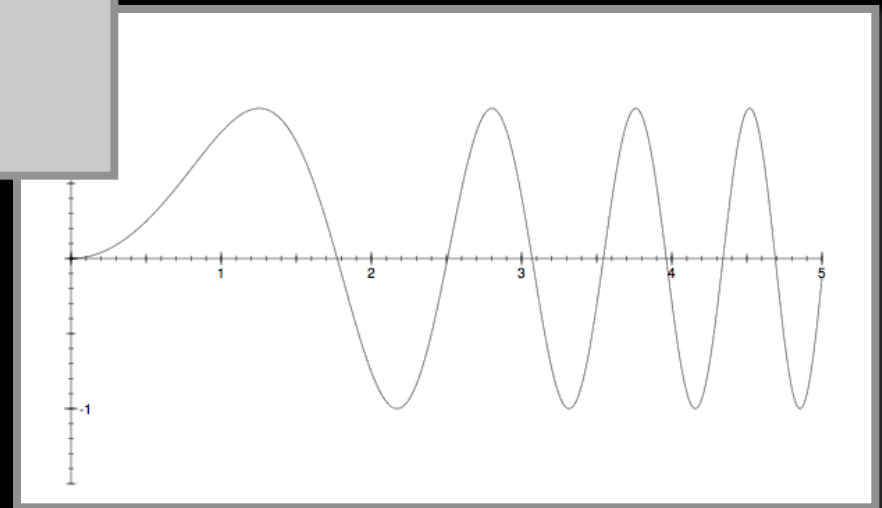
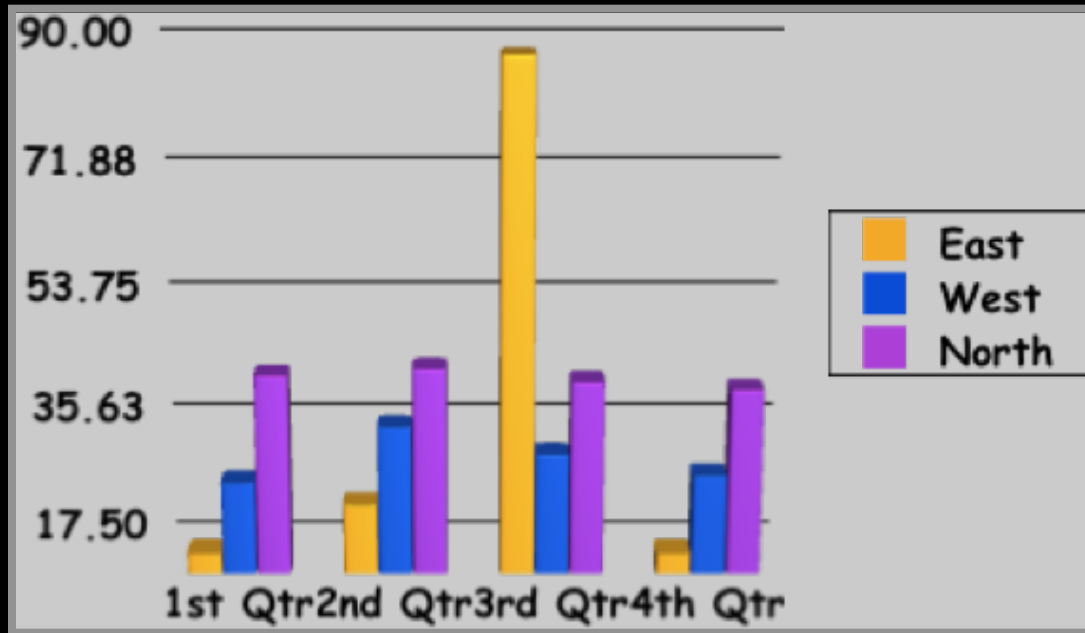
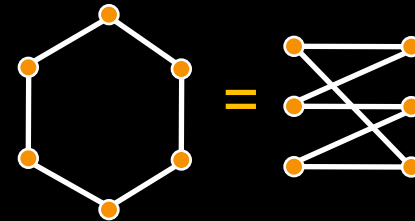
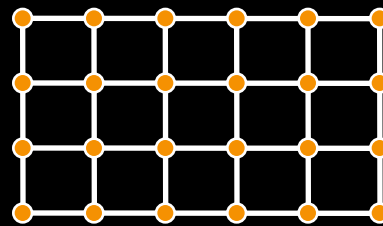
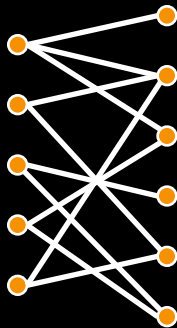
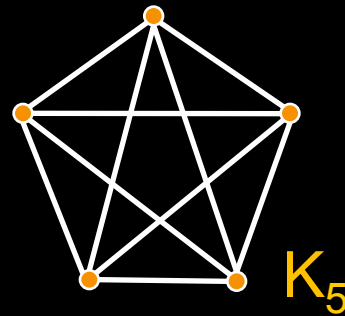
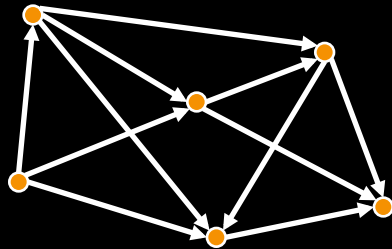


