We have now seen two operational models for programming languages: small-step and large-step. In this lecture, we consider a different semantic model, called denotational semantics.

The idea in denotational semantics is to express the meaning of a program as the mathematical function that expresses what the program computes. We can think of an IMP program $c$ as a function from stores to stores: given an an initial store, the program produces a final store. For example, the program foo $:=\mathrm{bar}+1$ can be thought of as a function that when given an input store $\sigma$, produces a final store $\sigma^{\prime}$ that is identical to $\sigma$ except that it maps foo to the integer $\sigma(\mathrm{bar})+1$; that is, $\sigma^{\prime}=\sigma[$ foo $\mapsto \sigma(\mathrm{bar})+1]$. We will model programs as functions from input stores to output stores. As opposed to operational models, which tell us how programs execute, the denotational model shows us what programs compute.

## 1 A Denotational Semantics for IMP

For each program $c$, we write $\mathcal{C} \llbracket c \rrbracket$ for the denotation of $c$, that is, the mathematical function that $c$ represents:

$$
\mathcal{C} \llbracket c \rrbracket: \text { Store } \boldsymbol{\sim} \text { Store. }
$$

Note that $\mathcal{C} \llbracket c \rrbracket$ is actually a partial function (as opposed to a total function), both because the store may not be defined on the free variables of the program and because program may not terminate for certain input stores. The function $\mathcal{C} \llbracket c \rrbracket$ is not defined for non-terminating programs as they have no corresponding output stores.

We will write $\mathcal{C} \llbracket c \rrbracket \sigma$ for the result of applying the function $\mathcal{C} \llbracket c \rrbracket$ to the store $\sigma$. That is, if $f$ is the function that $\mathcal{C} \llbracket c \rrbracket$ denotes, then we write $\mathcal{C} \llbracket c \rrbracket \sigma$ to mean the same thing as $f(\sigma)$.

We must also model expressions as functions, this time from stores to the values they represent. We will write $\mathcal{A} \llbracket a \rrbracket$ for the denotation of arithmetic expression $a$, and $\mathcal{B} \llbracket b \rrbracket$ for the denotation of boolean expression $b$.

$$
\begin{aligned}
& \mathcal{A} \llbracket a \rrbracket: \text { Store } \rightharpoonup \text { Int } \\
& \mathcal{B} \llbracket b \rrbracket: \text { Store } \rightharpoonup\{\text { true, false }\}
\end{aligned}
$$

Now we want to define these functions. To make it easier to write down these definitions, we will describe (partial) functions using sets of pairs. More precisely, we will represent a partial map $f: A \rightharpoonup B$ as a set of pairs $F=\{(a, b) \mid a \in A$ and $b=f(a) \in B\}$ such that, for each $a \in A$, there is at most one pair of the form $\left(a,{ }_{-}\right)$in the set. Hence $(a, b) \in F$ is the same as $b=f(a)$.

We can now define denotations for IMP. We start with the denotations of expressions:

$$
\begin{aligned}
\mathcal{A} \llbracket n \rrbracket= & \{(\sigma, n)\} \\
\mathcal{A} \llbracket x \rrbracket & =\{(\sigma, \sigma(x))\} \\
\mathcal{A} \llbracket a_{1}+a_{2} \rrbracket= & \left\{(\sigma, n) \mid\left(\sigma, n_{1}\right) \in \mathcal{A} \llbracket a_{1} \rrbracket \wedge\left(\sigma, n_{2}\right) \in \mathcal{A} \llbracket a_{2} \rrbracket \wedge n=n_{1}+n_{2}\right\} \\
\mathcal{B} \llbracket \text { true } \rrbracket= & \{(\sigma, \text { true })\} \\
\mathcal{B} \llbracket \text { fralse } \rrbracket= & \{(\sigma, \text { false })\} \\
\mathcal{B} \llbracket a_{1}<a_{2} \rrbracket= & \left\{(\sigma, \text { true }) \mid\left(\sigma, n_{1}\right) \in \mathcal{A} \llbracket a_{1} \rrbracket \wedge\left(\sigma, n_{2}\right) \in \mathcal{A} \llbracket a_{2} \rrbracket \wedge n_{1}<n_{2}\right\} \cup \\
& \left\{(\sigma, \text { false }) \mid\left(\sigma, n_{1}\right) \in \mathcal{A} \llbracket a_{1} \rrbracket \wedge\left(\sigma, n_{2}\right) \in \mathcal{A} \llbracket a_{2} \rrbracket \wedge n_{1} \geq n_{2}\right\}
\end{aligned}
$$

