

## Search Trees

## Some Search Structures

- Sorted Arrays

- Advantages

- Search in  $O(\log n)$  time (binary search)

- Disadvantages

- Need to know size in advance
- Insertion, deletion  $O(n)$  – need to shift elements

- Lists

- Advantages

- No need to know size in advance
- Insertion, deletion  $O(1)$  (not counting search time)

- Disadvantages

- Search is  $O(n)$ , even if list is sorted

## Search Trees

- Best of both!

- Search, insert, delete in  $O(\log n)$  time
- No need to know size in advance

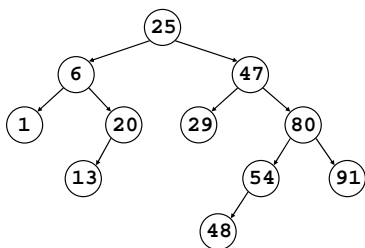
- Several flavors

- AVL trees, 2-3 trees, red-black trees, skip lists, random treaps, ...

## Binary Search Trees

- Every node has a *left child*, a *right child*, both, or neither
- Data elements are drawn from a totally ordered set (e.g., **Comparable**)
- Every node contains one data element
- Data elements are ordered in *inorder*

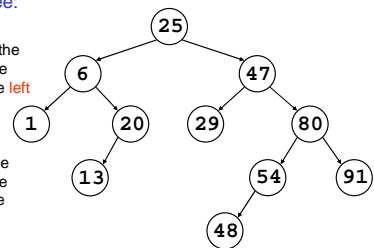
## A Binary Search Tree



## Binary Search Trees

In any subtree:

- all elements *smaller* than the element at the root are in the *left* subtree
- all elements *larger* than the element at the root are in the *right* subtree



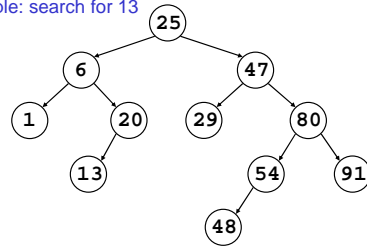
## Search

To search for an element  $x$ :

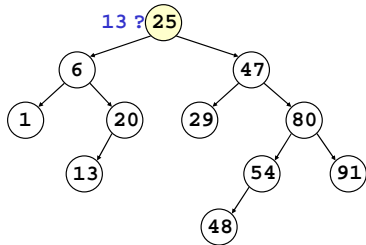
- if tree is empty, return false
- if  $x$  = object at root, return true
- If  $x <$  object at root, search left subtree
- If  $x >$  object at root, search right subtree

## Search

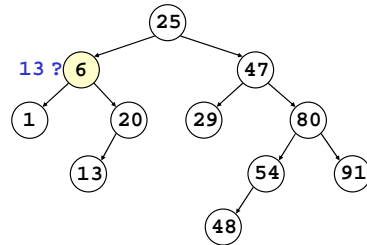
Example: search for 13



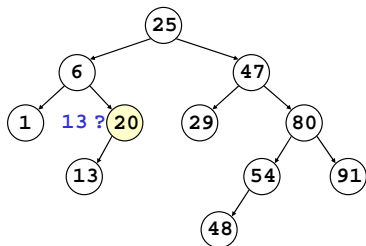
## Search



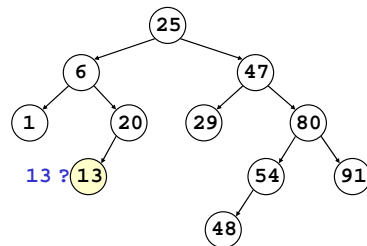
## Search



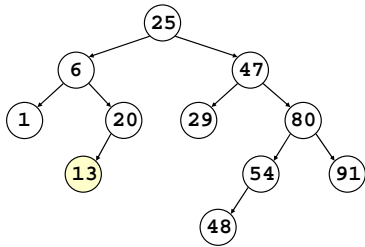
## Search



## Search



## Search



## Search

```
boolean treeSearch(Comparable x,
    TreeNode t) {
    if (t == null) return false;
    switch (x.compareTo(t.data)) {
        case 0: return true; //found
        case 1: return treeSearch(x, t.right);
        default: return treeSearch(x, t.left);
    }
}
```

