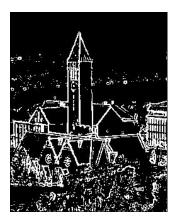
- Previous Lecture:
  - Working with images
- Today's Lecture:
  - More on manipulating images
    - "Noise" filtering
    - Edge finding





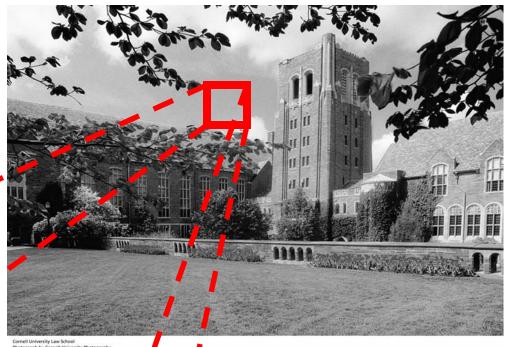
- Announcements:
  - Project 4 due tonight at 11pm

## An image as an array: values in [0..255]

0 = black255 = white

These are *integer* values

Type: uint8



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150	149	152	153	152	155
151	150	153	154	153	156
153	151	155	156	155	158
154	153	156	157	156	159
156	154	158	159	158	161
157	156	159	160	159	162

## Vectorized code to create a mirror image

```
A = imread('LawSchool.jpg')
       [nr,nc,np] = size(A);
     for c= 1:nc
                                                     B(:,c,1) = A(:,nc+1-c,1)
                                                     B(:,c,2) = A(:,nc+1-c,2)
imwrite(B, 'Laws Can improve efficiency by to be a 3-d size initializing the appropriate ) initializing the appropriate array of the appropriate (B, 'Can improve efficiency by the associate size array of the appropriate (B, 'Laws Can improve efficiency by the associate size array of the appropriate (B, 'Laws Can improve efficiency by the associate size array of the appropriate (B, 'Laws Can improve efficiency by the associate size array of the appropriate (B, 'Laws Can improve efficiency by the associate size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 3-d size array of the appropriate (B, 'Laws Can improve efficiency B to be a 
                                                     B(:,c,3) = A(:,nc+1-c,3)
```

## Example: produce a negative





## Problem: produce a negative

- "Negative" is what we say, but all color values are positive numbers!
- Think in terms of the extremes, 0 and 255. Then the "negative" just means the opposite side.
- So 0 is the opposite of 255;

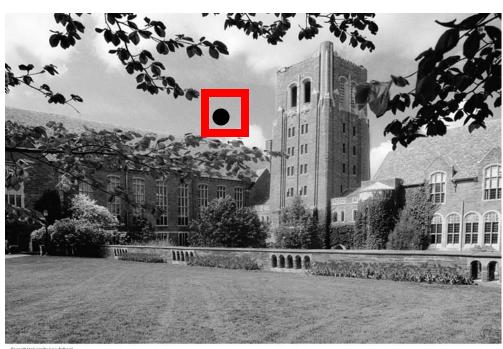
```
1 ... 254;
5 ... 250;
30 ... 225;
x ...
```

```
function newIm = toNegative(im)
% newIm is the negative of image data im
% im, newIm are 3-d arrays; each component is uint8
[nr,nc,np]= size(im); % dimensions of im
newIm= zeros(nr,nc); % initialize newIm
newIm= uint8(newIm); % Type for image color values
for r= 1:nr
   for c= 1:nc
       for p= 1:np
           newIm(r,c,p)= _____;
       end
   end
end
```

```
function newIm = toNegative(im)
% newIm is the negative of image im
% im, newIm are 3-d arrays; each component is uint8
[nr,nc,np]= size(im); % dimensions of im
newIm= zeros(nr,nc,np); % initialize newIm
newIm= uint8(newIm); % Type for image color values
for r= 1:nr
    for c= 1:nc
       for p= 1:np
           newIm(r,c,p) = 255 - im(r,c,p);
       end
   end
end
```

