#### CS3410

#### **Guest Lecture**

A Simple CPU: remaining branch instructions CPU Performance Pipelined CPU

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# Examples (big/little endian): # r5 contains 5 (0x00000005)

sb r5, 2(r0) lb r6, 2(r0)

sw r5, 8(r0) lb r7, 8(r0) lb r8, 11(r0)

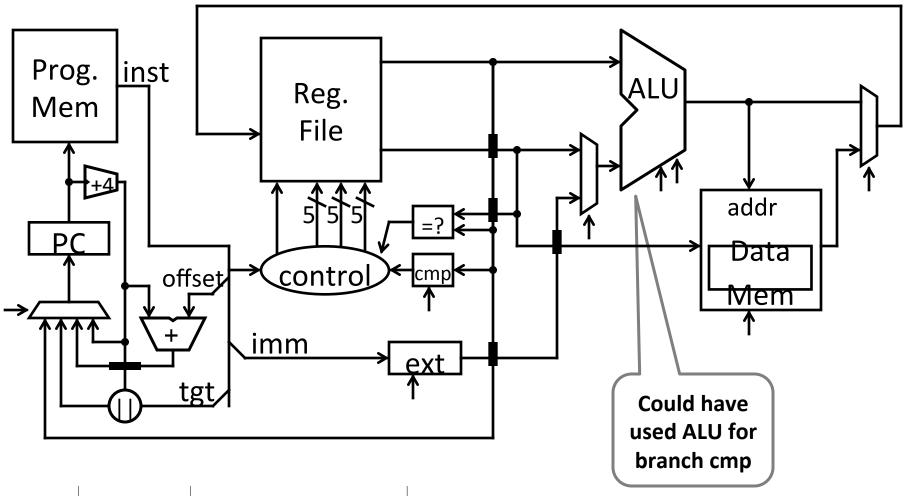
0x00000000
0x00000001
0x00000002
0x00000003
0x00000004
0x00000005
0x00000006
0x00000007
0x00000008
0x00000009
0x00000000a
0x0000000b
• • •
0xffffffff

Control Flow: More Branches

# Conditional Jumps (cont.)

#### 

				I
	ор	rs subop	offset -	almost I-Type
	6 bits	5 bits 5 bits	16 bits	
				igned offsets
ор	subop	mnemonic	description	miscus )
0x1	0x0	BLTZ rs, offset	if R[rs] < 0 then PC = PC+	4+ (offset<<2)
0x1	0x1	BGEZ rs, offset	if R[rs] ≥ 0 then PC = PC+	4+ (offset<<2)
0x6	0x0	BLEZ rs, offset	if R[rs] ≤ 0 then PC = PC+	4+ (offset<<2)
0x7	0x0	BGTZ rs, offset	if R[rs] > 0 then PC = PC+	4+ (offset<<2)



ор	subop	mnemonic	description
0x1	0x0	BLTZ rs, offset	if R[rs] < 0 then PC = PC+4+ (offset<<2)
0x1	0x1	BGEZ rs, offset	if R[rs] $\geq$ 0 then PC = PC+4+ (offset<<2)
0	0.40	חורז בב בבב	:t D[12] > U TP 22 DC - DC 1 V 1 /2ft 27 > 3/

