Dan Huttenlocher

University activities

- Ph.D. students Graduated
 - Xiangyang Lan, PhD, August 2007.
- Acting Director, Information Science, 2007-2008
- Chair, Information Science Recruiting Committee, 2007-2008
- Member, CIS Building Committee, 2006-present
- Member, CS Computing Facilities Committee, 2006-present

Professional Activities

- Area Chair, European Conference on Computer Vision (ECCV), 2008.
- Scientific advisory committee, MacArthur Foundation, 2007-present.
- ACM-AAAI Newell Award Committee, 2007-2010.
- Editorial Board Member, International Journal of Computer Vision (IJCV), 2006-present.

Publications

- Learning for Stereo Vision Using the Structured Support Vector Machine, Proceedings of the IEEE Computer Vision and Pattern Recognition Conference, 2008 (with Y. Li).
- Team Cornell's Skynet: Robust Perception and Planning in an Urban Environment, Journal of Field Robotics (with I. Miller, M. Campbell, A. Nathan, F. Kline, P. Moran, N. Zych, B. Schimpf, S. Lupashin, E. Garcia, J. Catlin and M. Kurdziel).

Lectures

- Team Cornell and the DARPA Urban Challenge:
 - o EPFL, Lausanne Switzerland, May 2008
 - o Army Research Labs, January 2008
 - o Google, January 2008
 - o TTI-Chicago, January 2008
- Vision in the 3D World, Intl. Workshop on Computer Vision, Venice, May 2008

Awards, honors, and grants

- Fellow of the ACM, 2007
- Finalist DARPA Urban Challenge, Team Cornell (team co-leader), 2007
- Phi Beta Kappa Visiting Scholar, 2007-08
- NSF 0705774 III-CXT: Computer Science Research Using the Cornell Web Lab to Study Social and Informational Processes on the Web, 2007-2009, \$900,000 (co-investigators William Arms and Jon Kleinberg).
- NSF IIS 0713185 RI: A Context-Based Approach to the Recognition and Localization of Visual Object Categories, 2007-2010, \$450,000.
- Kodak/NYSTAR-CEIS, Object Category Recognition, 2007-08, \$110,000.
- DARPA through ONR contract HR0011-06-C-0147 Urban Challenge: Team Cornell, 2006-2007, \$1,000,000 (co-investigators Mark Campbell and Ephrahim Garcia).