Friday 10 December 2004 2.5 hours

Problem 1: Filtering & Resampling (20 pts)

1. Consider an image consisting of a square of four adjacent white (pixel value = 1) pixels on a black (pixel value = 0) background:

What is the result of resampling this image to increase its resolution by a factor of $\frac{3}{2}$ using bilinear interpolation (that is, using a separable tent filter)? Assume that the upper left white pixel aligns exactly with a pixel in the resampled image. Compute your result by the separable filtering method, and give your answer as two arrays of numbers like the one above: one for the intermediate result and one for the final output.

2. Suppose we filter the same 2x2 square twice with the following discrete filter:

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

Show how to compute the result easily on paper using a small number of easy multiplication and addition operations (you can do it with less than a dozen individual operations, not counting multiplication by 1 and 0 and addition to 0). Take advantage of separability, associativity, commutativity, and symmetry. Give the final answer as another array of numbers, but use symmetry to reduce writing if you like.

2

Problem 2: Graphics Pipeline (25 pts)

Consider an eye-space triangle whose vertices have the following positions, normals, and texture coordinates assocated with them:

a: position (0.4, 0.2, -2), normal (-0.5, -0.3, 1), texcoord (0, 0)

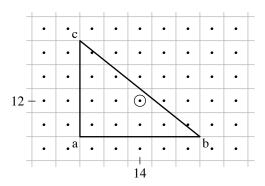
b: position (1.75, 0.25, -2.5), normal (0.5, -0.3, 1), texcoord (0.8, 0.4)

c: position (0.6, 1.5, -3), normal (-0.5, 0.5, 1), texcoord (0.3, 0.9)

The camera's field of view is 90 degrees horizontally and vertically, and the near and far distances are 1 and 5. The image is 20 by 20 pixels. This means the projection and viewport matrices are:

$$M_p = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1.5 & -2.5 \\ 0 & 0 & -1 & 0 \end{bmatrix} \qquad M_v = \begin{bmatrix} 10 & 0 & 9.5 \\ 0 & 10 & 9.5 \\ 0 & 0 & 1 \end{bmatrix}$$

(You may not need all this information, but it may be handy in checking answers.) Here is how the triangle looks in screen space:



- 1. What are the clip space coordinates of the vertices before and after the perspective divide?
- 2. Assuming the vertex processor hands a screen space position, a normal, and a texture coordinate to the rasterizer, how many quantities will the rasterizer interpolate (internally), and what do they all represent? Assume the rasterizer uses the barycentric coordinates β and γ (leaving α implied) for inside/outside testing and that the fragment processor will finish up perspective correction. Normals are to be interpolated without perspective correction.
- 3. What are the values at the three vertices from which the rasterizer will interpolate each of these quantities?

The triangle will be shaded using a Lambertian illumination model with no texture mapping (the texture coordinates won't be used). We'll compare two approaches to handling the shading in the pipeline: per-vertex lighting (Gouraud shading) and per-fragment lighting (Phong shading but still Lambertian illumination). The light source is a directional source (infinitely far away) in the direction (0,0,1) in eye space, the light intensity is (1,1,1), and the diffuse coefficient is a constant (0.5,0.5,1). Note that the normals specified by the application are not unit vectors; assume for the purposes of this problem that the vertex or fragment program will normalize the vector just before it's used.

- 4. In the Phong shading case, what will be the color at the circled fragment? Show how you computed this.
- 5. In the Gouraud shading case, will the color be darker, the same, or lighter? Why?

Problem 3: Transformations (15 pts)

The matrices

$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & \sqrt{2} & 0 \\ 0 & 0 & 0 & \sqrt{2} \end{bmatrix}, \qquad \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, \text{ and } \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

are a rotation by $+45^{\circ}$ about an axis through the origin in the direction (0,0,1), a nonuniform scale by 2 about the origin along the direction (0,1,0), and a reflection across the plane x=0, respectively. Using the same forms of description, describe what the following products of matrices do:

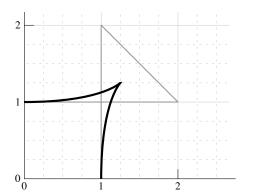
1.
$$\begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & -3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -\sqrt{3} & 0 \\ 0 & 2 & 0 & 0 \\ \sqrt{3} & 0 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

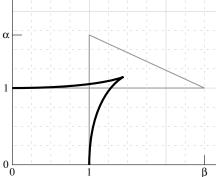
$$2. \begin{tabular}{c|cccc} 1 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{tabular} \end{tabular} \begin{tabular}{c|cccc} 2 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{tabular} \begin{tabular}{c|cccc} 1 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{tabular}$$

Hint: That last one is a little tricky.

Problem 4: Splines (25 pts)

A Bézier spline with the control points (1,0), (1,2), (2,1), (0,1) will form a cusp, as shown here on the left:





- 1. Sketch plots of the coordinate functions x(t) and y(t) and their derivatives. Explain how you can tell that the cusp happens by loooking at these plots.
- 2. What are the parametric (C^k) continuity and geometric (G^k) continuity at the cusp?

Let the lengths of the first and last segments of the control polygon be α and β , as shown at right in the figure above. We have seen that a cusp forms when $\alpha = \beta = 2$, but for many other values of α it is also possible to find a β for which a cusp will form.

- 3. Let t_x and t_y be the values of t at which x'(t) = 0 and y'(t) = 0 respectively. Find an expression for t_x as a function of β .
- 4. Use a simple symmetry argument to get t_y as a function of α , and then use your two functions to eliminate t and find β as a function of α .

Hint: Three easy ways to check your answer: (a) make sure it works for $\alpha = 2$; (b) by symmetry, swapping α and β will preserve the cusp; (c) the right-hand diagram is to scale.

Problem 5: Triangle Meshes (15 pts)

Consider the indexed triangle set defined by the vertex list [(-1, -1, -1) (-1, -1, 1) (1, -1, 1) (1, -1, -1) (0, 1, 0)] and the triangle list $[0\ 2\ 1, 0\ 2\ 3, 0\ 2\ 4, 4\ 0\ 1, 4\ 1\ 2, 4\ 2\ 3, 4\ 3\ 0]$.

- 1. What is the shape described?
- 2. As it stands this is not a manifold mesh. What two changes are required to make it into a manifold mesh?
- 3. Express the manifold mesh using a single triangle strip.