

## Priority Queues and Heaps

Lecture 15  
CS211 Summer 2008

## Priority Queue

- *lesser* elements (as determined by `compareTo()`) have *higher* priority
- `get()` returns the element with the highest priority = least in the `compareTo()` ordering
- break ties arbitrarily

## Examples

- Scheduling jobs to run on a computer
  - default priority = arrival time
  - priority can be changed by operator
- Scheduling events to be processed by an event handler
  - priority = time of occurrence
- Airline check-in
  - first class, business class, coach
  - FIFO within each class

## Priority Queues

```
java.util.PriorityQueue<E>  
  
boolean add(E e) {...} //insert an element (put)  
void clear() {...} //remove all elements  
E peek() {...} //return min element without removing  
           //(null if empty)  
E poll() {...} //remove min element (get)  
           //(null if empty)  
int size() {...}
```

## Priority Queues as Lists

- Maintain as *unordered* list
  - `add()` puts new element at front –  $O(1)$
  - `poll()` must search the list –  $O(n)$
- Maintain as *ordered* list
  - `add()` must search the list –  $O(n)$
  - `poll()` gets element at front –  $O(1)$
- In either case,  $O(n^2)$  to process  $n$  elements

Can we do better?

## Important Special Case

- Fixed number of priority levels  $0, \dots, p - 1$
- FIFO within each level
- Example: airline check-in, O/S scheduling
- `add()` – insert in appropriate queue –  $O(1)$
- `poll()` – must find a nonempty queue –  $O(p)$

## Heaps

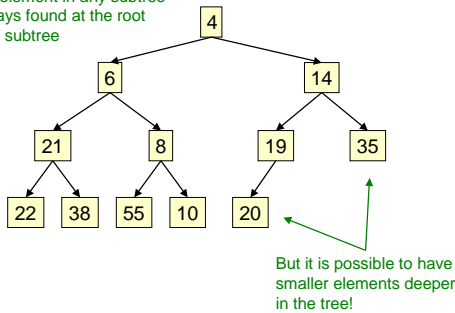
- A *heap* is a concrete data structure that can be used to implement priority queues
- Gives better complexity than either ordered or unordered list implementation:
  - `add()`, `poll()`:  $O(\log n)$
  - `size()`:  $O(1)$
- $O(n \log n)$  to process  $n$  elements
- Do not confuse with *heap memory*, where the Java virtual machine allocates space for objects – different usage of the word *heap*

## Heaps

- Binary tree with data at each node
- Satisfies the *Heap Order Invariant*:

The least (highest priority) element of any subtree is found at the root of that subtree

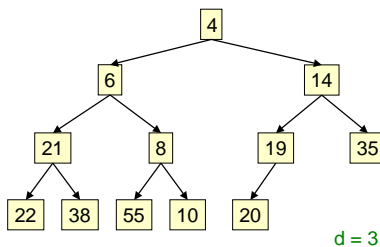
Least element in any subtree is always found at the root of that subtree



## Examples of Heaps

- Ages of people in family tree
  - parent is always older than children, but you can have an uncle who is younger than you
- Salaries of employees of a company
  - bosses generally make more than subordinates, but a VP in one subdivision may make less than a Project Supervisor in a different subdivision

## A Balanced Heap



## Balanced Heaps

Two restrictions:

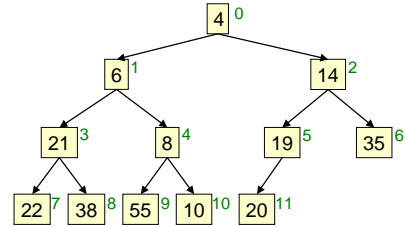
1. Any node of depth  $< d - 1$  has exactly 2 children, where  $d$  is the height of the tree
  - implies that any path from a root to a leaf is either of length  $d$  or  $d - 1$
  - Also implies that the tree has at least  $2^d$  nodes
2. All maximal paths of length  $d$  are to the left of those of length  $d - 1$

## Store in an Array or Vector

- Elements of the heap are stored in array in order, going across each level from left to right, top to bottom
- The children of the node at array index  $n$  are found at  $2n + 1$  and  $2n + 2$
- The parent of node  $n$  is found at  $(n - 1)/2$

