

- Previous Lecture:
  - “Divide and conquer” strategies
    - Binary search
    - Merge sort
- Today’s Lecture:
  - “Divide and conquer” strategies (cont’d)—recursion
    - Merge sort (review)
    - Removing a character (e.g., the blank) from a string
    - Tiling (subdividing) a triangle, e.g., Sierpinski Triangle
  - Some efficiency considerations
- Announcements
  - Project 6 due May 5<sup>th</sup> at 11pm
  - CS1112 final will be 5/12 (Thurs) 9am in Barton indoor field East. Email Prof Fan your *entire exam schedule* if you have a conflict. We must have this information by next Thursday (5/5).

Read Insight 14.1

### Merge sort is a “divide-and-conquer” strategy

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```
function y = mergeSort(x)
% x is a vector. y is a vector
% consisting of the values in x
% sorted from smallest to largest.

n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSort(x(1:m));
    yR = mergeSort(x(m+1:n));
    y = merge(yL,yR);
end
```

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```
function y=mergeSort(x)
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    yR=mergeSort(x(m+1:n));
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end
```

*mergeSort - 1<sup>st</sup> call*  
*(ms1)*

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### How do merge sort, insertion sort, and bubble sort compare?

- Insertion sort and bubble sort are similar
  - Both involve a series of comparisons and swaps
  - Both involve nested loops
- Merge sort uses recursion

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```
function x = insertSort(x)
% Sort vector x in ascending order with insertion sort

n = length(x);
for i = 1:n-1
    % Sort x(1:i+1) given that x(1:i) is sorted
    j= i;
    need2swap= x(j+1) < x(j);
    while need2swap
        % swap x(j+1) and x(j)
        temp= x(j);
        x(j)= x(j+1);
        x(j+1)= temp;

        j= j-1;
        need2swap= j>0 && x(j+1)<x(j);
    end
end
```

*Insertion sort is more efficient than bubble sort on average—fewer comparisons (Lecture 24)*

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How do merge sort and insertion sort compare?

- Insertion sort: (worst case) makes  $i$  comparisons to insert an element in a sorted array of  $i$  elements. For an array of length  $N$ :  
\_\_\_\_\_ for big  $N$
- Merge sort: \_\_\_\_\_
- Insertion sort is done *in-place*; merge sort (recursion) requires much more memory

How do merge sort and insertion sort compare?

- Insertion sort: (worst case) makes  $i$  comparisons to insert an element in a sorted array of  $i$  elements. For an array of length  $N$ :  
 $1+2+\dots+(N-1) = N(N-1)/2$ , say  $N^2$  for big  $N$
- Merge sort: \_\_\_\_\_

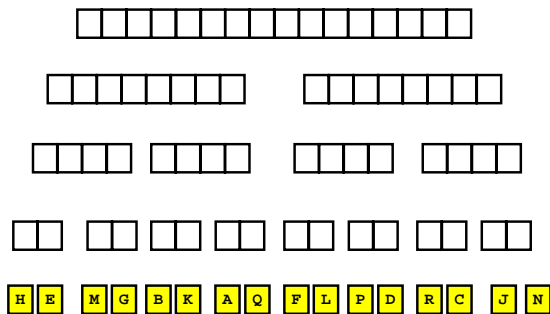
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function y = mergeSort(x)
% x is a vector. y is a vector
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n = length(x);
if n==1
    y = x;
else
    m = floor(n/2);
    yL = mergeSort(x(1:m));
    yR = mergeSort(x(m+1:n));
    y = merge(yL,yR);
end
```

All the comparisons between vector values are done in merge

```
function z = merge(x,y)
nx = length(x); ny = length(y);
z = zeros(1, nx+ny);
ix = 1; iy = 1; iz = 1;
while ix<=nx && iy<=ny
    if x(ix) <= y(iy)
        z(iz)= x(ix); ix=ix+1; iz=iz+1;
    else
        z(iz)= y(iy); iy=iy+1; iz=iz+1;
    end
end
while ix<=nx % copy remaining x-values
    z(iz)= x(ix); ix=ix+1; iz=iz+1;
end
while iy<=ny % copy remaining y-values
    z(iz)= y(iy); iy=iy+1; iz=iz+1;
end
```

Merge sort:  $\log_2(N)$  "levels";  $N$  comparisons each level



How do merge sort and insertion sort compare?

