

# Pipeline Operations

## **CS 4620 Lecture 13**

# Pipeline

you are here →

**APPLICATION**

**COMMAND STREAM**

3D transformations; shading →

**VERTEX PROCESSING**

**TRANSFORMED GEOMETRY**

conversion of primitives to pixels →

**RASTERIZATION**

**FRAGMENTS**

blending, compositing, shading →

**FRAGMENT PROCESSING**

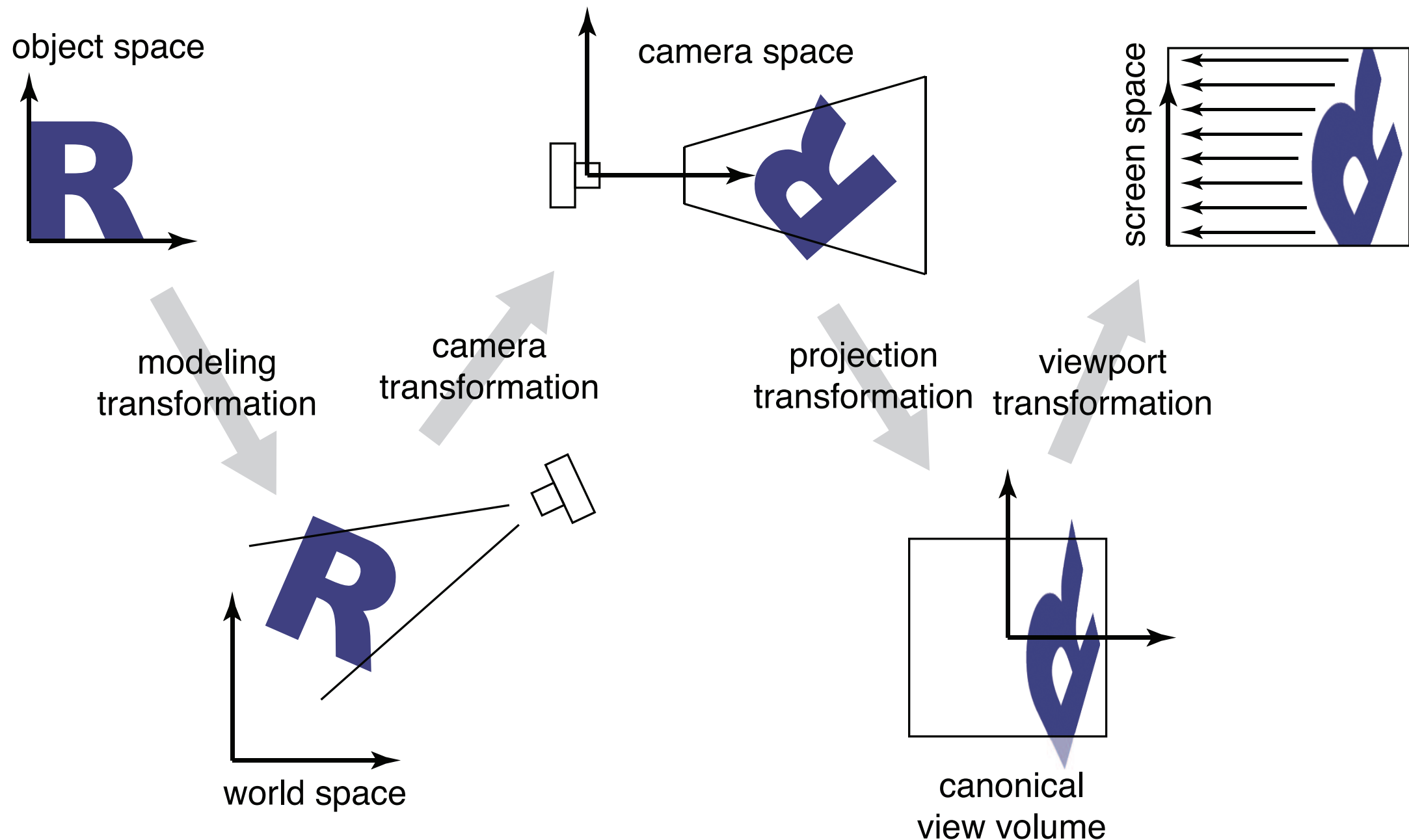
**FRAMEBUFFER IMAGE**

user sees this →

**DISPLAY**

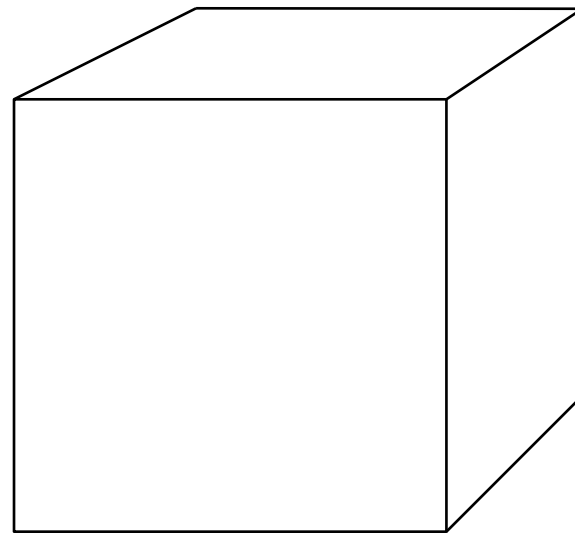
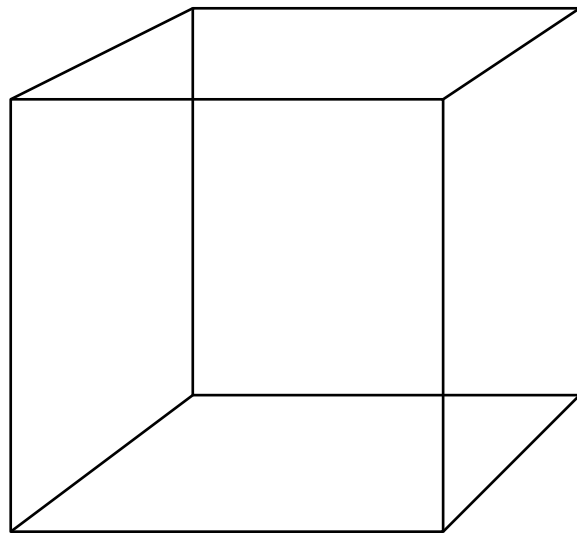
# Pipeline of transformations

- **Standard sequence of transforms**



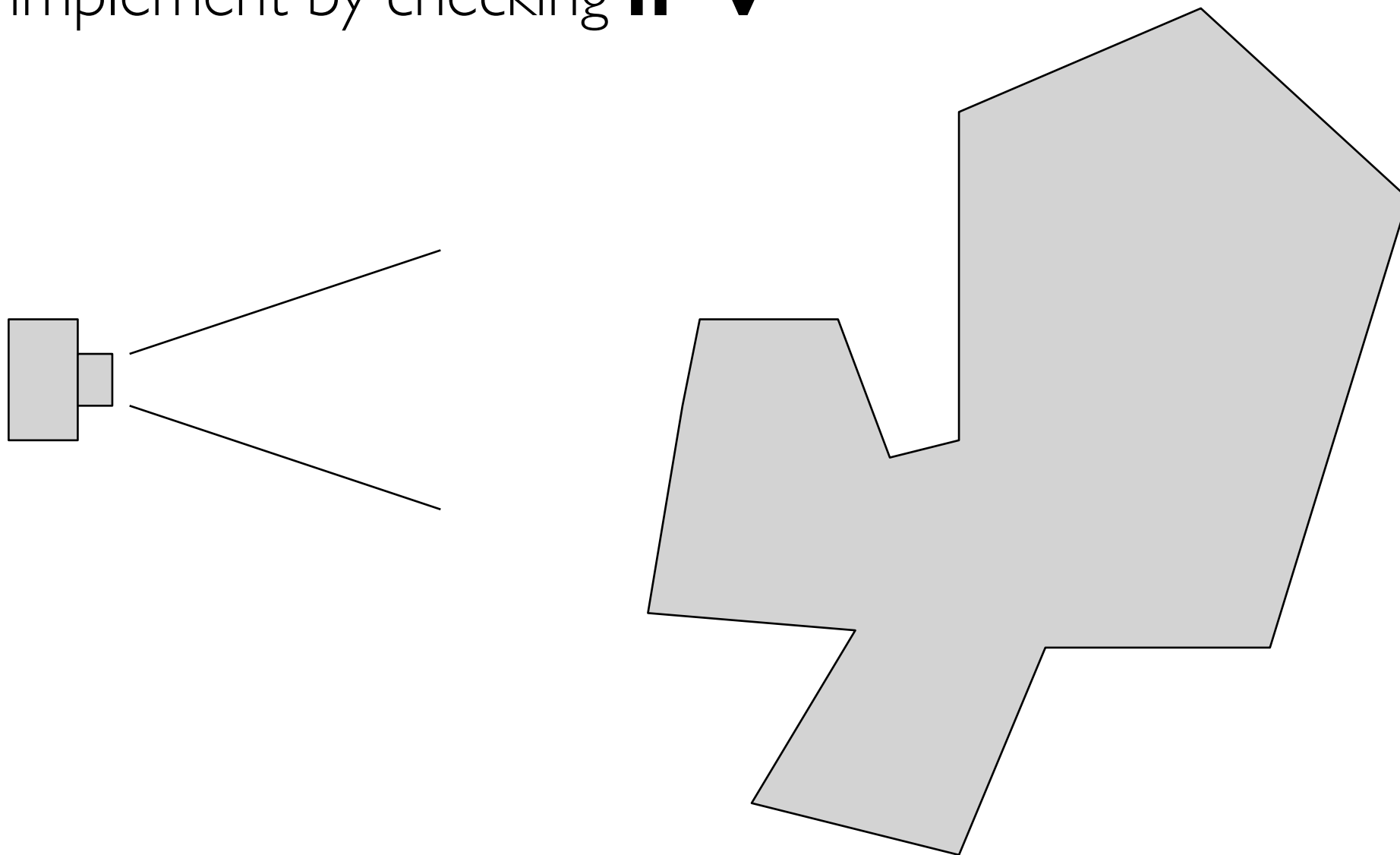
# Hidden surface elimination

- **We have discussed how to map primitives to image space**
  - projection and perspective are depth cues
  - occlusion is another very important cue



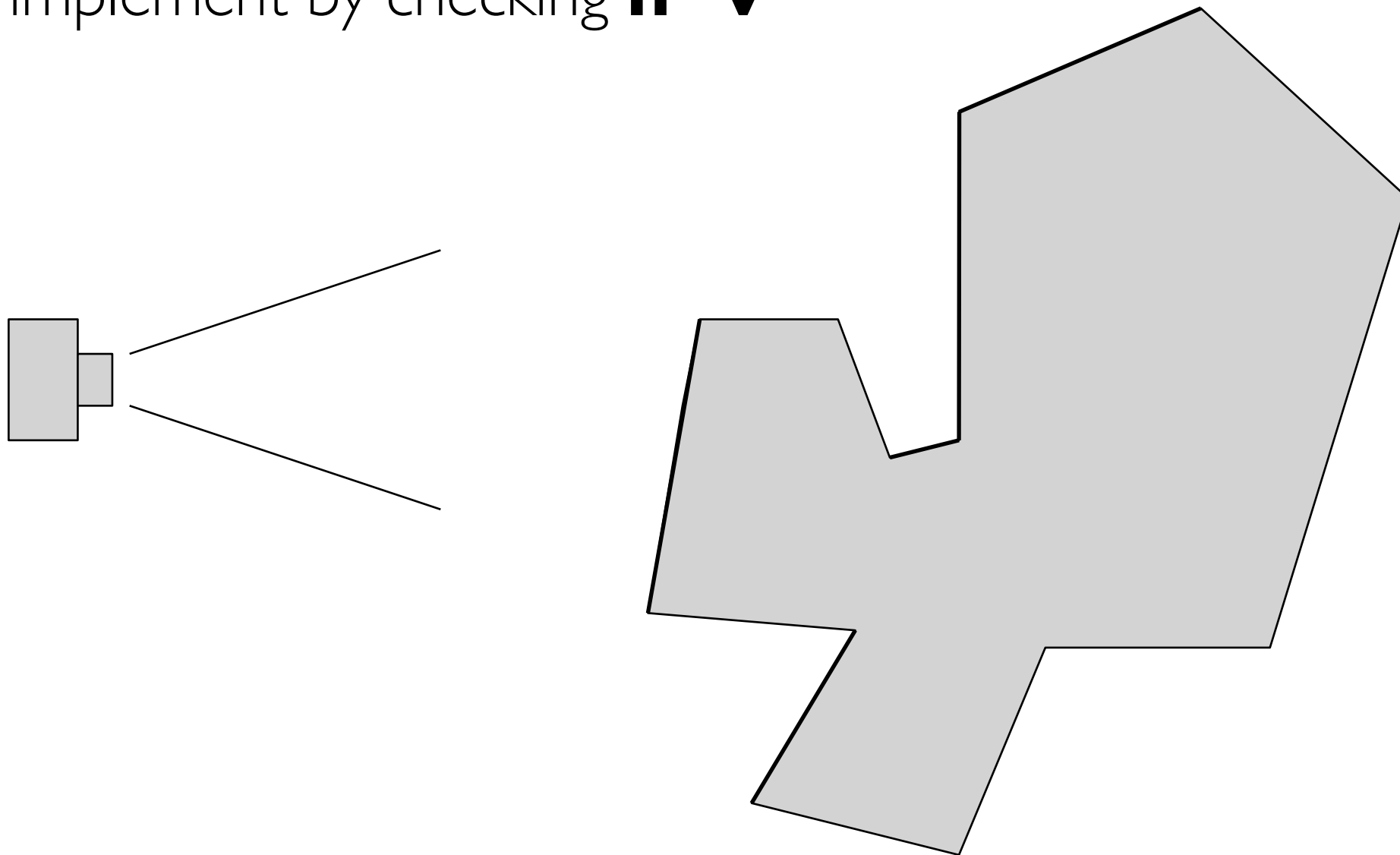
# Back face culling

- **For closed shapes you will never see the inside**
  - therefore only draw surfaces that face the camera
  - implement by checking  **$\mathbf{n} \cdot \mathbf{v}$**



