

- Previous Lecture:
 - Recursion
- Today's Lecture:
 - Sorting and searching
 - Insertion sort, linear search
 - Read about *Bubble Sort* in Insight
 - “Divide and conquer” strategies
 - Binary search
- Announcements
 - Discussion in computer lab this week
 - P6 due Thursday at 11pm
 - Final exam: Dec 7th 2pm for both Lec I and Lec 2

Sorting data allows us to search more easily

Phone Book

Name
Albert, Fat
Allan, Wong
Anderson, Bruce
Ann
Bailey, Bob
Bartl, Rainmar
Baumgardner, Bob
Beaudry, Mark
Berry, James
Beyss, Michael
Blank, Frederick
Bliss, Brian

Boston Marathon Top Women Finishers

Official Time	State	Country	Ctz
2:25:25		ETH	
2:25:27		RUS	
2:26:34		KEN	
2:28:12		LAT	
2:29:48		ETH	
2:30:52		ITA	
2:33:59		ROM	
2:34:37		ETH	
2:35:37		RUS	
2:44:44	IL	USA	CAN
2:45:54	NS	CAN	
2:46:25		KEN	
2:47:17	FL	USA	RUS
2:47:36		AUS	
2:48:43	MN	USA	

Name	Score	Grade
Jorge	92.1	
Ahn	91.5	
Oluban	90.6	
Chi	88.9	
Minale	88.1	

There are many algorithms for sorting

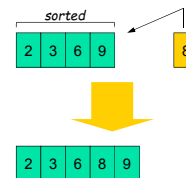
- Insertion Sort (to be discussed today)
 - Bubble Sort (read *Insight* §8.2)
 - Merge Sort (to be discussed Thursday)
 - Quick Sort (a variant used by Matlab's built-in `sort` function)
- Each has advantages and disadvantages. Some algorithms are faster (time-efficient) while others are memory-efficient
- Great opportunity for learning how to analyze programs and algorithms!

Lecture 26

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The Insertion Process

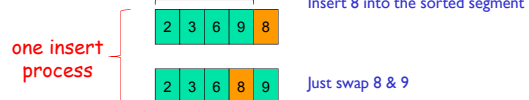
- Given a sorted array x , insert a number y such that the result is sorted



Lecture 26

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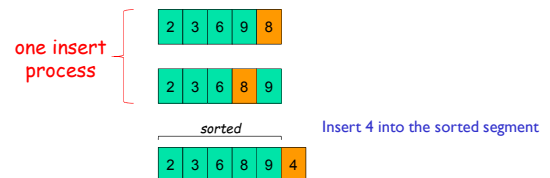
Insertion



Lecture 26

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Insertion



Lecture 26

8

Insertion

one insert process

Compare adjacent components:
swap 9 & 4

Lecture 26 9

Insertion

one insert process

Compare adjacent components:
swap 8 & 4

Lecture 26 10

Insertion

one insert process

Compare adjacent components:
swap 6 & 4

Lecture 26 11

Insertion

one insert process

Compare adjacent components:
DONE! No more swaps.

See `Insert.m` for the insert process

Lecture 26 12

Sort vector \mathbf{x} using the Insertion Sort algorithm

Need to start with a *sorted* subvector. How do you find one?

\mathbf{x}

Length 1 subvector is "sorted"

`Insert x(2): [x(1:2), C, S] = Insert(x(1:2))`

`Insert x(3): [x(1:3), C, S] = Insert(x(1:3))`

`Insert x(4): [x(1:4), C, S] = Insert(x(1:4))`

`Insert x(5): [x(1:5), C, S] = Insert(x(1:5))`

`Insert x(6): [x(1:6), C, S] = Insert(x(1:6))`

`InsertionSort.m`

Lecture 26 13

Insertion Sort vs. Bubble Sort

- Read about Bubble Sort in *Insight* §8.2
- Both algorithms involve the repeated comparison of adjacent values and swaps
- Find out which algorithm is more efficient on average

Lecture 26 14

Other efficiency considerations

- Worst case, best case, average case
- Use of subfunction incurs an “overhead”
- Memory use and access
- Example: Rather than directing the *insert* process to a subfunction, have it done “in-line.”
- Also, Insertion sort can be done “in-place,” i.e., using “only” the memory space of the original vector.

