

MATERIALS DISCOVERY FOR FUEL CELLS

NEW OPPORTUNITIES AT THE INTERSECTION OF CONSTRAINT REASONING AND LEARNING



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Cornell Fuel Cell Institute

Mission: develop **new materials** for **fuel cells**.

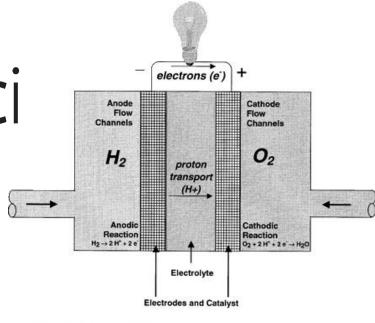


Figure 1. Fuel cell schematic.

Source: Annual Reveiws of Energy and the Environment. http://energy.annualreviews.org/cgi/content/full/24/1/281

An **Electrocatalyst** must:

- Be electronically conducting
- 2) Facilitate both reactions

Platinum is the best known metal to fulfill that role, but:

- The reaction rate is still considered slow (causing energy loss)
- Platinum is fairly costly, intolerant to fuel contaminants, and has a short lifetime.

Goal: Find an intermetallic compound that is a better catalyst than Pt.

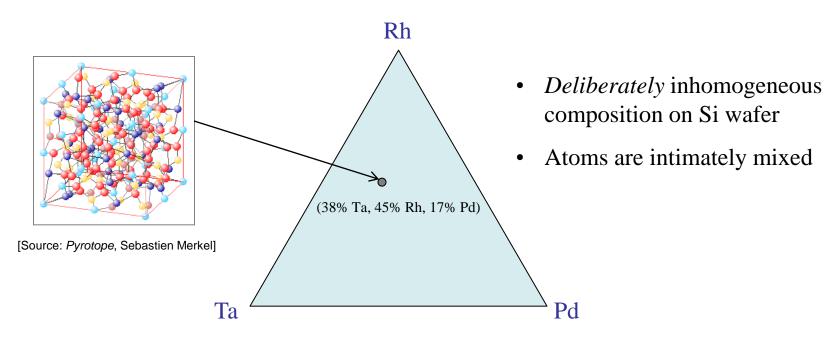






Recipe for finding alternatives to Platinum

- 1) In a vacuum chamber, place a silicon wafer.
- 2) Add three metals.
- 3) Mix until smooth, using three sputter guns.
- 4) Bake for 2 hours at 650°C



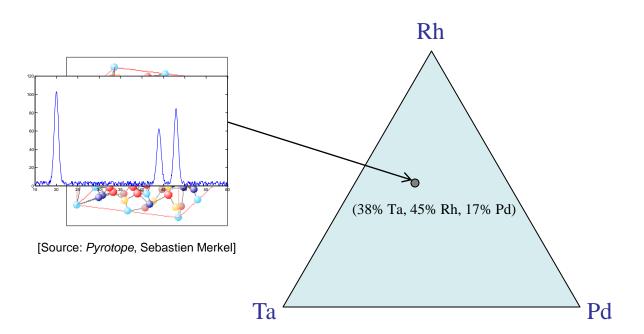


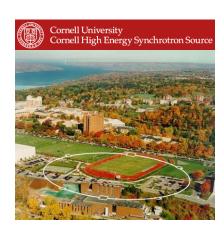




Identifying crystal structure using **X-Ray Diffraction** at CHESS

- XRD pattern characterizes the underlying crystal fairly well
- **Expensive** experimentations: Bruce van Dover's research team has access to the facility **one week every year**.