Control Flow: Jump and Link

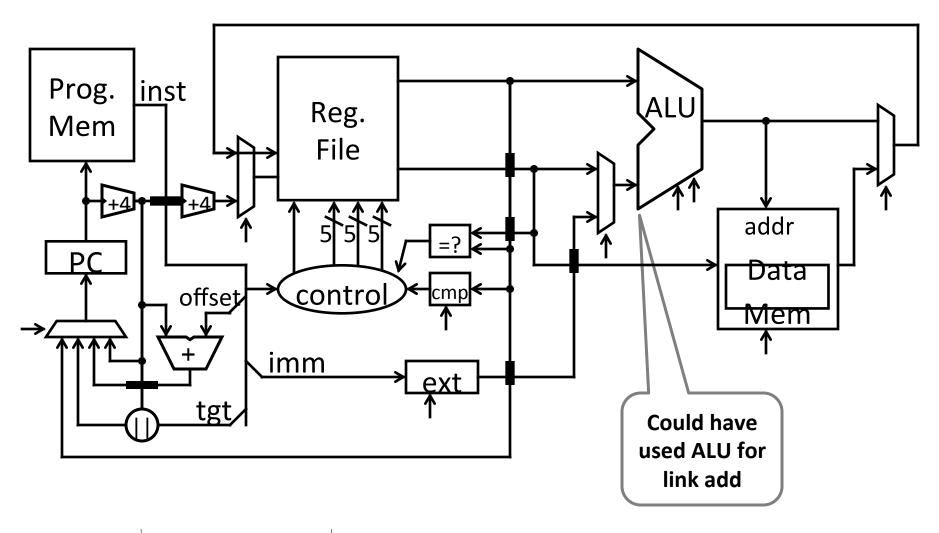
## Function/procedure calls

#### 00001100000001001000011000000010

op immediate J-Type
6 bits 26 bits

ор	mnemonic	description
0x3	JAL target	r31 = PC+8 (+8 due to branch delay slot) PC = (PC+4)    (target << 2)

ор	mnemonic	description	description	
0x2	J target	PC = (PC+4)	(target << 2)	



ор	mnemonic	description
0x3	JAL target	r31 = PC+8 (+8 due to branch delay slot) PC = (PC+4)    (target << 2)

# Performance

See: P&H 1.4

### What to look for in a computer system?

- Correctness: negotiable?
- Cost
- -purchase cost = f(silicon size = gate count, economics)
- -operating cost = f(energy, cooling)
- -operating cost >= purchase cost
- Efficiency
- -power = f(transistor usage, voltage, wire size, clock rate, ...)
- -heat = f(power)
  - Intel Core i7 Bloomfield: 130 Watts
  - AMD Turion: 35 Watts
  - Intel Core 2 Solo: 5.5 Watts
  - Cortex-A9 Dual Core @800MHz: 0.4 Watts
- Performance
- Other: availability, size, greenness, features, ...

### How to measure performance?

GHz (billions of cycles per second)
MIPS (millions of instructions per second)
MFLOPS (millions of floating point operations per second)
benchmarks (SPEC, TPC, ...)

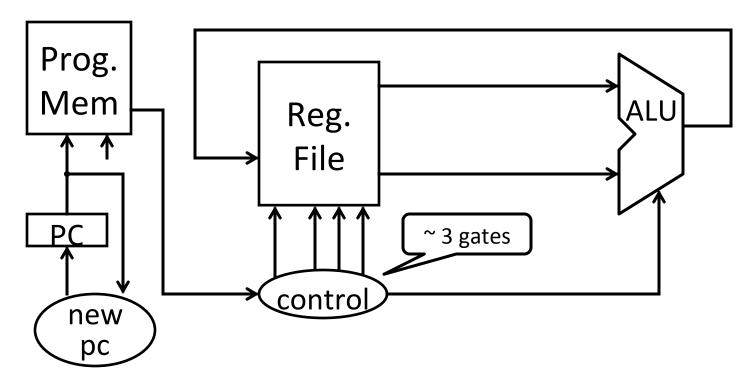
#### **Metrics**

latency: how long to finish my

program

throughput: how much work

finished per unit time



#### Assumptions:

- alu: 32 bit ripple carry + some muxes
- next PC: 30 bit ripple carry
- control: minimized for delay (~3 gates)
- transistors: 2 ns per gate
- prog,. memory: 16 ns (as much as 8 gates)
- register file: 2 ns access
- ignore wires, register setup time

#### Better:

- alu: 32 bit carry lookahead + some muxes (~ 9 gates)
- next PC: 30 bit carry lookahead (~ 6 gates)

#### Better Still:

• next PC: cheapest adder faster than 21 gate delays

#### All signals are stable

- 80 gates => clock period of at least 160 ns, max frequency  $^{\sim}6MHz$  Better:
- 21 gates => clock period of at least 42 ns, max frequency ~24MHz