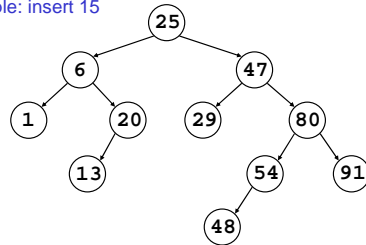
## Insertion

To insert an element x:

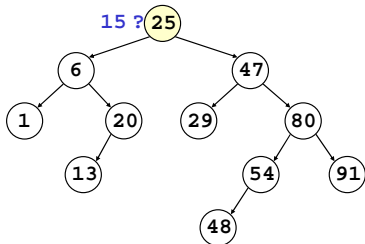
- search for x – if there, just return
- when arrive at a leaf y, make x a child of y
  - left child if  $x < y$
  - right child if  $x > y$

## Insertion

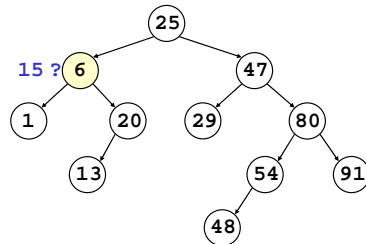
Example: insert 15



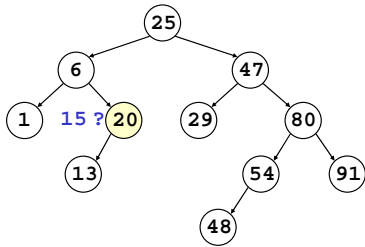
## Insertion



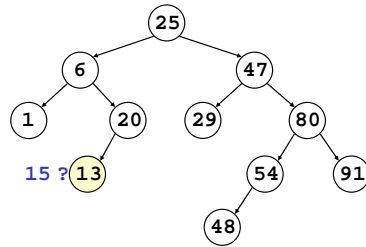
## Insertion



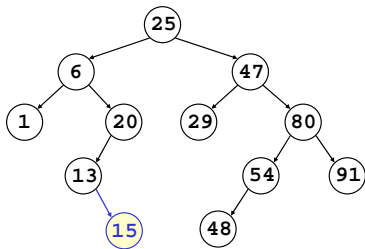
## Insertion



## Insertion



## Insertion



## Insertion

```
void insert(Comparable x, TreeNode t) {
    if (x.compareTo(t.data) == 0) return;
    if (x.compareTo(t.data) < 0) {
        if (t.left != null) insert(x, t.left);
        else t.left = new TreeNode(x);
    } else {
        if (t.right != null) insert(x, t.right);
        else t.right = new TreeNode(x);
    }
}
```

## Deletion

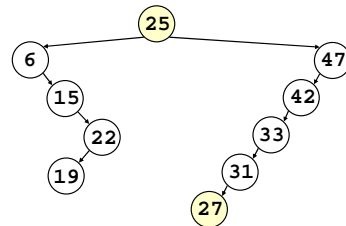
### To delete an element x:

- remove x from its node – this creates a hole
- if the node was a leaf, just delete it
- find greatest y less than x in the left subtree (or least y greater than x in the right subtree), move it to x's node
- this creates a hole where y was – repeat

## Deletion

### To find least y greater than x:

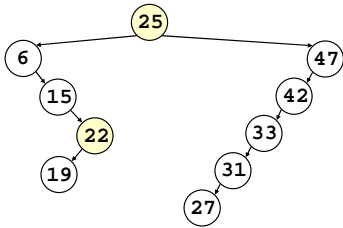
- follow left children as far as possible in right subtree