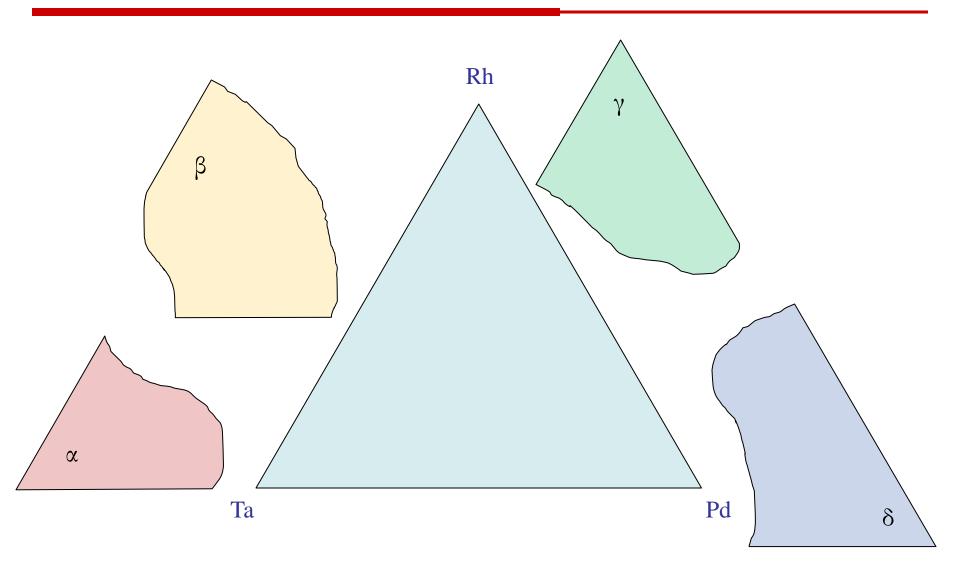








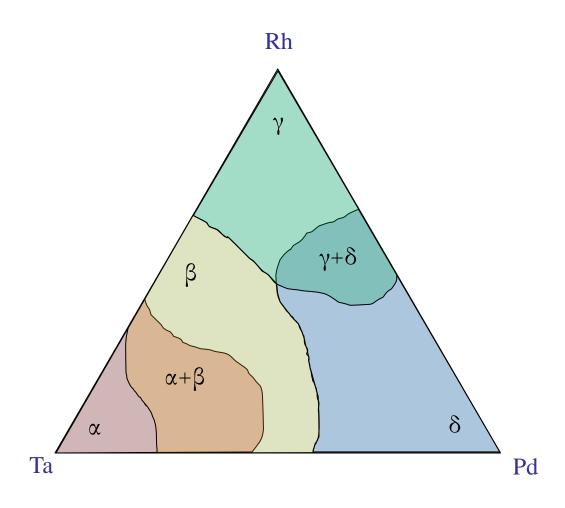








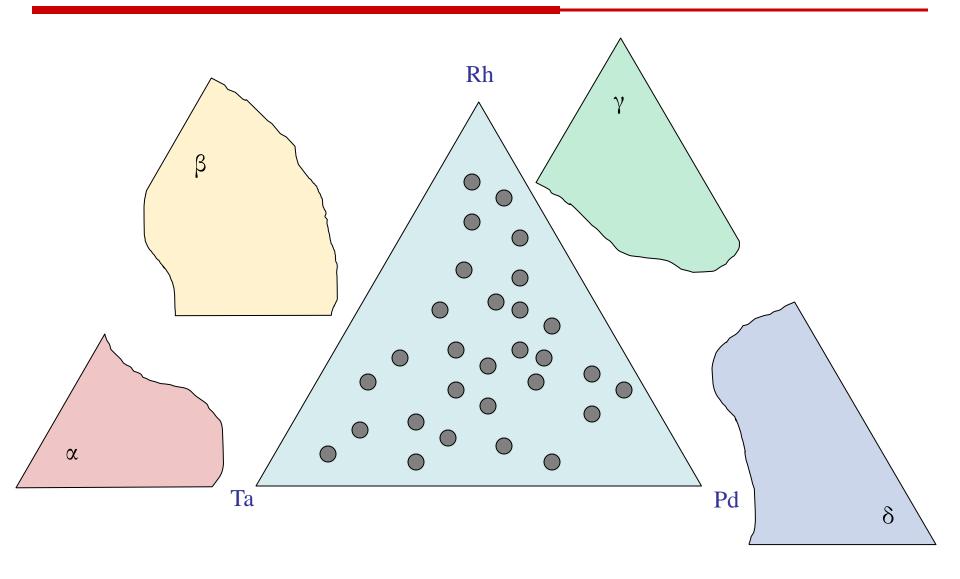








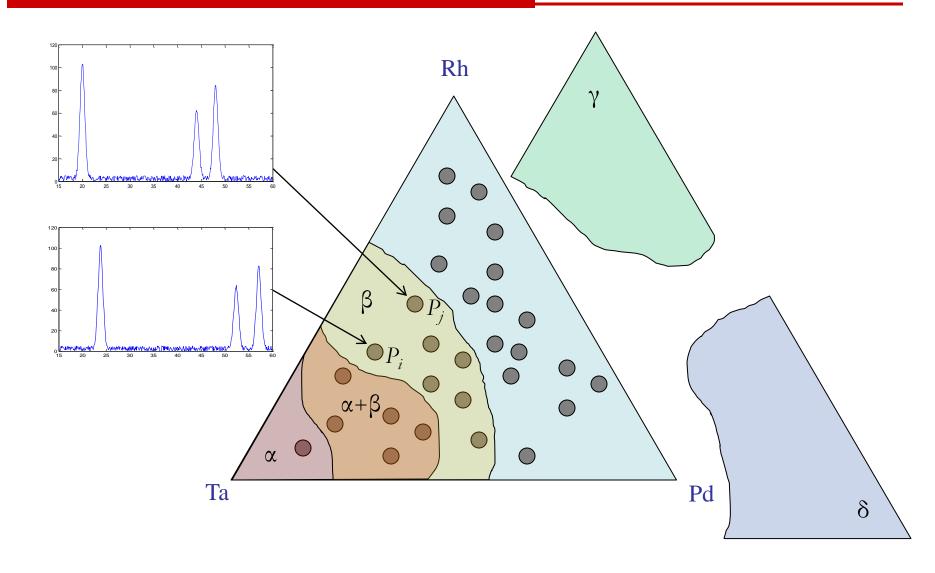








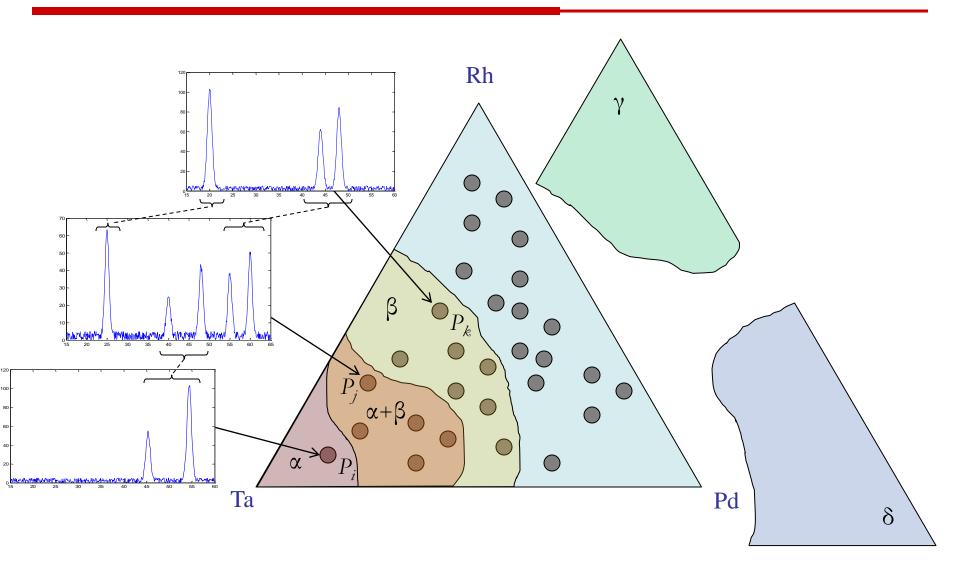








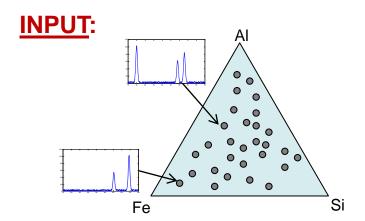


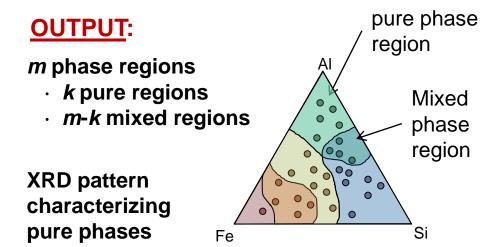












Additional Physical characteristics:

- Phase Connectivity
- Mixtures of ≤ 3 pure phases
- Peaks shift by ≤ 15% within a region
 - Continuous and Monotonic
- Noisy detection