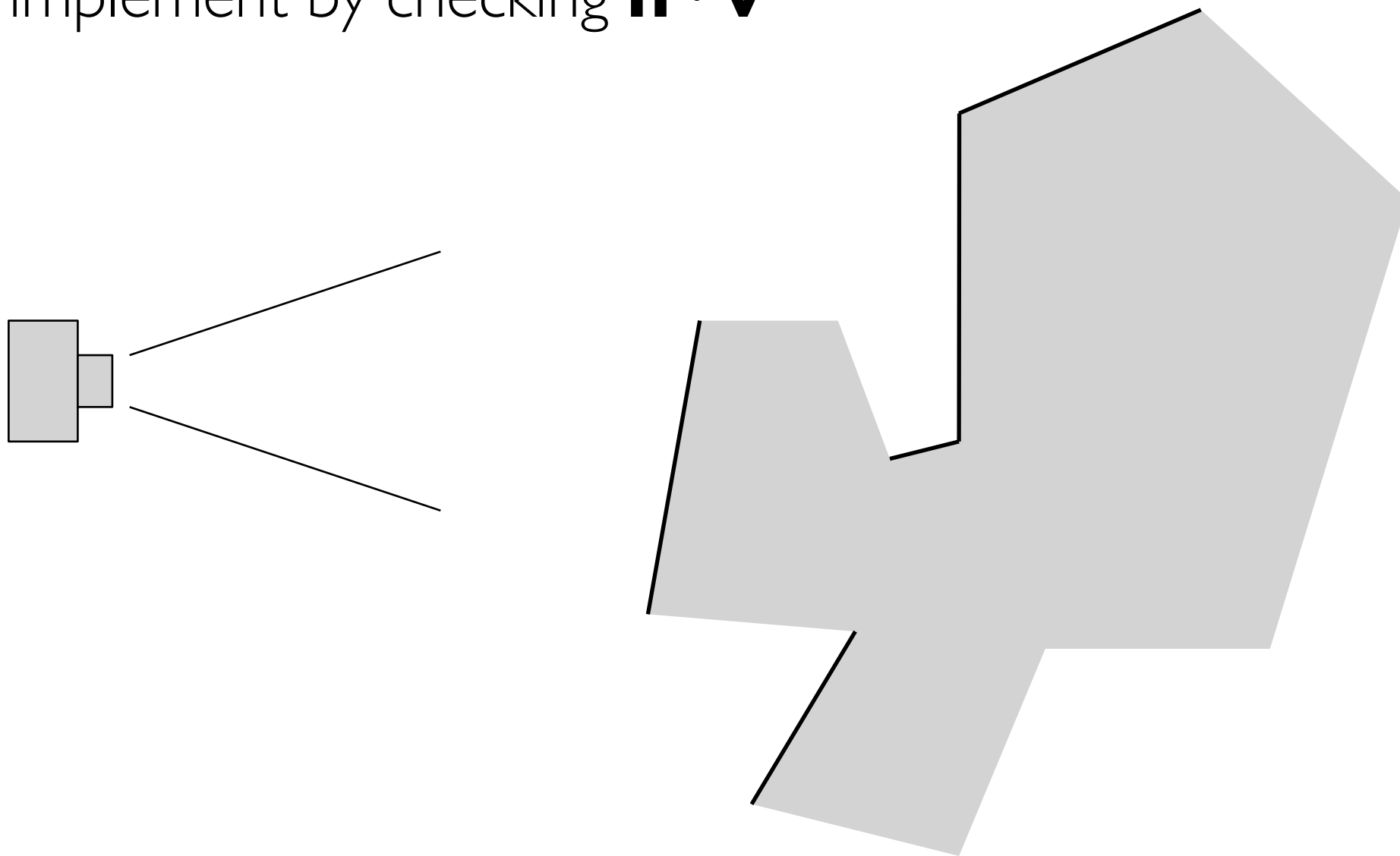
# Back face culling

- **For closed shapes you will never see the inside**
  - therefore only draw surfaces that face the camera
  - implement by checking  **$\mathbf{n} \cdot \mathbf{v}$**



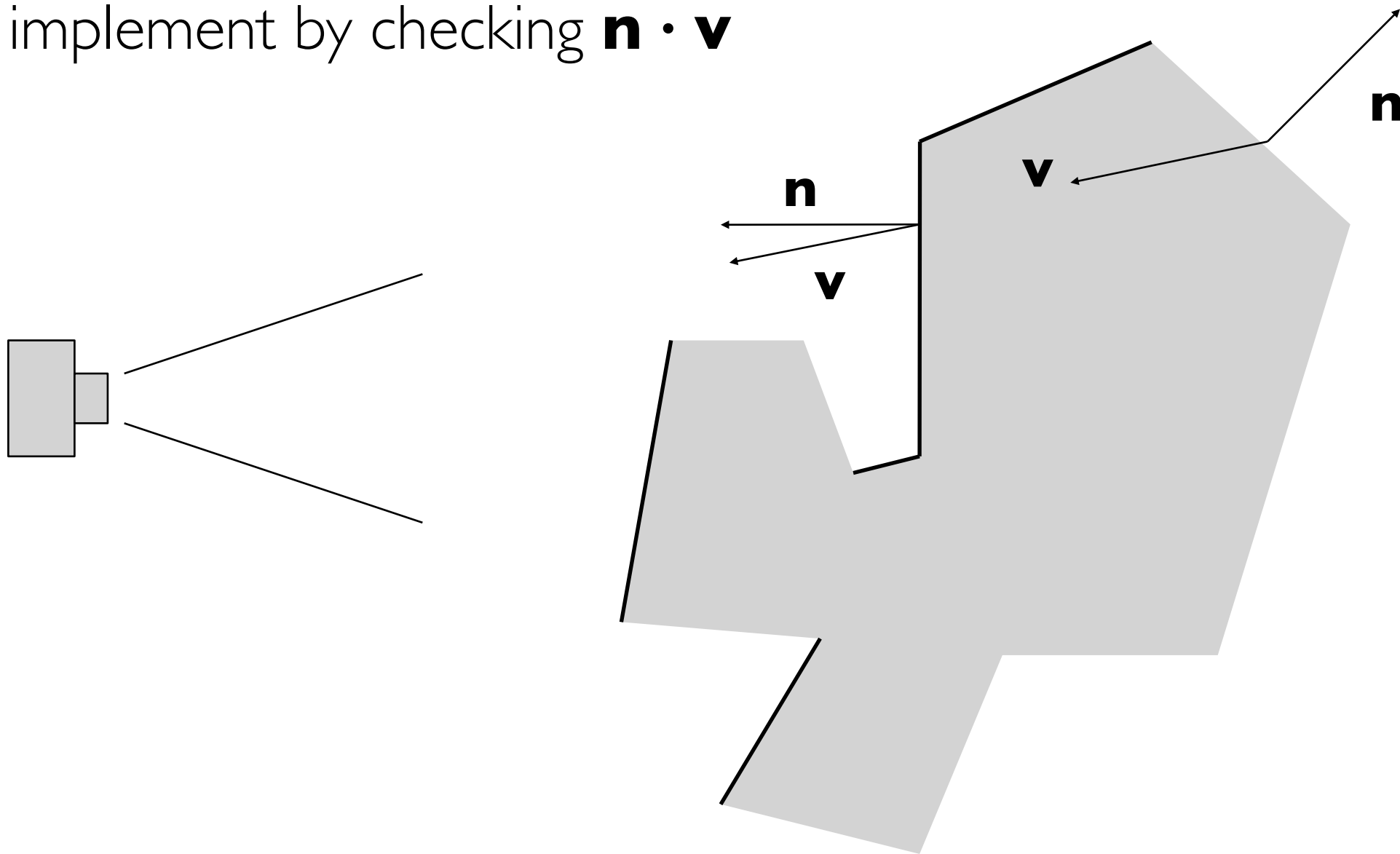
# Back face culling

- **For closed shapes you will never see the inside**
  - therefore only draw surfaces that face the camera
  - implement by checking  **$\mathbf{n} \cdot \mathbf{v}$**



# Back face culling

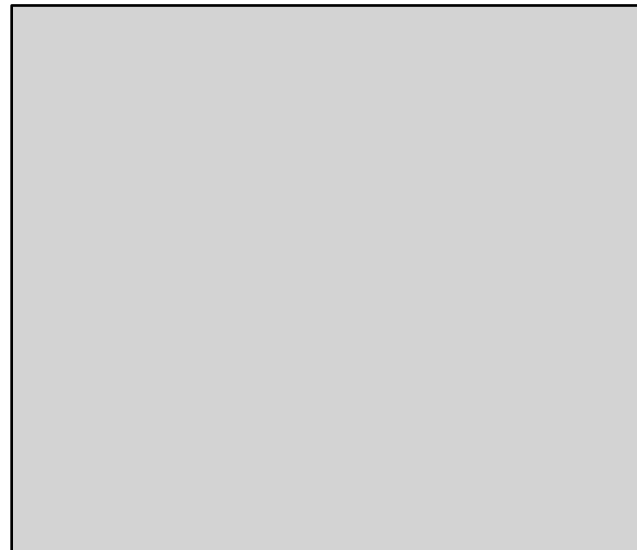
- **For closed shapes you will never see the inside**
  - therefore only draw surfaces that face the camera
  - implement by checking  $\mathbf{n} \cdot \mathbf{v}$





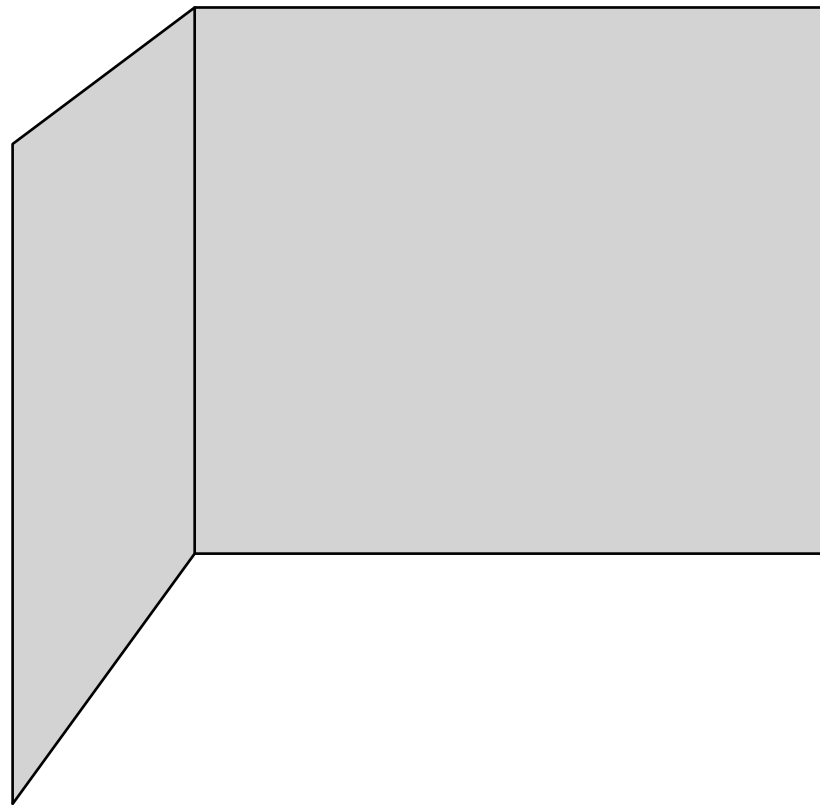
# Painter's algorithm

- **Simplest way to do hidden surfaces**
- **Draw from back to front, use overwriting in framebuffer**



