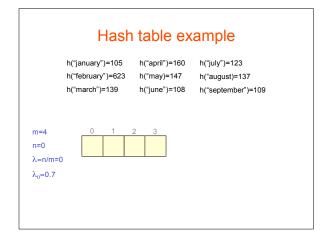


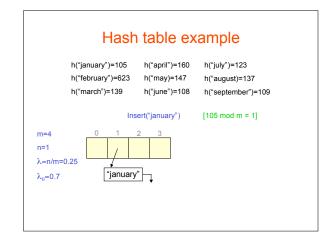
# Priority Queues and Heaps

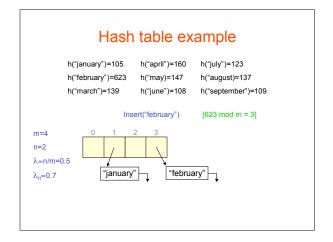
Lecture 15 CS211 Summer 2007

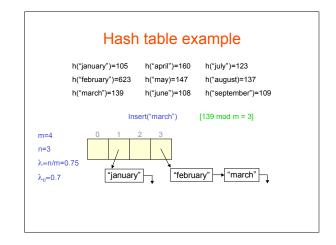
### **Announcements**

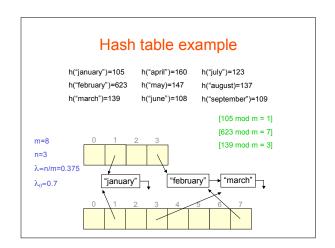
- Assignment 3 due tonight, 11:59
- Prelim grades on CMS

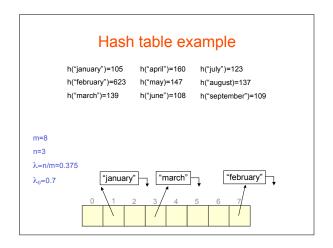


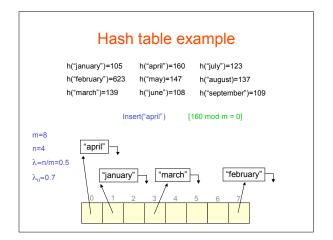


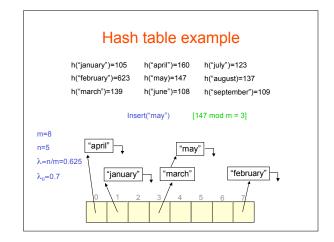


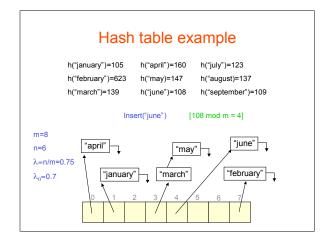


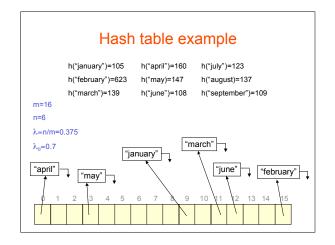






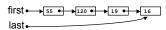






### Stacks and Queues as Lists

- Stack (LIFO) implemented as list
- put(), get() from front of list
- Queue (FIFO) implemented as list
   put () on back of list, get () from front of list



# **Priority Queue**

- lesser elements (as determined by compareTo()) have higher priority
- get() returns the element with the highest priority = least in the compareTo() ordering
- · break ties arbitrarily

# **Examples**

- · Scheduling jobs to run on a computer
  - default priority = arrival time
  - priority can be changed by operator
- Scheduling events to be processed by an event handler
  - priority = time of occurrence
- Airline check-in
  - first class, business class, coach
  - FIFO within each class

# **Priority Queues**

# **Priority Queues as Lists**

- Maintain as unordered list
  - add () puts new element at front O(1)
  - pol1() must search the list O(n)
- · Maintain as ordered list
  - add() must search the list O(n)
  - pol1() gets element at front O(1)
- In either case, O(n2) to process n elements

Can we do better?

# Important Special Case

- $\bullet$  Fixed number of priority levels 0,...,p-1
- FIFO within each level
- Example: airline check-in, O/S scheduling
- add () insert in appropriate queue O(1)
- •pol1 () must find a nonempty queue O(p)

## Heaps

- A heap is a concrete data structure that can be used to implement priority queues
- Gives better complexity than either ordered or unordered list implementation:

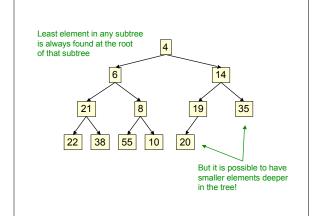
- add(), poll(): O(log n)
- size(): O(1)

- O(n log n) to process n elements
- Do not confuse with *heap memory*, where the Java virtual machine allocates space for objects – different usage of the word *heap*

# Heaps

- Binary tree with data at each node
- Satisfies the Heap Order Invariant:

The least (highest priority) element of any subtree is found at the root of that subtree



# **Examples of Heaps**

- · Ages of people in family tree
  - parent is always older than children, but you can have an uncle who is younger than you
- Salaries of employees of a company
  - bosses generally make more than subordinates, but a VP in one subdivision may make less than a Project Supervisor in a different subdivision