These are not Graphs



...not the kind we mean, anyway

These are Graphs



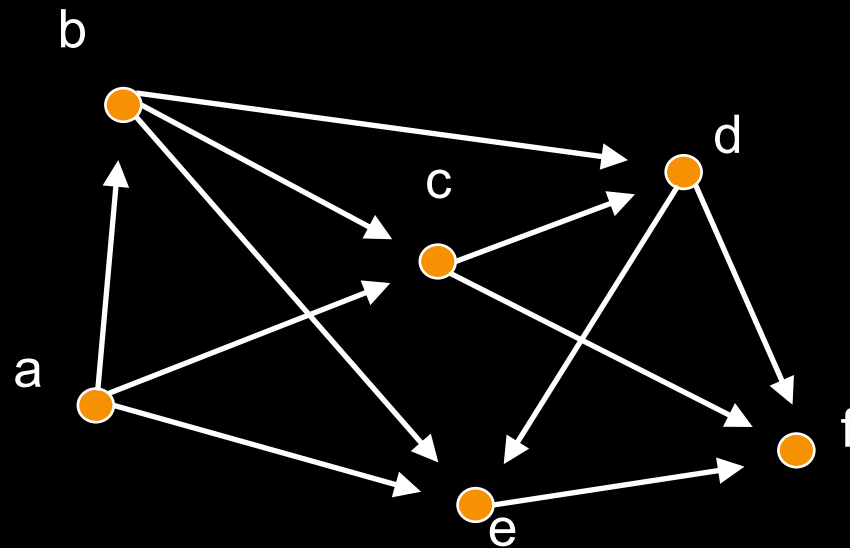
Applications of Graphs

- Communication networks; social networks
- Routing and shortest path problems
- Commodity distribution (network flow)
- Traffic control
- Resource allocation
- Numerical linear algebra (sparse matrices)
- Geometric modeling (meshes, topology, ...)
- Image processing (e.g., graph cuts)
- Computer animation (e.g., motion graphs)
- Systems biology
- ...

Graph Definitions

- A **directed graph** (or **digraph**) is a pair (V, E) where
 - V is a set
 - E is a set of ordered pairs (u, v) where $u, v \in V$
 - Usually require $u \neq v$ (i.e., no self-loops)
- An element of V is called a **vertex** or **node**
- An element of E is called an **edge** or **arc**
- $|V|$ = size of V , often denoted **n**
- $|E|$ = size of E , often denoted **m**

Example Directed Graph (Digraph)



$V = \{a,b,c,d,e,f\}$

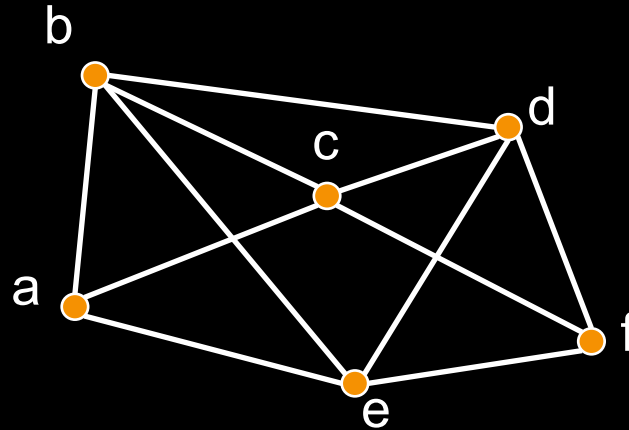
$E = \{(a,b), (a,c), (a,e), (b,c), (b,d), (b,e), (c,d), (c,f), (d,e), (d,f), (e,f)\}$