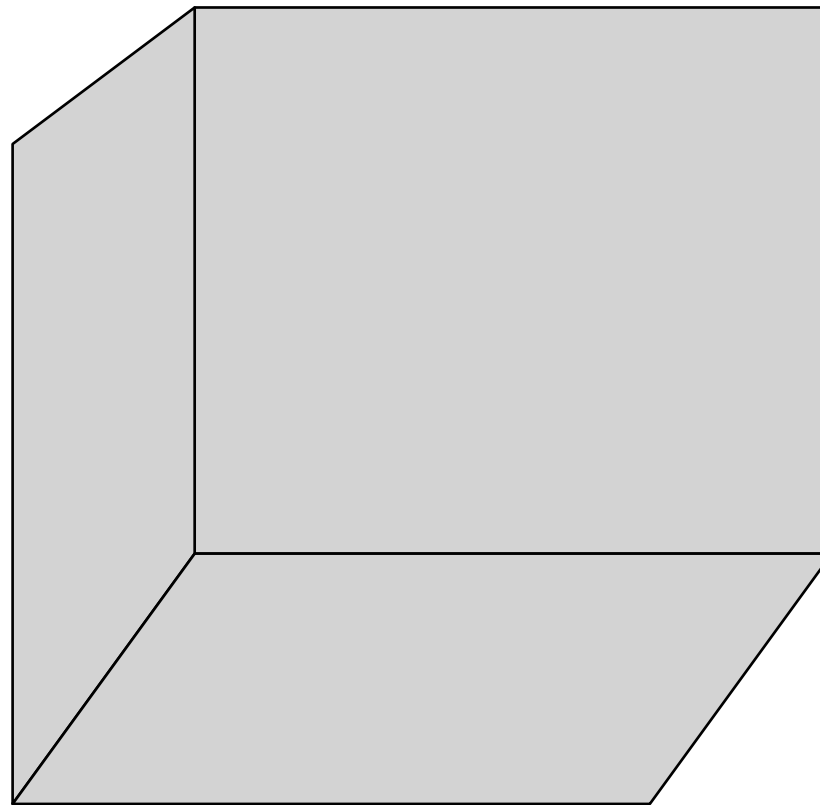
# Painter's algorithm

- **Simplest way to do hidden surfaces**
- **Draw from back to front, use overwriting in framebuffer**



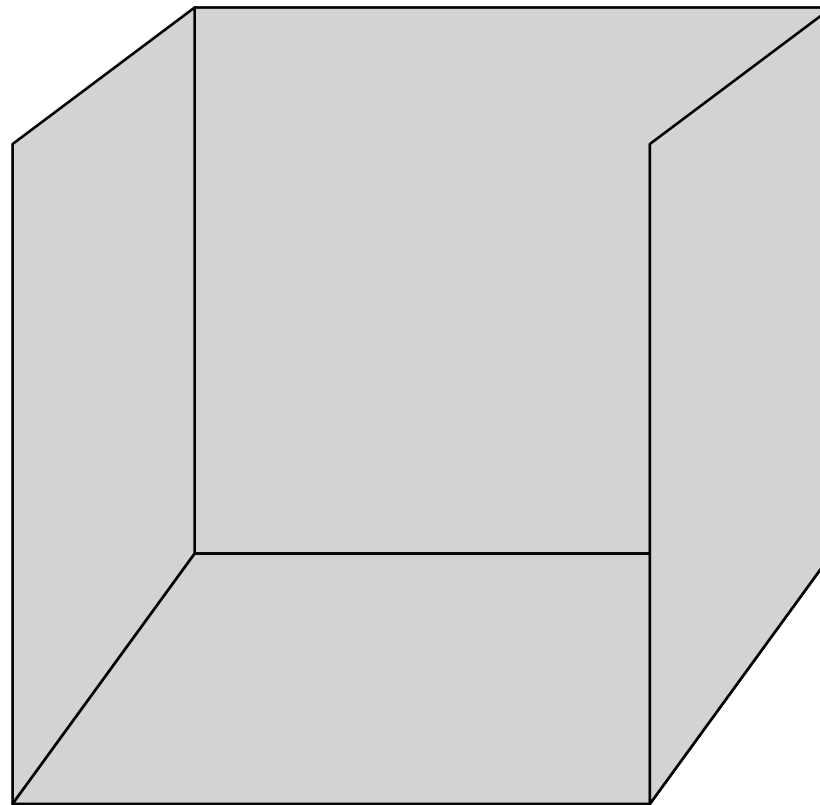
# Painter's algorithm

- **Simplest way to do hidden surfaces**
- **Draw from back to front, use overwriting in framebuffer**



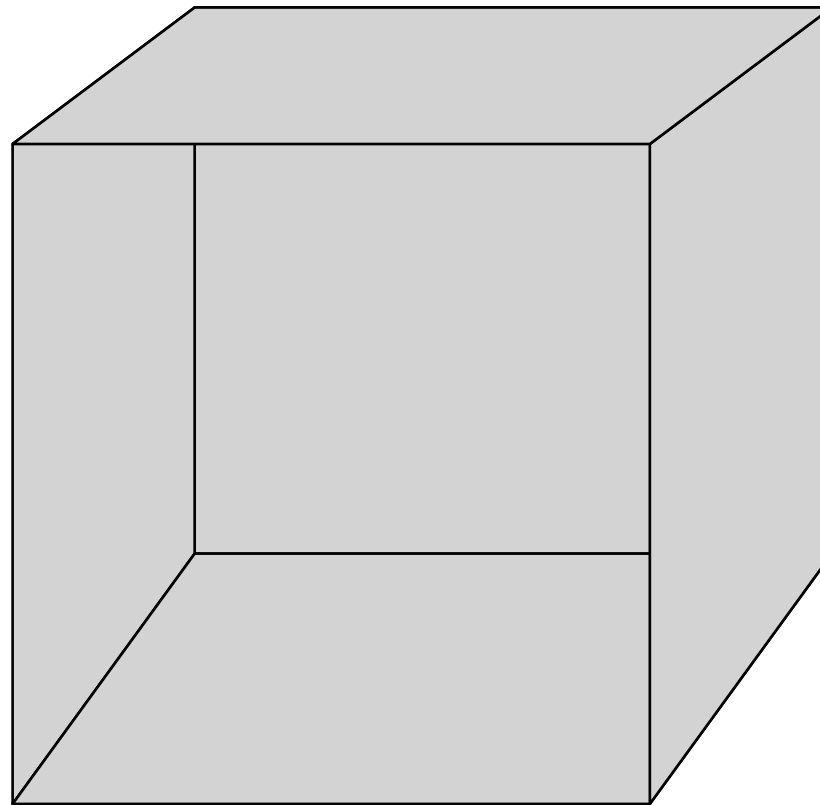
# Painter's algorithm

- **Simplest way to do hidden surfaces**
- **Draw from back to front, use overwriting in framebuffer**



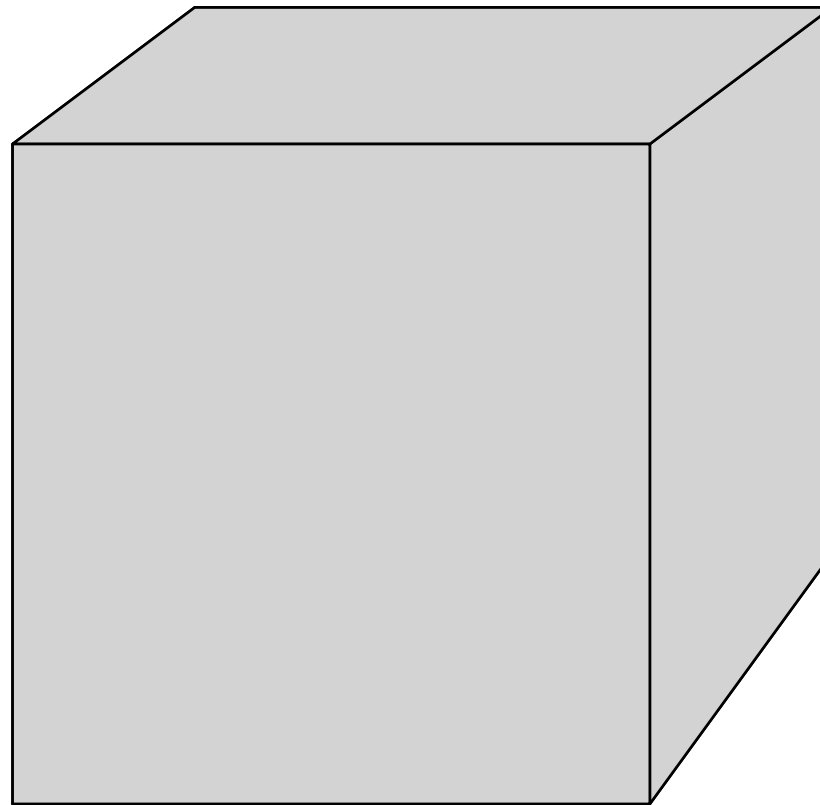
# Painter's algorithm

- **Simplest way to do hidden surfaces**
- **Draw from back to front, use overwriting in framebuffer**



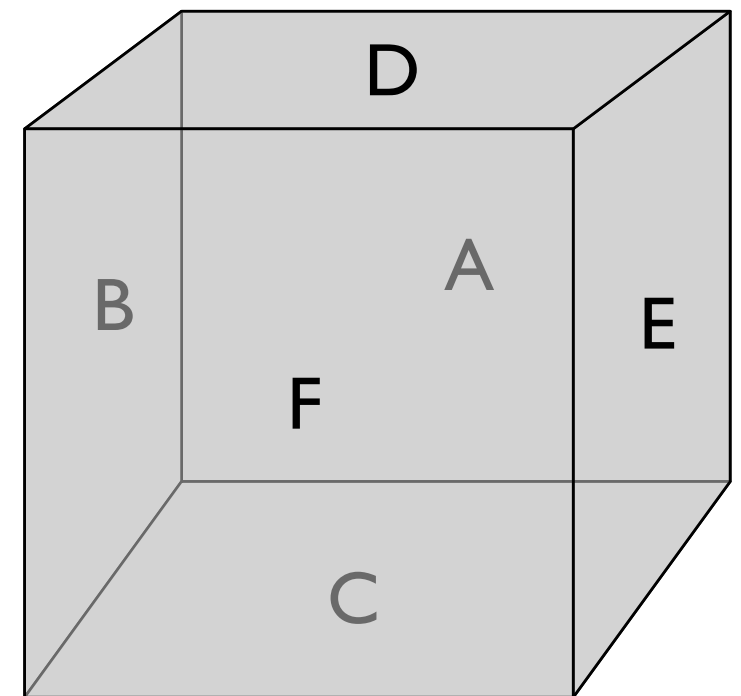
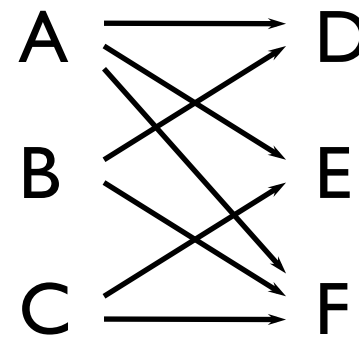
# Painter's algorithm

- **Simplest way to do hidden surfaces**
- **Draw from back to front, use overwriting in framebuffer**



