

Abstract

Accurately estimating the distribution of solutions to a problem, should such solutions exist, provides efficient search heuristics. We propose new ways of computing such estimates, with different degrees of accuracy and complexity. We build on the Expectation-Maximization Belief-Propagation (EMBP) framework proposed by Hsu et al. to solve Constraint Satisfaction Problems (CSPs). We propose two general approaches within the EMBP framework: we firstly derive update rules at the constraint level while enforcing domain consistency and then derive update rules globally, at the problem level. The contribution is two-fold: first, we derive new generic update rules suited to tackle any CSP; second, we propose an efficient EMBP-inspired approach, thereby improving this method and making it competitive with the state of the art.

Running Example & Motivation

4				2
			2	
	2	x_{13}		
2	1	3	4	5
	4	2	5	

Figure: A choice point in a QWH instance

Then, if we were enumerating all the solutions, we could deduce:

$$\blacktriangleright P(x_{13}) = \begin{cases} P(x_{13} = 1) = 2/5 \\ P(x_{13} = 4) = 2/5 \\ P(x_{13} = 5) = 1/5 \end{cases}$$

Instead, we try to approximate this probability distribution:

$$\blacktriangleright \theta_{x_{13}} = \begin{cases} \theta_{x_{13}}(1) = 0.391 \\ \theta_{x_{13}}(4) = 0.472 \\ \theta_{x_{13}}(5) = 0.137 \end{cases}$$

The EMBP Framework

Definitions. The EMBP framework introduces the following definitions:

- Θ Probability distribution of the variables
- y Binary-vector random variable indicating whether the constraints are satisfied
- z Satisfying configurations of the constraints

Essentially, EMBP aims at maximizing the loglikelihood of $P(y, z | \Theta)$.

Intuition. We observe a solution of the CSP (y) but we do not really know how the constraints are satisfied (z). Thus, we are asking EMBP to figure out how the variables are set (Θ).

Additional definition. Let $Q(z)$ be the distribution function $P(z | y, \Theta)$, representing each solution probability given the biases Θ and given the observation y that the constraints are satisfied.

EMBP (Hsu et al.) iteratively adjusts Θ in a two-step process:

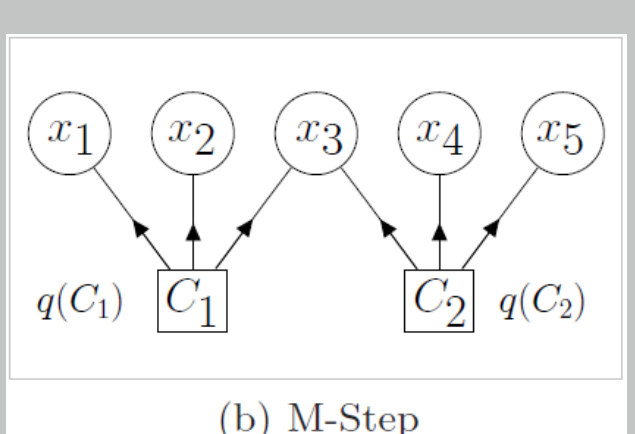
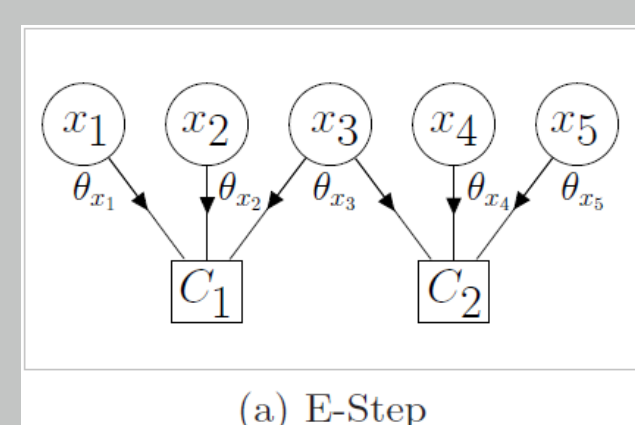


Figure: EMBP Steps

In the E-Step, we compute the probability of the satisfying configurations given the variable distribution:

$$Q(z) = \prod_{i=1}^m (q(C_i)),$$

where $q(C_i)$ is the probability of a given configuration for C_i .

