

Hash Tables

Prof. Clarkson Fall 2015

Today's music: Re-hash by Gorillaz

Review

Current topic: Reasoning about performance

- Efficiency
- Big Oh
- Amortized analysis

Today:

Implementation and efficiency analysis of hash tables

Question

How often do you dictionaries/maps/hash tables/associative arrays/etc. in your own programming?

- A. Never
- B. Infrequently
- C. Frequently
- D. Nearly every program I write
- E. Compilers

Maps*

end

```
module type MAP = sig
  type ('k, 'v) map
  val insert:
     'k \rightarrow 'v \rightarrow ('k, 'v) map \rightarrow ('k, 'v) map
  val find:
     'k -> ('k, 'v) map -> 'v option
  val remove:
     'k \rightarrow ('k, 'v) map \rightarrow ('k, 'v) map
```

*aka associative array, dictionary, symbol table

Mutable Maps*

```
module type MAP = sig
  type ('k, 'v) map
  val insert:
     'k -> 'v -> ('k, 'v) map -> unit
  val find:
     'k \rightarrow ('k, 'v) \text{ map } \rightarrow 'v \text{ option}
  val remove:
     'k -> ('k, 'v) map -> unit
end
```

*aka associative array, dictionary, symbol table

Map implementations

- Immutable:
 - Association lists
 - Balanced search trees
- Mutable
 - Arrays
 - Hash tables

Map implementations

For each implementation:

- What is the representation type?
- What is the abstraction function?
- What are the representation invariants (if any)?
- What is the efficiency of each operation?

Association lists

• Representation type:

```
type ('k, 'v) map = ('k*'v) list
```

- Abstraction function:
 - A list [(k1, v1); (k2, v2); ...] represents the map {k1=v1, k2=v2, ...}.
 - If k occurs more than once in the list, then in the map it is bound to the left-most value in the list.
- Efficiency:
 - insert: O(1)
 - find: O(n)
 - remove: O(n)

Balanced search trees

2-3 trees:

- Representation type: (omitted; see A3)
- Abstraction function: a node with label (k,v) and subtrees left (and middle) and right represents the smallest map containing the binding {k=v} unioned with the bindings of left (and middle) and right
- Representation invariant:
 - none for the map itself, but note that the tree has its own 2-3 tree invariants
- Efficiency:
 - insert: O(lg n)
 - find: $O(\lg n)$
 - remove: O(lg n)
- OCaml's Map module uses a closely-related balanced search tree called AVL trees

Arrays

• Representation type:

```
type ('k, 'v) map = 'v option array
```

- Assume we can convert 'k to int in constant time
 - Conversion must be *injective*: never maps two keys to the same integer
 - Then there is a unique *inverse* mapping integers to keys: inverse(i) = k
 - Easiest realization: restrict keys to be integers!

Arrays

- Abstraction function: An array [|v1; v2; ...|] represents the map {k1=v1, k2=v2, ...}, where k1=inverse(1), k2=inverse(2), ... If vi = None, then ki is not bound in the map.
- Aka direct address table
- Efficiency:
 - insert: O(1)
 - find: O(1)
 - remove: O(1)
 - wastes space, because some keys are unmapped

Map implementations

	insert	find	remove
Arrays	O(1)	O(1)	O(1)
Association lists	O(1)	O(n)	O(n)
Balanced search trees	O(lg n)	O(lg n)	O(lg n)

- Arrays guarantee constant efficiency, but require injective conversion of keys to integers (and waste space)
- Balanced search trees guarantee logarithmic efficiency

...we'd like the best of both worlds: constant efficiency with arbitrary keys

Hash tables

Main idea: give up on injectivity

- Allow conversion from 'k to int to map multiple keys to the same integer
- Conversion function called a hash function
- Location it maps to called a bucket
- When two keys map to the same bucket, called a collision

...how to handle collisions?

Collision resolution strategies

- 1. Store multiple key-value pairs in a collection at a bucket; usually the collection is a list
 - called open hashing, closed addressing, separate chaining
 - this is what OCaml's **Hashtbl** does
- 2. Store only one key-value pair at a bucket; if bucket is already full, find another bucket to use
 - called closed hashing, open addressing

Hash table implementation

• Representation type combines association list with array:

```
type ('k, 'v) map = ('k*'v) list array
```

Abstraction function: An array

```
[|[(k11,v11); (k12,v12);...];
[(k21,v21); (k22,v22);...]; ...|]
represents the map {k11=v11, k12=v12, ...}.
```

- If k occurs more than once in a bucket, then in the map it is bound to the left-most value in the bucket.
- Representation invariant:
 - A key k appears in array index b iff hash (k) =b
- Efficiency: ???
 - have to search through list to find key
 - no longer constant time

Question

Why does the representation type need to contain the $'\mathbf{k}$?

```
type ('k, 'v) map =
    ('k*'v) list array
```

- A. The type system requires it
- B. A given bucket might contain many keys
- C. To support an inverse operation
- D. The hash table representation invariant requires it
- E. None of the above

Question

Why does the representation type need to contain the $'\mathbf{k}$?