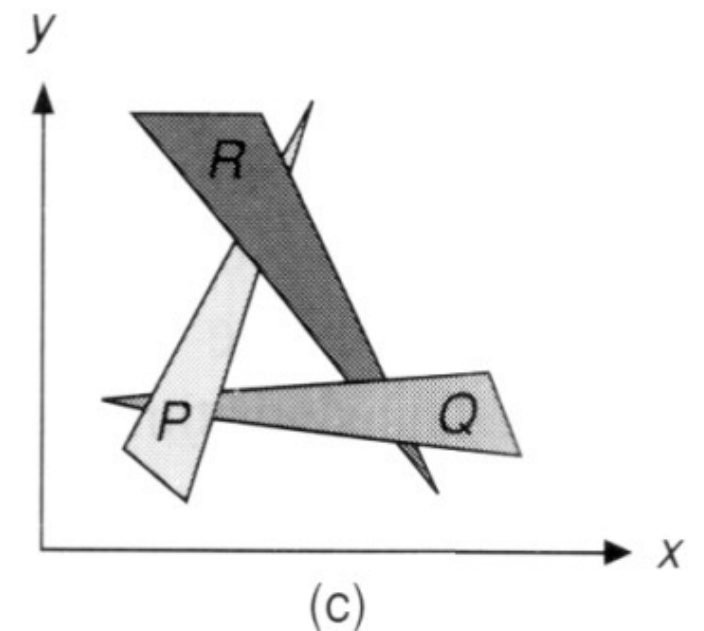
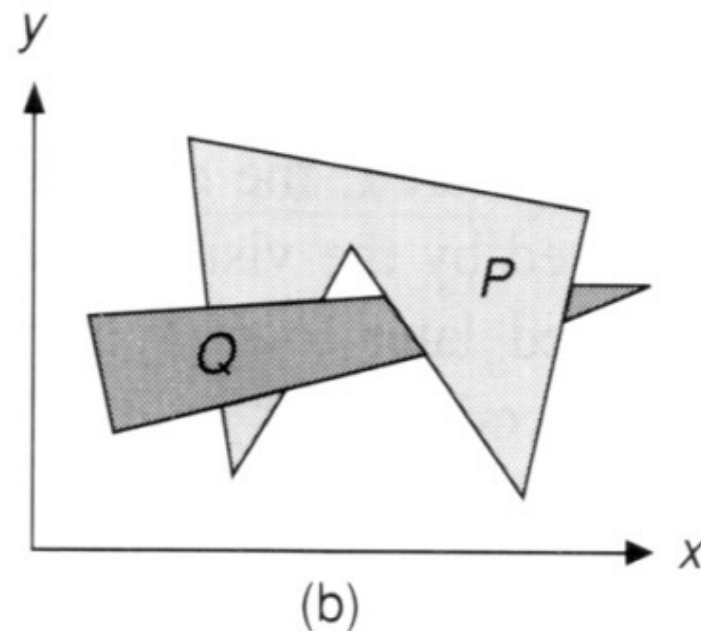
# Painter's algorithm

- **Amounts to a topological sort of the graph of occlusions**
  - that is, an edge from A to B means A sometimes occludes B
  - any sort is valid
    - ABCDEF
    - BADCFE
  - if there are cycles there is no sort



# Painter's algorithm

- **Amounts to a topological sort of the graph of occlusions**
  - that is, an edge from A to B means A sometimes occludes B
  - any sort is valid
    - ABCDEF
    - BADCFE
  - if there are cycles there is no sort

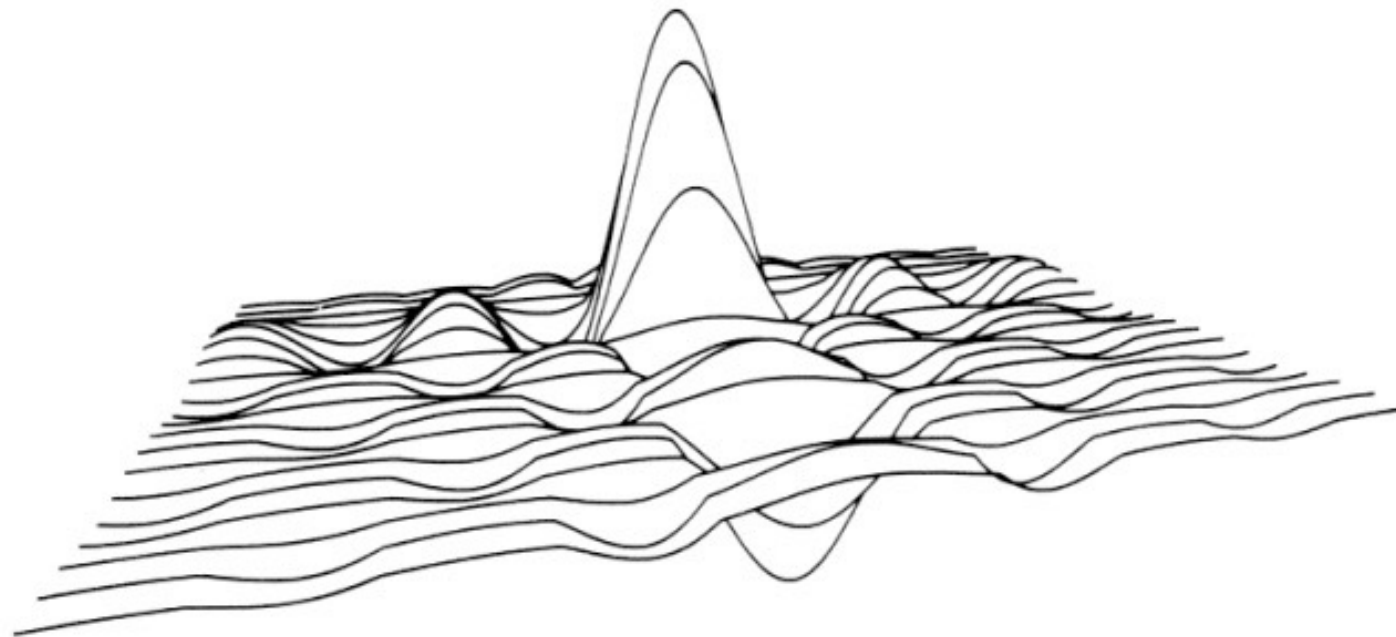


[Foley et al.]



# Painter's algorithm

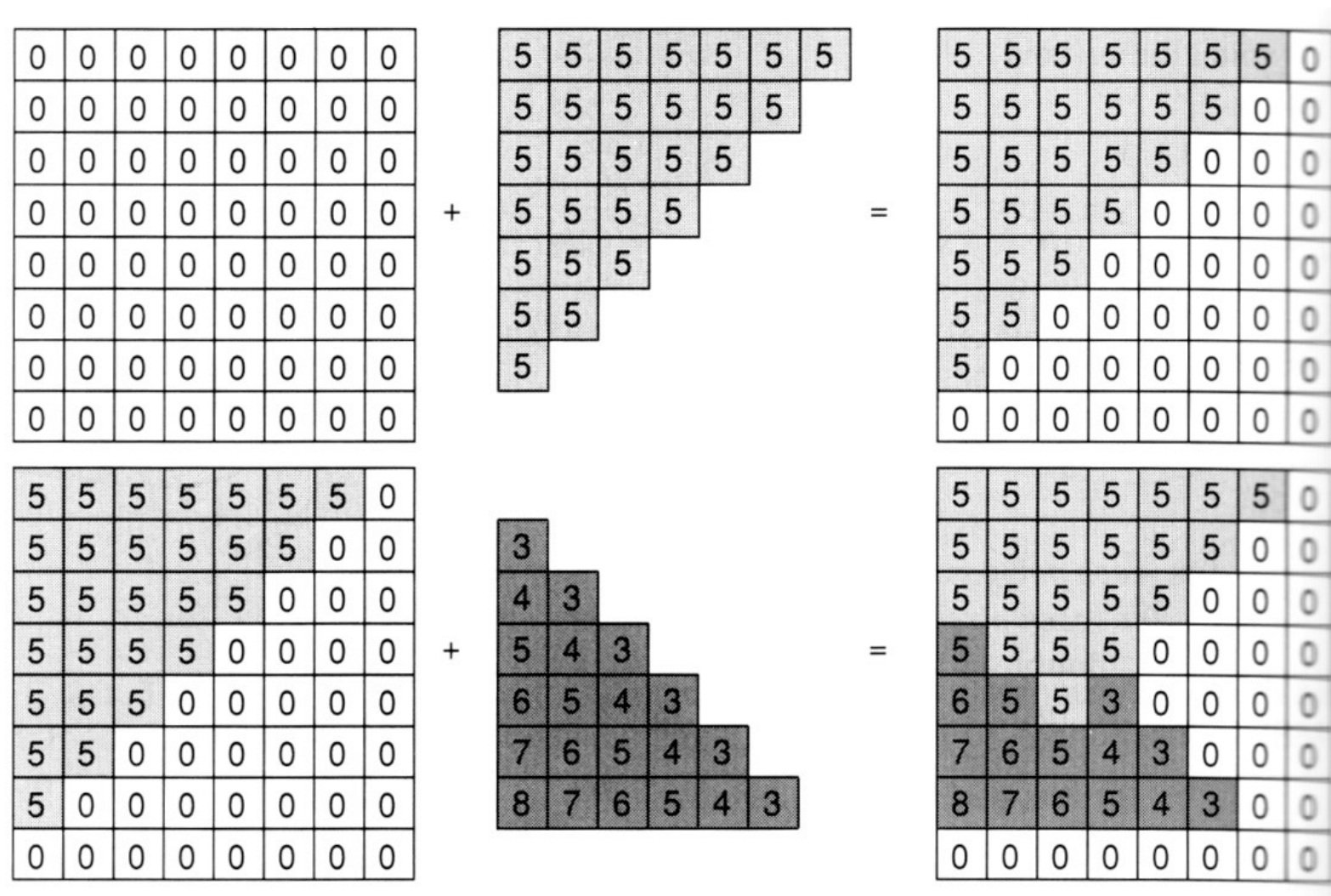
- **Useful when a valid order is easy to come by**
- **Compatible with alpha blending**



# The **z** buffer

- **In many (most) applications maintaining a z sort is too expensive**
  - changes all the time as the view changes
  - many data structures exist, but complex
- **Solution: draw in any order, keep track of closest**
  - allocate extra channel per pixel to keep track of closest depth so far
  - when drawing, compare object's depth to current closest depth and discard if greater
  - this works just like any other compositing operation

# The **z** buffer



[Foley et al.]

- another example of a memory-intensive brute force approach that works and has become the standard

# Precision in **z** buffer

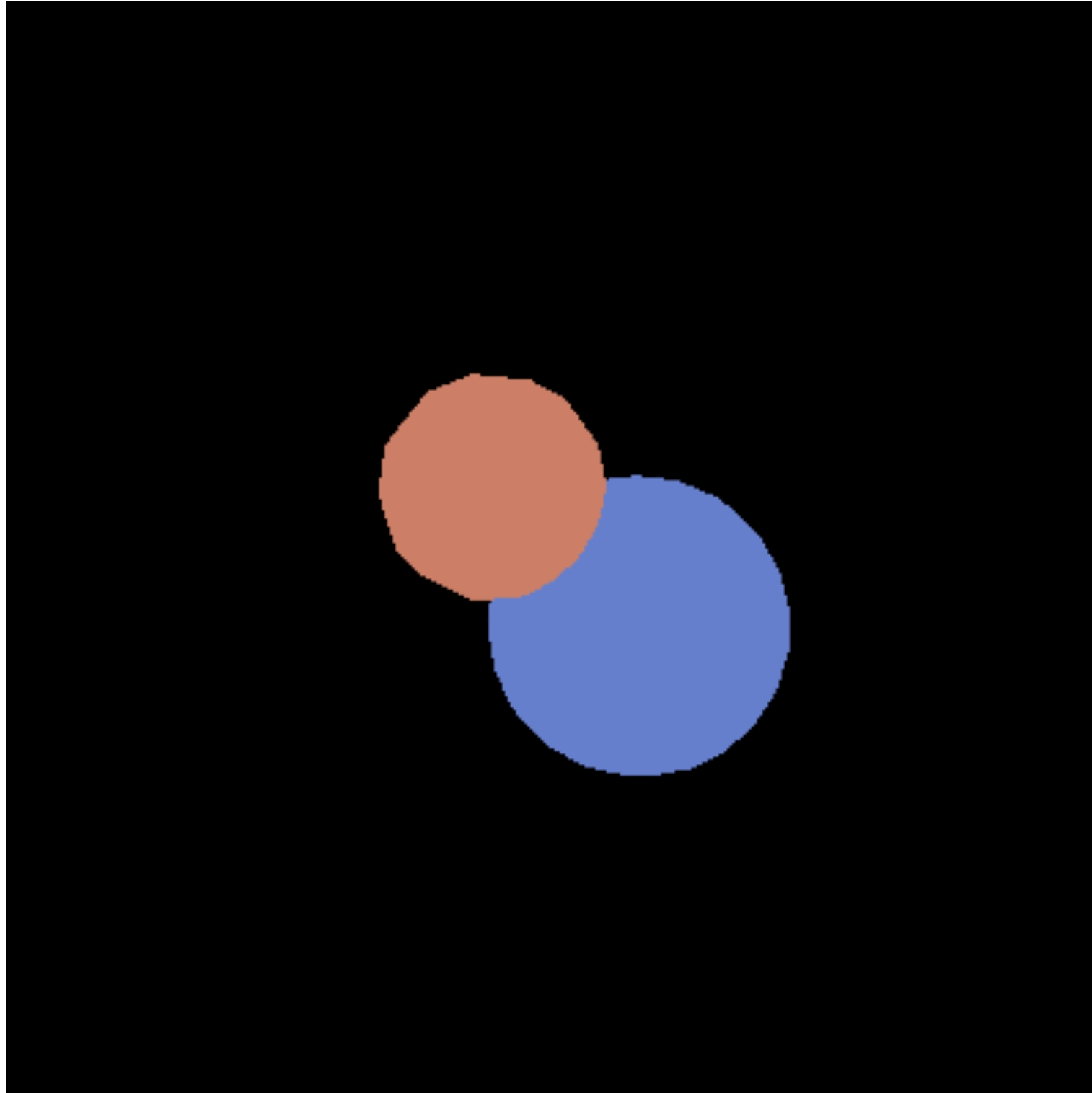
- **The precision is distributed between the near and far clipping planes**
  - this is why these planes have to exist
  - also why you can't always just set them to very small and very large distances
- **Traditionally use screen space depth (not eye-space) in z buffer**
  - screen space depth has to be interpolated linearly
    - and gives you more precision for near than far depths
  - eye-space depth has to be interpolated with perspective correction (a.k.a. w buffer)
    - and gives you uniform precision over [near, far]