$|V| = 6, |E| = 11$

Example Undirected Graph

An *undirected graph* is just like a directed graph, except the edges are *unordered pairs (sets)* $\{u,v\}$

Example:

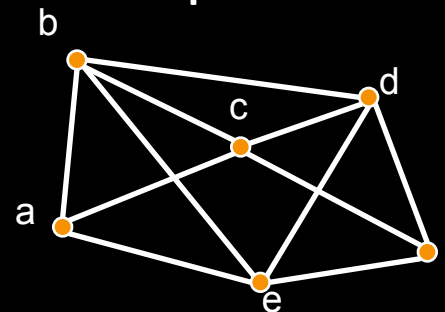
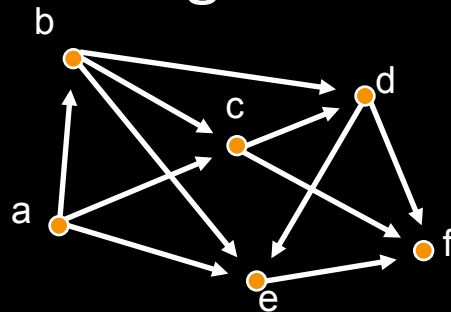


$$V = \{a,b,c,d,e,f\}$$

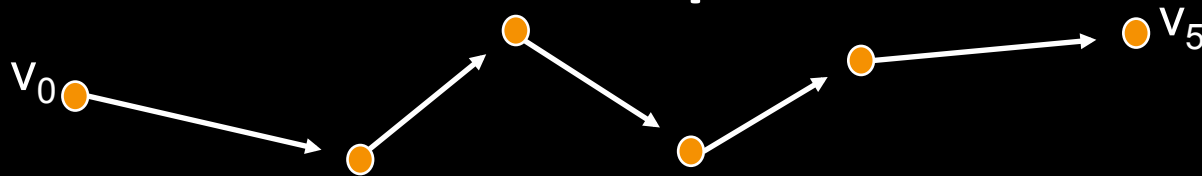
$$E = \{\{a,b\}, \{a,c\}, \{a,e\}, \{b,c\}, \{b,d\}, \{b,e\}, \{c,d\}, \{c,f\}, \{d,e\}, \{d,f\}, \{e,f\}\}$$

Some Graph Terminology

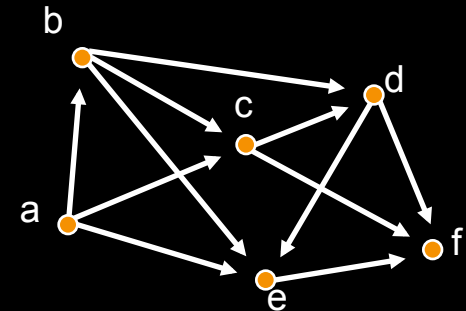
- Vertices u and v are called the **source** and **sink** of the directed edge (u,v) , respectively
- Vertices u and v are called the **endpoints** of (u,v)
- Two vertices are **adjacent** if they are connected by an edge
- The **outdegree** of a vertex u in a directed graph is the number of edges for which u is the source
- The **indegree** of a vertex v in a directed graph is the number of edges for which v is the sink
- The **degree** of a vertex u in an undirected graph is the number of edges of which u is an endpoint



