CS412/CS413

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Lecture 21: Generating Pentium Code 10 March 08

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Simple Code Generation

- Three-address code makes it easy to generate assembly ۲
 - Complex expressions in the input program already lowered to sequences of simple IR instructions
 - Just need to translate each low IR instruction into a sequence of assembly instructions

e.g. a = p+q mov 16(%ebp), %ecx add 8(%ebp), %ecx mov %ecx, -8(%ebp)

- Need to consider many language constructs:
 - Operations: arithmetic, logic, comparisons
 - Accesses to local variables, global variables
 - Array accesses, field accesses
 - Control flow: conditional and unconditional jumps
 - Method calls, dynamic dispatch
 - Dynamic allocation (new)
 - Run-time checks

x86 Quick Overview

- Registers:
 - General purpose 32bit: eax, ebx, ecx, edx, esi, edi
 - Also 16-bit: ax, bx, etc., and 8-bit: al, ah, bl, bh, etc.
 - Stack registers: esp, ebp
- Instructions:
 - Arithmetic: add, sub, inc, mod, idiv, imul, etc.
 - Logic: and, or, not, xor
 - Comparison: cmp, test
 - Control flow: jmp, jcc, jecz
 - Function calls: call, ret
 - Data movement: mov (many variants)
 - Stack manipulations: push, pop
 - Other: lea



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Memory Layout



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Accessing Stack Variables

- To access stack variables: use offsets from ebp
- Example: 8(%ebp) = parameter 1 12(%ebp) = parameter 2 -4(%ebp) =local 1



Accessing Stack Variables

- Translate accesses to variables:
 - For parameters, compute offset from %ebp using:
 - Parameter number
 - Sizes of other parameters
 - For local variables, decide on data layout and assign offsets from frame pointer to each local
 - Store offsets in the symbol table
 - Keep track of high-water mark for frame allocation

• Example:

- a: local, offset-4
- p: parameter, offset+16, q: parameter, offset+8
- Assignment a = p + q becomes equivalent to:

-4(%ebp) = 16(%ebp) + 8(%ebp)

– How to write this in assembly?

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Arithmetic

- How to translate: p+q?
 - Assume p and q are locals or parameters
 - Determine offsets for p and q
 - Perform the arithmetic operation
- Problem: the ADD instruction in x86 cannot take both operands from memory; notation for possible operands:
 - mem32: register or memory 32 bit (similar for r/m8, r/m16)
 - reg32: register 32 bit (similar for reg8, reg16)
 - imm32: immediate 32 bit (similar for imm8, imm16)
 - At most one operand can be mem !
- Translation requires using an extra register
 - Place p into a register (e.g. %ecx): mov 16(%ebp), %ecx
 - Perform addition of q and %ecx: add 8(%ebp), %ecx

Data Movement

- Translate a = p+q:
 - Load memory location (p) into register (%ecx) using a move instr.
 - Perform the addition
 - Store result from register into memory location (a):

mov 16(%ebp), %ecx	(load)
add 8(%ebp), %ecx	(arithmetic)
mov %ecx, -8(%ebp)	(store)

 Move instructions cannot have two memory operands Therefore, copy instructions must be translated using an extra register:

a = p ⇒ mov 16(%ebp), %ecx mov %ecx, -8(%ebp)

• However, loading constants doesn't require extra registers:

 $a = 12 \implies mov \$12, -8(\%ebp)$

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Accessing Global Variables

- Global (static) variables and constants not stack allocated
- Have fixed addresses throughout the execution of the program
 - Compile-time known addresses (relative to the base address where program is loaded)
 - Hence, can directly refer to these addresses using symbolic names in the generated assembly code
- Example: string constants

str: .string "Hello world!"

- The string will be allocated in the static area of the program
- Here, "str" is a label representing the address of the string
- Can use **\$str** as a constant in other instructions:

push \$str

Accessing Heap Data

- Heap data allocated with new (Java) or malloc (C/C++)
 - Such allocation routines return address of allocated data
 - References to data stored into local variables
 - Access heap data through these references
- Array accesses in language with dynamic array size
 - access a[i] requires:
 - Compute address of element: a + i * size
 - Access memory at that address
 - Can use indexed memory accesses to compute addresses
 - Example: assume size of array elements is 4 bytes, and local variables a, i (offsets -4, -8)

a[i] = 1mov -4(%ebp), %ebx(load a)mov -8(%ebp), %ecx(load i)mov \$1, (%ebx,%ecx,4)(store into the heap)

Control-Flow

- Label instructions
 - Simply translated as labels in the assembly code
 - E.g., label2: mov \$2, %ebx
- Unconditional jumps:
 - Use jump instruction, with a label argument
 - E.g., jmp label2
- Conditional jumps:
 - Translate conditional jumps using test/cmp instructions:
 - E.g., tjump b L cmp %ecx, \$0

jnz L

where %ecx hold the value of b, and we assume booleans are represented as 0=false, 1=true

Run-time Checks

- Run-time checks:
 - Check if array/object references are non-null
 - Check if array index is within bounds
- Example: array bounds checks:
 - if v holds the address of an array, insert array bounds checking code for v before each load (...=v[i]) or store (v[i] = ...)
 - Assume array length is stored just before array elements:

cmp \$0, -12(%ebp) jl ArrayBoundsError mov –8(%ebp), %ecx mov –4(%ecx), %ecx cmp –12(%ebp), %ecx jle ArrayBoundsError

(compare i to 0)
(test lower bound)
(load v into %ecx)
(load array length into %ecx)
(compare i to array length)
(test upper bound)

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X86 Assembly Syntax

- Two different notations for assembly syntax:
 - AT&T syntax and Intel syntax
 - In the examples: AT&T syntax
- Summary of differences:

Order of operands	op a, b : b is destination	op a, b : a is destination
Memory addressing	disp(base,offset,scale)	[base + offset*scale + disp]
Size of memory operands	instruction suffixes (b,w,l) (e.g., movb, movw, movl)	operand prefixes (byte ptr, word ptr, dword ptr)
Registers	%eax, %ebx, etc.	eax, ebx, etc.
Constants	\$4, \$foo, etc	4, foo, etc