

- Previous Lecture:

- Nested loops
- Developing algorithms and code

- Today, Lecture 8:

- Review nested loops
- User-defined functions, part I

- Announcement:

- Project 2 due Monday 2/17 at 11pm
- Watch MatTV episode “Executing a Function”
- Lunch with instructors! RSVP via website survey. Friday, Feb 14, Risley Hall, 11:50



Rational approximation of π

- $\pi = 3.141592653589793\dots$
- Can be closely approximated by fractions,
e.g., $\pi \approx 22/7$
- Rational number: a quotient of two integers
- Approximate π as p/q where p and q are positive integers $\leq M$
- Start with a straight forward solution:
 - Get M from user
 - Calculate quotient p/q for all combinations of p and q
 - Pick best quotient \rightarrow smallest error

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Check all possible denominators
```

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Check all possible denominators
```

```
for q = 1:M
```

```
end
```

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Check all possible denominators
```

```
for q = 1:M
```

For current q find best numerator p...
Check all possible numerators

```
end
```

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Check all possible denominators
```

```
for q = 1:M
```

```
    % At this q, check all possible numerators
```

```
    for p = 1:M
```

```
        end
```

```
    end
```

Pattern: Best in set

Algorithm: Finding the best in a set

Init bestSoFar (value & quality)

Loop over set

 if current is better than bestSoFar

 bestSoFar \leftarrow current

 end

end

bestSoFar is best overall

```
% Rational approximation of pi
```

```
M = input('Enter M: ');
```

```
% Best q, p, and error so far
```

```
qBest=1; pBest=1;
```

```
err_pq = abs(pBest/qBest - pi);
```

```
% Check all possible denominators
```

```
for q = 1:M
```

```
    % At this q, check all possible numerators
```

```
    for p = 1:M
```

```
        end
```

```
    end
```

```
myPi = pBest/qBest;
```



```

% Rational approximation of pi

M = input('Enter M: ');
% Best q, p, and error so far
qBest=1;  pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M
        if abs(p/q - pi) < err_pq % best p/q found
            err_pq = abs(p/q - pi);
            pBest= p;
            qBest= q;
        end
    end
end

myPi = pBest/qBest;

```

| |
|----------|
| piFrac.m |
|----------|

% Complicated version in the book

```
M = input('Enter M: ');
```

```
% Best q, p, and error so far
```

```
qBest=1; pBest=1;
```

```
err_pq = abs(pBest/qBest - pi);
```

```
% Check all possible denominators
```

```
for q = 1:M
```

```
% At this q, check all possible numerators
```

```
p0=1; e0=abs(p0/q - pi); % best p & error so far
```

```
for p = 1:M
```

```
    if abs(p/q - pi) < e0 % new best numerator found
```

```
        p0=p; e0 = abs(p/q - pi);
```

```
    end
```

```
end
```

```
% Is best quotient for this q the best overall?
```

```
if e0 < err_pq
```

```
    pBest=p0; qBest=q; err_pq=e0;
```

```
end
```

```
end
```

```
myPi = pBest/qBest;
```

Algorithm: Finding the best in a set

Init bestSoFar

Loop over set

if current is better than bestSoFar

bestSoFar \leftarrow current

end

end

Analyzing cost

- See Eg3_1 and FasterEg3_1 in the book

```
for a = 1:n
    disp('alpha')
    for b = 1:m
        disp('beta')
    end
end
```

How many times are “alpha”
and “beta” displayed?

A: n, m

B: m, n

C: $n, n+m$

D: $n, n*m$

E: $m*n, m$

The savvy programmer...

- Learns useful **programming patterns** and use them where appropriate
- Seeks inspiration by **working through test data “by hand”**
 - Asks, “**What am I doing?**” at each step
 - Sets up a variable for each piece of information maintained when working the problem by hand
- **Decomposes** the problem into manageable subtasks
 - **Refines the solution iteratively**, solving simpler subproblems first
- Remembers to check the problem’s boundary conditions
- Validates the solution (program) by trying it on test data

Stepping back... what do we know about scripts?