## Dirt in the image!

Note how the "dirty pixels" look out of place

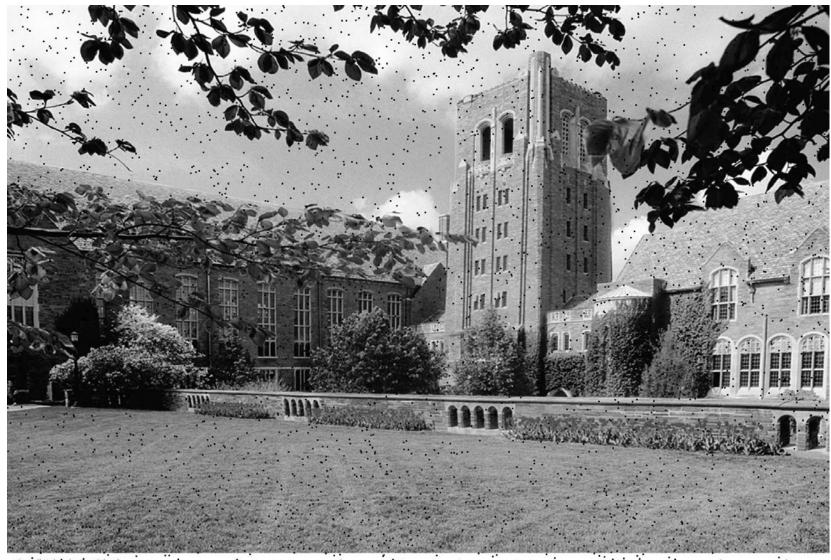


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150	149	152	153	152	155
151	150	153	154	153	156
153	2	3	156	155	158
154	2	1	157	156	159
156	154	158	159	158	161
157	156	159	160	159	162

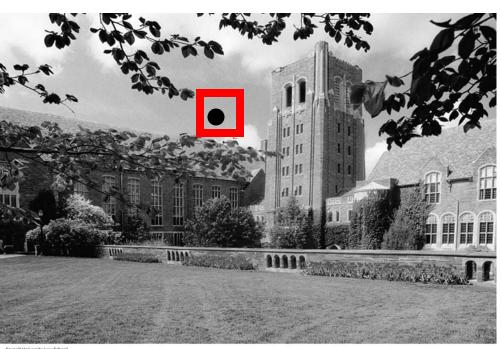
## Clean up "noise" — median filtering



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## What to do with the dirty pixels?

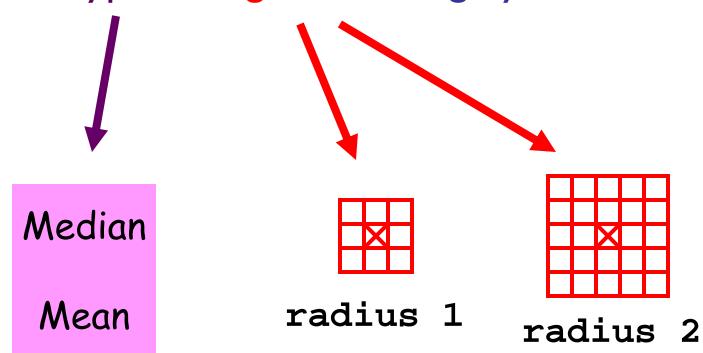
Assign "typical" neighborhood gray values to "dirty pixels"



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150	149	152	153	152	155
151	150	153	154	153	156
153	?	?	156	155	158
154	?	?	157	156	159
156	154	158	159	158	161
157	156	159	160	159	162

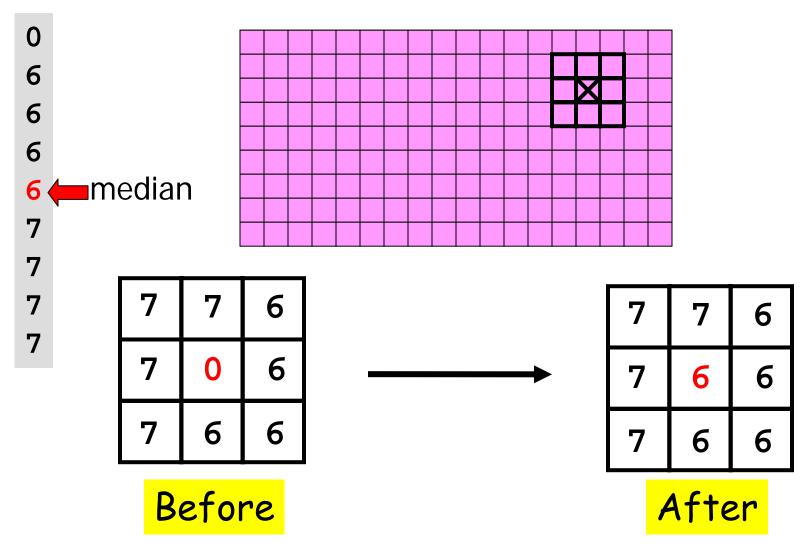
## What are "typical neighborhood gray values"?