# Pipeline for minimal operation

**Demo**

- **Vertex stage (input: position / vtx)**
  - transform position (object to screen space)
- **Rasterizer**
  - nothing (extra) to interpolate
- **Fragment stage (output: color)**
  - write a fixed color to color planes
  - (color is a “uniform” quantity that is infrequently updated)

# Result of minimal pipeline

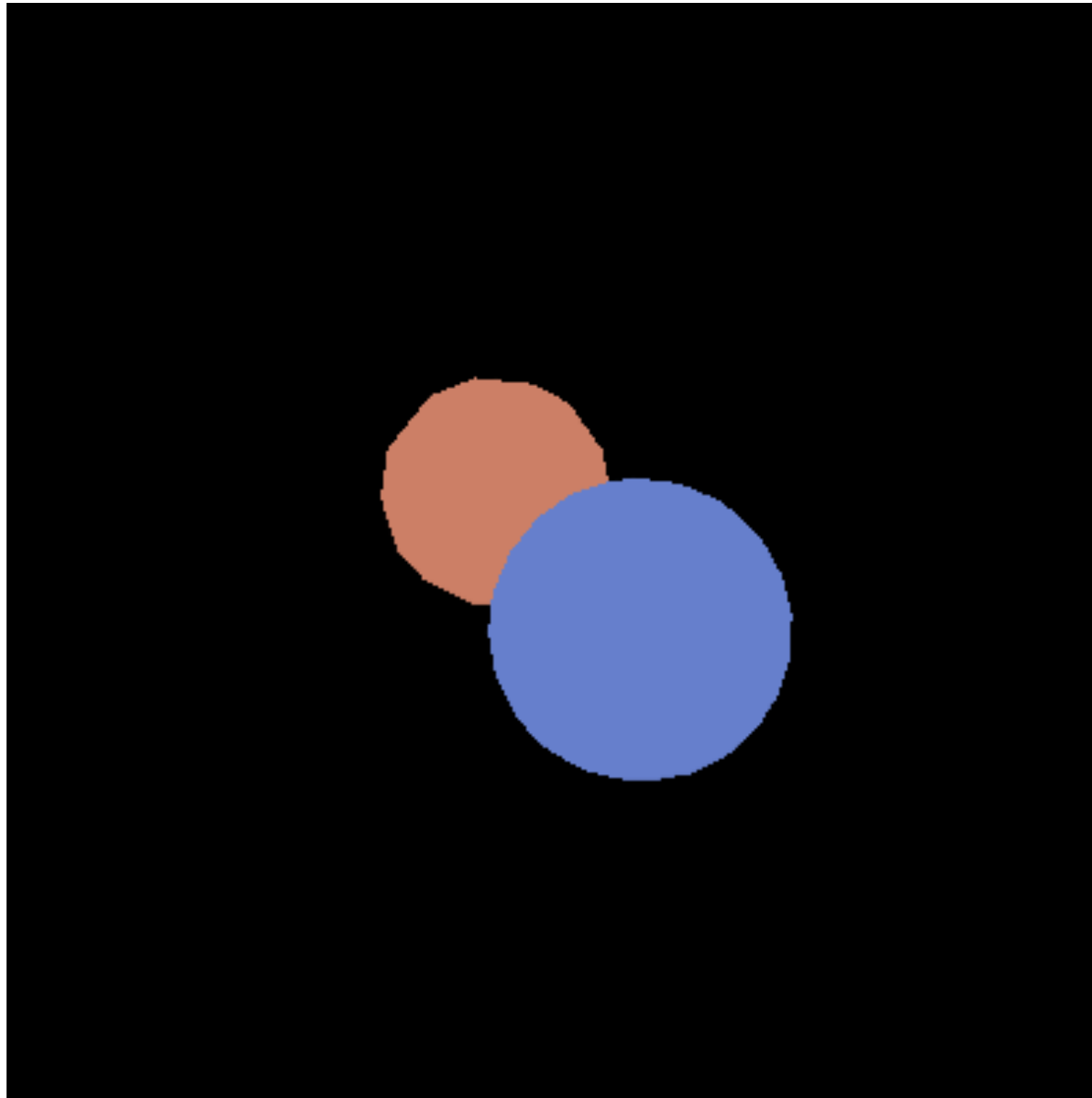


# Pipeline for basic $z$ buffer

**Demo**

- **Vertex stage (input: position / vtx)**
  - transform position (object to screen space)
- **Rasterizer**
  - interpolated parameter:  $z'$  (screen  $z$ )
- **Fragment stage (output: color,  $z'$ )**
  - write fixed color to color planes only if interpolated  $z' <$  current  $z'$

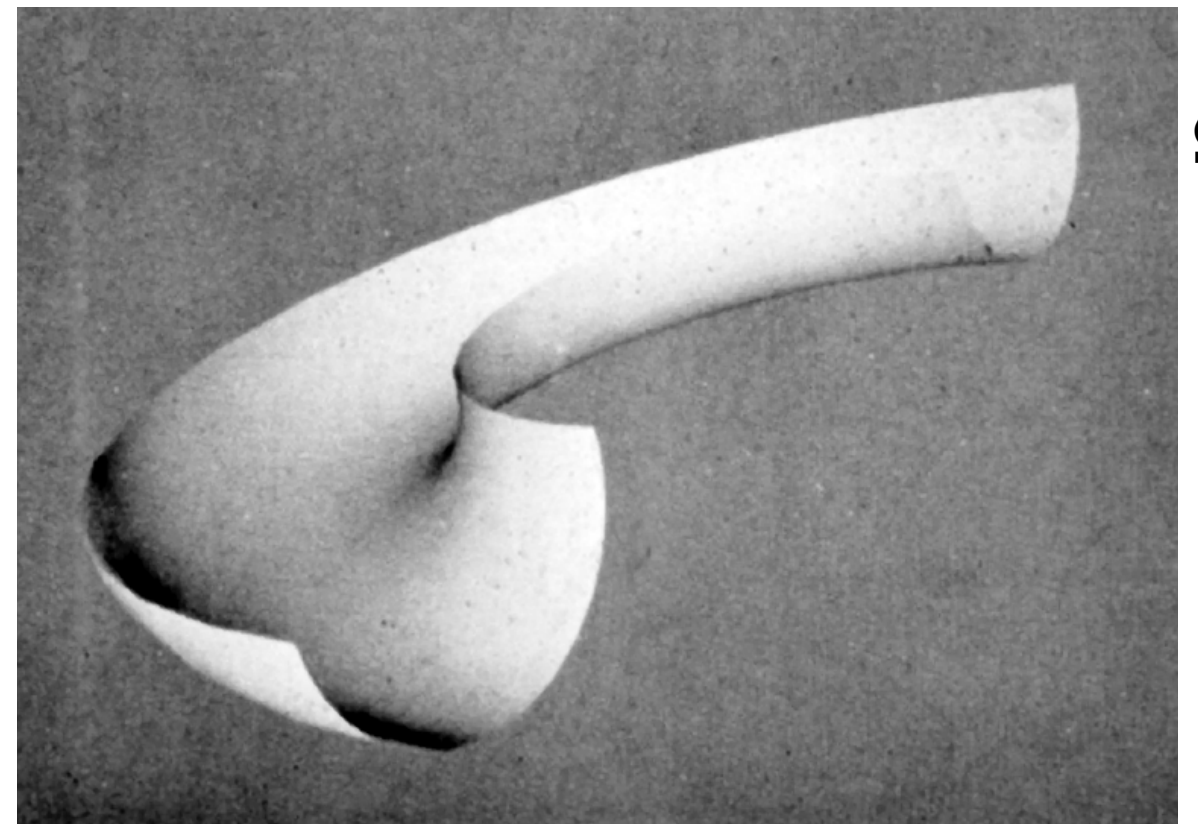
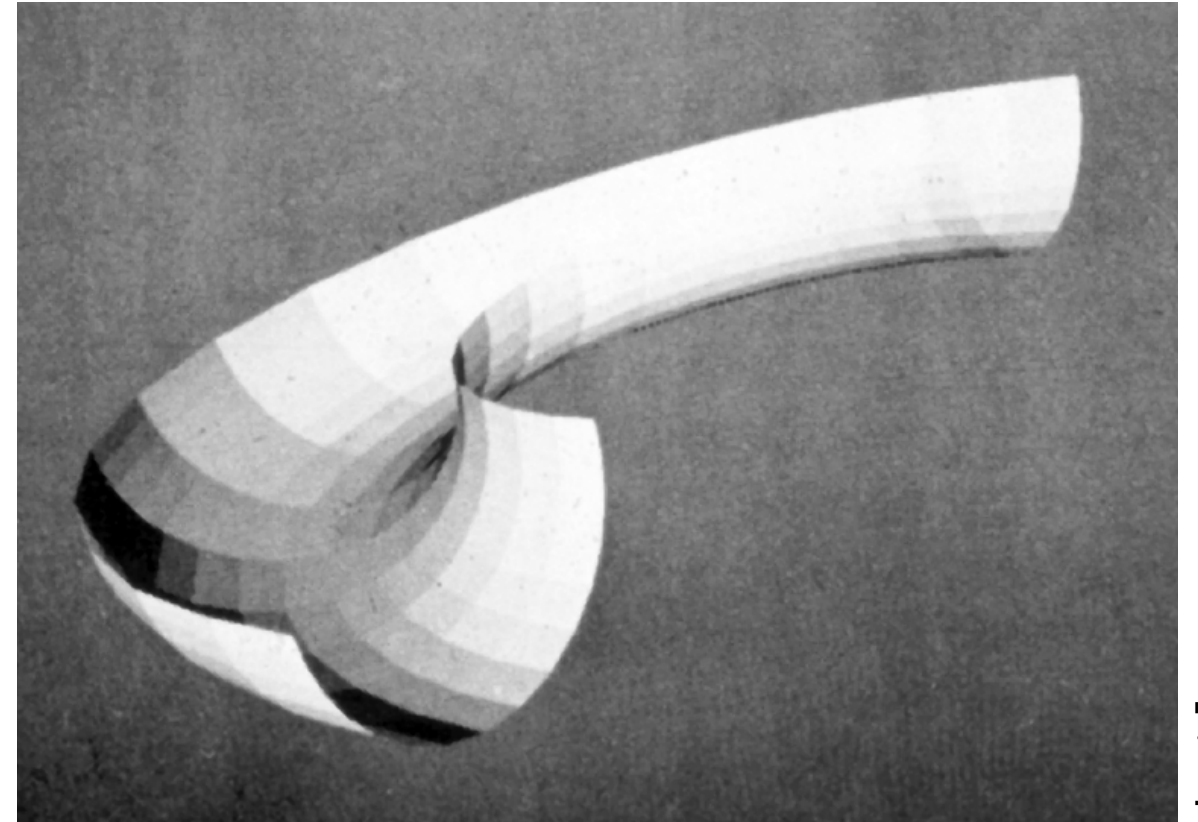
# Result of **z**-buffer pipeline