- Bundle complicated logic conveniently under one name
 - To find best rational approx. to π , just run `piFrac`
- Inputs and outputs interact with humans
 - `input()`, `fprintf()`
- Share variables in common workspace
 - Danger: inheriting bad initialization from previous computation

What if...

- Inputs and outputs interacted with other code?
 - Interaction with humans considered a “side effect”
- Behavior not affected by other computations?

Built-in functions

- We've used many Matlab built-in functions, e.g., `rand()`, `abs()`, `floor()`, `rem()`
- Example: `abs(x-0.5)`
- Observations:
 - `abs()` is set up to be able to work with any valid data
 - `abs()` doesn't prompt us for input; it expects that we provide data that it'll then work on
 - `abs()` returns a value that we can use in our program

```
yDistance= abs(y2-y1);
```

```
while abs(myPi-pi) > .0001  
    ...
```

User-defined functions

We can write our own functions to perform a specific task:

- **Example:** draw a disk with specified radius, color, and center coordinates
 - Inputs: center, radius, color
 - Outputs: none
 - Side effects: Shows disk to user
- **Example:** generate a random floating point number in a specified interval
 - Inputs: interval lower bound, interval upper bound
 - Outputs: random number
- **Example:** convert polar coordinates to x-y (Cartesian) coordinates
 - Inputs: r -coordinate, θ -coordinate
 - Outputs: x-coordinate, y-coordinate

Multiple outputs are allowed!

Functions step-by-step

1. Identify candidates

- Look for opportunities to reuse logic or improve clarity

2. Design interface

- Name, inputs, outputs, side effects

3. Implement function

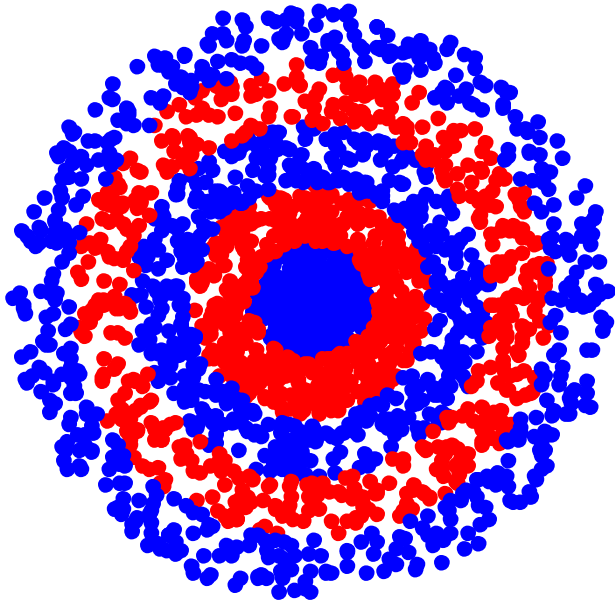
- “Write code”

4. Test

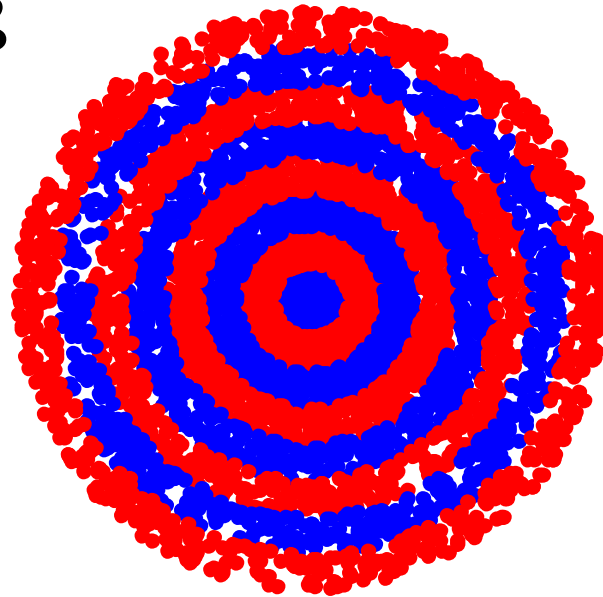
- Try it out (and try to break it)

