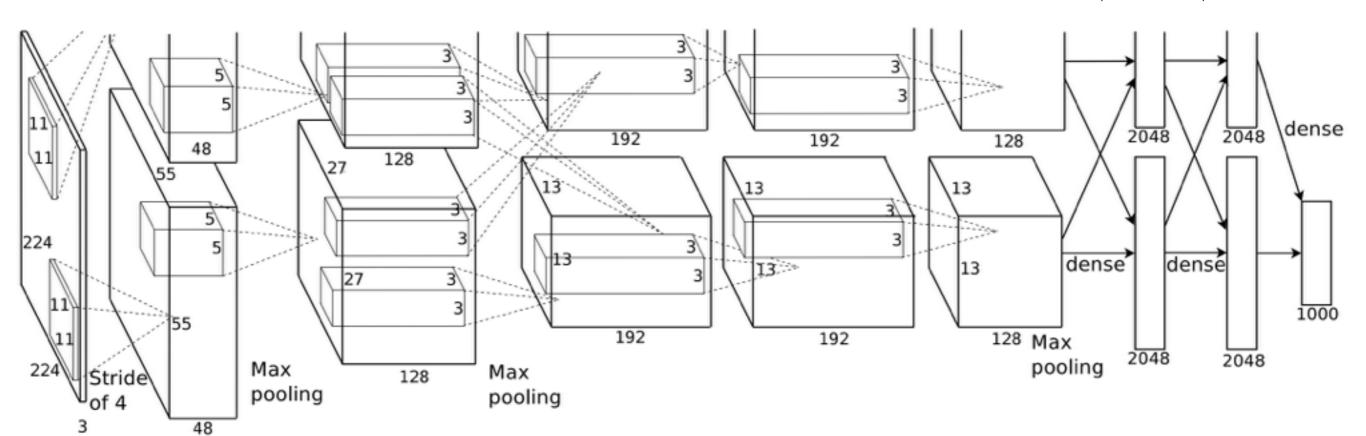


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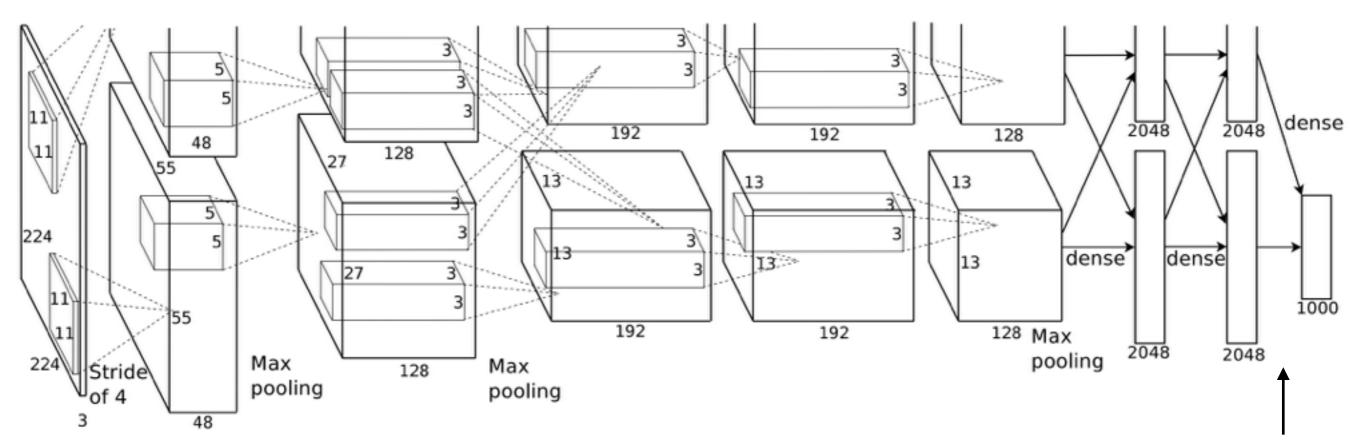


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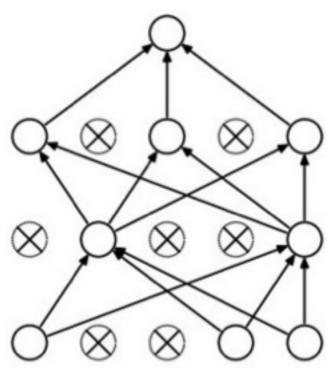


But not here — why?

[Krizhevsky et al, "ImageNet Classification with Deep Convolutional Neural Networks", NIPS 2012]

```
p = 0.5 # probability of keeping a unit active. higher = less dropout
def train_step(X):
  """ X contains the data """
  # forward pass for example 3-layer neural network
  H1 = np.maximum(0, np.dot(W1, X) + b1)
  U1 = np.random.rand(*H1.shape) 
  H1 *= U1 # drop!
  H2 = np.maximum(0, np.dot(W2, H1) + b2)
  U2 = np.random.rand(*H2.shape) < p # second dropout mask
 H2 *= U2 # drop!
  out = np.dot(W3, H2) + b3
  # backward pass: compute gradients... (not shown)
  # perform parameter update... (not shown)
```

Example forward pass with a 3- layer network using dropout



(note, here X is a single input)

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Expected value of a neuron h with dropout:

$$E[h] = ph + (1-p)0 = ph$$

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def predict(X):
    # ensembled forward pass
H1 = np.maximum(0, np.dot(W1, X) + b1) * p # NOTE: scale the activations
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We want to keep the same expected value

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 Step down by a factor of 0.1 every 50,000 mini-batches (used by SuperVision [Krizhevsky 2012])

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- Scale by exp(-t)

Hints for PA5

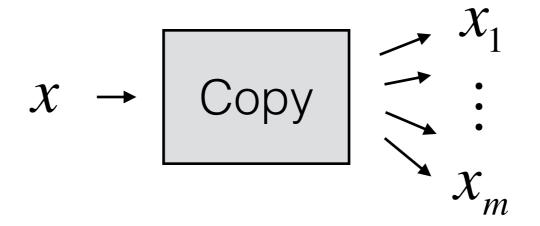
How does backprop work for shared parameters?