## Deletion

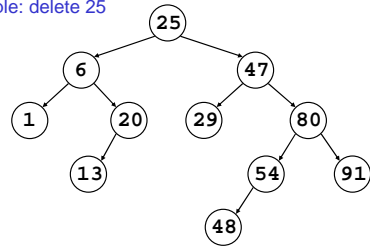
To find greatest y less than x:

- follow **right** children as far as possible in **left** subtree

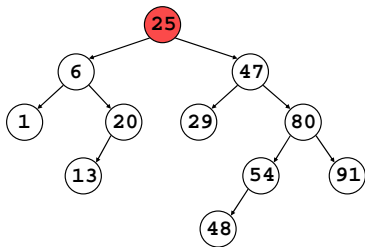


## Deletion

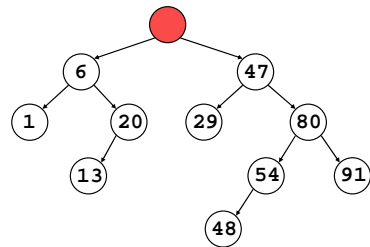
Example: delete 25



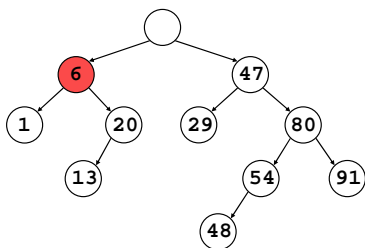
## Deletion



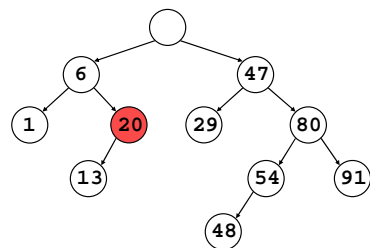
## Deletion



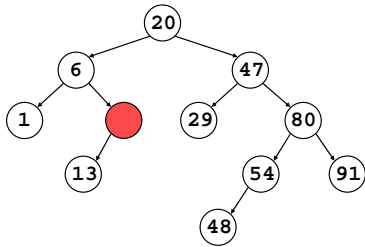
## Deletion



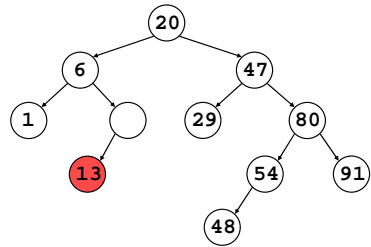
## Deletion



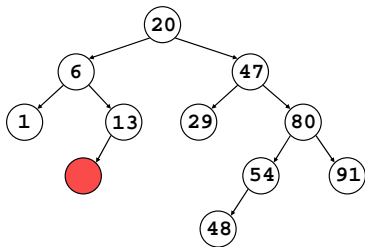
### Deletion



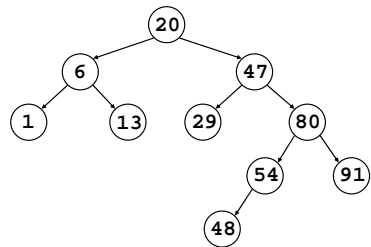
### Deletion



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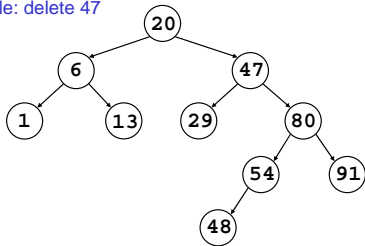


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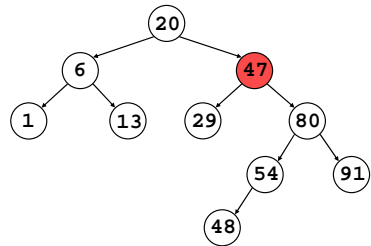