# Gouraud shading

- **Often we're trying to draw smooth surfaces, so facets are an artifact**
  - compute colors at vertices using vertex normals
  - interpolate colors across triangles
  - “Gouraud shading”
  - “Smooth shading”

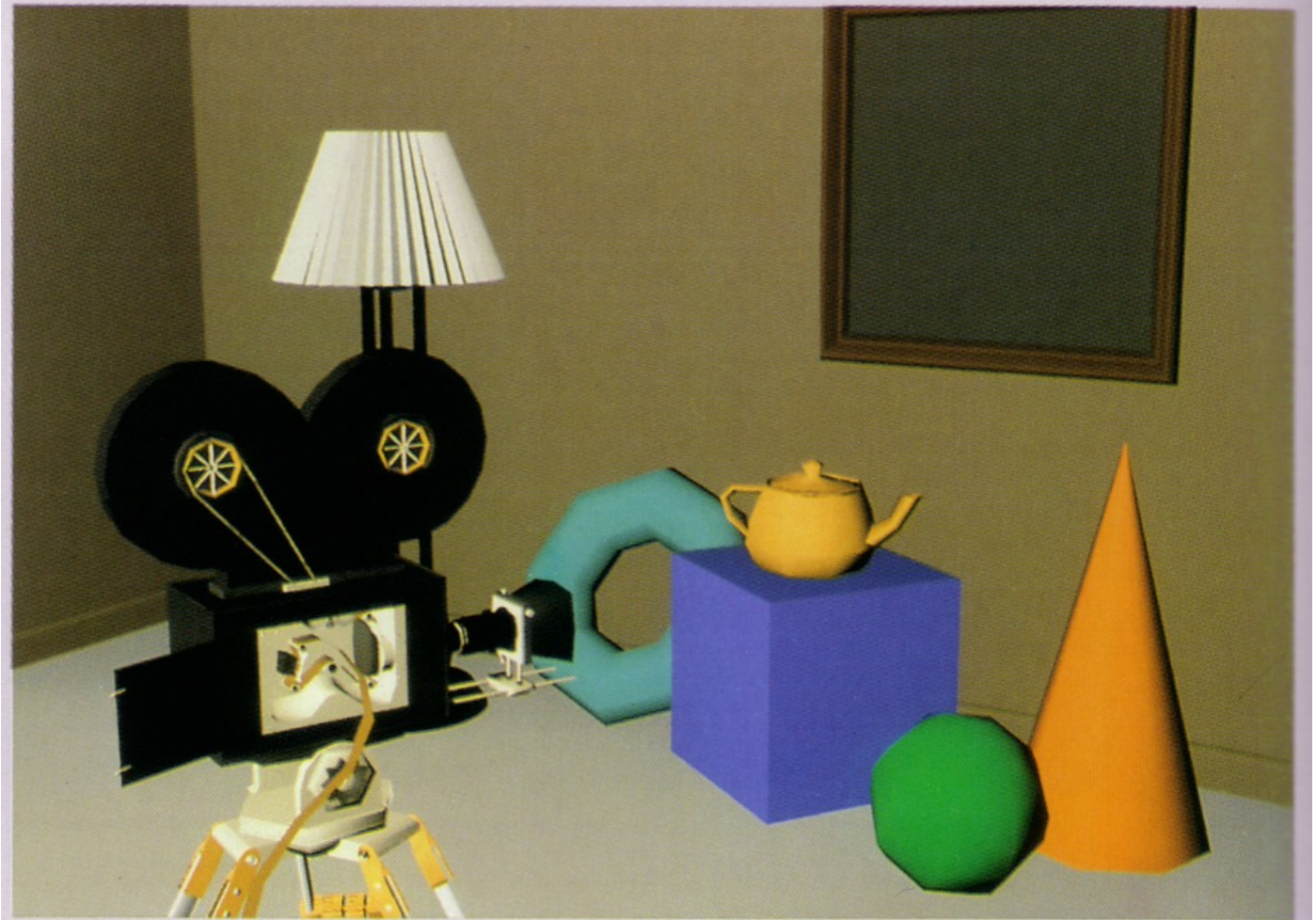


[Gouraud thesis]

# Gouraud shading

- **Often we're trying to draw smooth surfaces, so facets are an artifact**
  - compute colors at vertices using vertex normals
  - interpolate colors across triangles
  - “Gouraud shading”
  - “Smooth shading”

**Plate II.30** *Shutterbug*. Gouraud shaded polygons with diffuse reflection (Sections 14.4.3 and 16.2.4). (Copyright © 1990, Pixar. Rendered by Thomas Williams and H.B. Siegel using Pixar's PhotoRealistic RenderMan™ software.)



[Foley et al.]

# Pipeline for Gouraud shading

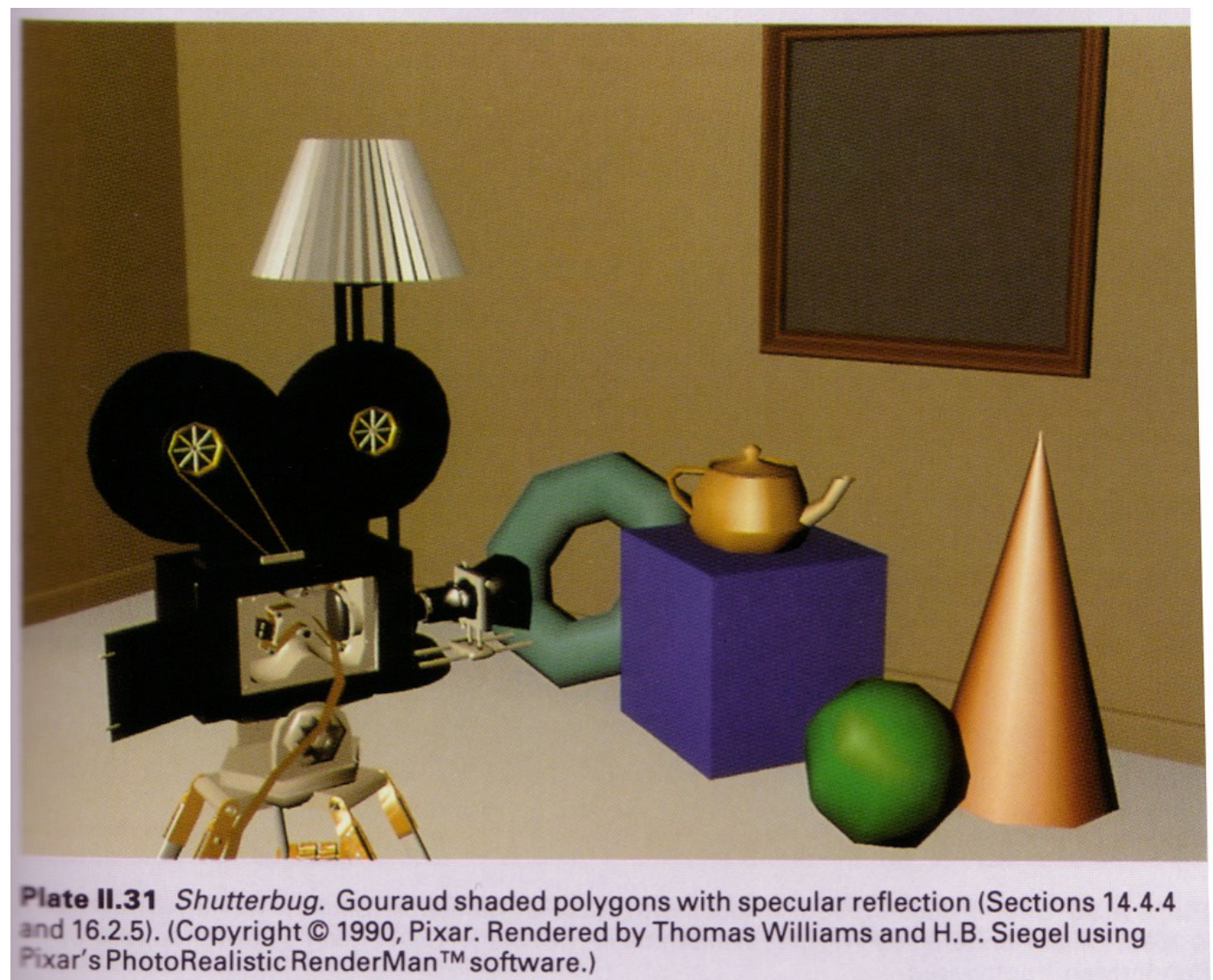
**Demo**

- **Vertex stage (input: position and normal / vtx)**
  - transform position and normal (object to eye space)
  - compute shaded color per vertex (using fixed diffuse color)
  - transform position (eye to screen space)
- **Rasterizer**
  - interpolated parameters:  $\mathbf{z}'$  (screen  $\mathbf{z}$ );  $r, g, b$  color
- **Fragment stage (output: color,  $\mathbf{z}'$ )**
  - write to color planes only if interpolated  $\mathbf{z}' <$  current  $\mathbf{z}'$

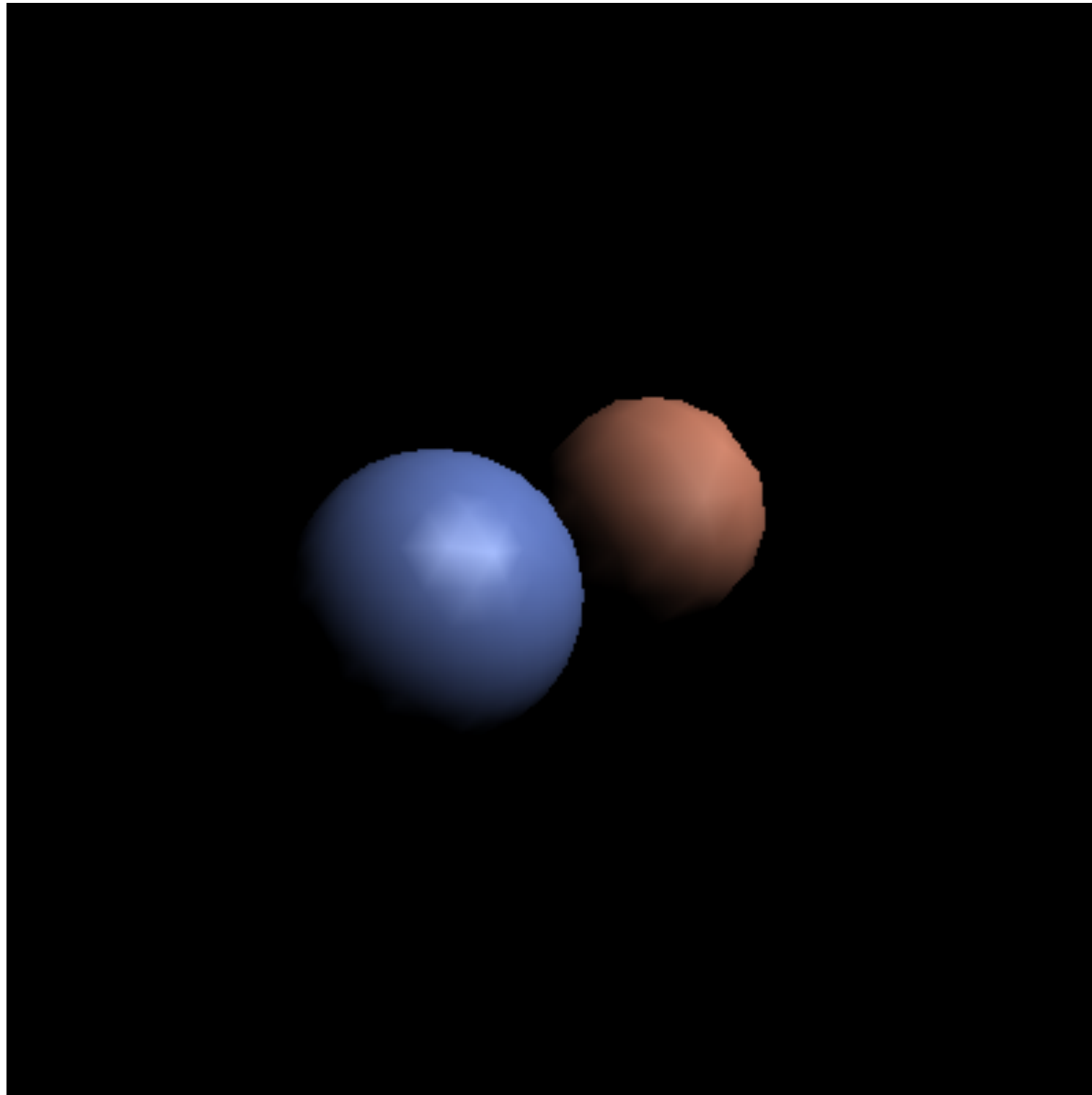


# Non-diffuse Gouraud shading

- **Can apply Gouraud shading to any illumination model**
  - it's just an interpolation method
- **Results are not so good with fast-varying models like specular ones**
  - problems with any highlights smaller than a triangle