The denotations for commands are as follows:

$$
\begin{aligned}
\mathcal{C} \llbracket \mathbf{s k i p} \rrbracket & =\{(\sigma, \sigma)\} \\
\mathcal{C} \llbracket x:=a \rrbracket & =\{(\sigma, \sigma[x \mapsto n \rrbracket) \mid(\sigma, n) \in \mathcal{A} \llbracket a \rrbracket\} \\
\mathcal{C} \llbracket c_{1} ; c_{2} \rrbracket & =\left\{\left(\sigma, \sigma^{\prime}\right) \mid \exists \sigma^{\prime \prime} .\left(\left(\sigma, \sigma^{\prime \prime}\right) \in \mathcal{C} \llbracket c_{1} \rrbracket \wedge\left(\sigma^{\prime \prime}, \sigma^{\prime}\right) \in \mathcal{C} \llbracket c_{2} \rrbracket\right)\right\}
\end{aligned}
$$

Note that $\mathcal{C} \llbracket c_{1} ; c_{2} \rrbracket=\mathcal{C} \llbracket c_{2} \rrbracket \circ \mathcal{C} \llbracket c_{1} \rrbracket$, where $\circ$ is the composition of relations, defined as follows: if $R_{1} \subseteq$ $A \times B$ and $R_{2} \subseteq B \times C$ then $R_{2} \circ R_{1} \subseteq A \times C$ is $\left.R_{2} \circ R_{1}=\left\{(a, c) \mid \exists b \in B .(a, b) \in R_{1} \wedge(b, c) \in R_{2}\right\}.\right)$ If $\mathcal{C} \llbracket c_{1} \rrbracket$ and $\mathcal{C} \llbracket c_{2} \rrbracket$ are total functions, then $\circ$ is function composition.

$$
\begin{aligned}
\mathcal{C} \llbracket i f b \text { then } c_{1} \text { else } c_{2} \rrbracket= & \left\{\left(\sigma, \sigma^{\prime}\right) \mid(\sigma, \text { true }) \in \mathcal{B} \llbracket b \rrbracket \wedge\left(\sigma, \sigma^{\prime}\right) \in \mathcal{C} \llbracket c_{1} \rrbracket\right\} \cup \\
& \left\{\left(\sigma, \sigma^{\prime}\right) \mid(\sigma, \text { false }) \in \mathcal{B} \llbracket b \rrbracket \wedge\left(\sigma, \sigma^{\prime}\right) \in \mathcal{C} \llbracket c_{2} \rrbracket\right\} \\
\mathcal{C} \llbracket \text { while } b \text { do } c \rrbracket= & \{(\sigma, \sigma) \mid(\sigma, \text { false }) \in \mathcal{B} \llbracket b \rrbracket\} \cup \\
& \left\{\left(\sigma, \sigma^{\prime}\right) \mid(\sigma, \text { true }) \in \mathcal{B} \llbracket b \rrbracket \wedge \exists \sigma^{\prime \prime} .\left(\left(\sigma, \sigma^{\prime \prime}\right) \in \mathcal{C} \llbracket c \rrbracket \wedge\left(\sigma^{\prime \prime}, \sigma^{\prime}\right) \in \mathcal{C} \llbracket \text { while } b \text { do } c \rrbracket\right)\right\}
\end{aligned}
$$

But now we have a problem: the last "definition" is not really a definition because it expresses $\mathcal{C}$ [while $b$ do $c \rrbracket$ in terms of itself! This is not a definition but a recursive equation. What we want is the solution to this equation.