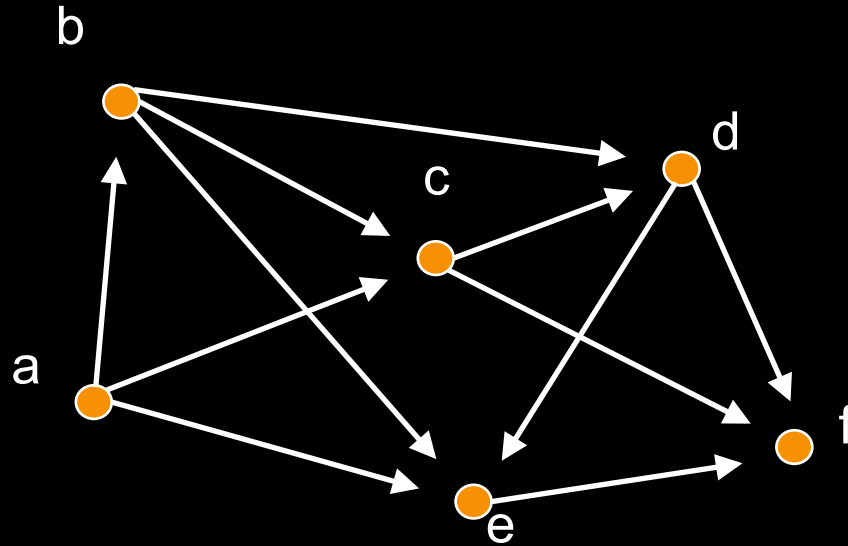
More Graph Terminology



- A **path** is a sequence $v_0, v_1, v_2, \dots, v_p$ of vertices such that $(v_i, v_{i+1}) \in E, 0 \leq i \leq p-1$
- The **length of a path** is its number of edges
 - In this example, the length is 5
- A path is **simple** if it does not repeat any vertices
- A **cycle** is a path $v_0, v_1, v_2, \dots, v_p$ such that $v_0 = v_p$
- A cycle is **simple** if it does not repeat any vertices except the first and last
- A graph is **acyclic** if it has no cycles
- A directed acyclic graph is called a **dag**



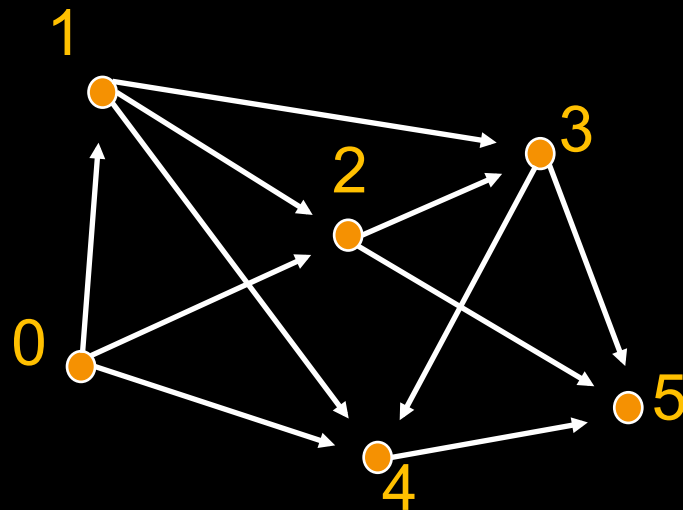
Is This a Dag?



- Intuition:
 - If it's a dag, there must be a vertex with indegree zero
- This idea leads to an algorithm
 - A digraph is a dag if and only if we can iteratively delete indegree-0 vertices until the graph disappears

Topological Sort

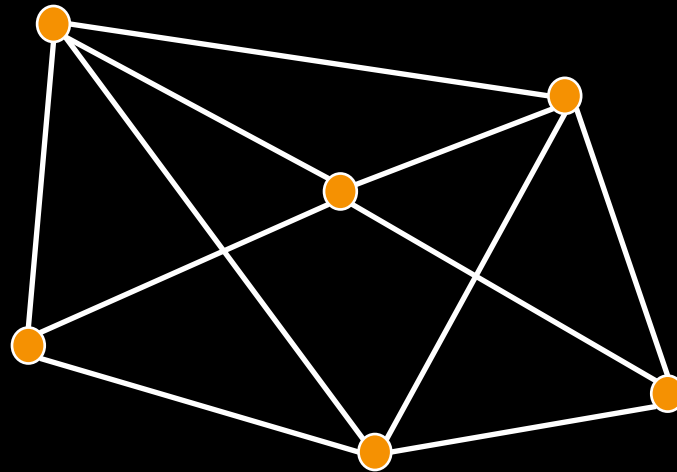
- We just computed a **topological sort** of the dag
 - This is a numbering of the vertices such that all edges go from lower- to higher-numbered vertices