# **Balanced Heaps**

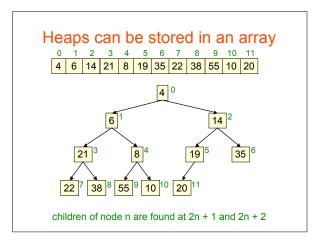
### Two restrictions:

- Any node of depth < d 1 has exactly 2 children, where d is the height of the tree
  - implies that any path from a root to a leaf is either of length d or d 1
  - Also implies that the tree has at least 2<sup>d</sup> nodes
- 2. All maximal paths of length d are to the left of those of length d-1

# A Balanced Heap 4 14 19 35 22 38 55 10 20 d = 3

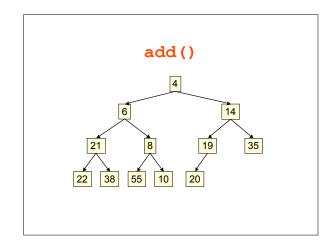
# Store in an Array or Vector

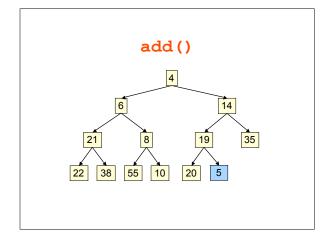
- Elements of the heap are stored in array in order, going across each level from left to right, top to bottom
- The children of the node at array index n are found at 2n + 1 and 2n + 2
- The parent of node n is found at (n 1)/2

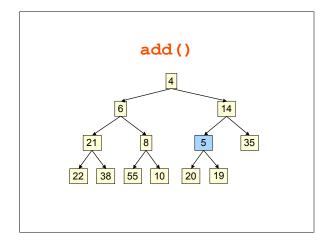


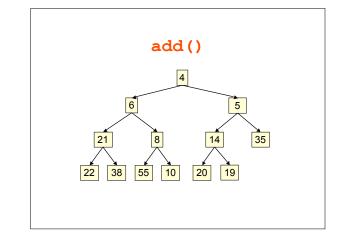
### add()

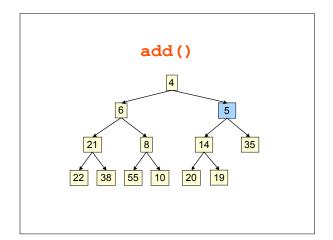
- Put the new element at the end of the array
- If this violates heap order because it is smaller than its parent, swap it with its parent
- Continue swapping it up until it finds its rightful place
- The heap invariant is maintained!

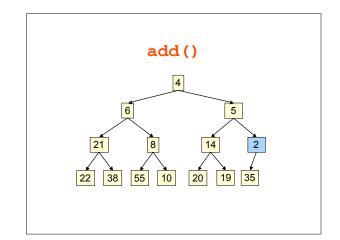


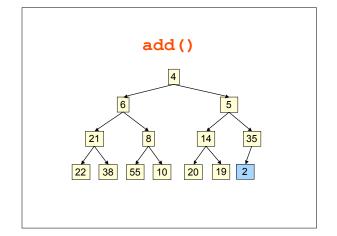


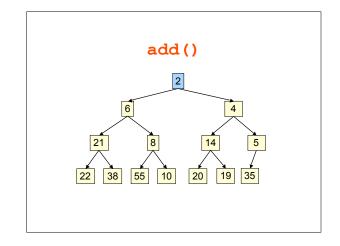


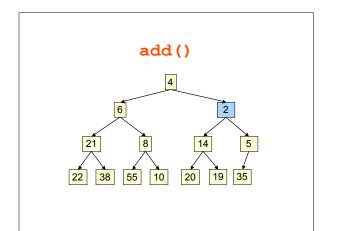


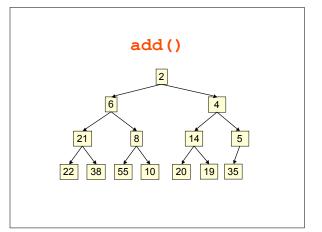












### add()

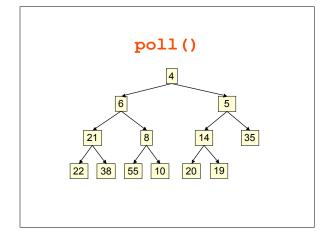
- Time is O(log n), since the tree is balanced
  - size of tree is exponential as a function of depth
  - depth of tree is logarithmic as a function of size

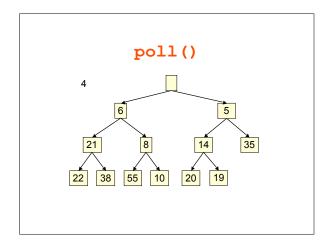
### add()