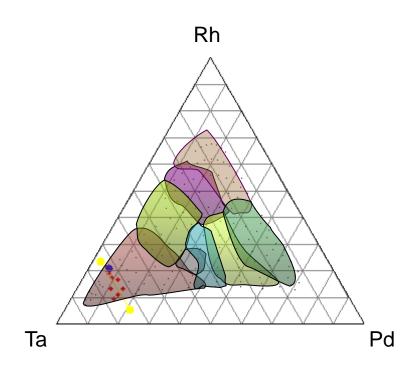


Figure 1: Phase regions of Ta-Rh-Pd

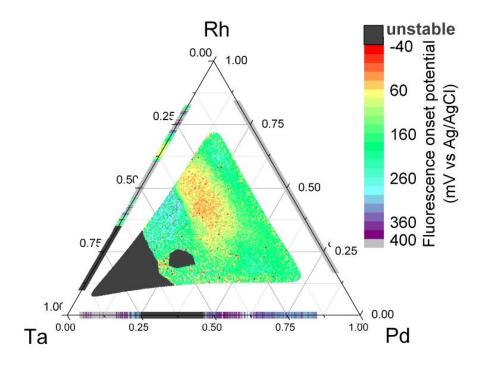


Figure 2: Fluorescence activity of Ta-Rh-Pd



Outline





- Motivation
- Problem Definition (Part I)
- Previous Work: Non-negative Matrix Factorization
- Problem Definition (Part II)
- Our Work: Satisfiability Modulo Theories Approach
- Conclusion and Future work



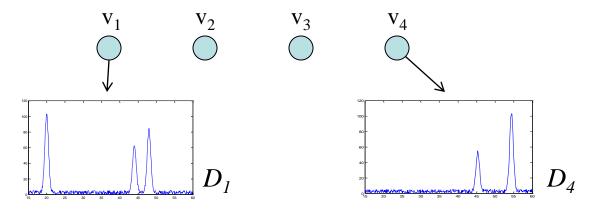
Problem Definition (Part I)



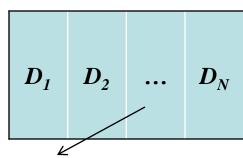


• Input:

• A list of points on the silicon wafer



- A real vector D_i per vertex v_i (diffraction patterns)
- K = user specified number of pure phases
- Goal: a basis of K vectors for





$$\boldsymbol{D}_i = a_{il}\boldsymbol{B}_1 + \dots + a_{iK}\boldsymbol{B}_K$$

Problem Definition (Part I)





• There is **experimental noise**

$$\boldsymbol{D}_i = a_{il}\boldsymbol{B}_1 + \dots + a_{iK}\boldsymbol{B}_K$$



$$\min ||D_i - (a_{il}B_1 + \dots + a_{ik}B_K)||$$

• Non-negative basis vectors and coefficients

$$\boldsymbol{B_i} \ge \boldsymbol{0}$$
 , $a_{ij} \ge 0$

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Non-negative Matrix Factorization [Long et al., 2009]





Advantages: scales up very well, accurately solves simple systems

Drawbacks: overlooks critical physical behavior, making the results physically meaningless for more complex systems.

LiO₂ Illustration on synthetic instances from the *Al-Li-Fe* ternary system Al₂O₃ Synthetic Relative Phase Concentration 1.000 0.875 0.750 0.625 0.500 0.375 NMF 0.250 0.125 0.000



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Problem Definition (Part II)





• There is experimental noise

$$\boldsymbol{D}_i = a_{il}\boldsymbol{B}_1 + \dots + a_{iK}\boldsymbol{B}_K$$



$$\min \| \mathbf{D}_i - (a_{il}\mathbf{B}_1 + \dots + a_{ik}\mathbf{B}_K) \|$$

Minimize norm instead

• Non-negative basis vectors and coefficients

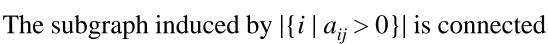
$$B_i \ge 0$$
, $a_{ij} \ge 0$

• At most M (=3) non-zero coefficients per point

$$|\{j \mid a_{ij} > 0\}| \le M$$

• Basis patterns appear in **contiguous** locations on silicon wafer

Build a graph G of the points on the silicon wafer V_1 V_2 V_3





G

 V_{Δ}

Problem Definition (Part II)





