# *CS 213 -- Lecture #23*

"Late Night Guide to C++" Chapter 12 pg. 330 - 338

SPACE ALLOCATION

### Administrative...

- Remember, second prelim on 11/23!
  - In class, closed book, similar to prelim #1
  - Will cover entire semester, main focus on second half of year.
  - Slightly more "coding"
- Last two lecture will be "fun" lectures:
  - I will take attendance :-)
  - Official course eval
  - Fun and games

### Memory Allocation

- No matter what system or platform you are programming for, there is one constant
- · Memory allocation is slow!
- The general problem is that no matter how good the generic memory management algorithm is behind the new operator, it is burdened by the fact that it must be prepared to allocate and manage blocks of memory which are of varying sizes.
- Now, please keep in mind that *slow* is a *relative term*. When looked at individually, even the slowest memory allocation is still fairly fast under a modern OS and/or modern hardware.
- Under MacOS, memory management is particularly slow due to there being an extra layer of indirection present (handles).
- So, what a perfect platform to talk about memory management on!

## Demonstration 1

Lots o' Dynamic Allocation

### Memory Management (cont)

- As you can see, even though memory allocation is slow, it still takes *a lot* of memory allocations to slow us down.
- But, in the "real world", you'd be surprised at how quickly repeated memory allocation can slow down your program.
- Acknowledging this, C++ lets you do something truly bizarre...
- You can overload the new operator and define your own memory management routines.
- Just try doing that in Java!!!!
- Of course, if you can overload new you must be able to overload delete as well.
- Overloading the new and delete operators is done just like any other operator overload, except there is a slightly special syntax:
  - void \*operator new(size\_t);
  - void operator delete(void \*);

### Memory Management (cont)

- OK, but that means I actually have to *implement* some memory management routines!
- WHY would I want to do that?
- $\bullet \ \ Because the generic memory management routines are slow!$
- They're slow because they have to be able to deal with any size object.
- If you know you will need to dynamically allocate a lot of the same objects during the course of your program you can define your own memory management routines for allocations of that object type.
- A typical memory management routine to handle repeated allocations of the same type can be implemented in a way that will be more efficient than the generic routine.
- · Let's do it!

### Memory Management (cont)

- The idea is somewhat simple, when you think about it.
- You allocate a block of memory (using the generic routine) to form an "array" of the objects in question.
- When YourObject::operator new is called, you "give out" one of your previously allocated objects.
- That means you need to keep track of what's allocated and what is not!
- · When you start out, you'll have something like this:

Array of Objects						Unallocated Allocated					

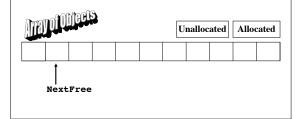
### Memory Management (cont)

- But how do you "dole out" pre-allocated objects in an orderly fashion?
- First, you'll need a pointer variable which will be used to point to consecutive items in your array. We'll call it NextFree.
- It will, of course, start at the beginning of the array.

Array of Objects					Unallocated Allocate					
Next	Free									

### Memory Management (cont)

- When one object is allocated via a call to YourObject::operator new, we'll return the object that NextFree is pointing at and then increment NextFree to the next item in the array.
- · That would look like this:



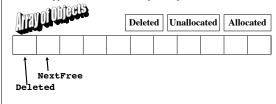
### Memory Management (cont)

- But what happens when YourObject::operator delete is called?
- We need to keep track of deleted objects as well.
- We do this in the form of a "pseudo" linked list.
- I say pseudo because in a regular linked list, the implication is that each element is allocated only when necessary.
- What we're going to do is make each object in our pre-allocated array similar to a linked list Node with two fields, the first is an instance of YourObject, the second is a "next" pointer.
- It might look like this:

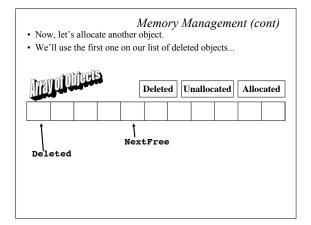
```
class Element {
public:
  YourObject theObject;
  Element *nextElement;
};
```

### Memory Management (cont)

- Now, when we delete an object, we'll put it at the beginning of a linked list of "deleted" objects.
- Whenever YourObject::operator new is called, we'll first check to see if there are any objects on the "deleted objects" list.
- If there are, we'll return the first object from that list instead of the object pointed at by NextFree.
- · What happens if we delete that object we just allocated...