In the M-Step, the variables adjust their distribution taking into account the probability of the valid tuples of the constraints:

$$\theta_{x_i}(v) = \frac{1}{\eta} \sum_{C_k \in \mathcal{C}: x_i \in X(C_k)} \left(\sum_{z \in S_{z: x_i=v}} Q(z) \right)$$

Computing EMBP. Within the EMBP framework, the definition of $Q(z)$ remains however unspecified. Computing $Q(z)$ exactly implies expressing every single solution of the problem, which is clearly intractable. Hence, we approximate $Q(z)$ and the following methods gradually improve the accuracy of the estimation of $Q(z)$.

EMBP for the alldifferent constraint

Within the *alldifferent* constraint, the probability that variable x_i is assigned the value v can be approximated by the probability that no other variable in the constraint takes the value v .

4	3,5	1,5	1,3	2
1,3,5	3,5	1,4,5	2	1,3,4
1,3,5	2	1	1,3	1,3,4
2	1	3	4	5
1,3	4	2	5	1,3

Figure: EMBPa on the running example

$$\theta_{x_i}(v) = \frac{1}{\eta} \sum_{C_k \in \mathcal{C}: x_i \in X(C_k)} \left(\prod_{x_j \in X(C_k) \setminus x_i} (1 - \theta_{x_j}(v)) \right)$$

where η is a normalizing constant.

(Hsu et al., 2007)

EMBP-Lsup - First Contribution

We propose to derive local X-consistency EMBP methods, which are a fairly natural extension to EMBPa, to improve the accuracy of EMBPa and extend this approach to any constraint.

We consider all assignments $y = b$ that are X-consistent with the assignment $x = a$ within a constraint to compute $\theta_x(a)$ for a given constraint.

4	3,5	1,5	1,3	2
1,3,5	3,5	1,4,5	2	1,3,4
1,3,5	2	1	1,3	1,3,4
2	1	3	4	5
1,3	4	2	5	1,3

Figure: EMBP-Lsup on the running example

$$\theta_{x_i}(v) = \frac{1}{\eta} \sum_{C_k \in \mathcal{C}: x_i \in X(C_k)} \left(\prod_{x_j \in X(C_k) \setminus x_i} \sum_{v' \in \tilde{D}_{x_j=v}(x_j)} \theta_{x_j}(v') \right)$$

where $\tilde{D}_{x_i=v}(x_j)$ represents the reduced domain of the variable x_j after assigning $x_i = v$ and enforcing X-consistency on C_i .

EMBP-Gsup - Second Contribution

We suggest to go one step further in terms of accuracy for the computation of $Q(z)$. With EMBP-Gsup, the problem is considered as a whole and the method directly exploits the dependence between constraints when computing $Q(z)$. EMBP-Gsup improves the quality of the approximation taking into account supports that are X consistent after propagating every constraint of the problem.

4	3,5	1,5	1,3	2
1,3,5	3,5	1,4,5	2	1,3,4
1,3,5	2	1	1,3	1,3,4
2	1	3	4	5
1,3	4	2	5	1,3

Figure: EMBP-Gsup on the running example

$$\theta_{x_i}(v) = \frac{1}{\eta} \prod_{x_j \in \mathcal{X} \setminus x_i} \sum_{v' \in \hat{D}_{x_i=v}(x_j)} \theta_{x_j}(v')$$