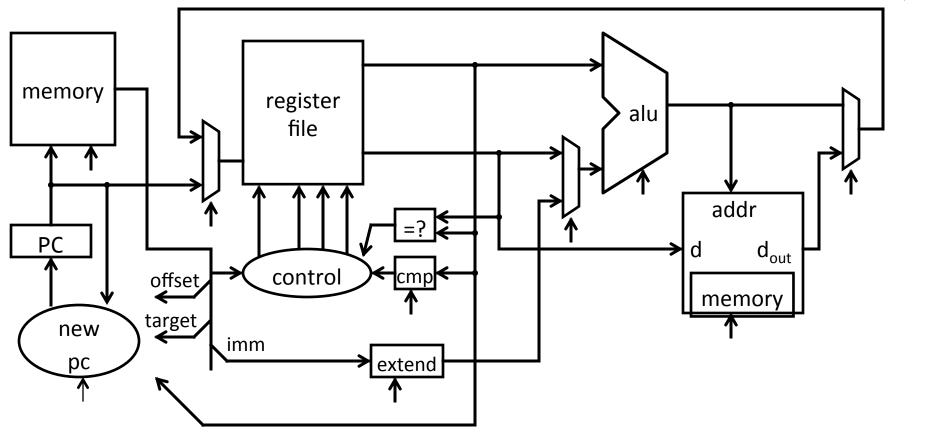
32 Bit Adder Design	Space	Time
Ripple Carry	≈ 300 gates	≈ 64 gate delays
2-Way Carry-Skip	≈ 360 gates	≈ 35 gate delays
3-Way Carry-Skip	≈ 500 gates	≈ 22 gate delays
4-Way Carry-Skip	≈ 600 gates	≈ 18 gate delays
2-Way Look-Ahead	≈ 550 gates	≈ 16 gate delays
Split Look-Ahead	≈ 800 gates	≈ 10 gate delays
Full Look-Ahead	≈ 1200 gates	≈ 5 gate delays

#### Critical Path

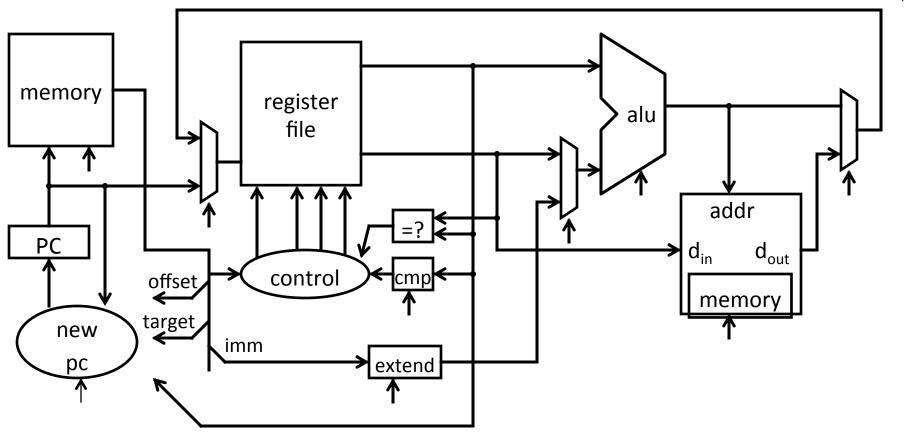
- Longest path from a register output to a register input
- Determines minimum cycle, maximum clock frequency

### Strategy 1 (we just employed)

- Optimize for delay on the critical path
- Optimize for size / power / simplicity elsewhere
  - next PC



ор	mnemonic	description
0x20	LB rd, offset(rs)	R[rd] = sign_ext(Mem[offset+R[rs]])
0x23	LW rd, offset(rs)	R[rd] = Mem[offset+R[rs]]
0x28	SB rd, offset(rs)	Mem[offset+R[rs]] = R[rd]
0x2h	SW/rd offset(rs)	Meminffset+Rirsil = Rirdi



ор	func	mnemonic	description
0x0	0x08	JR rs	PC = R[rs]

ор	mnemonic	description		
0x2	J target	PC = (PC+4)	(target << 2)	4

#### Strategy 2

Multiple cycles to complete a single instruction

#### E.g: Assume:

load/store: 100 ns

arithmetic: 50 ns

branches: 33 ns

#### Multi-Cycle CPU

- 3 cycles per load/store
- 2 cycles per arithmetic
- 1 cycle per branch

Faster than Single-Cycle CPU? 10 MHz (100 ns cycle) with

1 cycle per instruction

#### *Instruction mix* for some program P, assume:

- 25% load/store (3 cycles / instruction)
- 60% arithmetic (2 cycles / instruction)
- 15% branches (1 cycle / instruction)

Multi-Cycle performance for program P:

$$3 * .25 + 2 * .60 + 1 * .15 = 2.1$$

average cycles per instruction (CPI) = 2.1

Multi-Cycle @ 30 MHz Single-Cycle @ 10 MHz Single-Cycle @ 15 MHz

800 MHz PIII "faster" than 1 GHz P4

# Goal: Make Multi-Cycle @ 30 MHz CPU (15MIPS) run 2x faster by making arithmetic instructions faster

#### *Instruction mix* (for P):

- 25% load/store, CPI = 3
- 60% arithmetic, CPI = 2
- 15% branches, CPI = 1

#### Amdahl's Law

Execution time after improvement =

```
execution time affected by improvement + execution time unaffected amount of improvement
```