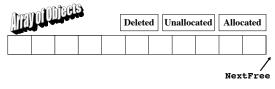


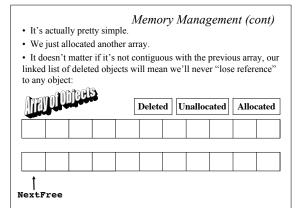
# • OK, now let's say that we allocated three more objects and then delete the second object we allocated in that run. Deleted Unallocated Allocated NextFree Deleted

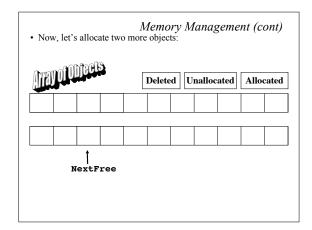


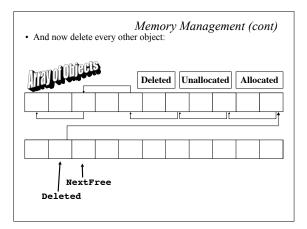
### Memory Management (cont)

- But what happens if we allocate all the elements in our array?
- You can always fall back on the default operator new in your YourObject::operator new code.
- As a matter of fact, in YourOperator::operator new, you should always check that the size requested matches the size of the object you've defined the memory handler for, and default to ::operator new if it doesn't.
- But what happens in this situation:









# • Any questions on the memory management algorithm? • Let's look at some code: void \*MyString::operator new(size\_t size) { // Make sure size requested matches a MyString size if (size != sizeof(MyString)) return ::new(size); } // First, check the free list if (deletedMyStrings) { void \*freePtr = deletedMyStrings; deletedMyStrings = deletedMyStrings > theNextString; return freePtr; }

Memory Management (cont)

### 

# Demonstration 2

Better Dynamic Allocation???

### Allocator Classes

- The fact that default memory management can be overridden and improved for specialized cases is significant in the following scenario.
- Consider a class named allocator which implemented a couple of basic memory allocation member functions:

```
class allocator
{
public:
    void *allocate(size_t size);
    void deallocate(void *);
};
```

### Allocator Classes (cont)

• Now consider that this class implements the two member functions in the following way:

```
void *allocator::allocate(size_t size)
{
  return ((void *) new char[size]);
}

void allocator::deallocate(void *ptr)
{
  char *thisPtr = (char *) ptr;
  delete [] thisPtr;
}
```

### Allocator Classes (cont)

• Now consider that my fancy memory management algorithm could be implemented to take object size as a parameter and then fit into this same type of allocator class:

```
template<int objectSize>
class RonsAllocator {
public:
    void *allocate(size_t size);
    void deallocate(void *ptr);
private:
    // all necessary private members here...
};
```

### Allocator Classes (cont)

- NOW consider that this allocator class could be taken as a template argument itself...
- Hmmm, did I ever tell you about default template arguments?

### Allocator Classes (cont)

- This concept is what is meant when we talk about Allocator Classes.
- The "real" allocator classes are used all over the standard template library.
- They are passed as template arguments to any STL container.
- They have default template arguments of allocator<T> which is the default allocator class which just relies on new and delete.
- So, you could implement your own memory management for type (presumably of the same size) and pass that to any of the STL containers to help make dynamic memory allocation faster.
- The actual allocator classes are a little more complicated, LNG doesn't even go into them.
- Consult Stroustrup for more information. (Well, his book, not necessarily him)

# Final Thoughts

- Assignments #10 due on 11/30
- Prelim #2 given in class next Tuesday
- That's it for LNG
- Classes on 11/30 and 12/2...