5. Use

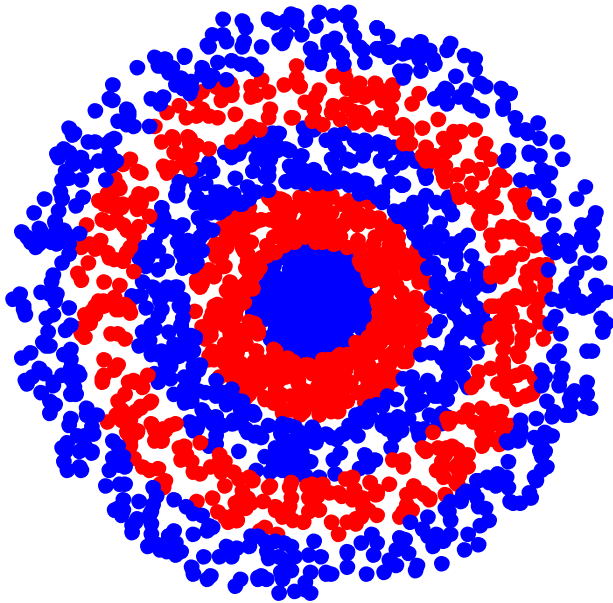
Draw a bulls eye figure with randomly placed dots



- Dots are randomly placed within concentric rings
- User decides how many rings, how many dots per ring

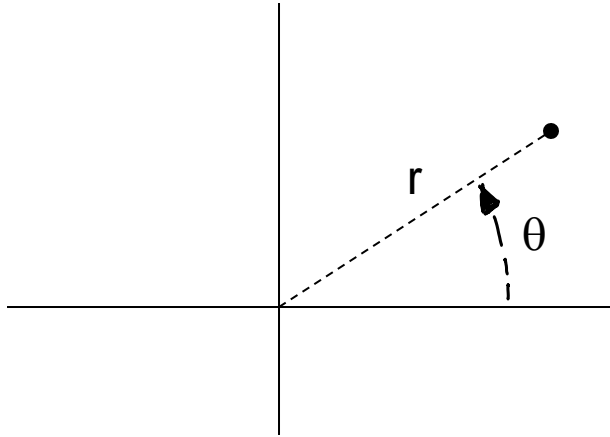


Draw a bulls eye figure with randomly placed dots

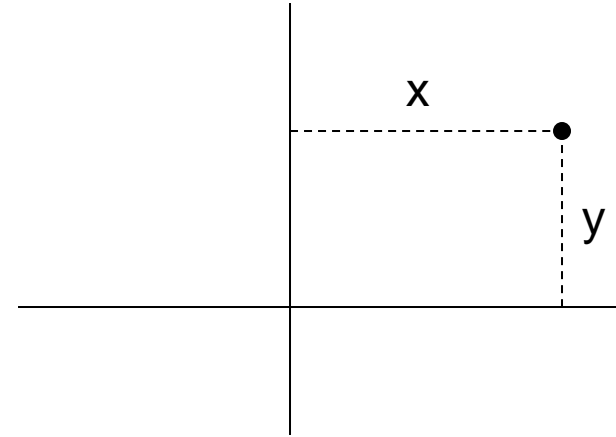
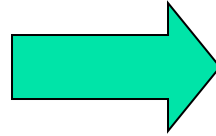


- What are the main tasks?
- Accommodate variable number of rings—loop
- For each ring
 - Need many dots (another loop)
 - For each dot
 - Generate random position
 - Choose color
 - Draw it

Convert from polar to Cartesian coordinates



Polar coordinates



Cartesian coordinates

```
c= input('How many concentric rings? ');  
d= input('How many dots? ');
```

```
% Put dots btwn circles with radii rRing and (rRing-1)
```

```
for rRing= 1:c
```

```
    % Draw d dots
```

```
    for count= 1:d
```

```
        % Generate random dot location (polar coord.)
```

```
        theta= _____
```

```
        r= _____
```

```
        % Convert from polar to Cartesian
```

```
        x= _____
```

```
        y= _____
```

```
        % Use plot to draw dot
```

```
    end
```

```
end
```