### Deletion

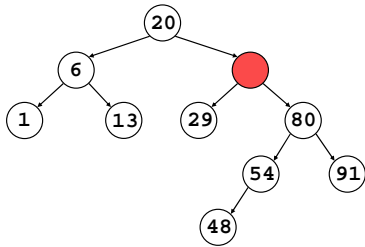
Example: delete 47



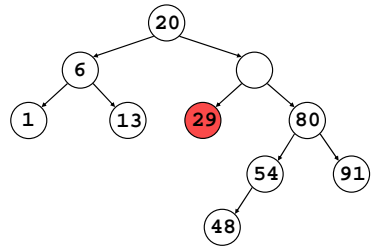
### Deletion



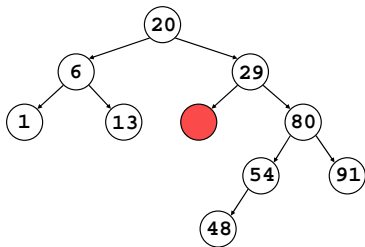
### Deletion



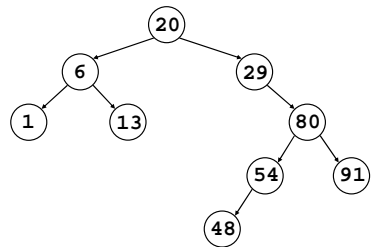
### Deletion



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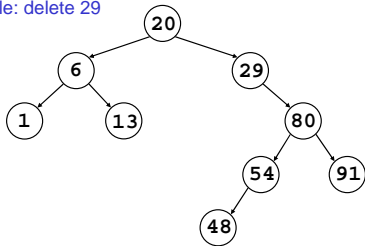


### Deletion

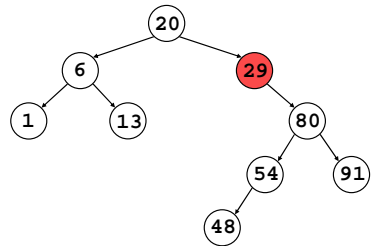


### Deletion

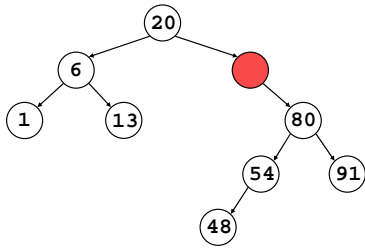
Example: delete 29



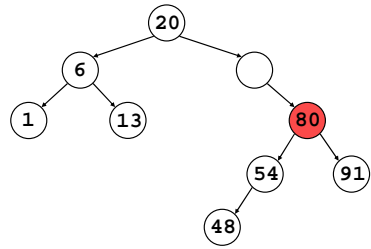
### Deletion



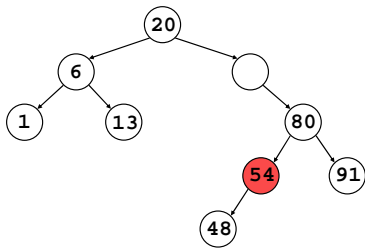
Deletion



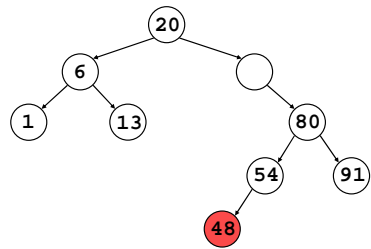
Deletion



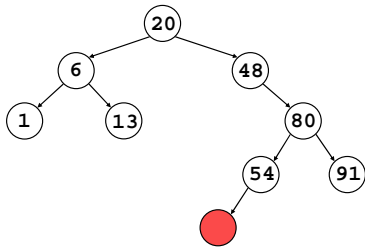
Deletion



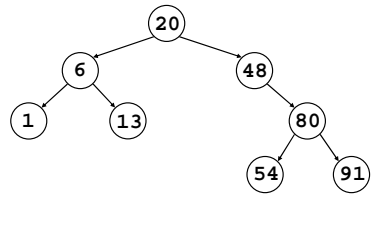
Deletion



Deletion



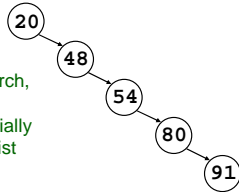
Deletion



## Observation

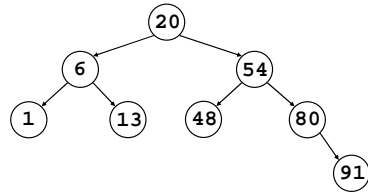
- These operations take time proportional to the height of the tree (length of the longest path)
- $O(n)$  if tree is not sufficiently balanced