- Useful in job scheduling with precedence constraints

Graph Coloring

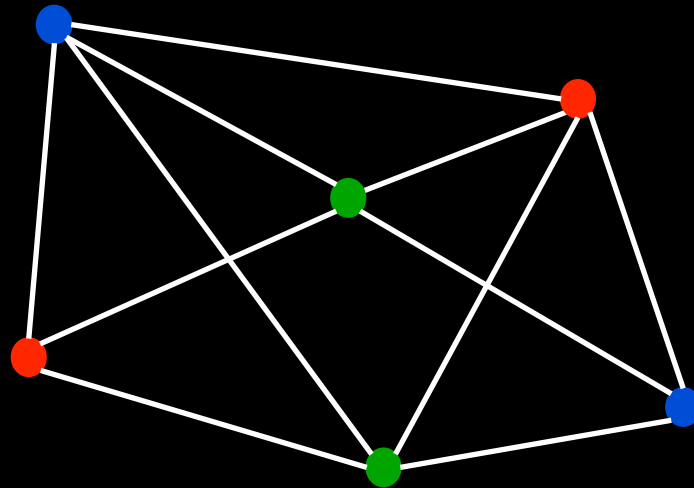
- A **coloring** of an undirected graph is an assignment of a color to each node such that no two adjacent vertices get the same color



- How many colors are needed to color this graph?

Graph Coloring

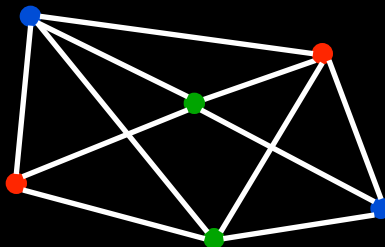
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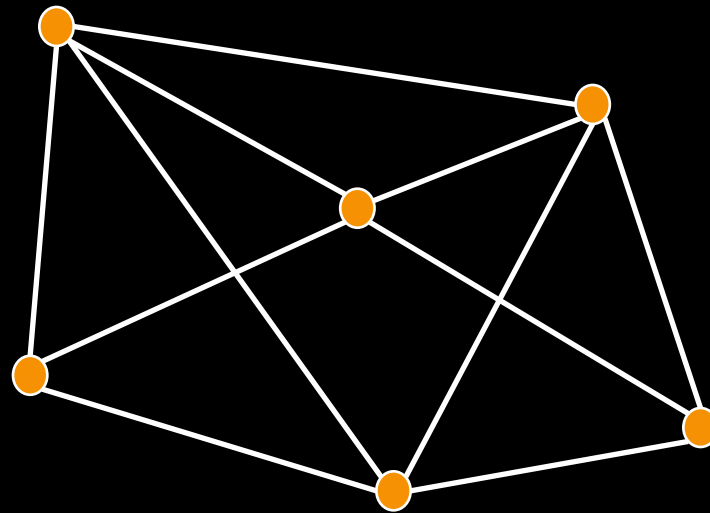
An Application of Coloring

- Vertices are jobs
- Edge (u,v) is present if jobs u and v each require access to the same shared resource, and thus cannot execute simultaneously
- Colors are time slots to schedule the jobs
- Minimum number of colors needed to color the graph = minimum number of time slots required



Planarity

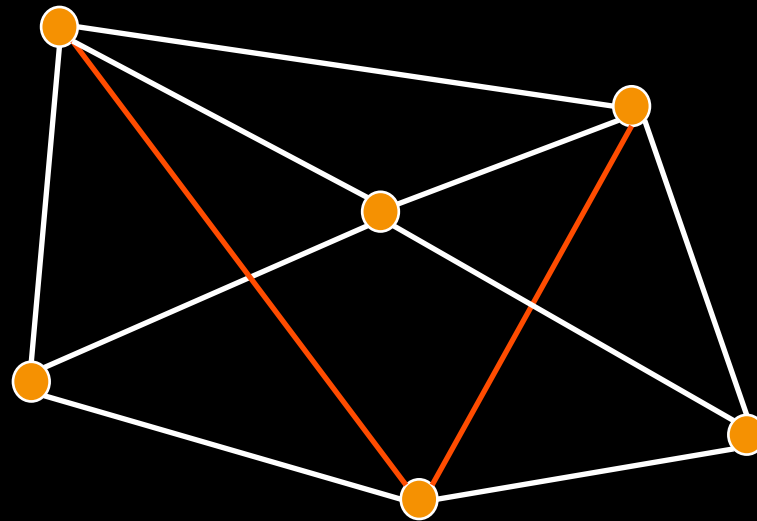
- A graph is **planar** if it can be embedded in the plane with no edges crossing



- Is this graph planar?