Lecture 26

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```
function x = InsertionSortInplace(x)
% Sort vector x in ascending order with insertion sort

n = length(x);
for i= 1:n-1
    % Sort x(1:i+1) given that x(1:i) is sorted

end
```

Lecture 26

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Sort an array of objects

- Given *x*, a 1-d array of *Interval* references, sort *x* according to the widths of the *Intervals* from narrowest to widest
- Use the insertion sort algorithm
- How much of our code needs to be changed?

A. No change

B. One or two statements

C. About half the code

D. Most of the code

Lecture 26

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Searching for an item in an unorganized collection?

- May need to look through the whole collection to find the target item
- E.g., find value *x* in vector *v*

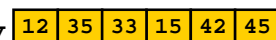

v 
 x 

- Linear search

Lecture 27

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```
% Linear Search
% f is index of first occurrence
% of value x in vector v.
% f is -1 if x not found.
k= 1;
while k<=length(v) && v(k)~=x
    k= k + 1;
end
if k>length(v)
    f= -1; % signal for x not found
else
    f= k;
end
```

v 
 x 

Lecture 27

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```
% Linear Search
% f is index of first occurrence
% of value x in vector v.
% f is -1 if x not found.
k= 1;
while k<=length(v) && v(k)~=x
    k= k + 1;
end
if k>length(v)
    f= -1; % signal for x not found
else
    f= k;
end
```

A. squared

B. doubled

C. the same

D. halved

Suppose another vector is twice as long as *v*. The expected “effort” required to do a linear search is ...


```
% Linear Search
% f is index of first occurrence
% of value x in vector v.
% f is -1 if x not found.
```

```
k= 1;
while k<=length(v) && v(k)~=x
    k= k + 1;
end
if k>length(v)
    f= -1; % signal for x not found
else
    f= k;
end
```

v 12 15 33 35 42 45

x 31

What if **v** is sorted?

Searching in
a sorted list should
require less work

Lecture 27

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An ordered (sorted) list

The Manhattan phone book has 1,000,000+ entries.

How is it possible to locate a name by examining just a tiny, tiny fraction of those entries?

Lecture 27

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Key idea of “phone book search”: repeated halving

To find the page containing **Pat Reed**’s number...

```
while (Phone book is longer than 1 page)
    Open to the middle page.
    if “Reed” comes before the first entry,
        Rip and throw away the 2nd half.
    else
        Rip and throw away the 1st half.
    end
end
```

Lecture 27

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What happens to the phone book length?

```
Original:      3000 pages
After 1 rip:   1500 pages
After 2 rips:  750 pages
After 3 rips:  375 pages
After 4 rips:  188 pages
After 5 rips:   94 pages
:
After 12 rips:  1 page
```

Lecture 27

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Binary Search

Repeatedly halving the size of the “search space” is the main idea behind the method of **binary search**.

An item in a sorted array of length **n** can be located with just $\log_2 n$ comparisons.