• Basis vector can be **shifted**

• Shifts coefficients are **bounded**, **continuous** and **monotonic**

$$|S_{12} - S_{11}| \le c$$

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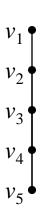






• Initial graph *G* and number *K* of basis patterns

K=2 basis patterns



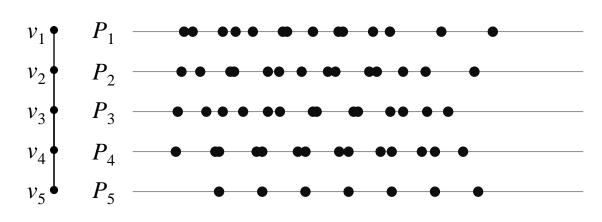






- Initial graph G and number K of basis patterns
- Peak detection to extract a set of peaks P_i for each diffraction pattern D_i

K=2 basis patterns



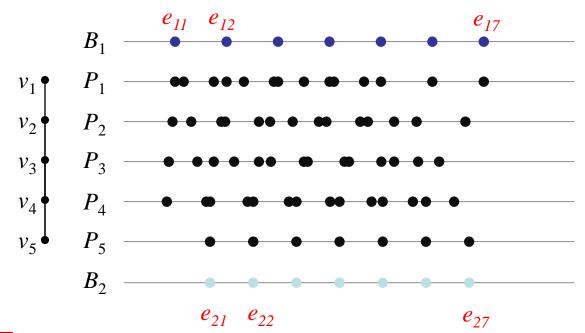






- Initial graph G and number K of basis patterns
- Peak detection to extract a set of peaks P_i for each diffraction pattern D_i
- Real variable e_{jk} for the **location of peak** k in basis B_j



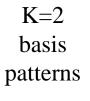


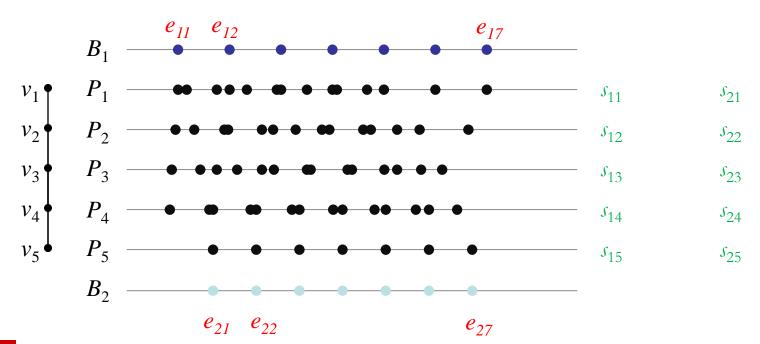






- Initial graph G and number K of basis patterns
- Peak detection to extract a set of peaks P_i for each diffraction pattern D_i
- Real variable e_{jk} for the **location of peak** k in basis B_j
- Real variable s_{ij} for the **shift** coefficient of basis B_j in point P_i



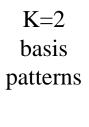


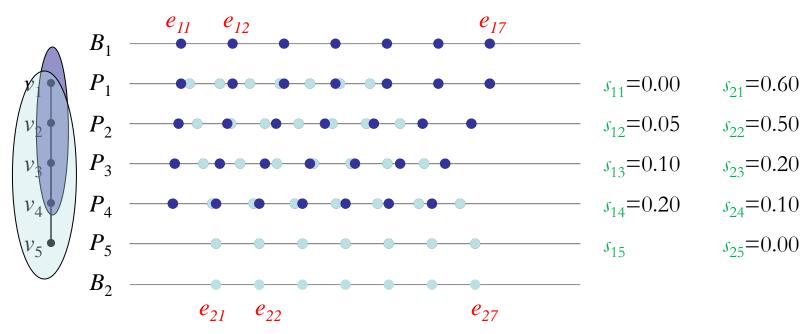






- An observed peak p is "explained" if there exists s_{ij} , e_{jk} s.t. $|p (s_{ij} + e_{jk})| \le \varepsilon$
- Every observed peak must be *explained*