## Heaps can be stored in an array

0	1	2	3	4	5	6	7	8	9	10	11
4	6	14	21	8	19	35	22	38	55	10	20

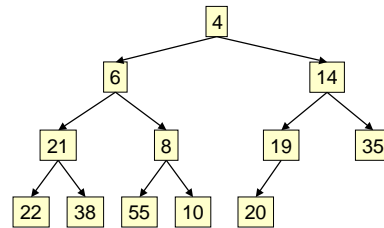


children of node  $n$  are found at  $2n + 1$  and  $2n + 2$

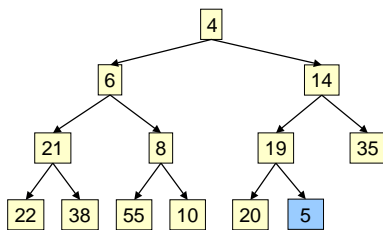
## add()

- Put the new element at the end of the array
- If this violates heap order because it is smaller than its parent, swap it with its parent
- Continue swapping it up until it finds its rightful place
- The heap invariant is maintained!

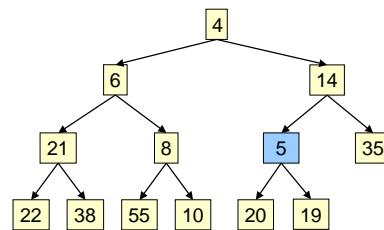
## add()



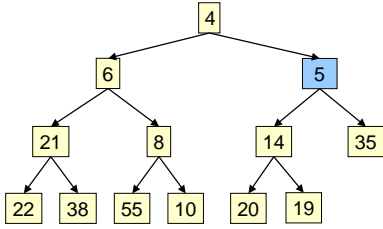
## add()



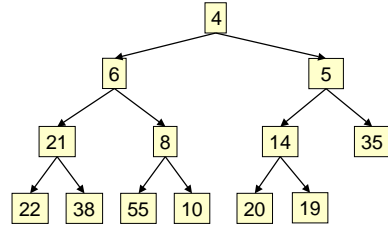
## add()



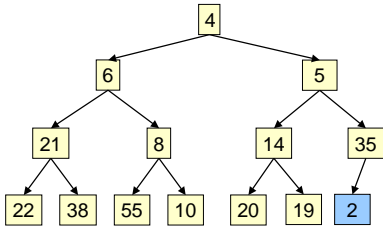
add()



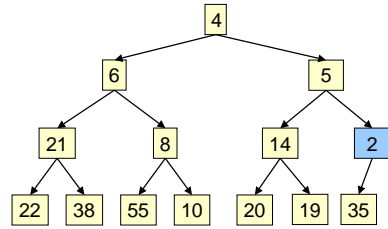
add()



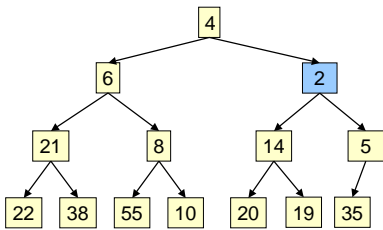
add()



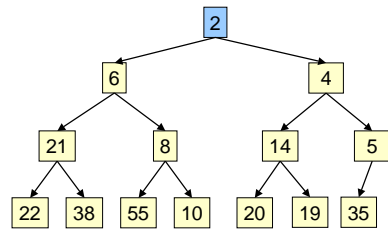
add()



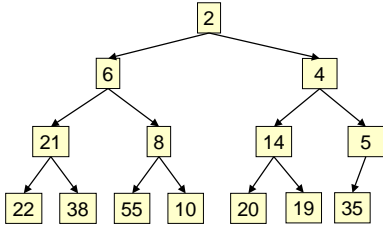
add()



add()



## add()



## add()

- Time is  $O(\log n)$ , since the tree is balanced
  - size of tree is exponential as a function of depth
  - depth of tree is logarithmic as a function of size