```
% Linear Search
% f is index of first occurrence of value x in vector v.
% f is -1 if x not found.
k= 1;
while k<=length(v) && v(k)~=x
    k= k + 1;
end
if k>length(v)
    f= -1; % signal for x not found
else
    f= k;
end
```

n comparisons against the target
are needed in worst case,
 $n=length(v)$.

Lecture 27

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Lecture 27

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Binary Search

Repeatedly halving the size of the “search space” is the main idea behind the method of **binary search**.

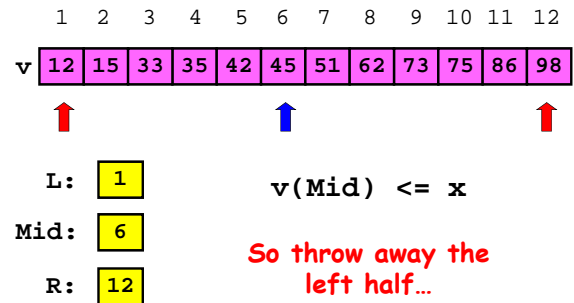
An item in a sorted array of length n can be located with just $\log_2 n$ comparisons.

“Savings” is significant!

n	$\log_2(n)$
100	7
1000	10
10000	13

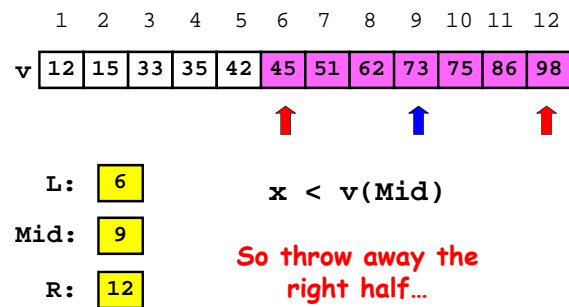
Lecture 27

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Binary search: target $x = 70$ 

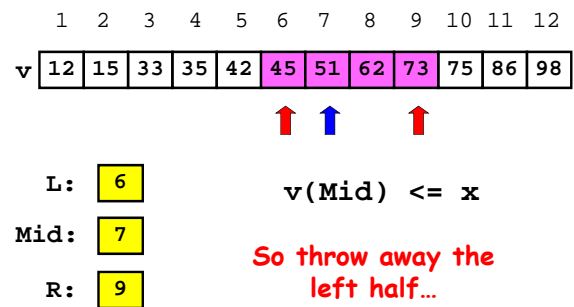
Lecture 27

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Binary search: target $x = 70$ 

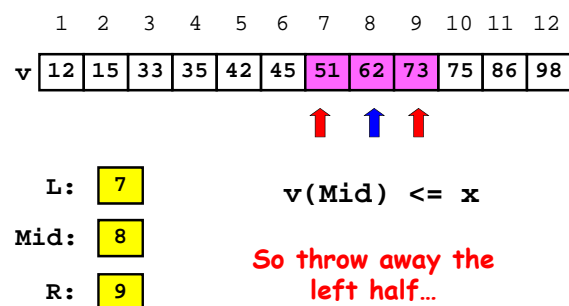
Lecture 27

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Binary search: target $x = 70$ 

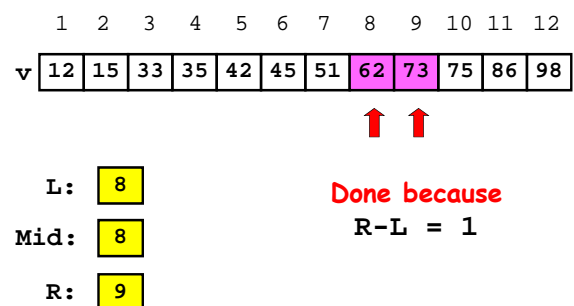
Lecture 27

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Binary search: target $x = 70$ 

Lecture 27

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Binary search: target $x = 70$ 

Lecture 27

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```

function L = binarySearch(x, v)
% Find position after which to insert x. v(1)<...<v(end).
% L is the index such that v(L) <= x < v(L+1);
% L=0 if x<v(1). If x>v(end), L=length(v) but x~=v(L).

% Maintain a search window [L..R] such that v(L)<=x<v(R).
% Since x may not be in v, initially set ...
L=0; R=length(v)+1;

% Keep halving [L..R] until R-L is 1,
% always keeping v(L) <= x < v(R)
while R ~= L+1
    m= floor((L+R)/2); % middle of search window
    if
        v(m) <= x
            L= m;
        else
            R= m;
    end
end
end

```

```

function L = binarySearch(x, v)
% Find position after which to insert x. v(1)<...<v(end).
% L is the index such that v(L) <= x < v(L+1);
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    m= floor((L+R)/2); % middle of search window
    if v(m) <= x
        L= m;
    else
        R= m;
    end
end
end

```

This version is different from that in *Insight*

```

function L = binarySearch(x, v)
% Find position after which to insert x. v(1)<...<v(end).
% L is the index such that v(L) <= x < v(L+1);
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    if v(m) <= x
        L= m;
    else
        R= m;
    end
end
end

```

Play with showBinarySearch.m

20	30	40	46	50	52	68	70
0	1	2	3	4	5	6	7