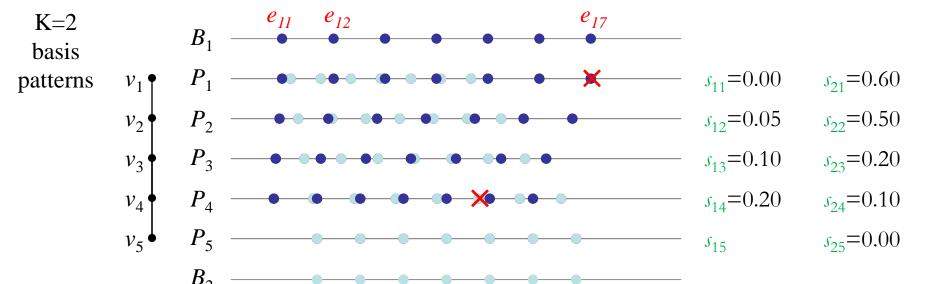








- An observed peak p is "explained" if there exists s_{ij} , e_{jk} s.t. $|p (s_{ij} + e_{jk})| \le \varepsilon$
- Every observed peak must be *explained*
- Some peaks might be missing (unobserved)
- Bound the number of missing peaks $\leq T$
- Minimization by (binary) search on T

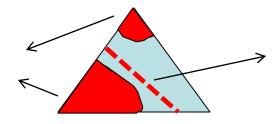






- Linear phase usage constraints (up to *M* basis patterns per point)
- Linear constraints for shift monotonicity and continuity ($s_{ij} \leq s_{lm}$)
- Lazy connectivity: add a cut if current solution is not connected

If disconnected regions explained with phase 1



Then Phase 1 must appear in at least one of these points

- Symmetry breaking:
 - Renaming of pure phases
 - Ordering of the peak locations e_{ik} (per basis pattern)



Quantifier-free linear arithmetic

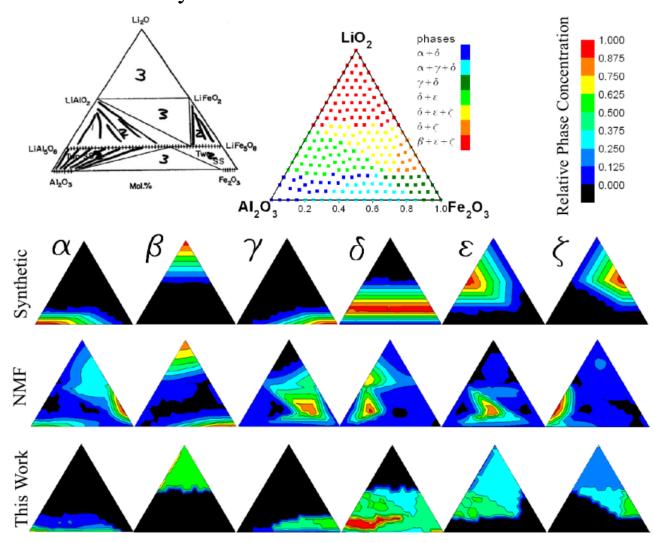


Experimental Results





•Illustration on Al-Li-Fe system





Conclusion and Future work





- Novel SMT encoding for Materials Discovery
- Good performance on synthetic data:
 - Scales to realistic sized problems (~50 points)
 - Provides physically-meaningful solutions
 - Good accuracy (>90% precision and recall)
 - Outperforms both Constraint Programming and Mixed Integer Programming direct translations of the SMT model
- Future work: online adaptive sampling during data collection
- Exciting results analyzing and explaining real-world data





THANK YOU!



Extra slides







Runtime





# Points	Unknown Phases	Arithmetic + Z3 (s)	Set-based + CPLEX (s)
10	3	8	0.5
	6	12	Timeout
15	3	13	0.5
	6	20	Timeout
18	3	29	384.8
	6	125	Timeout
29	3	78	276
	6	186	Timeout
45	6	518	Timeout

Z3 scales to realistic sized problems!