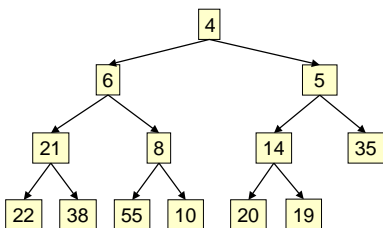
## add()

```
class PriorityQueue<E> extends java.util.Vector<E> {  
    public void add(E obj) {  
        super.add(obj); //add new element to end of array  
        rotateUp(size() - 1);  
    }  
  
    private void rotateUp(int index) {  
        if (index == 0) return;  
        int parent = (index - 1)/2;  
        if (elementAt(parent).compareTo(elementAt(index)) <= 0)  
            return;  
        swap(index, parent);  
        rotateUp(parent);  
    }  
}
```

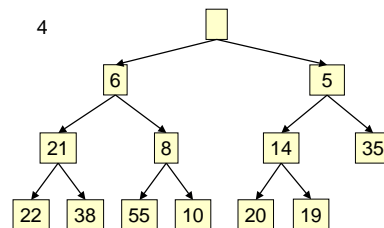
## poll()

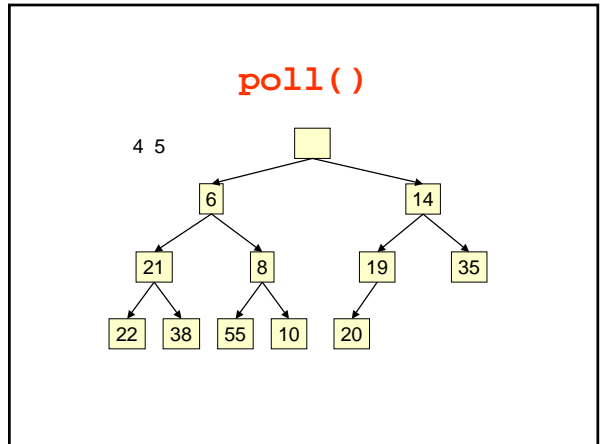
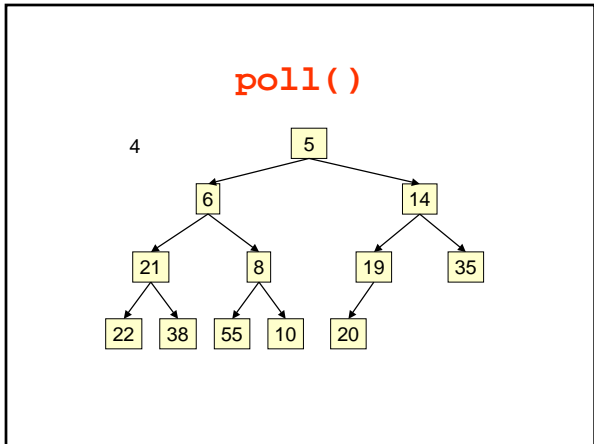
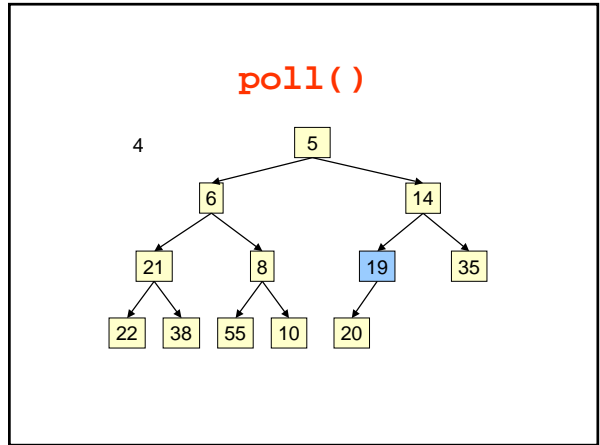
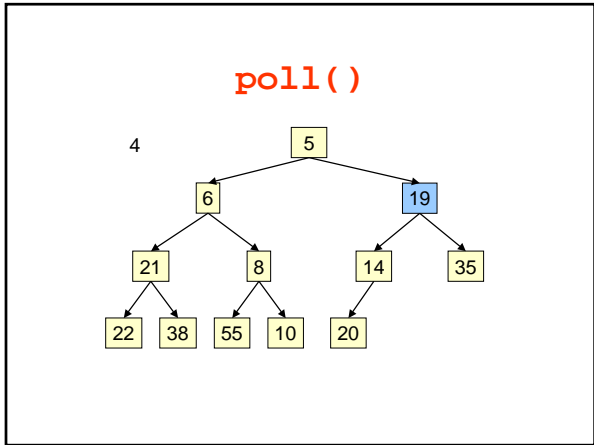
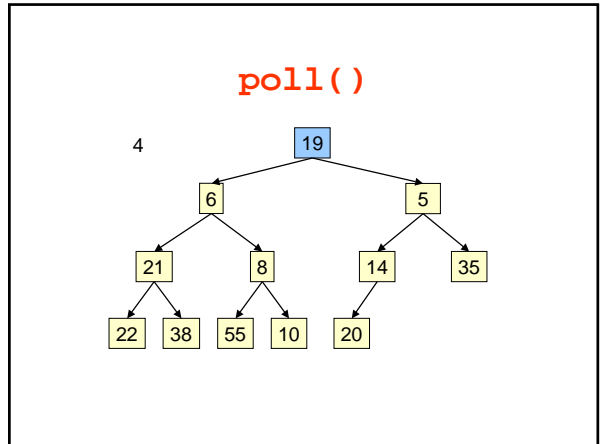
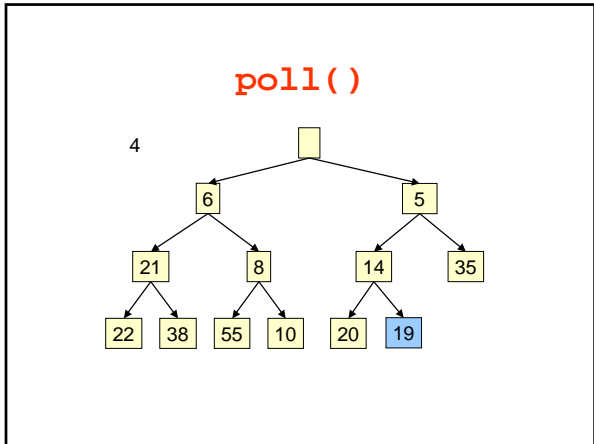
- Remove the least element – it is at the root
- This leaves a hole at the root – fill it in with the last element of the array
- If this violates heap order because the root element is too big, swap it down with the smaller of its children
- Continue swapping it down until it finds its rightful place
- The heap invariant is maintained!