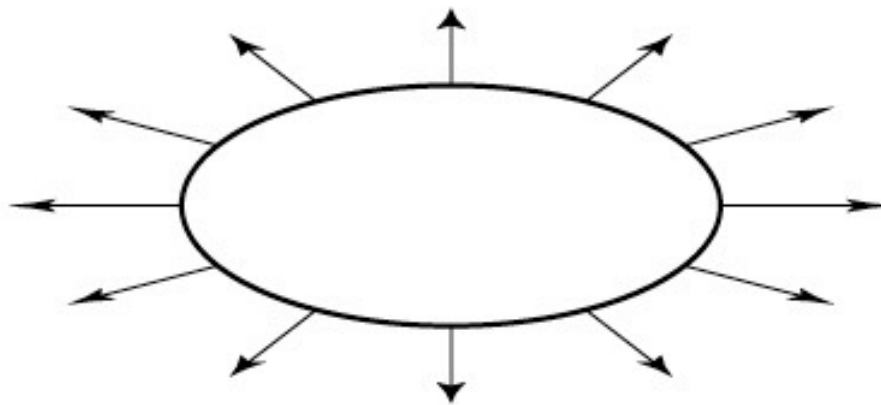
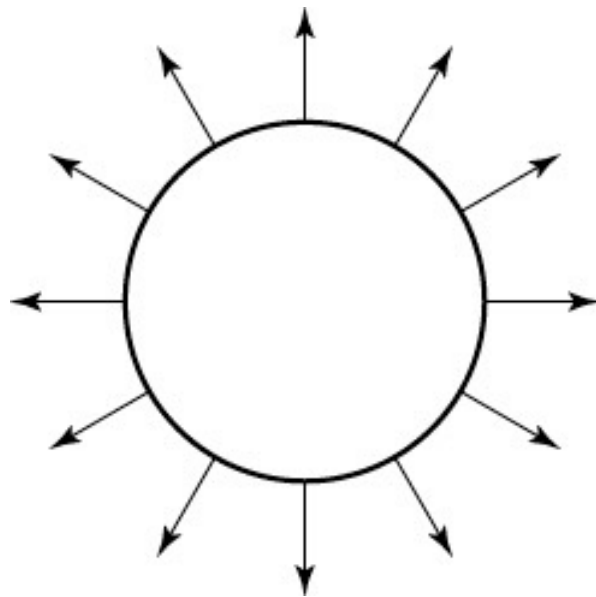
# Result of Gouraud shading pipeline



# Transforming normal vectors

- **Transforming surface normals**

- differences of points (and therefore tangents) transform OK
- normals do not --> use inverse transpose matrix



have:  $\mathbf{t} \cdot \mathbf{n} = \mathbf{t}^T \mathbf{n} = 0$

want:  $M\mathbf{t} \cdot X\mathbf{n} = \mathbf{t}^T M^T X\mathbf{n} = 0$

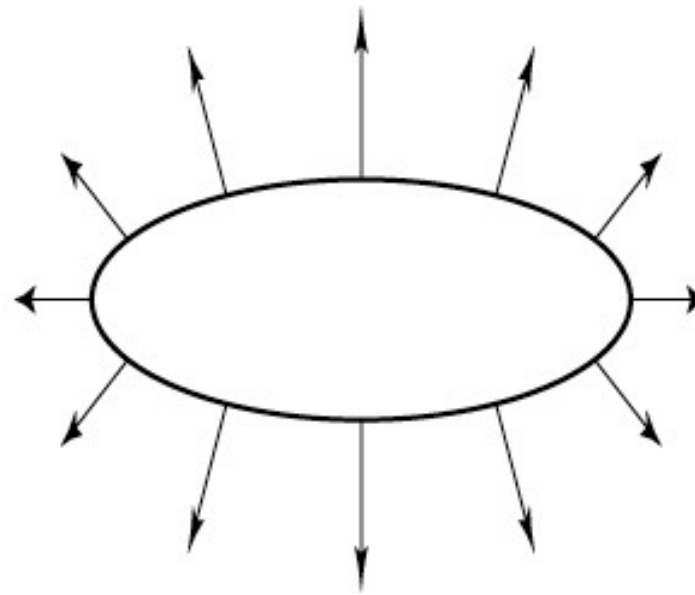
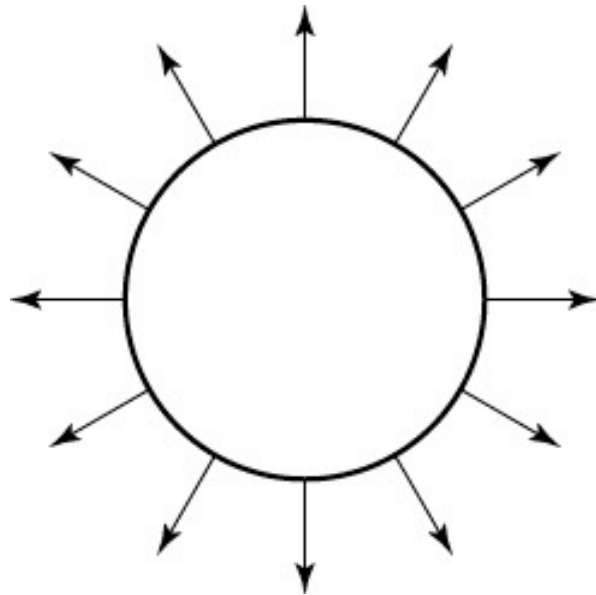
so set  $X = (M^T)^{-1}$

then:  $M\mathbf{t} \cdot X\mathbf{n} = \mathbf{t}^T M^T (M^T)^{-1} \mathbf{n} = \mathbf{t}^T \mathbf{n} = 0$

# Transforming normal vectors

- **Transforming surface normals**

- differences of points (and therefore tangents) transform OK
- normals do not --> use inverse transpose matrix



have:  $\mathbf{t} \cdot \mathbf{n} = \mathbf{t}^T \mathbf{n} = 0$

want:  $M\mathbf{t} \cdot X\mathbf{n} = \mathbf{t}^T M^T X\mathbf{n} = 0$

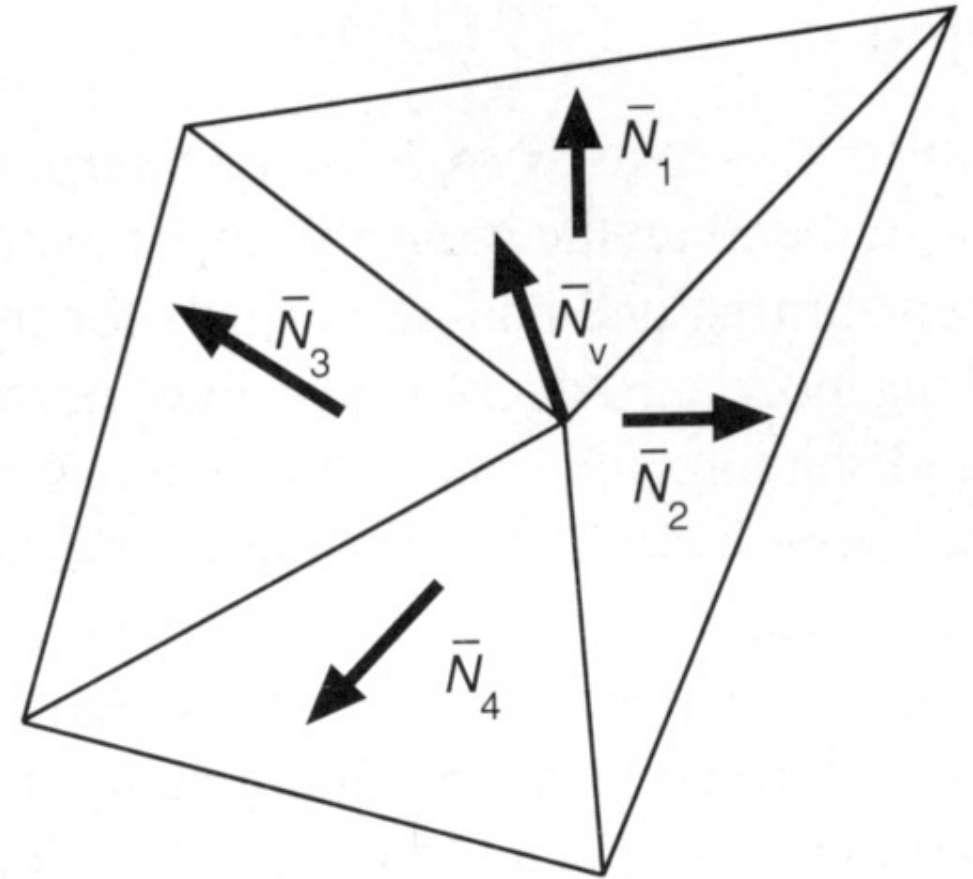
so set  $X = (M^T)^{-1}$

then:  $M\mathbf{t} \cdot X\mathbf{n} = \mathbf{t}^T M^T (M^T)^{-1} \mathbf{n} = \mathbf{t}^T \mathbf{n} = 0$

# Vertex normals

- **Need normals at vertices to compute Gouraud shading**
- **Best to get vtx. normals from the underlying geometry**
  - e. g. spheres example
- **Otherwise have to infer vtx. normals from triangles**
  - simple scheme: average surrounding face normals

$$N_v = \frac{\sum_i N_i}{\|\sum_i N_i\|}$$

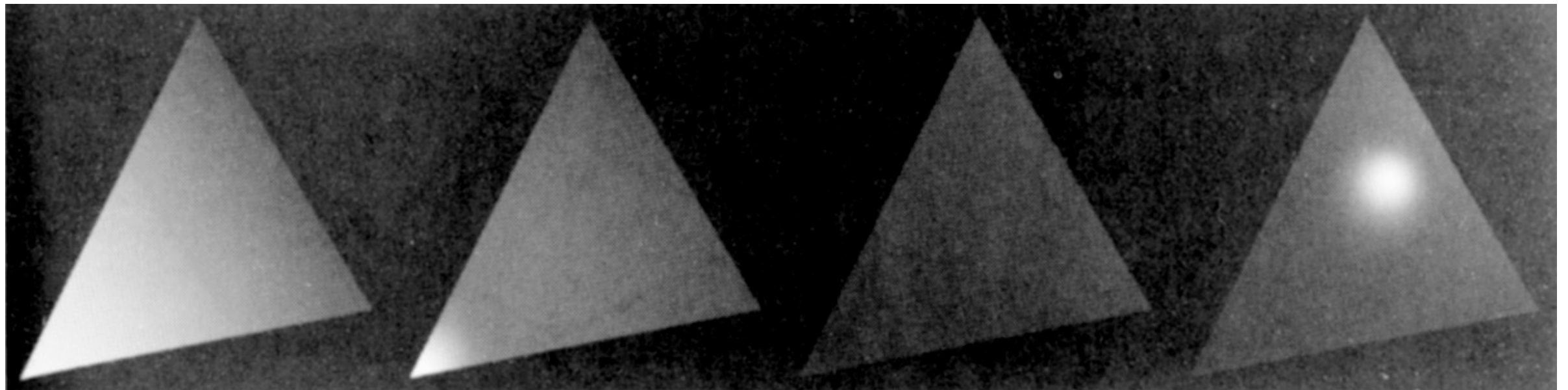


[Foley et al.]