Bad case for search, insertion, and deletion – essentially like searching a list



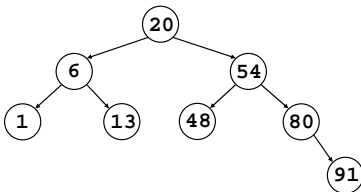
## Solution

Try to keep the tree **balanced** (all paths roughly the same length)



## Balanced Trees

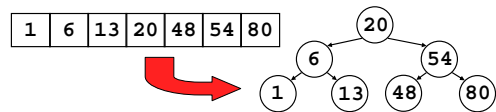
- Size is exponential in height
- Height =  $\log_2(\text{size})$
- Search, insert, delete will be  $O(\log n)$



## Creating a Balanced Tree

Creating one from a sorted array:

- Find the median, place that at the root
- Recursively form the left subtree from the left half of the array and the right subtree from the right half of the array



## Keeping the Tree Balanced

- Insertions and deletions can put tree out of balance – we may have to rebalance it
- Can we do this efficiently?

## AVL Trees

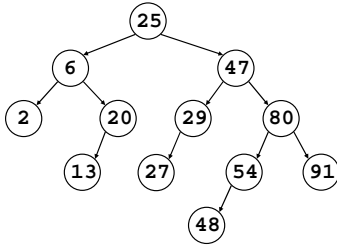
Adelson-Velsky and Landis, 1962

**AVL Invariant:**

The difference in height between the left and right subtrees of any node is never more than one

## An AVL Tree

- Nonexistent children are considered to have height  $-1$
- Note that paths can differ in length by more than 1 (e.g., paths to 2, 48)



## AVL Trees are Balanced

The AVL invariant implies that:

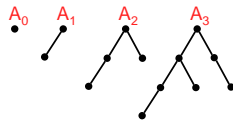
- Size is **at least** exponential in height
  - $n \geq \varphi^d$ , where  $\varphi = (1 + \sqrt{5})/2 \sim 1.618$ , the golden ratio!
- Height is **at most** logarithmic in size
  - $d \leq \log n / \log \varphi \sim 1.44 \log n$

## AVL Trees are Balanced

### AVL Invariant:

The difference in height between the left and right subtrees of any node is never more than one

To see that  $n \geq \varphi^d$ , look at the **smallest possible** AVL trees of each height

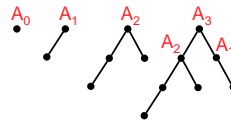


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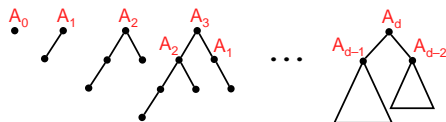


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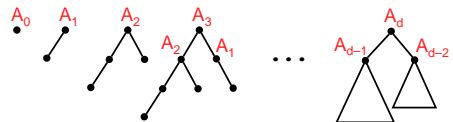


## AVL Trees are Balanced

$$A_0 = 1$$

$$A_1 = 2$$

$$A_d = A_{d-1} + A_{d-2} + 1, \quad d \geq 2$$



## AVL Trees are Balanced

$$\begin{aligned} A_0 &= 1 \\ A_1 &= 2 \\ A_d &= A_{d-1} + A_{d-2} + 1, \quad d \geq 2 \end{aligned}$$

1 2 4 7 12 20 33 54 88 ...