Planarity

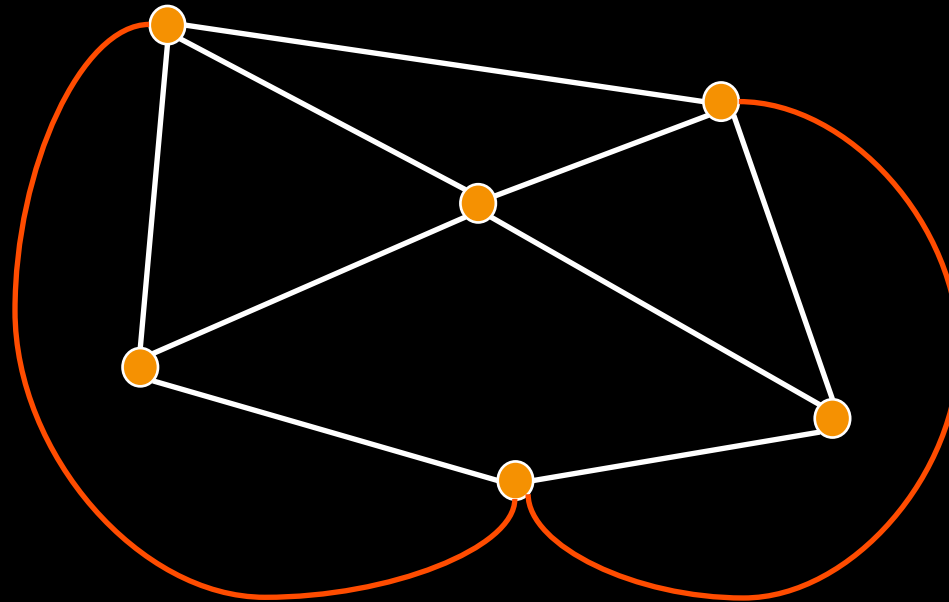
- A graph is **planar** if it can be embedded in the plane with no edges crossing



- Is this graph planar?
 - Yes

Planarity

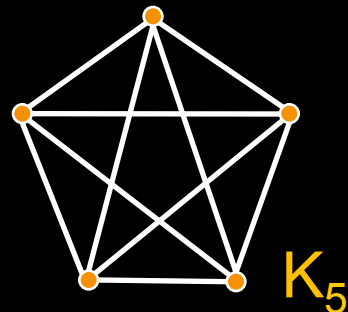
- A graph is **planar** if it can be embedded in the plane with no edges crossing