Outline

- For each ring
- For each dot
 - Generate random position
 - Choose color
 - Draw dot

A common task! Create a function `polar2xy` to do this. `polar2xy` likely will be useful in other problems as well.

```
% Generate random dot location (polar)
theta= _____ % degrees
r= _____
```

} Not our
job!

```
% Convert from polar to Cartesian
rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

Part of a script

```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads= theta*pi/180;    % radian
x= r*cos(rads);
y= r*sin(rads);
```

A function file
polar2xy.m

```
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.
```

```
rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

A function file
`polar2xy.m`

Think of `polar2xy` as a factory



```
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r, theta) to
% Cartesian coordinates (x, y).
% theta is in degrees.
```

```
rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

A function file
polar2xy.m

```
r= input('Enter radius: ');
theta= input('Enter angle in degrees: ');
```

```
rads= theta*pi/180; % radian
x= r*cos(rads);
y= r*sin(rads);
```

(Part of) a
script file

Functions step-by-step

1. Identify candidates

- Look for opportunities to reuse logic or improve clarity

2. Design interface

- Name, inputs, outputs, side effects

3. Implement function

- “Write code”

4. Test

- Try it out (and try to break it)

5. Use

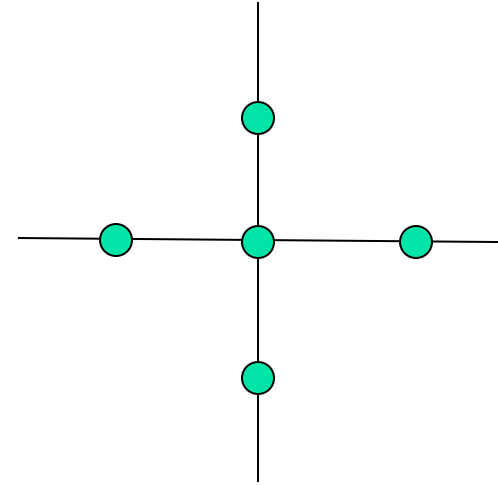
Time for testing

■ Good test cases:

- $r = 0$
- $\theta = 0, \pi/2, \pi, 3\pi/2$
- $\theta = -\pi, 3\pi$

■ How to test

- $[x, y] = \text{polar2xy}(r, \theta)$
- Command window
- Test script
- **DON'T** try to “run” the function file



```

c= input('How many concentric rings? ');
d= input('How many dots? ');

% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
    % Draw d dots
    for count= 1:d

        % Generate random dot location (polar coord.)
        theta= _____
        r= _____

        % Convert from polar to Cartesian
        x= _____
        y= _____

        % Use plot to draw dot
    end
end
end

```

A common task! Create a function **polar2xy** to do this. **polar2xy** likely will be useful in other problems as well.

```

c= input('How many concentric rings? ');
d= input('How many dots? ');

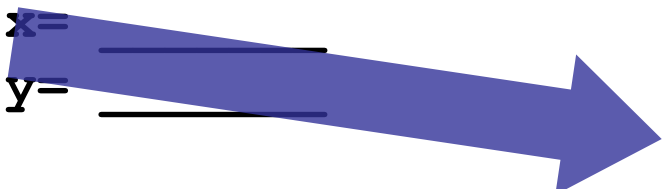
% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
    % Draw d dots
    for count= 1:d