# Per-pixel (Phong) shading

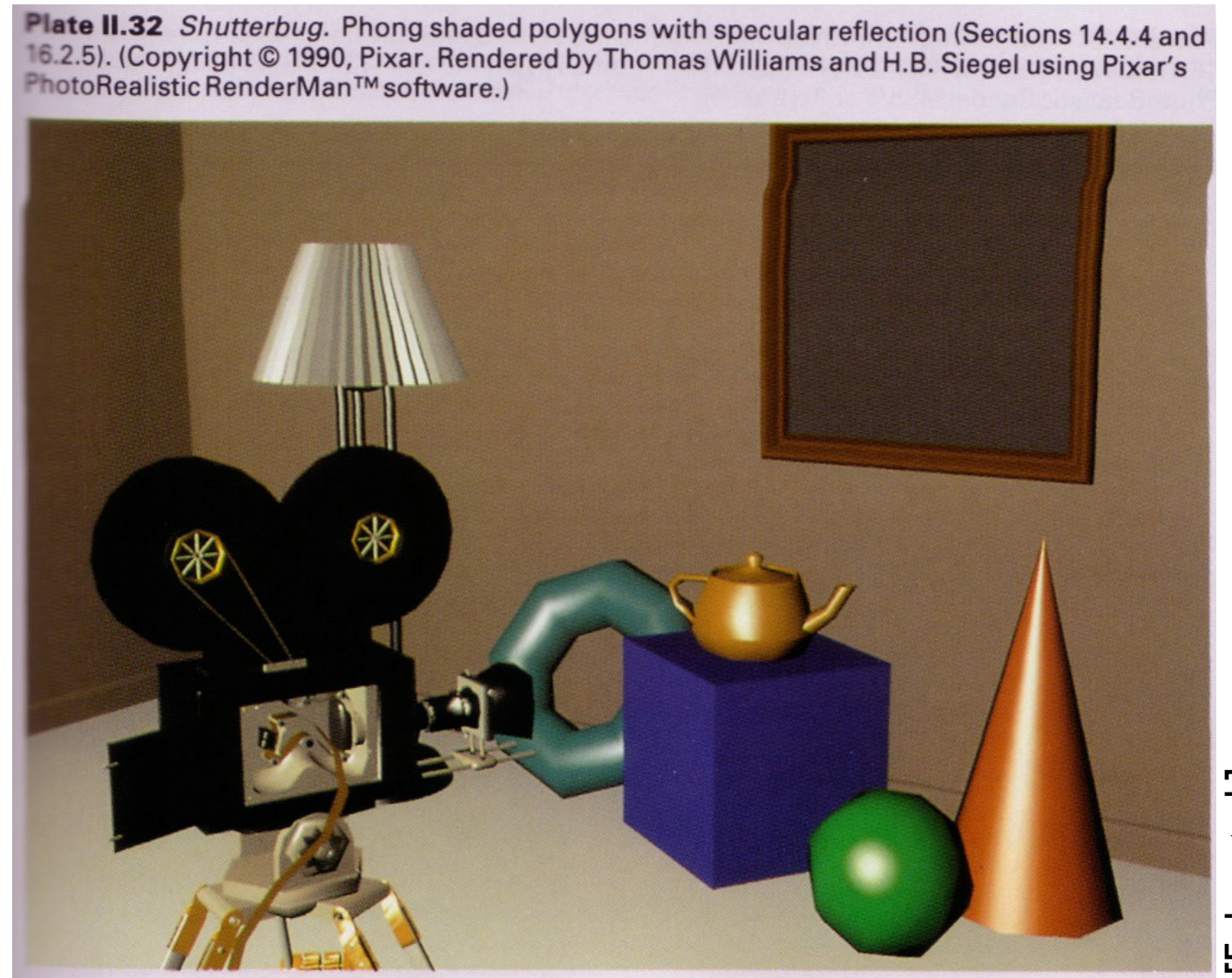
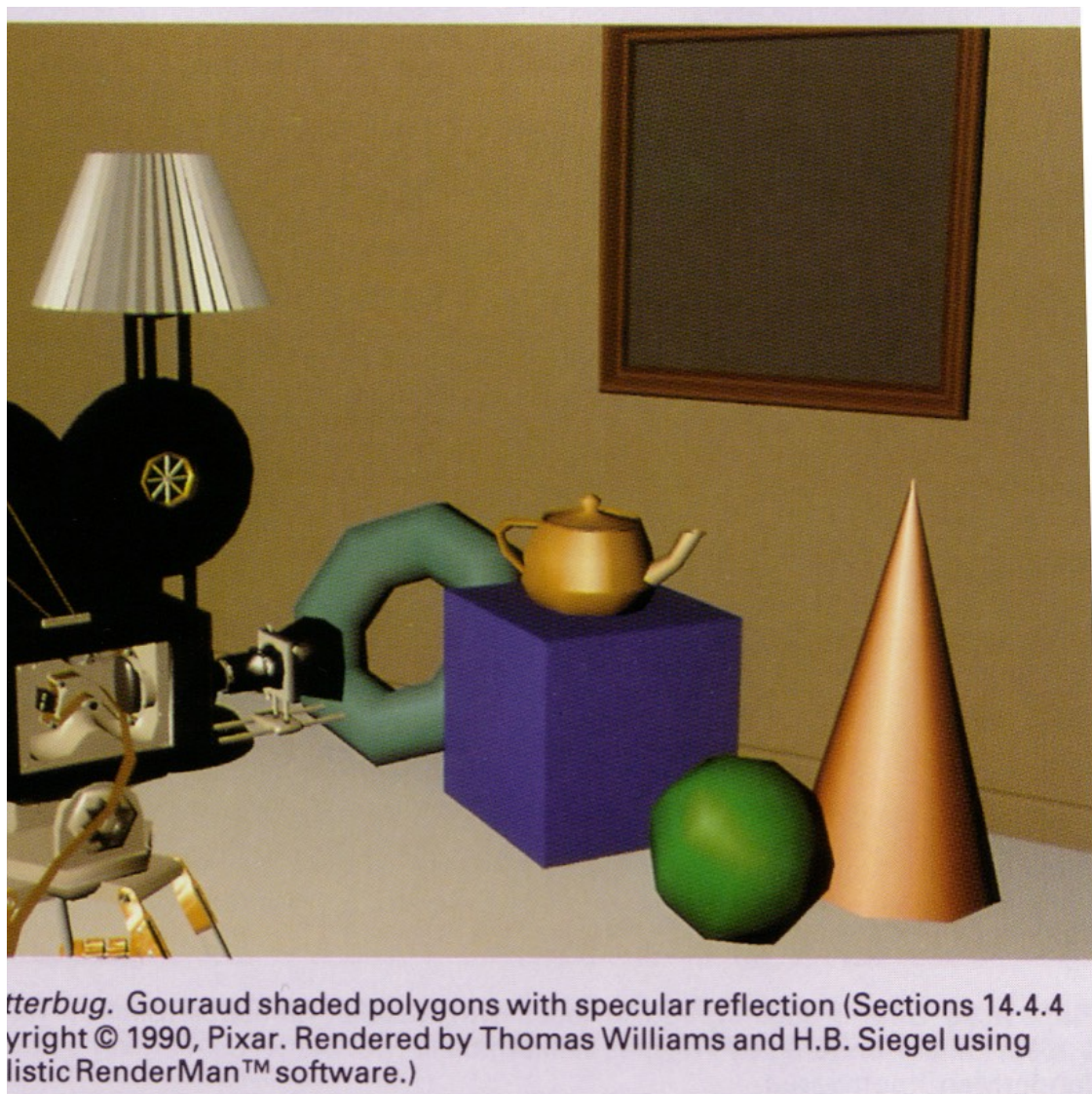
- **Get higher quality by interpolating the normal**
  - just as easy as interpolating the color
  - but now we are evaluating the illumination model per pixel rather than per vertex (and normalizing the normal first)
  - in pipeline, this means we are moving illumination from the vertex processing stage to the fragment processing stage





# Per-pixel (Phong) shading

- **Bottom line: produces much better highlights**



[Foley et al.]

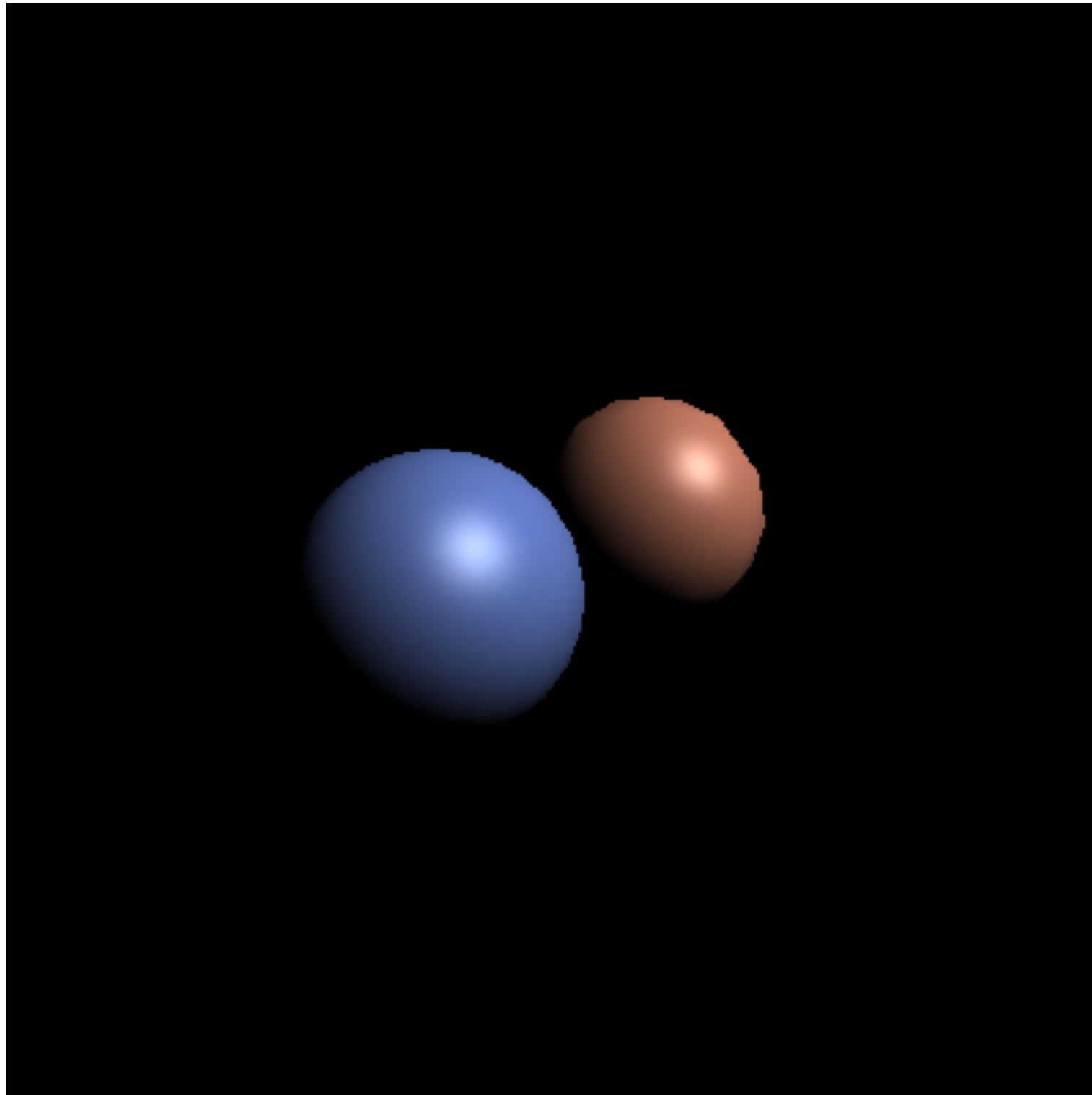
# Pipeline for per-pixel shading

**Demo**

- **Vertex stage (input: position and normal / vtx)**
  - transform position and normal (object to eye space)
  - transform position (eye to screen space)
- **Rasterizer**
  - interpolated parameters:  $z'$  (screen  $z$ );  $x, y, z$  normal
- **Fragment stage (output: color,  $z'$ )**
  - compute shading using fixed color and interpolated normal
  - write to color planes only if interpolated  $z' <$  current  $z'$



# Result of per-pixel shading pipeline



# Programming hardware pipelines

- **Modern hardware graphics pipelines are flexible**
  - programmer defines exactly what happens at each stage
  - do this by writing *shader programs* in domain-specific languages called *shading languages*
  - rasterization is fixed-function, as are some other operations (depth test, many data conversions, ...)
- **One example: OpenGL and GLSL (GL Shading Language)**
  - several types of shaders process primitives and vertices; most basic is the *vertex program*
  - after rasterization, fragments are processed by a *fragment program*

# GLSL Shaders