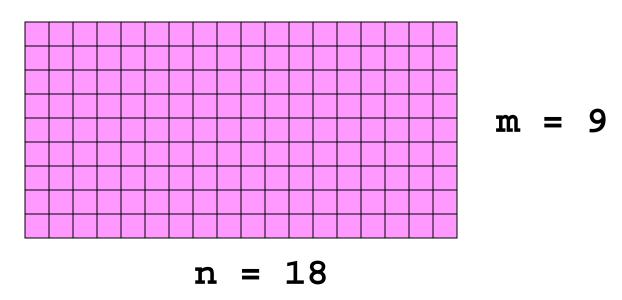
## Median Filtering

- Visit each pixel
- Replace its gray value by the median of the gray values in the "neighborhood"

## Using a radius I "neighborhood"

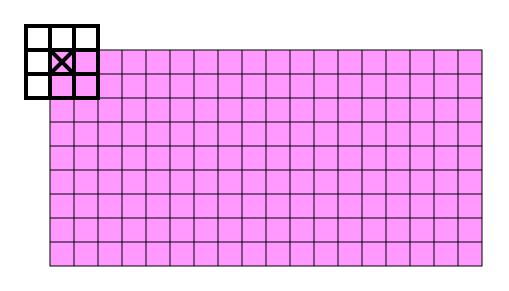


#### Visit every pixel; compute its new value.

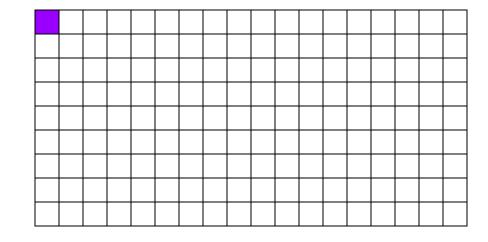


```
for i=1:m
   for j=1:n
        Compute new gray value for pixel (i,j).
   end
end
```