Arithmetic encoding translated to CP and MIP:

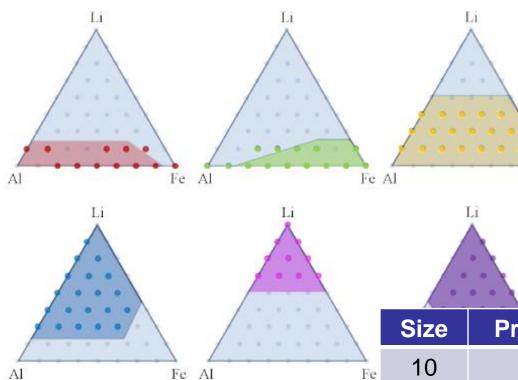
- MIP is appealing because it can optimize the objective
- They don't scale → SMT solving strategy



Precision/Recall







Recovers ground truth

Size	Precision	Recall
10	95.8	100
15	96.6	100
18	97.2	96.6
29	96.1	92.8
45	95.8	91.6

Ground SMT

Truth Results

Patterns



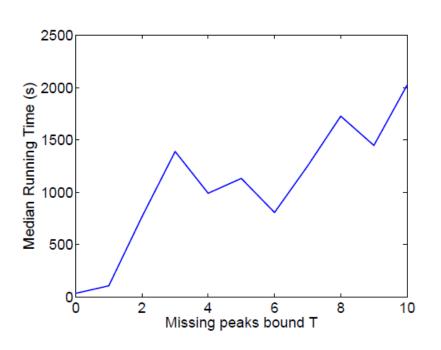
Robustness





- Remove some peaks to simulate experimental noise
- Size = 15 points

Missing Peaks	Precision	Recall
1	96.1	99.6
2	96.3	99.3
3	96.7	99.5
4	95.3	98.9
5	94.8	99.7



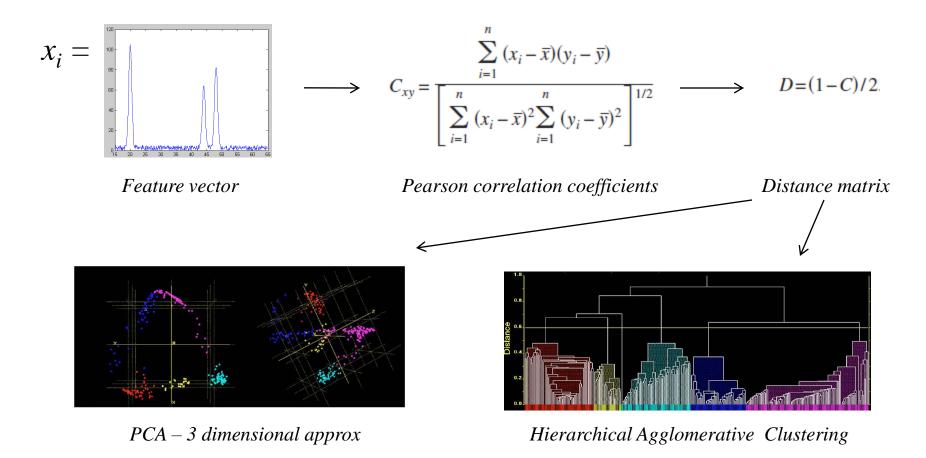
Solutions are still accurate. Runtime increases approx linearly.



Previous Work 1: Cluster Analysis [Long et al., 2007]







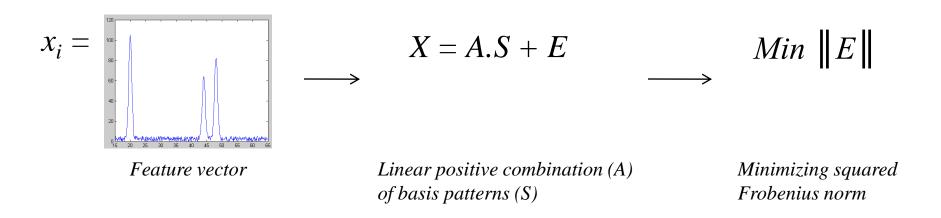
Drawback: Requires sampling of pure phases, detects phase regions (not phases), overlooks peak shifts, may violate physical constraints (phase continuity, etc.).



Previous Work 2: NMF [Long et al., 2009]







Drawback: Overlooks peak shifts (linear combination only), may violate physical constraints (phase continuity, etc.).



SMT formulation





Parameters

- Number of pure phases K, tolerance ε
- Key components
 - Variables peak positions per base
 - Shifts per point
 - Point p is explained by base k



SMT formulation





- New arithmetic-based encoding:
 - Real variables e_{ii} for the peak locations in each B_i
 - Real variables for the shift coefficients s_{ij} (per base, per point)
 - An observed peak p is explained if $|p-s_{ij}-e_{ij}| \le \varepsilon$ (Match the height of the peaks)
 - Bound the number of missing peaks ≤ *T*