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Consider a "copy" layer that replicates its input:

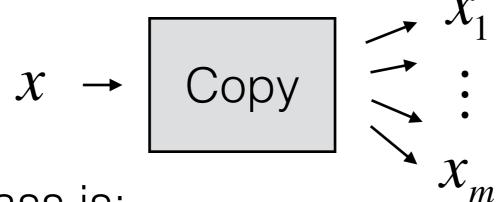
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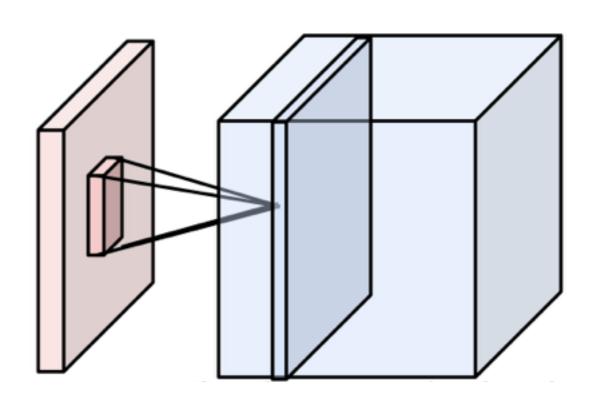
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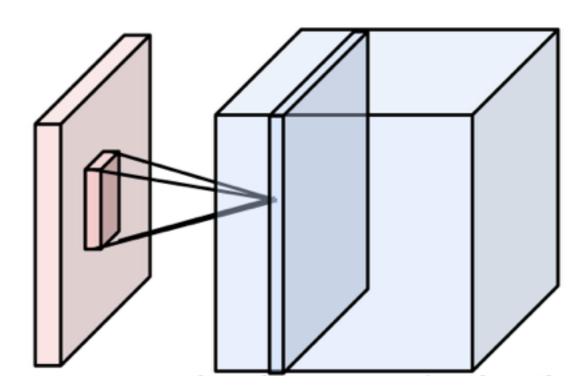
The backwards pass is:

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Thus, when values are shared, their gradients get added

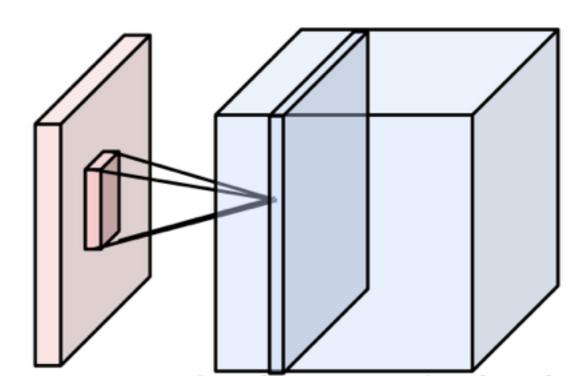


Backwards pass for convolution:



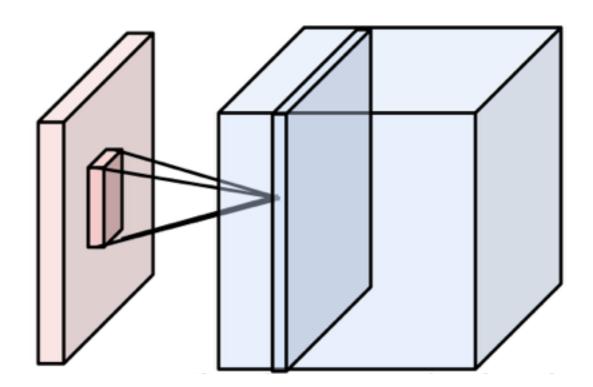
Backwards pass for convolution:

- Convolution has weight sharing across positions



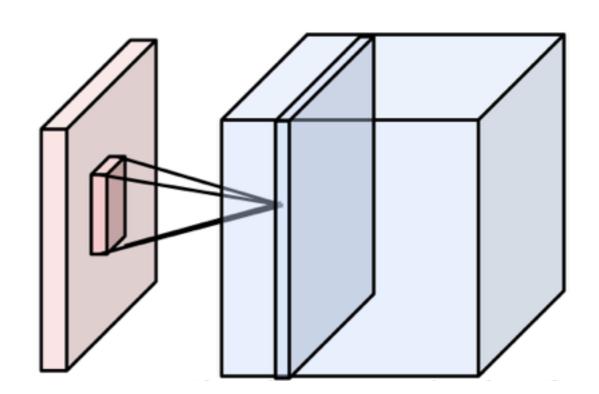
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Heads up: we *might* make the backwards pass of convolution required (not extra-credit)