$$i = 1$$

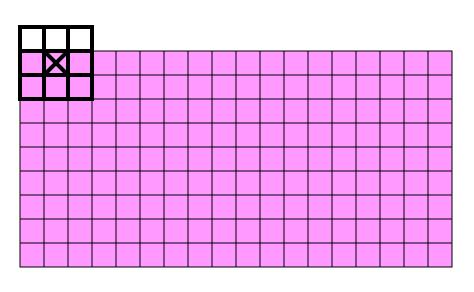




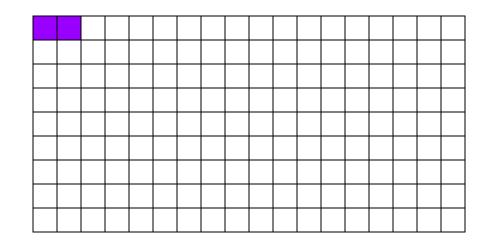


$$i = 1$$

$$j = 2$$

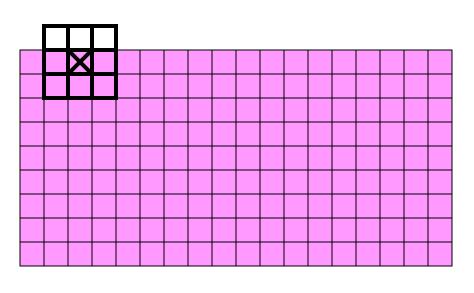




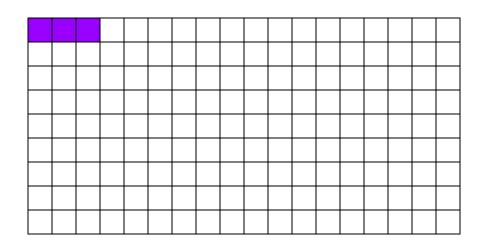


$$i = 1$$

$$j = 3$$

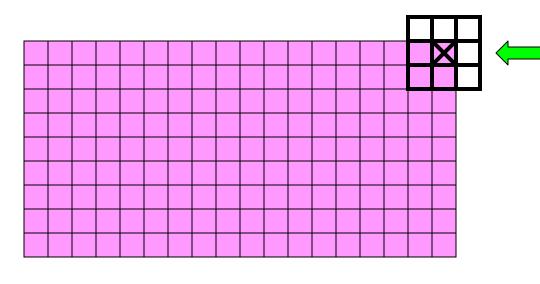




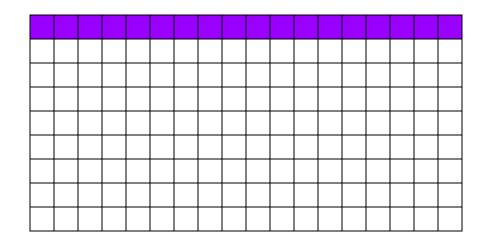


$$i = 1$$

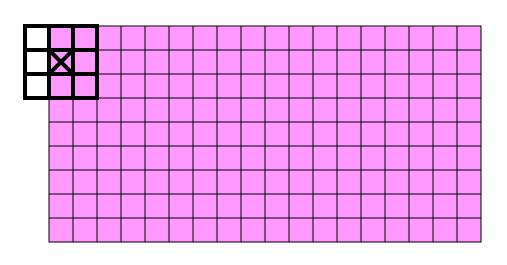
$$j = n$$



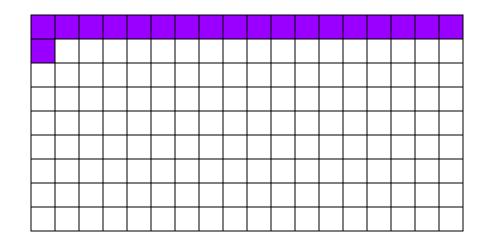




$$i = 2$$

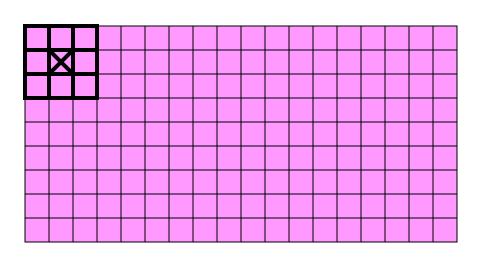




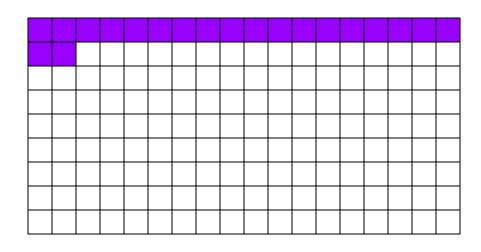


$$i = 2$$

$$j = 2$$

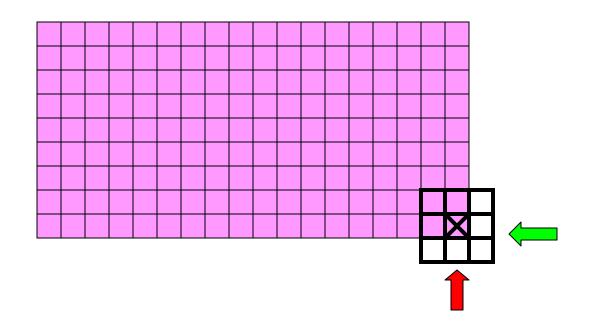


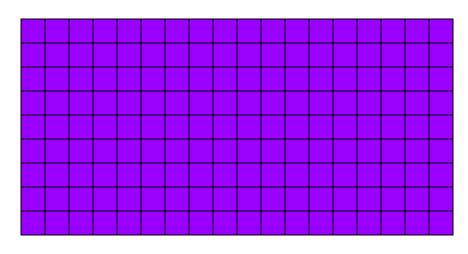




$$i = m$$

$$j = n$$





#### What We Need...

 (I) A function that computes the median value in a 2-dimensional array C:

```
m = medVal(C)
```