## AVL Trees are Balanced

$$\begin{aligned} A_0 &= 1 \\ A_1 &= 2 \\ A_d &= A_{d-1} + A_{d-2} + 1, \quad d \geq 2 \end{aligned}$$

1 2 4 7 12 20 33 54 88 ...

1 1 2 3 5 8 13 21 34 55 ...  
The Fibonacci sequence

## AVL Trees are Balanced

$$\begin{aligned} A_0 &= 1 \\ A_1 &= 2 \\ A_d &= A_{d-1} + A_{d-2} + 1, \quad d \geq 2 \end{aligned}$$

1 2 4 7 12 20 33 54 88 ...  
1 1 2 3 5 8 13 21 34 55 ...  
 $A_d = F_{d+2} - 1 = O(\phi^d)$

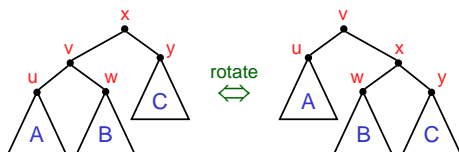
## Rebalancing

- Insertion and deletion can invalidate the AVL invariant
- May have to *rebalance*

## Rebalancing

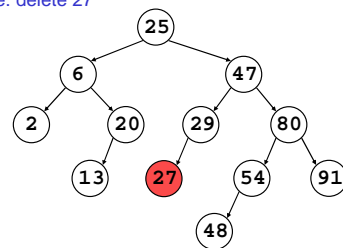
### Rotation

- A local rebalancing operation
- Preserves inorder ordering of the elements
- The AVL invariant can be reestablished with at most  $O(\log n)$  rotations up and down the tree

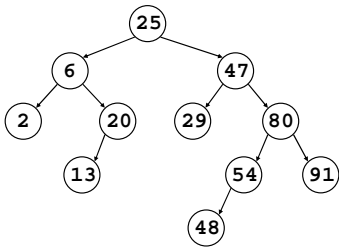


## Rebalancing

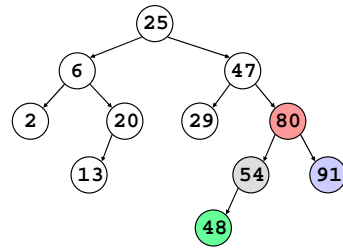
Example: delete 27



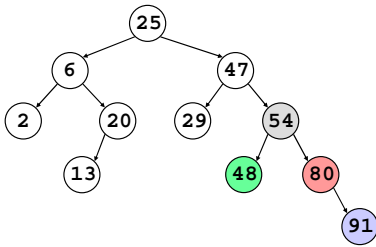
### Rebalancing



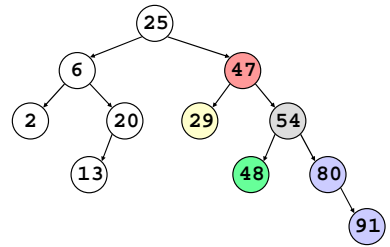
### Rebalancing



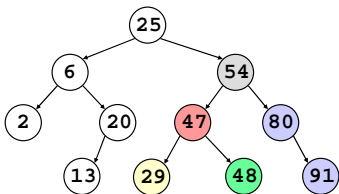
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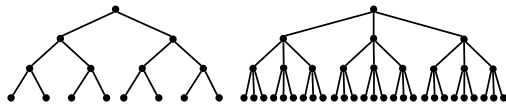


### 2-3 Trees

#### Another balanced tree scheme

- Data stored only at the leaves
- Ordered left-to-right
- All paths of the same length
- Every non-leaf has either 2 or 3 children
- Each internal node has smallest, largest element in its subtree (for searching)