#### Or:

Speedup is limited by popularity of improved feature

#### Corollary:

Make the common case fast

#### Caveat:

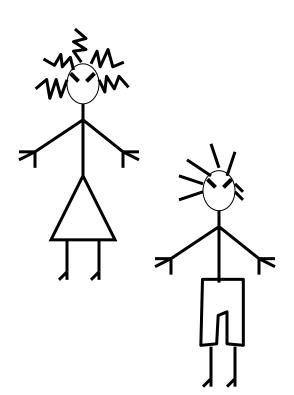
Law of diminishing returns

# **Pipelining**

See: P&H Chapter 4.5

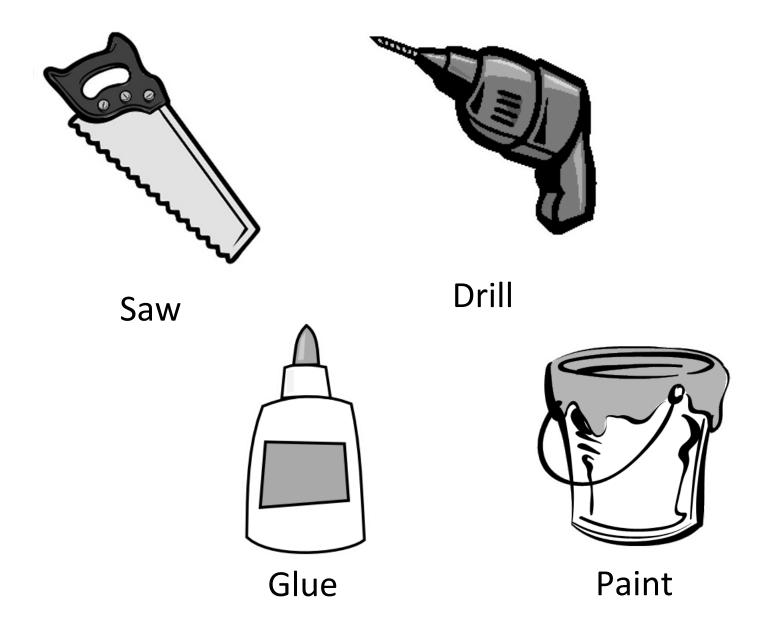
Alice

Bob

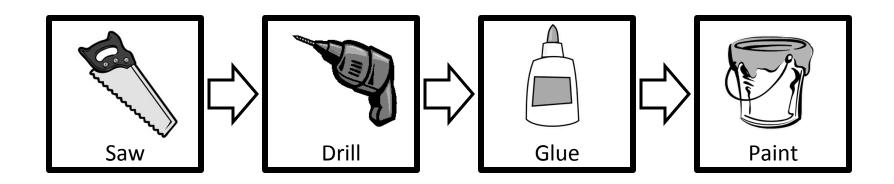


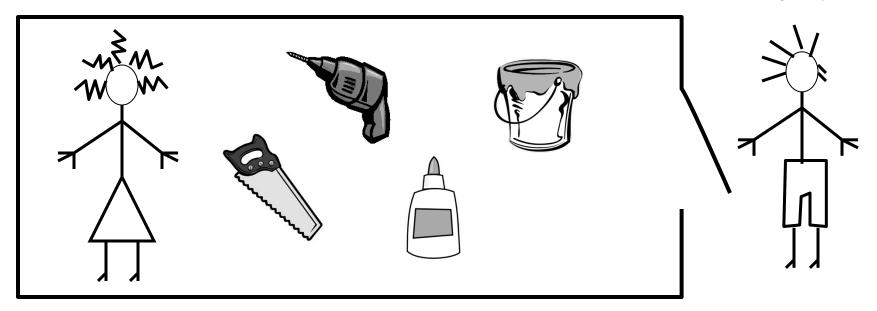
They don't always get along...