 (2) A function that builds the filtered image by using median values of radius r neighborhoods:

B = medFilter(A,r)

#### Computing Medians

```
21 | 89 | 36 |
                     28 | 19 |
x = sort(x)
              21
                 28 36
n = length(x); % n = 7
m = ceil(n/2); % m = 4
                  % med = 36
med = x(m);
```

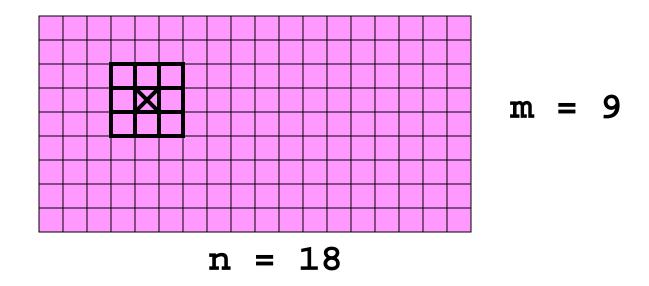
If n is even, then use: med = x(m)/2 + x(m+1)/2

## Median of a 2D Array

```
function med = medVal(C)
[p,q] = size(C);
\mathbf{x} = [];
for k=1:p
   x = [x C(k,:)];
end
%Compute median of x and assign to med
```

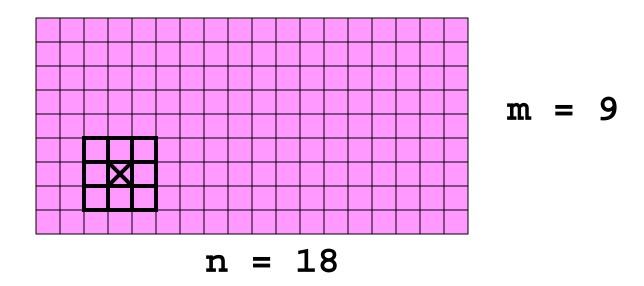
See medVal.m

## Back to Filtering...



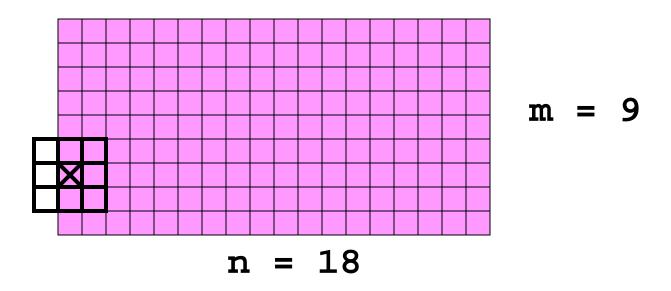
```
for i=1:m
    for j=1:n
        Compute new gray value for pixel (i,j)
        end
end
```

#### When window is inside...



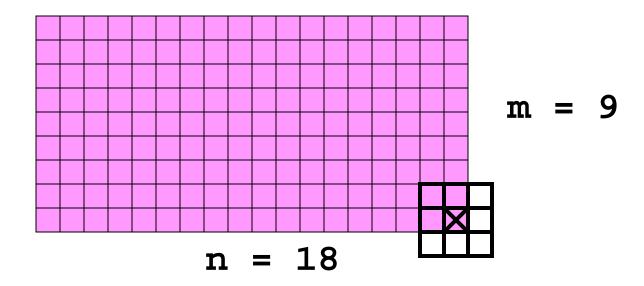
```
New gray value for pixel (7,4) = medVal( A(6:8,3:5) )
```

#### When window is partly outside...



```
New gray value for pixel (7,1) = medVal( A(6:8,1:2) )
```

#### When window is partly outside...

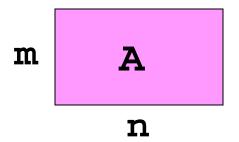


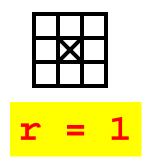
```
New gray value for pixel (9,18) = medVal( A(8:9,17:18) )
```

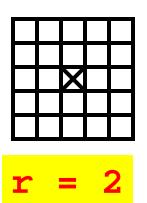
```
function B = medFilter(A,r)
% B from A via median filtering
% with radius r neighborhoods.
[m,n] = size(A);
B = uint8(zeros(m,n));
for i=1:m
   for j=1:n
      C = pixel (i,j) neighborhood
      B(i,j) = medVal(C);
   end
end
```