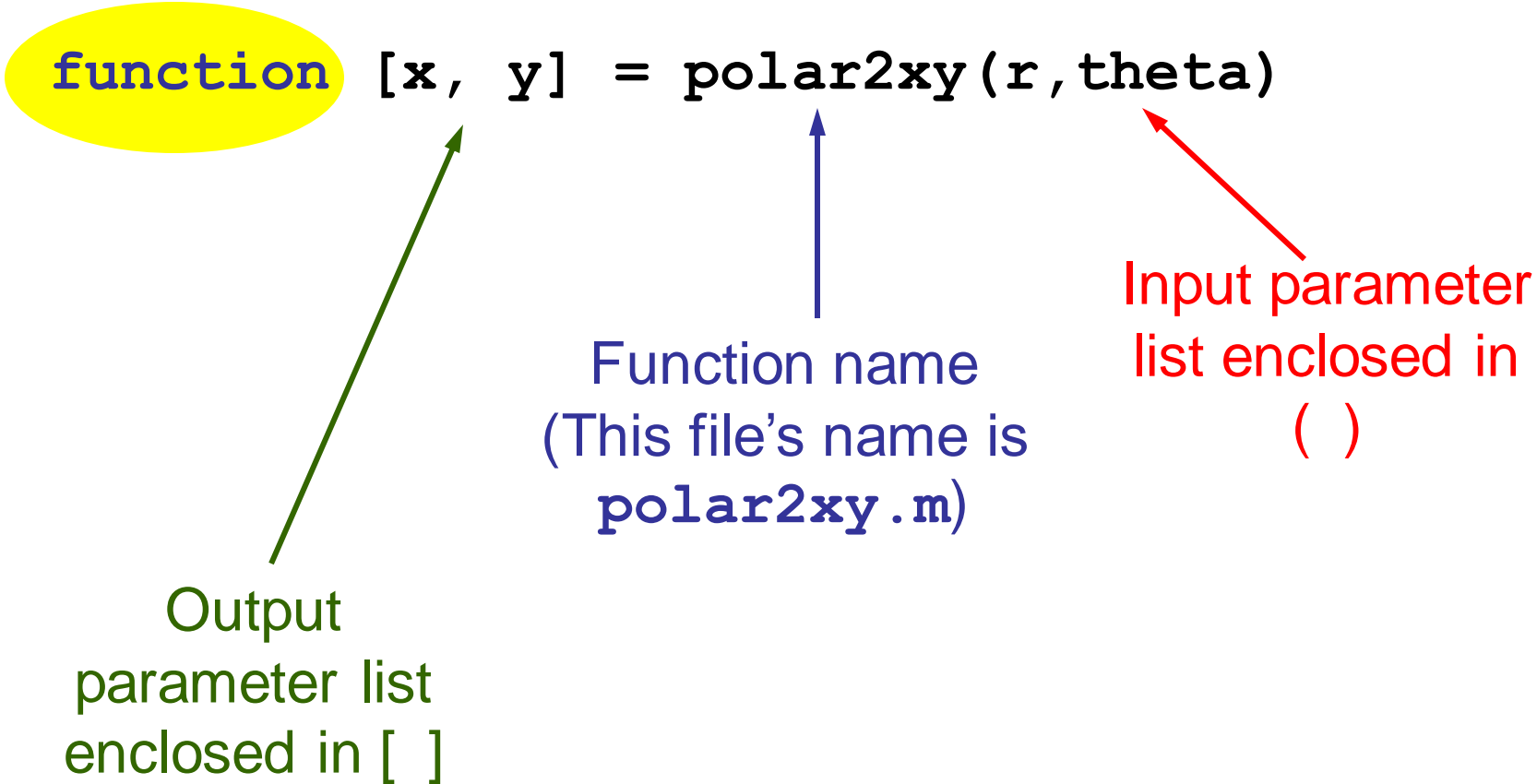
        % Generate random dot location (polar coord.)
        theta= _____
        r= _____

        % Convert from polar to Cartesian
        x= _____
        y= _____
        [x,y] = polar2xy(r,theta);

        % Use plot to draw dot
    end
end
end

```





Function header is the “contract” for how the function will be used (called)

You have this function:

```
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r, theta) to
% Cartesian coordinates (x,y). Theta in degrees.
...
```

Code to call the above function:

```
% Convert polar (r1,t1) to Cartesian (x1,y1)
r1 = 1; t1 = 30;
[x1, y1] = polar2xy(r1, t1);
plot(x1, y1, 'b*')
...
```

Function header is the “contract” for how the function will be used (called)

You have this function:

```
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y) Theta in degrees.
...
```

Code to call the above function:

```
% Convert polar (r1,t1) to Cartesian (x1,y1)
r1=1 t1= 30;
[x1, y1]= polar2xy(r1, t1);
plot(x1, y1, 'b*')
...
```