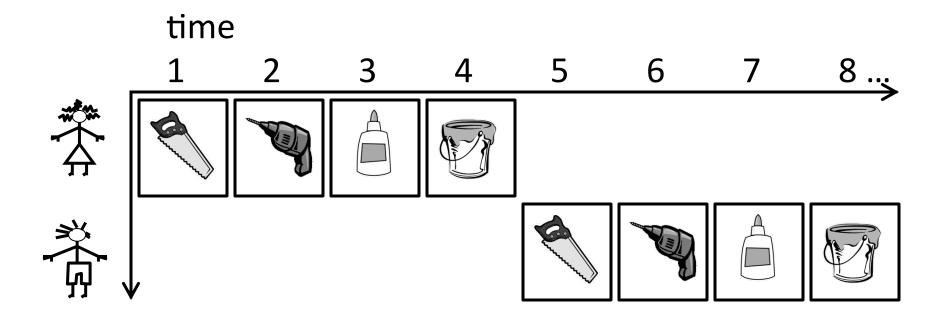
### N pieces, each built following same sequence:





Alice owns the room

Bob can enter when Alice is finished
Repeat for remaining tasks
No possibility for conflicts

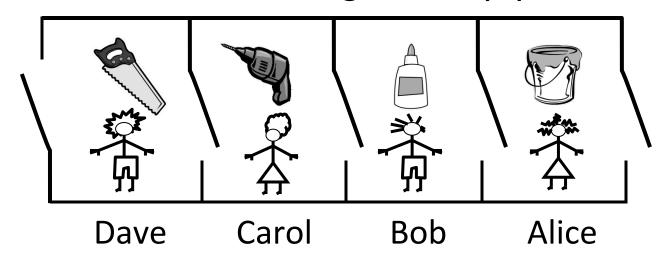


Throughput:

Concurrency:

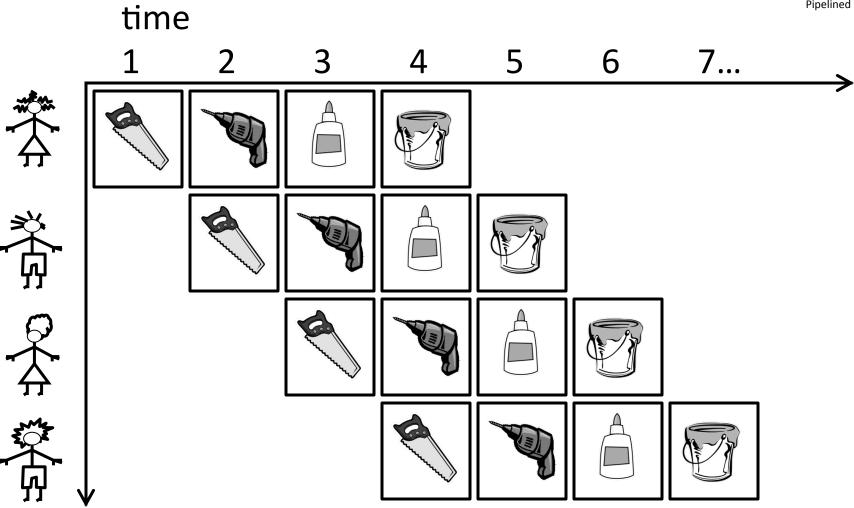
Can we do better?

#### Partition room into stages of a pipeline



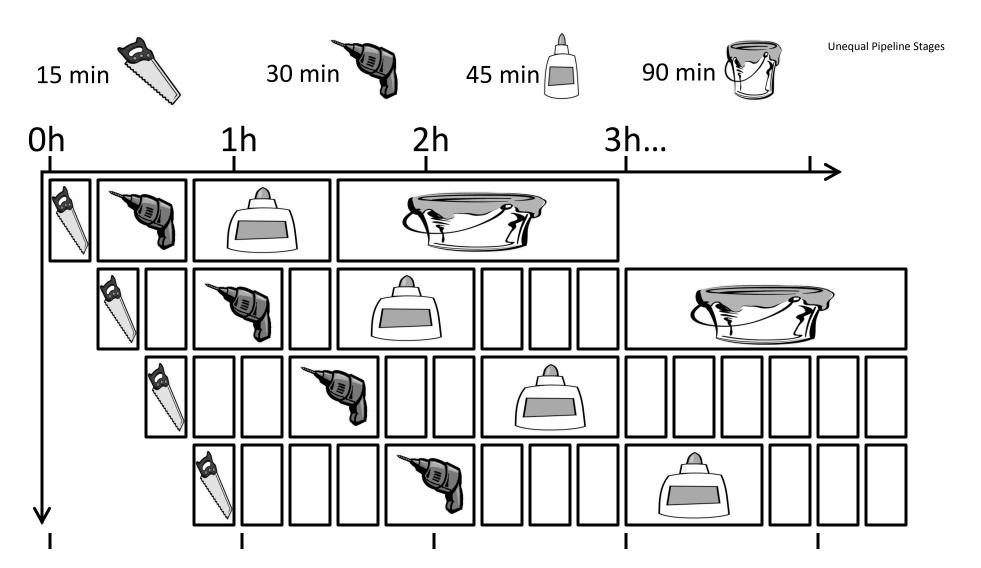
One person owns a stage at a time 4 stages