## The Pixel (i,j) Neighborhood

```
iMin = i-r
iMax = i+r
jMin = j-r
jMax = j+r
C = A(iMin:iMax,jMin:jMax)
```



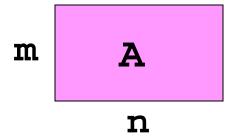


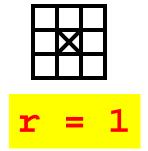


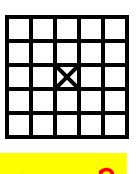
## The Pixel (i,j) Neighborhood

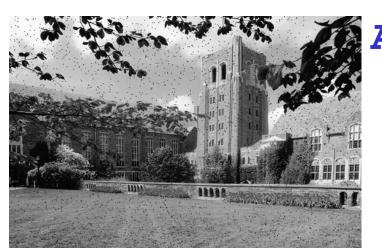
```
iMin = max(1,i-r)
iMax = min(m,i+r)
jMin = max(1,j-r)
jMax = min(n,j+r)

C = A(iMin:iMax,jMin:jMax)
```







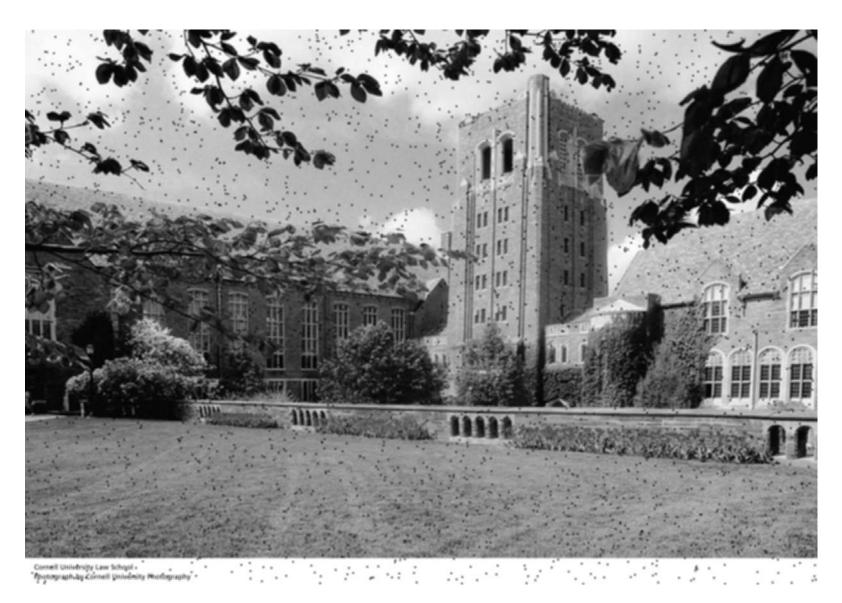


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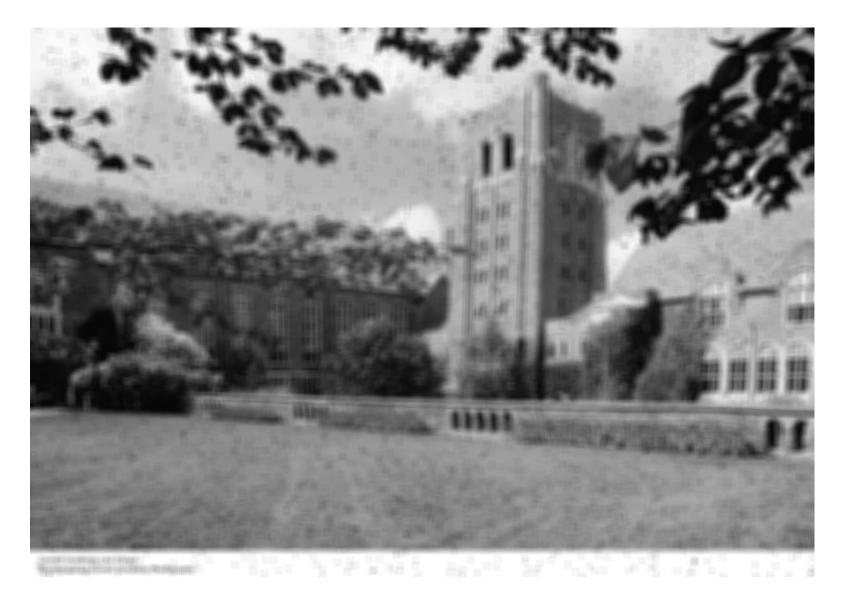
B = medianFilter(A,3)



