

## Lab 10 Worksheet: Shall we execute some commands?

### 1. Call Me Maybe

#### Part 1A

When a program performs a system call, several steps need to be taken as control transfers between the user space and the operating system kernel. Given the following steps, please arrange them in the **correct order of execution**.

- A. Switch to kernel space
- B. Return to instruction after the system call
- C. Handler finishes
- D. Application makes a system call (ecall on RISC-V)
- E. Switch to user space
- F. Trap handler runs

#### Part 1B

Compare **traps**, **interrupts**, and **system calls** – how are they similar and how do they differ?

### 2. Fork or be Forked

Assume the **parent process's PID is 5** and that when the **fork** call succeeds, the **child process is assigned PID**

10. Please fill in the results of the print statements for parts (a) and (b) and answer part (c):

```
// omitted imports
int main(void) {
    pid_t pid = fork();
    if (pid) { printf("A: pid = %d\n", pid); } (a) "A: pid = _____"
    else { printf("B: pid = %d\n", pid); } (b) "B: pid = _____"
    wait(NULL);
    printf("C: pid = %d\n", pid); (c) How many line C's are printed? _____
    return 0;
}
```

Is there an order? \_\_\_\_\_

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### 3. Caught Napping

#### Part 3A

Examine the following partial implementation of `myint`, which sleeps for  $n$  seconds (in 1-second chunks) before sending `SIGINT` to itself. Please complete the `main` function.

```
// omitted imports
int main(int argc, char **argv) {
    for (int i = 0; i < atoi(argv[1]); i++) { (a)_____((1)); }
    kill((b)_____, (c)_____);
    exit(0);
}
```

#### Part 3B

If we insert `pid_t pid = fork();` before the `for` loop, how do we modify the program such that `SIGTERM` is sent to the child process? What is the exit code of the main program?

#### Part 3C

Explain briefly the difference between the `SIGINT`, `SIGTERM`, and `SIGKILL` signals.

## 4. Reaping Child Processes

Examine the following program and answer the following questions:

```
int main() {
    int status;
    pid_t pid = fork();
    if (pid == 0) {
        exit(3);
    }
    waitpid(pid, &status, 0);
    if (WIFEXITED(status)) {
        printf("Exited");
    } else if (WIFSIGNALED(status)) {
        printf("Terminated");
    }
    return 0;
}
```

What will be printed when this program is run?

- A. “Exited”
- B. “Terminated”

Suppose `exit(3)` is replaced with `abort()`. What will be printed now?

- A. “Exited”
- B. “Terminated”

Suppose the child crashes due to an invalid memory access (segmentation fault). What will the program print?

- A. “Exited”
- B. “Terminated”