4 people working simultaneously Everyone moves right in lockstep



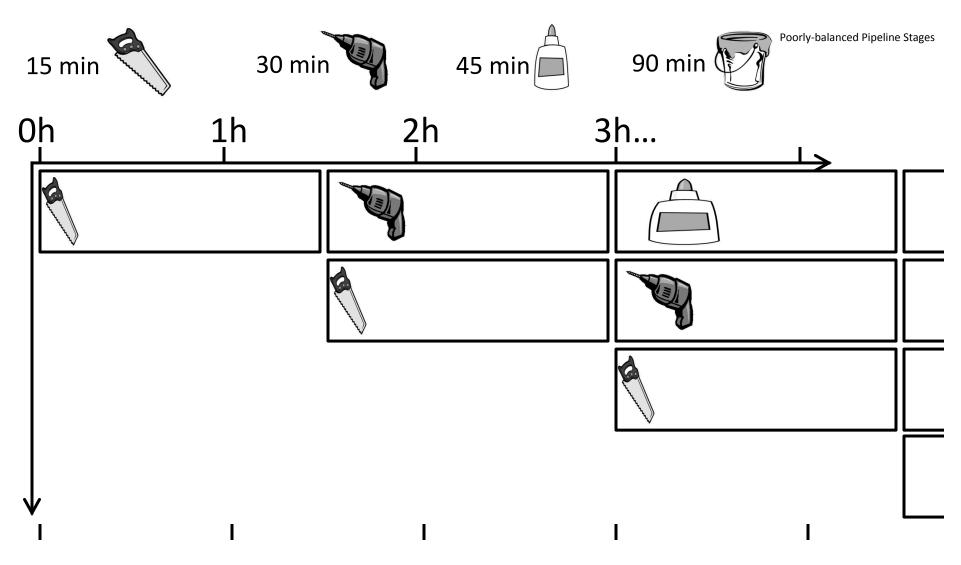
Throughput:

Concurrency:



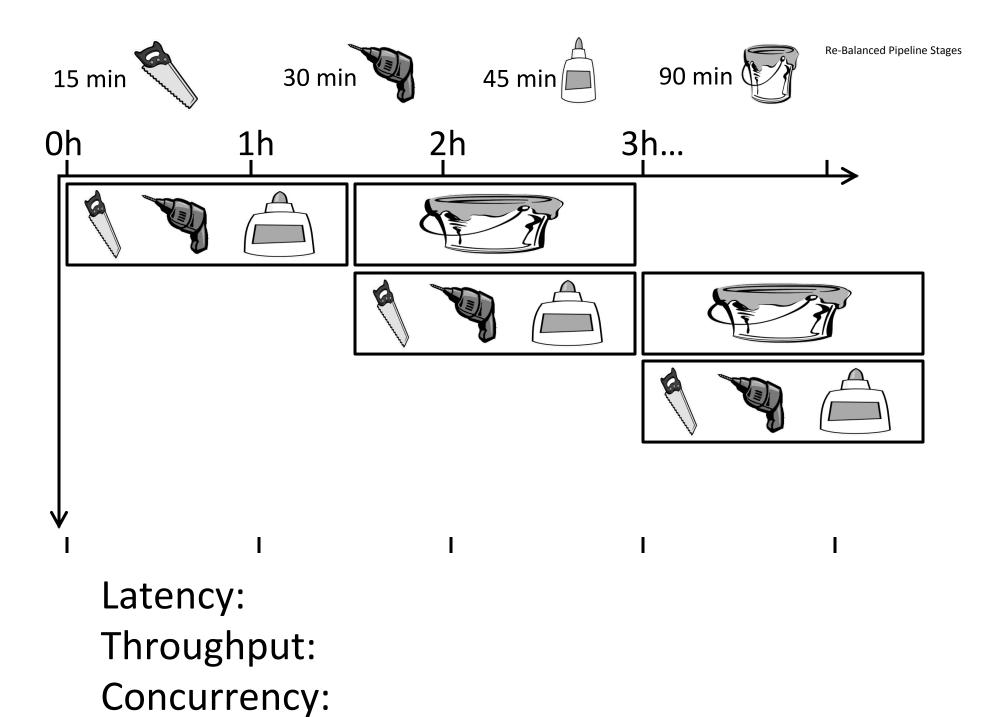
Throughput:

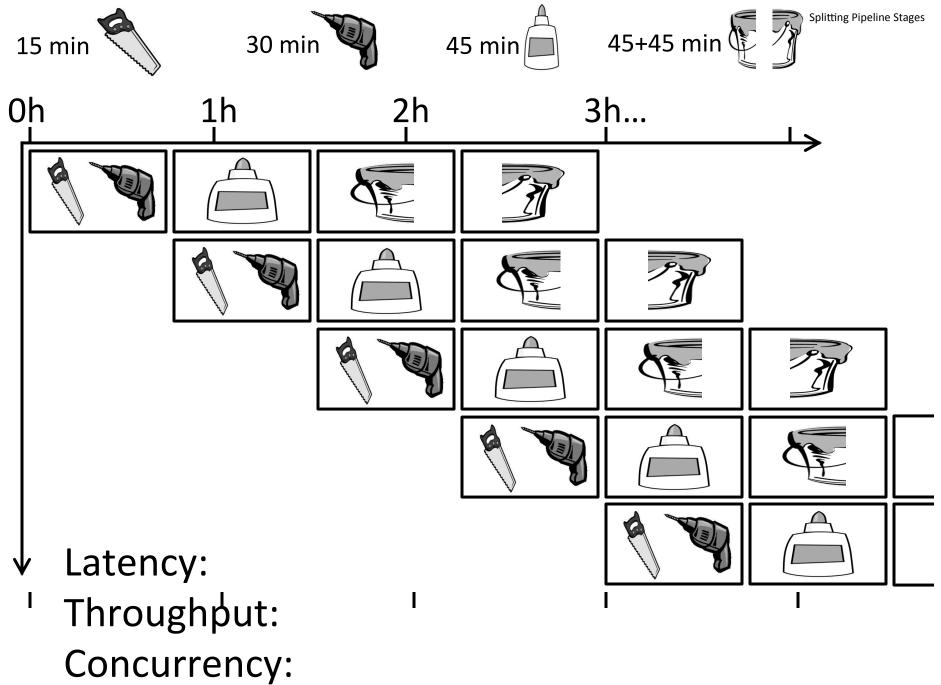
Concurrency:



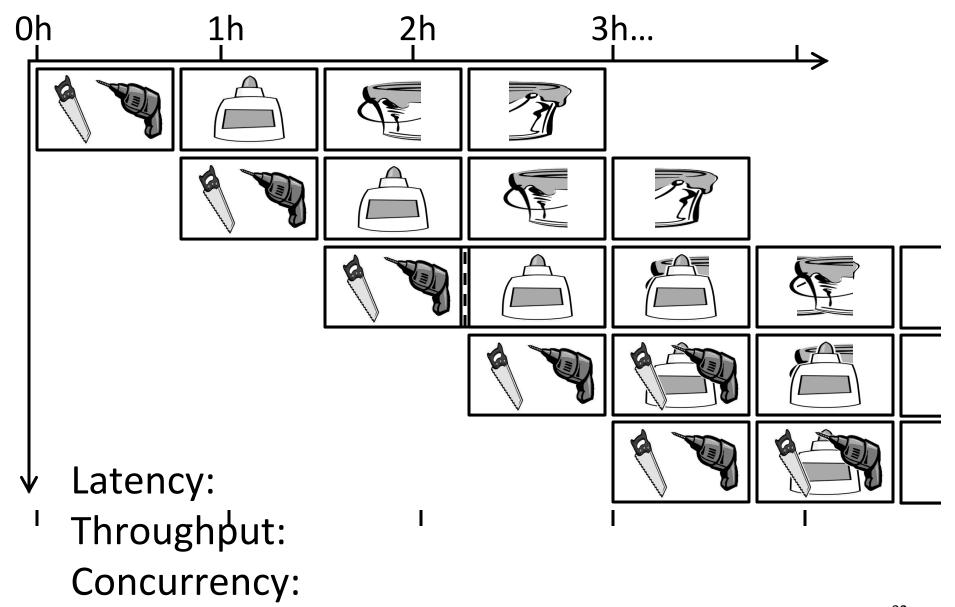
Throughput:

Concurrency:





Q: What if glue step of task 3 depends on output of task 1?