## 2 Fixed points

We gave a recursive equation that the function $\mathcal{C} \llbracket$ while $b$ do $c \rrbracket$ must satisfy. To understand some of the issues involved, let's consider a simpler example. Consider the following equation for a function $f: \mathbb{N} \rightarrow$ $\mathbb{N}$.

$$
f(x)= \begin{cases}0 & \text { if } x=0  \tag{1}\\ f(x-1)+2 x-1 & \text { otherwise }\end{cases}
$$

This is not a definition for $f$, but rather an equation that we want $f$ to satisfy. What function, or functions, satisfy this equation for $f$ ? The only solution to this equation is the function $f(x)=x^{2}$.

In general, there may be no solutions for a recursive equation (e.g., there are no functions $g: \mathbb{N} \rightarrow \mathbb{N}$ that satisfy the recursive equation $g(x)=g(x)+1$ ), or multiple solutions (e.g., find two functions $g: \mathbb{R} \rightarrow \mathbb{R}$ that satisfy $\left.g(x)=4 \times g\left(\frac{x}{2}\right)\right)$.

We can compute solutions to such equations by building successive approximations. Each approximation is closer and closer to the solution. To solve the recursive equation for $f$, we start with the partial
function $f_{0}=\emptyset$ (i.e., $f_{0}$ is the empty relation; it is a partial function with the empty set for it's domain). We compute successive approximations using the recursive equation.

$$
\begin{aligned}
f_{0} & =\emptyset \\
f_{1} & = \begin{cases}0 & \text { if } x=0 \\
f_{0}(x-1)+2 x-1 & \text { otherwise }\end{cases} \\
& =\{(0,0)\} \\
f_{2} & = \begin{cases}0 & \text { if } x=0 \\
f_{1}(x-1)+2 x-1 & \text { otherwise }\end{cases} \\
& =\{(0,0),(1,1)\} \\
f_{3} & = \begin{cases}0 & \text { if } x=0 \\
f_{2}(x-1)+2 x-1 & \text { otherwise }\end{cases} \\
& =\{(0,0),(1,1),(2,4)\}
\end{aligned}
$$

This sequence of successive approximations $f_{i}$ gradually builds the function $f(x)=x^{2}$.
We can model this process of successive approximations using a higher-order function $F$ that takes one approximation $f_{k}$ and returns the next approximation $f_{k+1}$ :

$$
F:(\mathbb{N} \rightharpoonup \mathbb{N}) \rightarrow(\mathbb{N} \rightharpoonup \mathbb{N})
$$

where

$$
(F(f))(x)= \begin{cases}0 & \text { if } x=0 \\ f(x-1)+2 x-1 & \text { otherwise }\end{cases}
$$

A solution to the recursive equation 1 is a function $f$ such that $f=F(f)$. In general, given a function $F: A \rightarrow A$, we have that $a \in A$ is a fixed point of $F$ if $F(a)=a$. We also write $a=$ fix $(F)$ to indicate that $a$ is a fixed point of $F$.

So the solution to the recursive equation 1 is a fixed-point of the higher-order function $F$. We can compute this fixed point iteratively, starting with $f_{0}=\emptyset$ and at each iteration computing $f_{k+1}=F\left(f_{k}\right)$. The fixed point is the limit of this process:

$$
\begin{aligned}
f & =\operatorname{fix}(F) \\
& =f_{0} \cup f_{1} \cup f_{2} \cup f_{3} \cup \ldots \\
& =\emptyset \cup F(\emptyset) \cup F(F(\emptyset)) \cup F(F(F(\emptyset))) \cup \ldots \\
& =\bigcup_{i \geq 0} F^{i}(\emptyset)
\end{aligned}
$$