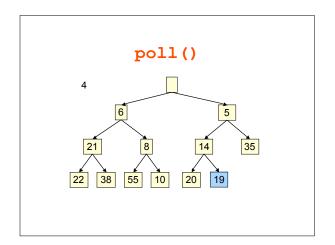
```
class PriorityQueue<E> extends java.util.Vector<E> {
  public void add(E obj) {
    super.add(obj); //add new element to end of array
    rotateUp(size() - 1);
  }
  private void rotateUp(int index) {
    if (index == 0) return;
    int parent = (index - 1)/2;
    if (elementAt(parent).compareTo(elementAt(index)) <= 0)
        return;
    swap(index, parent);
    rotateUp(parent);
  }
}</pre>
```

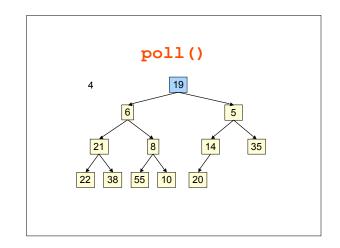
### pol1()

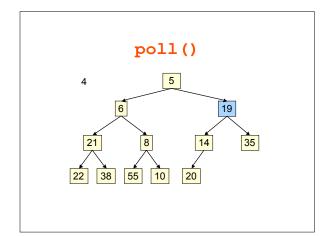
- Remove the least element it is at the root
- This leaves a hole at the root fill it in with the last element of the array
- If this violates heap order because the root element is too big, swap it down with the smaller of its children
- Continue swapping it down until it finds its rightful place
- The heap invariant is maintained!

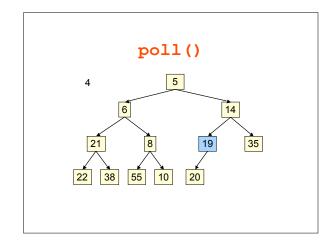


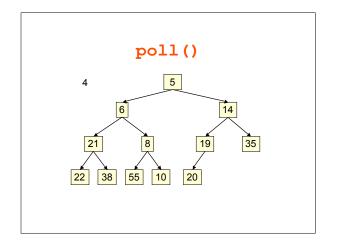


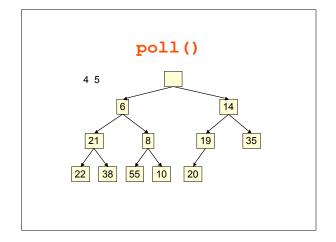


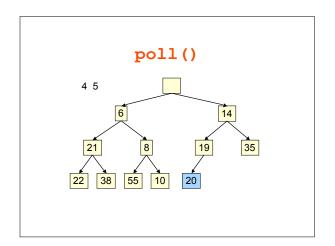


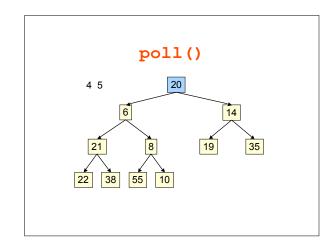


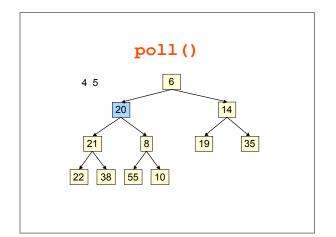


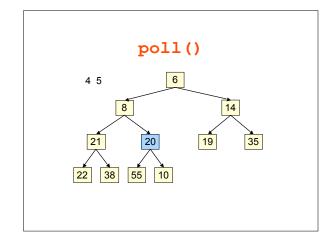


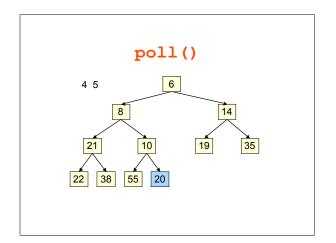


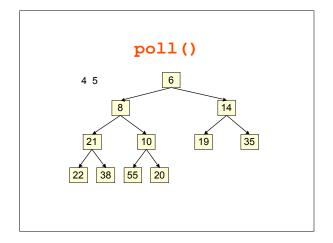












### pol1()

• Time is O(log n), since the tree is balanced

### poll()

```
public E poll() {
   if (size() == 0) return null;
   E temp = elementAt(0);
   setBlementAt(0, elementAt(size() - 1));
   setSize(size() - 1);
   rotateDown(0);
   return temp;
}
private void rotateDown(int index) {
   int child = 2*(index + 1); //right child
   if (child >= size()
   || elementAt(child - 1).compareTo(elementAt(child)) < 0)
        child == 1;
   if (child >= size()) return;
   if (elementAt(index).compareTo(elementAt(child)) <= 0)
        return;
   swap(index, child);
   rotateDown(child);
}</pre>
```

## HeapSort

Given a Comparable[] array of length n,

- 1. Put all n elements into a heap O(n log n)
- 2. Repeatedly get the min O(n log n)

# PQ Application: Simulation

- Example: Probabilistic model of bank-customer arrival times and transaction times, how many tellers are needed?
  - Assume we have a way to generate random inter-arrival times
  - Assume we have a way to generate transaction times
- Can simulate the bank to get some idea of how long customers must wait

#### Time-Driven Simulation

 Check at each tick to see if any event occurs

### **Event-Driven Simulation**

- Advance clock to next event, skipping intervening ticks
- This uses a PQ!