## 2-3 Trees

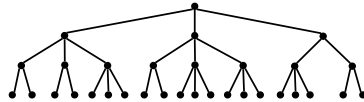


smallest 2-3 tree of height  $d = 3$   
 $2^d = 8$  data elements

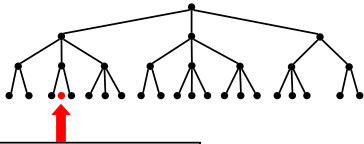
largest 2-3 tree of height  $d = 3$   
 $3^d = 27$  data elements

- number of elements satisfies  $2^d \leq n \leq 3^d$
- height satisfies  $d \leq \log n$

## Insertion in 2-3 Trees

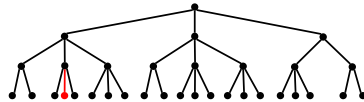


## Insertion in 2-3 Trees

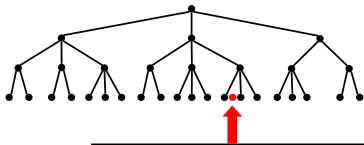


want to insert new element here

## Insertion in 2-3 Trees

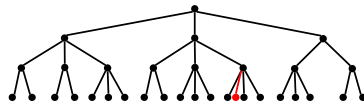


## Insertion in 2-3 Trees

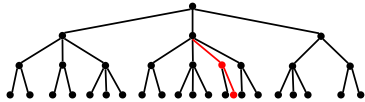


want to insert new element here

## Insertion in 2-3 Trees



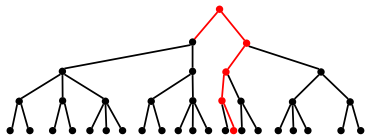
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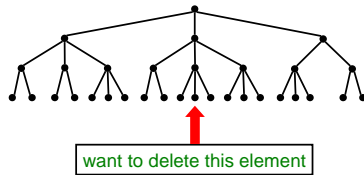
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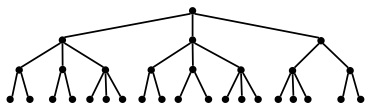
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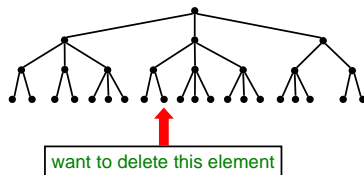
### Deletion in 2-3 Trees



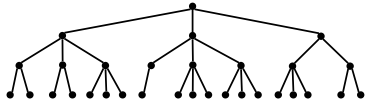
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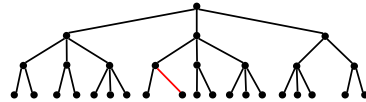


## Deletion in 2-3 Trees



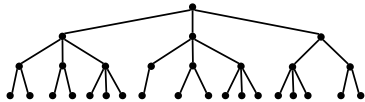
If neighbor has 3 children, borrow one

## Deletion in 2-3 Trees



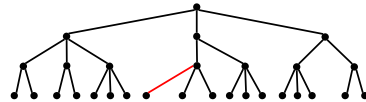
If neighbor has 3 children, borrow one

## Deletion in 2-3 Trees



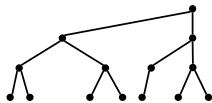
If neighbor has 2 children, coalesce with neighbor

## Deletion in 2-3 Trees



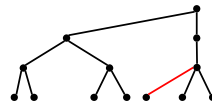
If neighbor has 2 children, coalesce with neighbor

## Deletion in 2-3 Trees



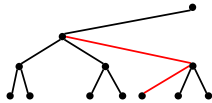
This may cascade up the tree!

## Deletion in 2-3 Trees



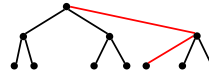
This may cascade up the tree!

## Deletion in 2-3 Trees



This may cascade up the tree!

## Deletion in 2-3 Trees



This may cascade up the tree!

## Conclusion

### Balanced search trees are good

- Search, insert, delete in  $O(\log n)$  time
- No need to know size in advance
- Several different versions
  - AVL trees, 2-3 trees, red-black trees, skip lists, random treaps, Huffman trees, ...
  - find out more about them in CS482