- Is this graph planar?
 - Yes

Detecting Planarity

- Kuratowski's Theorem

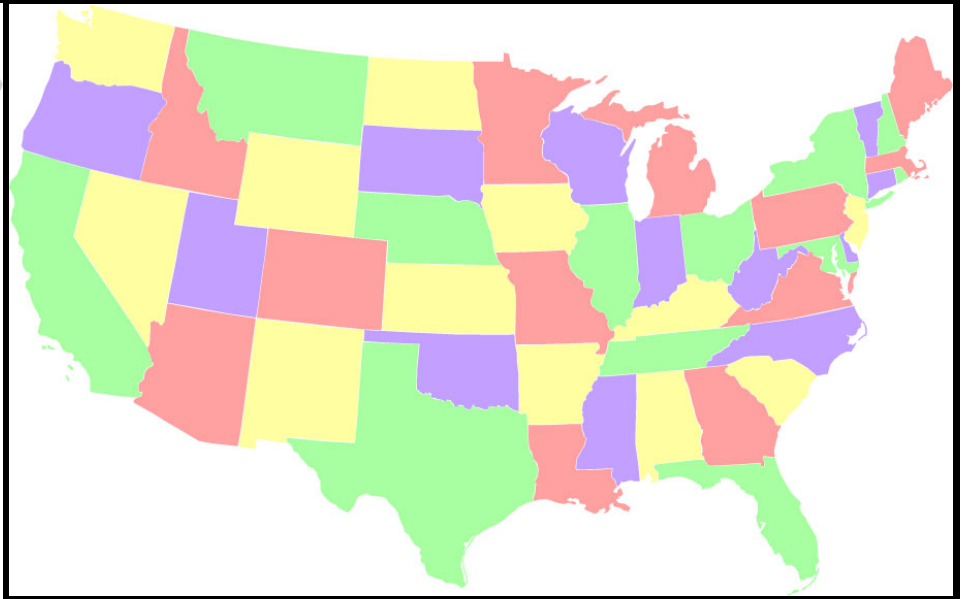
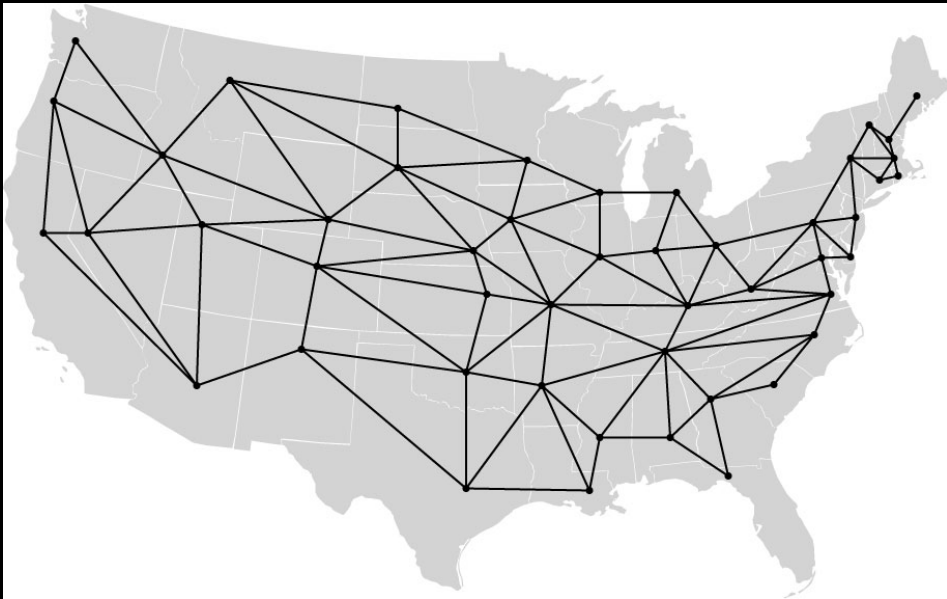


- A graph is planar if and only if it does not contain a copy of K_5 or $K_{3,3}$ (possibly with other nodes along the edges shown)

Four-Color Theorem:
Every planar graph
is 4-colorable.
(Appel & Haken, 1976)



