

CS 4110

Programming Languages & Logics

Lecture 19
Continuations



Continuations

In the preceding translations, the control structure of the source language was translated directly into the corresponding control structure in the target language.

For example:

$$\mathcal{T}[\lambda x. e] = \lambda x. \mathcal{T}[e]$$

$$\mathcal{T}[e_1 e_2] = \mathcal{T}[e_1] \mathcal{T}[e_2]$$

What can go wrong with this approach?

Continuations

- A snippet of code that represents “the rest of the program”
- Can be used directly by programmers...
- ...or in program transformations by a compiler
- Make the control flow of the program explicit
- Also useful for defining the meaning of features like exceptions

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The original expression is equivalent to k_3 1, or:

$$(\lambda c. (\lambda b. (\lambda a. (\lambda v. (\lambda x. x) v) (a - 4)) (3 * b)) (c + 2)) 1$$

Example (Continued)

Recall that $\text{let } x = e \text{ in } e'$ is syntactic sugar for $(\lambda x. e') e$.

Hence, we can rewrite the expression with continuations more succinctly as

```
let c = 1 in
let b = c + 2 in
let a = 3 * b in
let v = a - 4 in
( $\lambda x. x$ ) v
```

CPS Transformation

We write $CPS[e] k = \dots$ instead of $CPS[e] = \lambda k. \dots$

We assume that the new variables introduced are “fresh.”

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$$CPS[\#1 e] k = CPS[e] (\lambda v. k (\#1 v))$$

$$CPS[\#2 e] k = CPS[e] (\lambda v. k (\#2 v))$$