#### Mean Filter with radius 3



#### Mean Filter with radius 10



# Mean filter fails because the mean does not capture representative values.

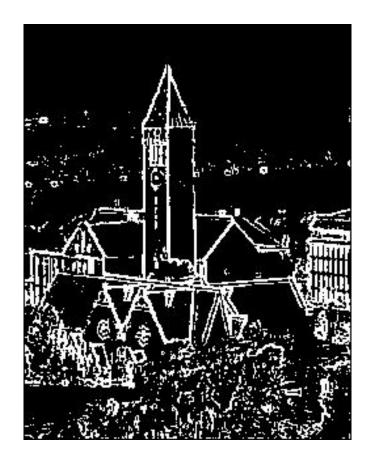
150	149	152	153	152	155
151	150	153	154	153	156
153	2	3	156	155	158
154	2	1	157	156	159
156	154	158	159	158	161
157	156	159	160	159	162

85 8687 88

mean-filtered values

## Finding Edges





# What is an Edge?

# Near an edge, grayness values change abruptly

200	200	200	200	200	200
200	200	200	200	200	100
200	200	200	200	100	100
200	200	200	100	100	100
200	200	100	100	100	100
200	100	100	100	100	100



# General plan for showing the edges in in image

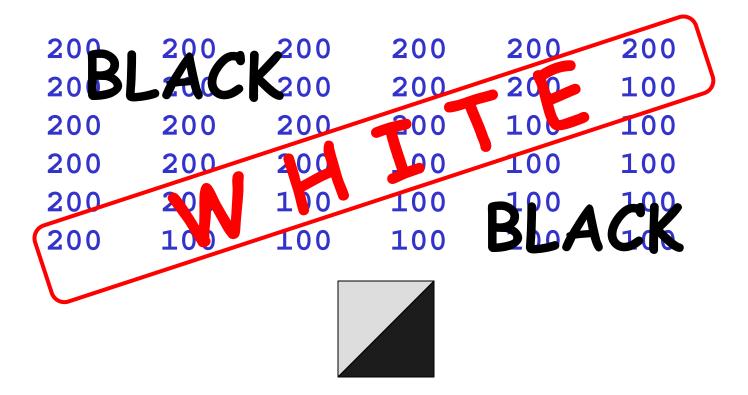
- Identify the "edge pixels"
- Highlight the edge pixels
  - make edge pixels white; make everything else black

200	200	200	200	200	200
200	200	200	200	200	100
200	200	200	200	100	100
200	200	200	100	100	100
200	200	100	100	100	100
200	100	100	100	100	100



# General plan for showing the edges in in image

- Identify the "edge pixels"
- Highlight the edge pixels
  - make edge pixels white; make everything else black



# The Rate-of-Change-Array

Suppose A is an image array with integer values between 0 and 255

Let B(i,j) be the maximum value in

```
A(max(1,i-1):min(m,i+1),...
max(1,j-1):min(n,j+1)) - A(i,j)
```

Neighborhood of A(i,j)

# Rate-of-change example

90	81	65
62	60	59
56	57	58

Rate-of-change at middle pixel is 30

Remember that we're doing "uint8 arithmetic"! 57 - 60 is 0 in uint8

#### There can be different definitions for the rate-of-change

#### A

1	1	1	1	1	1
1	1	1	1	1	1
1	1	1	1	90	90
1	1	1	90	90	90
1	1	90	90	90	90
1	1	90	90	90	90

## Neighborhood - A(i,j)

0	0	0	0	0	0
0	0	0	89	89	89
0	0	89	89	0	0
0	89	89	0	0	0
0	89	0	0	0	0
0	89	0	0	0	0

#### | Neighborhood - A(i,j) |

0	0	0	0	0	0
0	0	0	89	89	89
0	0	89	89	89	89
0	89	89	89		0
0	89	89	89	0	0
0	89	89	0	0	0