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- D. The hash table representation invariant requires it
- E. None of the above

Efficiency of hash table

- Terrible hash function: hash (k) = 42
 - All keys collide; stored in single bucket
 - Degenerates to an association list in that bucket
 - insert: O(1)
 - find & remove: O(n)
- Perfect hash function: injective
 - Each key in its own bucket
 - Degenerates to array implementation
 - insert, find & remove: O(1)
 - Surprisingly, possible to design
 - if you know the set of all keys that will ever be bound in advance
 - size of array is the size of that set
 - so you want the size of the set to be much smaller than the size of the universe of possible keys
- Middleground? Compromise?

Efficiency of hash table

- New goal: constant-time efficiency on average
 - Desired property of hash function: distribute keys randomly among buckets to keep average bucket length small
 - If expected length is on average L:
 - insert: O(1)
 - find & remove: O(L)
- Two new problems to solve:
 - 1. How to make L a constant that doesn't depend on number of bindings in table?
 - 2. How to design hash function that distributes keys randomly?

Independence from # bindings

Let's think about the load factor...

- = average number of bindings in a bucket = expected bucket length
- = n/m, where n=# bindings in hash table, m=# buckets in array
 - e.g., 10 bindings, 10 buckets, load factor = 1.0
 - e.g., 20 bindings, 10 buckets, load factor = 2.0
 - e.g., 5 bindings, 10 buckets, load factor = 0.5
- Both OCaml Hashtbl and java.util.HashMap provide functionality to find out current load factor
- Implementor of hash table can't prevent client from adding or removing bindings
 - so n isn't under control
- But can resize array to be bigger or smaller
 - so m can be controlled
 - hence load factor can be controlled
 - hence expected bucket length can be controlled

Control the load factor

- If load factor gets too high, make the array bigger, thus reducing load factor
 - OCaml Hashtbl and java.util.HashMap: if load factor > 2.0 then:
 - double array size
 - rehash elements into new buckets
 - thus bringing load factor back to around 1.0
 - Efficiency on average for that strategy:
 - insert: O(1)
 - find & remove: O(2), which is still constant time
 - rehashing: let's come back to that...
- If load factor gets too small (hence memory is being wasted), could shrink the array, thus increasing load factor
 - Neither OCaml nor Java does this

Question

How would you resize this representation type?

```
type ('k, 'v) map =
  ('k*'v) list array
```

- A. Mutate the array elements
- B. Mutate the array itself
- C. Neither of the above

Question

How would you resize this representation type?

```
type ('k, 'v) map =
  ('k*'v) list array
```

- A. Mutate the array elements
- B. Mutate the array itself (can't—it's immutable)
- C. Neither of the above

Resizing the array

Requires a new representation type:

```
type ('k, 'v) map =
  ('k*'v) list array ref
```

- Mutate an array element to insert or remove
- Mutate array ref to resize

Hashtbl in OCaml library

Why not use list? Probably to save on one indirection.

Hash tables: physicist's method

- Simplifying assumptions:
 - no remove operation
 - ignore cost of all operations until load factor reaches 1 for the first time
- Potential: U(h) = 4(n m)
 - where n is number of elements in h
 - and m is number of buckets in h
 - Causes potential to increase as load factor (=n/m) grows
 - When load factor is 1, it holds that m=n, so U(h)=0
 - no extra credit stored up immediately after resize
 - When load factor is 2, it holds that m=n/2, so U(h)=2n
 - enough extra credit stored up to pay to rehash and insert each element just when we need to resize

Hash tables: physicist's method

- Amortized cost of insert (including resize)
 - Let n be # elements and m be # buckets before insert
 - If no resize is triggered:
 - Actual cost of 1 each to hash and insert element
 - Change in potential = 4(n+1-m) 4(n m) = 4n +4 4m
 4n + 4m = 4
 - Amortized cost = actual + change = 1 + 1 + 4 = 6 = O(1)

Hash tables: physicist's method

- Amortized cost of insert (including resize)
 - Let n be # elements and m be # buckets before insert
 - If resize is triggered:
 - Then n+1 = 2m
 - Actual cost of 2(n+1) to hash and insert n+1 elements
 - Change in potential = 4(n+1-2m) 4(n-m) = 4n + 4 8m 4n + 4m = 4 4m = 4 2(2m) = 4 2(n+1) = 4 2n 2
 - Amortized cost = actual + change = 2(n + 1) + 4 2n 2 = 2n + 2 + 4 2n 2 = 4 = O(1)
- Whether resize occurs or not, amortized cost of O(1)

Hash tables

Conclusion: resizing hash tables have amortized expected worst-case running time that is constant!

Upcoming events

- [Wed-Fri] No class: Happy Thanksgiving!
- [next Thursday] A6 (including Project Implementation) due

This is #3110.

THIS IS 3110