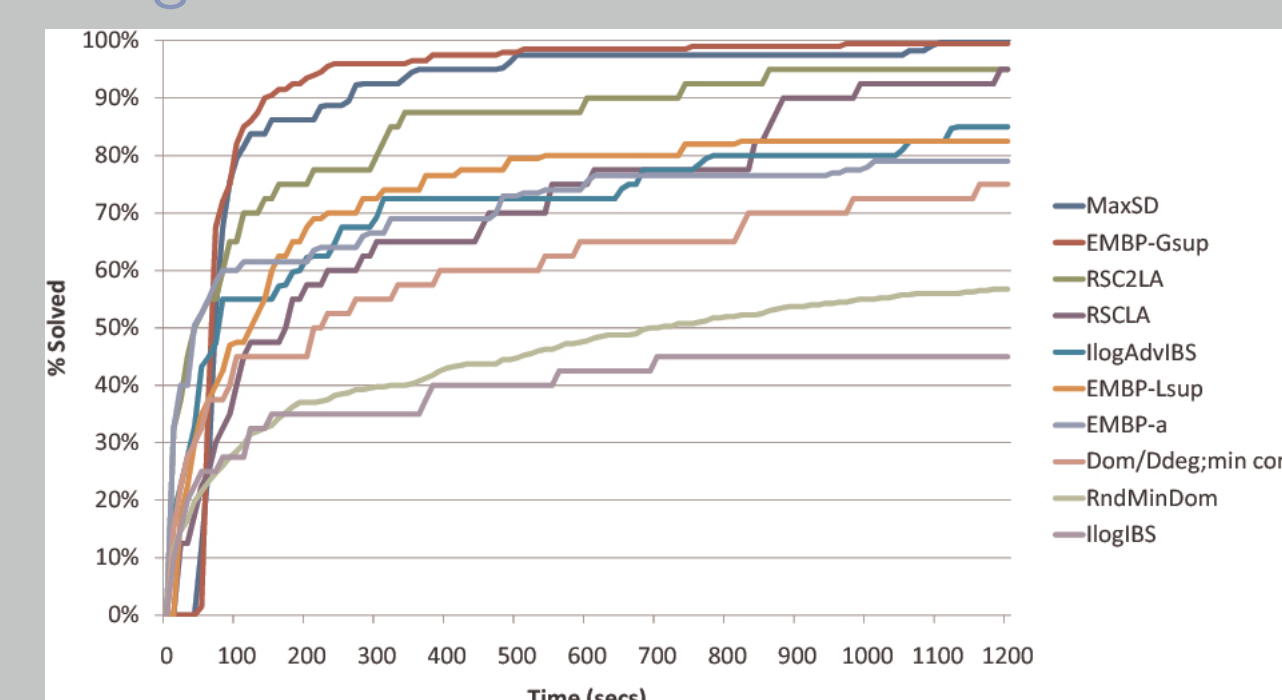
where $\hat{D}_{x_i=v}(x_j)$ represents the reduced domain of the variable x_j after assigning $x_i = v$ and enforcing X-consistency on the CSP.

Experiment Results on 40 hard QWH instances of order 30

Table: Time, bkts and % of solved inst.

heuristics	total time	avg btk	solved
rndMinDom	26328.2	1300056	56.8%
MaxSD	4939.1	3503	100.0%
llogIBS	29017.0	1001570	45.0%
llogAdvIBS	13795.8	914849	85.0%
RSC-LA	14019.9	856	95.0%
RSC2-LA	7178.7	4880	95.0%
EMBP _a	13932.2	82158	79.0%
EMBP-Lsup	12814.2	6642	82.5%
EMBP-Gsup	3946.9	55	99.5%