### A(i,j) - Neighborhood

0	0	0	0	0	0
0	0	0	0	0	0
0	0	0	0	89	89
0	0	0	89	89	0
0	0	89	89	0	0
0	0	89	0	0	0

```
function Edges(jpgIn,jpgOut,tau)
% jpgOut is the "edge diagram" of image jpgIn.
% At each pixel, if rate-of-change > tau
% then the pixel is considered to be on an edge.
A = rgb2gray(imread(jpgIn)); Built-in function to
                                convert to grayscale.
[m,n] = size(A);
                                Returns 2-d array.
B = uint8(zeros(m,n));
for i = 1:m
    for j = 1:n
        B(i,j) = ?????
    end
end
```

# Recipe for rate-of-change B(i,j)

```
% The 3-by-3 subarray that includes
% A(i,j) and its 8 neighbors
 Neighbors = A(i-1:i+1,j-1:j+1);
% Subtract A(i,j) from each entry
 Diff = Neighbors - A(i,j));
% Compute largest value in each column
 colMax = max(Diff);
% Compute the max of the column max's
 B(i,j) = max(colMax);
```

```
function Edges(jpgIn,jpgOut,tau)
% jpgOut is the "edge diagram" of image jpgIn.
% At each pixel, if rate-of-change > tau
% then the pixel is considered to be on an edge.
A = rgb2gray(imread(jpgIn));
[m,n] = size(A);
B = uint8(zeros(m,n));
for i = 1:m
  for j = 1:n
    Neighbors = A(\max(1,i-1):\min(i+1,m), ...
                  \max(1,j-1):\min(j+1,n));
    B(i,j) = max(max(Neighbors - A(i,j)));
  end
end
```

#### "Edge pixels" are now identified; display them with maximum brightness (255)

#### A

1	1	1	1	1	1
1	1	1	1	1	1
1	1	1	1	90	90
1	1	1	90	90	90
1	1	90	90	90	90
1	1	90	90	90	90

if	B(i,j)	> 1	tau
	B(i,j)	) =	255;
end	l		

## B(i,j)

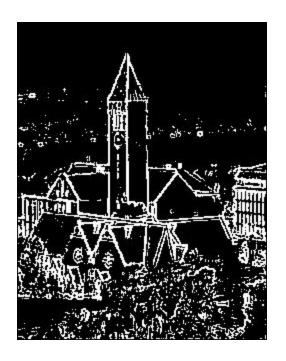
0	0	0	0	0	0
0	0	0	89	89	89
0	0	89	89	0	0
0	89	89	0	0	0
0	89	0	0	0	0
0	89	0	0	0	0

0	0	0	0	0	0
0	0	0	255	255	255
0	0	255	255	0	0
0	255	255	0	0	0
0	255	0	0	0	0
0	255	0	0	0	0

```
function Edges(jpgIn,jpgOut,tau)
% jpgOut is the "edge diagram" of image jpgIn.
% At each pixel, if rate-of-change > tau
% then the pixel is considered to be on an edge.
A = rgb2gray(imread(jpgIn));
[m,n] = size(A);
B = uint8(zeros(m,n));
for i = 1:m
  for j = 1:n
    Neighbors = A(max(1,i-1):min(i+1,m), ...
                  \max(1,j-1):\min(j+1,n));
    B(i,j) = max(max(Neighbors - A(i,j)));
    if B(i,j) > tau
     B(i,j) = 255;
    end
  end
end
```

```
function Edges(jpgIn,jpgOut,tau)
% jpgOut is the "edge diagram" of image jpgIn.
% At each pixel, if rate-of-change > tau
% then the pixel is considered to be on an edge.
A = rgb2gray(imread(jpgIn));
[m,n] = size(A);
B = uint8(zeros(m,n));
for i = 1:m
  for j = 1:n
    Neighbors = A(max(1,i-1):min(i+1,m), ...
                  \max(1,j-1):\min(j+1,n));
    B(i,j) = max(max(Neighbors - A(i,j)));
    if B(i,j) > tau
     B(i,j) = 255;
    end
  end
end
imwrite(B, jpgOut, 'jpg')
```





tau = 30



tau = 20



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