- Insertion sort: (worst case) makes  $i$  comparisons to insert an element in a sorted array of  $i$  elements. For an array of length  $N$ :  
 $1+2+\dots+(N-1) = N(N-1)/2$ , say  $N^2$  for big  $N$   $O(N^2)$
- Merge sort:  $N \cdot \log_2(N)$   $O(N \log_2(N))$  ← Order of magnitude
- Insertion sort is done *in-place*; merge sort (recursion) requires much more memory

How to choose??

- Depends on application
- Merge sort is especially good for sorting **large data set** (but watch out for memory usage)
- Insertion sort is “order  $N^2$ ” at **worst case**, but what about an **average case**? If the application requires that you *maintain* a sorted array, insertion sort may be a good choice

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Why not just use Matlab's sort function?

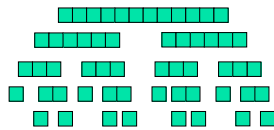
- **Flexibility**
- E.g., to maintain a sorted list, just write the code for insertion sort
- E.g., sort strings or other complicated structures
- Sort according to some criterion set out in a function file
  - Observe that we have the comparison  $x(j+1) < x(j)$
  - The comparison can be a function that returns a **boolean** value
- Can combine different sort/search algorithms for specific problem

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Back to Recursion

- Merge sort



- Remove all occurrences of a character from a string

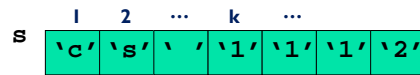
'gc aatc gga c ' → 'gcaatcggac'

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Example: removing all occurrences of a character

- Can solve using iteration—check one character (one component of the vector) at a time



Subproblem 1:  
Keep or discard s(1)

Subproblem 2:  
Keep or discard s(2)

Subproblem k:  
Keep or discard s(k)

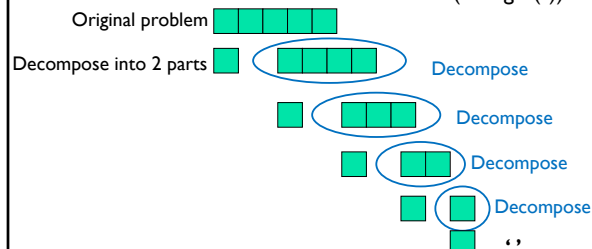
Iteration:  
Divide problem into sequence of equal-sized, identical subproblems

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Example: removing all occurrences of a character

- Can solve using **recursion**
  - Original problem: **remove all the blanks** in string s
  - Decompose into two parts: 1. **remove blank in s(1)**
  - 2. **remove blanks in s(2:length(s))**



```
function s = removeChar(c, s)
% Return string s with character c removed

if length(s)==0 % Base case: nothing to do
    return
else
    if s(1)~=c

    else

    end
end
```

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```
function s = removeChar(c, s)
if length(s)==0
return
else
if s(1)~=c
s = [s(1) removeChar(c, s(2:length(s)))];
else
s = removeChar(c, s(2:length(s)));
end
end
end
```

s = [d \_ o \_ g]

c = [ ]

removeChar - 1<sup>st</sup> call

```
function s = removeChar(c, s)
if length(s)==0
return
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s = [d \_ o \_ g]

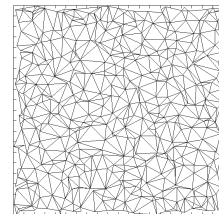
c = [ ]

removeChar - 1<sup>st</sup> call

removeChar - 2<sup>nd</sup> call

Divide-and-conquer methods also show up in geometric situations

Chop a region up into triangles with smaller triangles in "areas of interest"



Recursive mesh generation