Figure: % of solved instances vs time

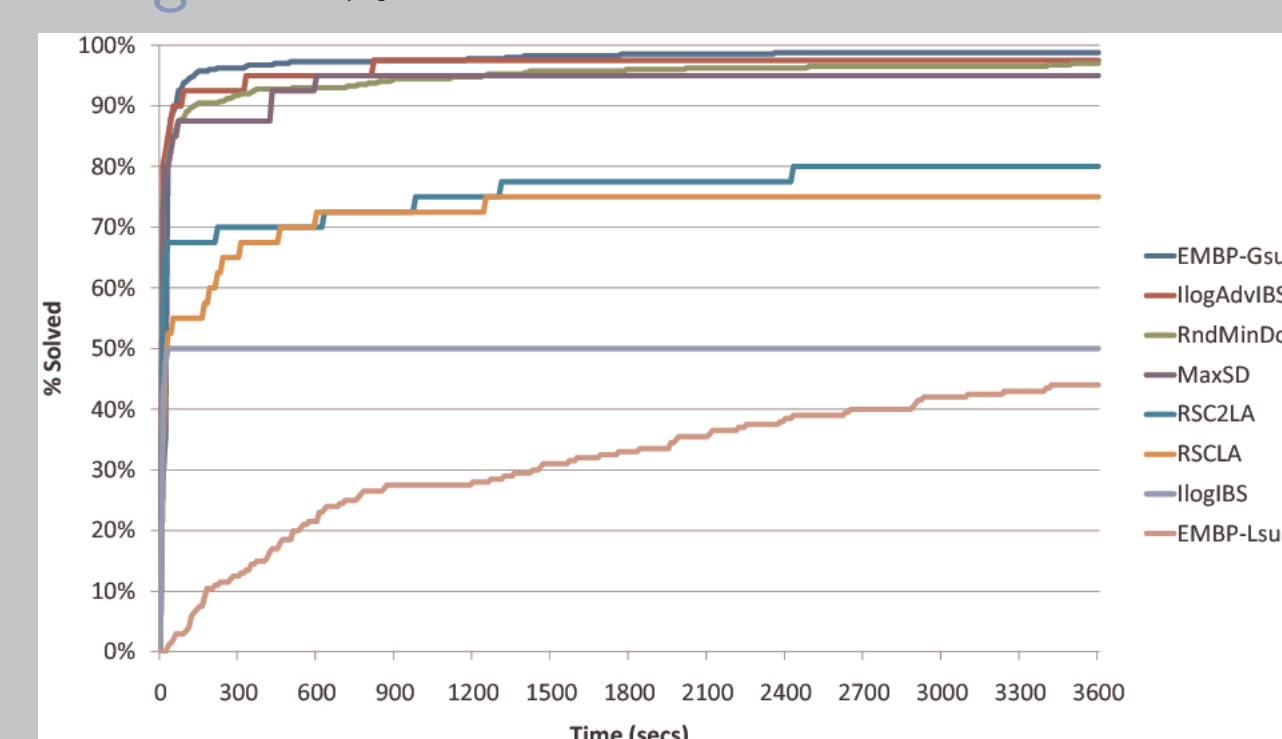


Experiment Results on 40 Magic Square instances

Table: Time, bkts and % of solved inst.

heuristics	total time	avg btk	solved
rndMinDom	7397.0	4018251	97.0%
MaxSD	8895.7	242290	95.0%
llogIBS	72078.2	22396381	50.0%
llogAdvIBS	5067.9	2224191	97.5%
RSC-LA	39612.4	48759	75.0%
RSC2-LA	34524.3	1180456	80.0%
EMBP-Lsup	98910.7	20572	43.0%
EMBP-Gsup	3758.2	895	98.8%

Figure: % of solved instances vs time



Summary

- \blacktriangleright We propose new efficient extensions to the EMBP framework that present better accuracy, due to the propagation at the constraint level (EMBP-Lsup) and at the problem level (EMBP-Gsup).
- \blacktriangleright The methods are generic and can be applied to any constraint (EMBP-Lsup) or any CSP (EMBP-Gsup).
- \blacktriangleright EMBP-Gsup tends to be consistent on the problems we experimented and is really competitive with existing approaches.

Future Work

- \blacktriangleright What is the most efficient way to use biases information?
- \blacktriangleright How can we make EMBP-Gsup faster?
- \blacktriangleright Could we exploit Expectation-Maximization Survey Propagation to derive similar EMSP-based update rules?