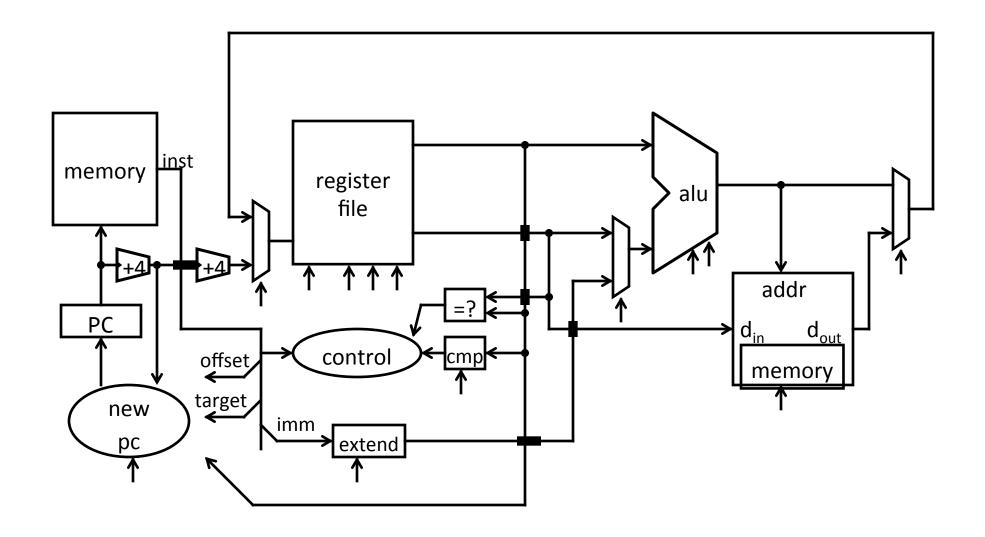


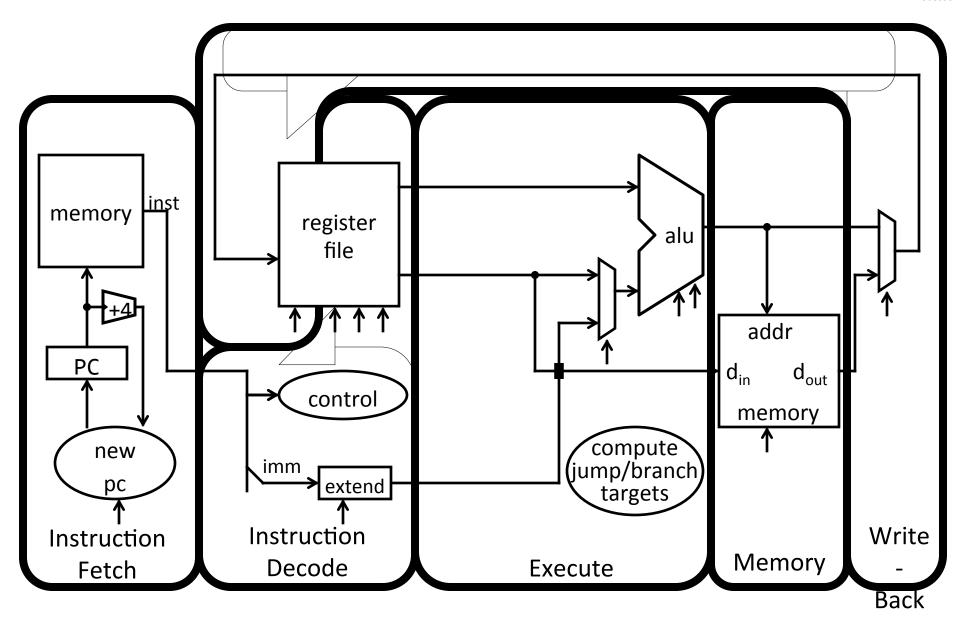
### Principle:

Throughput increased by parallel execution

#### Pipelining:

- Identify pipeline stages
- Isolate stages from each other
- Resolve pipeline *hazards*





### Five stage "RISC" load-store architecture

- 1. Instruction fetch (IF)
  - get instruction from memory, increment PC
- 2. Instruction Decode (ID)
  - translate opcode into control signals and read registers
- 3. Execute (EX)
  - perform ALU operation, compute jump/branch targets
- 4. Memory (MEM)
  - access memory if needed
- 5. Writeback (WB)
  - update register file

Break instructions across multiple clock cycles (five, in this case)

Design a separate stage for the execution performed during each clock cycle

Add pipeline registers (flip-flops) to isolate signals between different stages