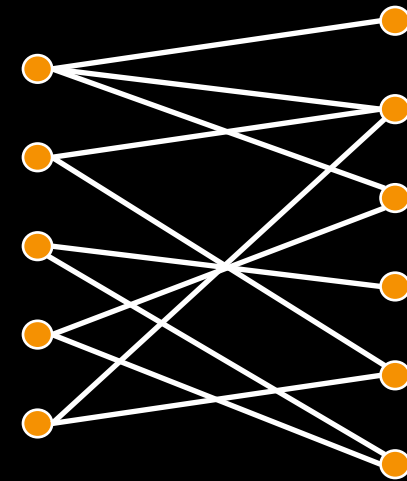
Another 4-colored planar graph



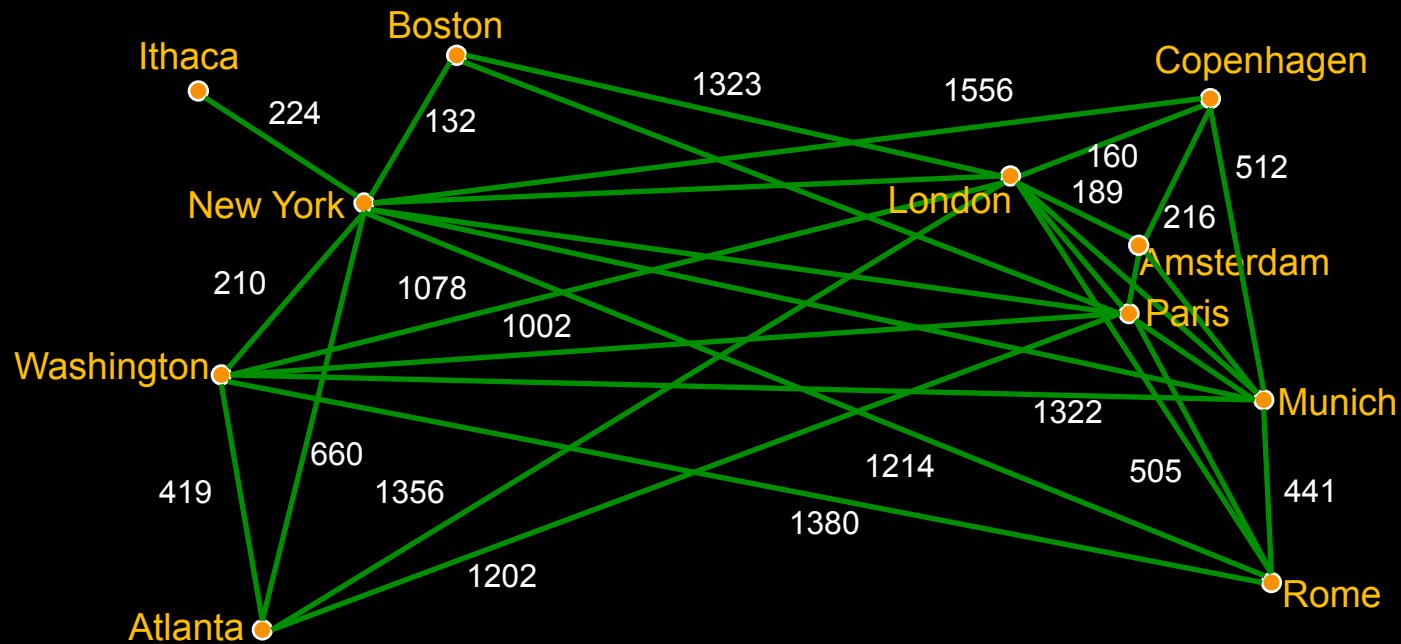
<http://www.cs.cmu.edu/~bryant/boolean/maps.html>

Bipartite Graphs

- A directed or undirected graph is **bipartite** if the vertices can be partitioned into two sets such that all edges go between the two sets
- The following are equivalent
 - G is bipartite
 - G is 2-colorable
 - G has no cycles of odd length

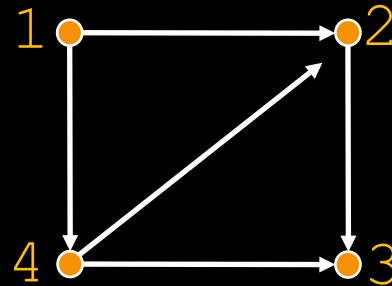


Traveling Salesperson

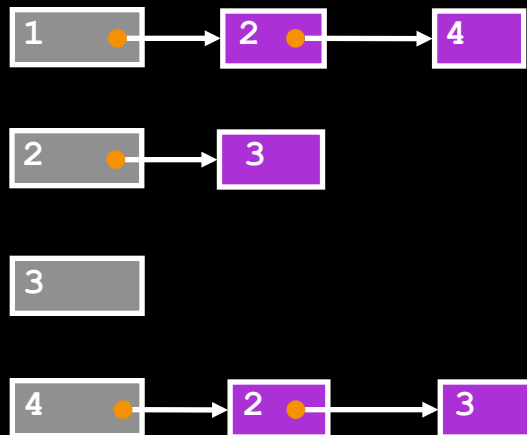


- Find a path of minimum distance that visits every city

Representations of Graphs



Adjacency List



Adjacency Matrix

	1	2	3	4
1	0	1	0	1
2	0	0	1	0
3	0	0	0	0
4	0	1	1	0

Adjacency Matrix or Adjacency List?

- Definitions
 - n = number of vertices
 - m = number of edges
 - $d(u)$ = degree of u = number of edges leaving u
- Adjacency Matrix
 - Uses space $O(n^2)$
 - Can iterate over all edges in time $O(n^2)$
 - Can answer “Is there an edge from u to v ?” in $O(1)$ time
 - Better for dense graphs (lots of edges)
- Adjacency List
 - Uses space $O(m+n)$
 - Can iterate over all edges in time $O(m+n)$
 - Can answer “Is there an edge from u to v ?” in $O(d(u))$ time
 - Better for sparse graphs (fewer edges)

Graph Algorithms

- Search
 - depth-first search
 - breadth-first search
- Shortest paths
 - Dijkstra's algorithm
- Minimum spanning trees
 - Prim's algorithm
 - Kruskal's algorithm