



What is CUUAV:

Cornell University UAV team is a group of undergraduate engineering students who work together to design, construct, test and eventually fly an autonomous fixed wing aircraft in *AUVSI's International Student Unmanned Aerial Vehicle Competition*. The competition was first held in the summer of 2002 at Webster field in Maryland and Cornell came home with first place. The plane must complete a series of tasks including way point navigation via autonomous flight, target identification, and much more. This year will mark the third year of a quickly growing competition that we are very excited to be a part of.



Prototype platform:

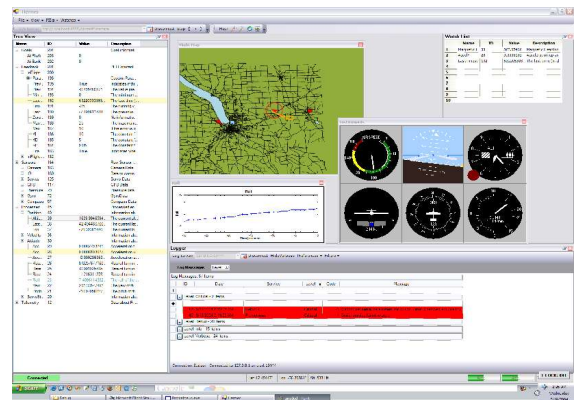
- * Sig Rascal 6200 airframe, 100" wingspan and 30cc gas engine.
- * PC-104 form factor 800Mhz crusec processor runs on-board autopilot
- * RS-232 interface to flight sensors such as Gyro, GPS, Pressure.
- * CCD Camera and 430mhz HAM-TV video telemetry subsystem
- * Uplink/Downlink via 918Mhz serial telemetry and custom packets.

Innovative software:

- * Embedded XP runs Custom autopilot developed in VS.NET(TM)
- * Interface with MS Flight Simulator for low risk, low cost testing.
- * Customizable GCS.
- * Flight tracking and way point setting using PocketPC(TM)

2004-2005 Objectives:

- * Move to a delta wing configuration.
- * Vision Processing
- * Assisted takeoff/Parachute Landing



Last year's sponsors:



For more information, visit our website at
WWW.CUUAV.ORG

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