

March 22, 2021

Subspace iteration

$$\{ \underline{Q}_0 \in \mathbb{R}^{n \times d} \quad \underline{Q}_0^T \underline{Q}_0 = I$$

for $k=0, 1, 2, \dots$

$$\underline{z}_k = A \underline{Q}_k$$

$$\underline{Q}_{k+1} \underline{R}_{k+1} = \underline{z}_k$$

$$|\lambda_d / \lambda_{d+1}|^k \rightarrow 0$$

$d=1 \Rightarrow$ power method

$d=n$

$$\hat{A} = \hat{Q}_k = \hat{Q}_{k+1} \hat{R}_{k+1}$$

$$A = \underline{Q}_{k+1} \underline{R}_{k+1} \underline{Q}_k^T$$

$$\underline{Q}_k = \underline{Q}_{k+1} = \underline{Q} \quad A = \underline{Q} \begin{matrix} \diagup \\ \diagdown \end{matrix} \underline{Q}^T$$

Schur form!

$$\textcircled{1} \underline{Q}_k^T A \underline{Q}_k = \underline{T}_k \rightarrow T$$

\textcircled{2} Diagonal of $T \Rightarrow$ evals of A

\textcircled{3} $\underline{T}_k \Rightarrow$ approx evals of A

$$\begin{aligned} \underline{T}_{k+1} &= \underline{Q}_{k+1}^T A \underline{Q}_{k+1} \\ &= \underbrace{\underline{Q}_{k+1}^T A \underline{Q}_k}_{\underline{R}_{k+1}} \underbrace{\underline{Q}_k^T \underline{Q}_{k+1}}_{\underline{Q}_{k+1}} \end{aligned}$$

QR iteration

$$\underline{T}_0 = A$$

for $k=0, 1, 2, \dots$

$$(QR) \quad \underline{Q}_{k+1} \underline{R}_{k+1} = \underline{T}_k \quad \underline{R}_{k+1} = \underline{Q}_{k+1}^T \underline{T}_k$$

$$\begin{aligned} (\text{Matmul}) \underline{T}_{k+1} &= \underline{R}_{k+1} \underline{Q}_{k+1} \\ &= \underline{Q}_{k+1}^T \underline{T}_k \underline{Q}_{k+1} \end{aligned}$$

Can show: $\underline{Q}_{k+1} = \underline{Q}_1 \dots \underline{Q}_k$
 \underline{R} same as in SF ($d=n$)

Things to worry about

① QR fact + matmul each step $\Rightarrow O(n^3)$ per step

T_{R^v}

$Q_0^T Q_0$

Q_0

Q_0

③ Stable?

just QR, mult by orthog matrices

$$(M = Q B Q^T) \quad B \text{ sym}$$
$$M^T = (Q^T)^T B^T Q^T$$
$$= Q B Q^T$$