## poll()



## poll()







## poll()

- Time is  $O(\log n)$ , since the tree is balanced

## poll()

```
public E poll() {
    if (size() == 0) return null;
    E temp = elementAt(0);
    setElementAt(0, elementAt(size() - 1));
    setSize(size() - 1);
    rotateDown(0);
    return temp;
}

private void rotateDown(int index) {
    int child = 2*(index + 1); //right child
    if (child >= size()
        || elementAt(child - 1).compareTo(elementAt(child)) < 0)
        child -= 1;
    if (child >= size()) return;
    if (elementAt(index).compareTo(elementAt(child)) <= 0)
        return;
    swap(index, child);
    rotateDown(child);
}
```

## HeapSort

Given a `Comparable[]` array of length  $n$ ,

1. Put all  $n$  elements into a heap –  $O(n \log n)$
2. Repeatedly get the min –  $O(n \log n)$

```
public static void heapSort(Comparable[] a) {
    PriorityQueue<Comparable> pq
    = new PriorityQueue<Comparable>();
    for (Comparable x : a) { pq.add(x); }
    for (int i = 0; i < a.length; i++) { a[i] = pq.poll(); }
}
```

## PQ Application: Simulation

- Example: Probabilistic model of bank-customer arrival times and transaction times, how many tellers are needed?
    - Assume we have a way to generate random inter-arrival times
    - Assume we have a way to generate transaction times
    - Can simulate the bank to get some idea of how long customers must wait
- Time-Driven Simulation**
- Check at each *tick* to see if any event occurs
- Event-Driven Simulation**
- Advance clock to next event, skipping intervening *ticks*
  - This uses a PQ!