## Materials Discovery for Fuel Cells <br> New Opportunities at the Intersection of Constraint Reasoning and Learning



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Computer Science
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Materials Science/Physics

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## Motivation



## Cornell Fuel Cell Institute

Mission: develop new materials for fuel cells.


Figure 1. Fuel cell schematic.
Source: Annual Reveiws of Energy and the Environment. http://energy.annualreviews.org' cgi/content/full/24/1/281

An Electrocatalyst must:

1) Be electronically conducting
2) Facilitate both reactions

Platinum is the best known metal to fulfill that role, but:

1) The reaction rate is still considered slow (causing energy loss)
2) Platinum is fairly costly, intolerant to fuel contaminants, and has a short lifetime.

Goal: Find an intermetallic compound that is a better catalyst than Pt.

## Motivation

## Recipe for finding alternatives to Platinum

1) In a vacuum chamber, place a silicon wafer.
2) Add three metals.
3) Mix until smooth, using three sputter guns.
4) Bake for 2 hours at $650^{\circ} \mathrm{C}$


Identifying crystal structure using X-Ray Diffraction at CHESS

- XRD pattern characterizes the underlying crystal fairly well
- Expensive experimentations: Bruce van Dover's research team has access to the facility one week every year.



## Motivation



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## INPUT:



OUTPUT:
$m$ phase regions

- k pure regions
- m-k mixed regions

XRD pattern characterizing pure phases


## Additional Physical characteristics:

- Phase Connectivity
- Mixtures of $\leq 3$ pure phases
- Peaks shift by $\leq 15 \%$ within a region
- Continuous and Monotonic
- Noisy detection


## Motivation



Figure 1: Phase regions of Ta-Rh-Pd


Figure 2: Fluorescence activity of Ta-Rh-Pd

## Outline

- Motivation
- Problem Definition (Part I)
- Previous Work: Non-negative Matrix Factorization
- Problem Definition (Part II)
- Our Work: Satisfiability Modulo Theories Approach
- Conclusion and Future work


## Problem Definition (Part I)

## - Input:

- A list of points on the silicon wafer


- A real vector $\boldsymbol{D}_{\boldsymbol{i}}$ per vertex $v_{i}$ (diffraction patterns)
- $K=$ user specified number of pure phases
- Goal: a basis of K vectors for


$$
\boldsymbol{D}_{i}=a_{i l} \boldsymbol{B}_{1}+\ldots+a_{i K} \boldsymbol{B}_{K}
$$

## Problem Definition (Part I)

- There is experimental noise

$$
\boldsymbol{D}_{i}=a_{i 1} \boldsymbol{B}_{1}+\ldots+a_{i K} \boldsymbol{B}_{\boldsymbol{K}}
$$

Minimize norm instead


- Non-negative basis vectors and coefficients

$$
\boldsymbol{B}_{i} \geq \mathbf{0}, a_{i j} \geq 0
$$

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## Non-negative Matrix Factorization [Long et al., 2009]

Advantages: scales up very well, accurately solves simple systems
Drawbacks: overlooks critical physical behavior, making the results physically meaningless for more complex svstems.

Illustration on synthetic instances from the Al-Li-Fe ternary system


Relative Phase Concentration

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## Problem Definition (Part II)

Ics

## Minimize norm instead

- There is experimental noise

$$
\boldsymbol{D}_{i}=a_{i 1} \boldsymbol{B}_{1}+\ldots+a_{i K} \boldsymbol{B}_{K}
$$

$$
\stackrel{\nearrow}{\min \left\|\boldsymbol{D}_{i}-\left(a_{i 1} \boldsymbol{B}_{1}+\ldots+a_{i K} \boldsymbol{B}_{K}\right)\right\|}
$$

- Non-negative basis vectors and coefficients

$$
B_{i} \geq 0, a_{i j} \geq 0
$$

- At most $\mathbf{M}(=3)$ non-zero coefficients per point

$$
\left|\left\{j \mid a_{i j}>0\right\}\right| \leq M
$$

- Basis patterns appear in contiguous locations on silicon wafer

Build a graph $G$ of the points on the silicon wafer
The subgraph induced by $\left|\left\{i \mid a_{i j}>0\right\}\right|$ is connected


## Problem Definition (Part II)

- Basis vector can be shifted

$$
\min \left\|\boldsymbol{D}_{\boldsymbol{i}}-\left(a_{i 1} S\left(\boldsymbol{B}_{1,}, s_{i l}\right)+\ldots+a_{i K} S\left(\boldsymbol{B}_{\boldsymbol{K}}, s_{i K}\right)\right)\right\|
$$

- Shifts coefficients are bounded, continuous and monotonic

$$
\bigcirc_{-}^{S_{11} \leq S_{12} \leq S_{13} \leq S_{14}} \left\lvert\, \begin{aligned}
& S_{12}-S_{11} \mid \leq c
\end{aligned}\right.
$$

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## Satisfiability Modulo Theories Approach

- Initial graph $G$ and number $K$ of basis patterns

$$
\begin{array}{cc}
\begin{array}{c}
\mathrm{K}=2 \\
\text { basis } \\
\text { patterns }
\end{array} & v_{1} \\
& v_{2} \\
& v_{3} \\
& v_{4} \\
& v_{5}
\end{array}
$$

## Satisfiability Modulo Theories Approach

- Initial graph $G$ and number $K$ of basis patterns
- Peak detection to extract a set of peaks $P_{i}$ for each diffraction pattern $\boldsymbol{D}_{\boldsymbol{i}}$



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- Real variable $e_{j k}$ for the location of peak $k$ in basis $B_{j}$



## Satisfiability Modulo Theories Approach

- Initial graph $G$ and number $K$ of basis patterns
- Peak detection to extract a set of peaks $P_{i}$ for each diffraction pattern $\boldsymbol{D}_{\boldsymbol{i}}$
- Real variable $e_{j k}$ for the location of peak $k$ in basis $B_{j}$
- Real variable $s_{i j}$ for the shift coefficient of basis $B_{j}$ in point $P_{i}$



## Satisfiability Modulo Theories Approach

- An observed peak $p$ is "explained" if there exists $s_{i j}, e_{j k}$ s.t. $\left|p-\left(s_{i j}+e_{j k}\right)\right| \leq \varepsilon$
- Every observed peak must be explained



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- An observed peak $p$ is "explained" if there exists $s_{i j}, e_{j k}$ s.t. $\left|p-\left(s_{i j}+e_{j k}\right)\right| \leq \varepsilon$
- Every observed peak must be explained
- Some peaks might be missing (unobserved)
- Bound the number of missing peaks $\leq T$
- Minimization by (binary) search on $T$



## Satisfiability Modulo Theories Approach

- Linear phase usage constraints (up to $M$ basis patterns per point)
- Linear constraints for shift monotonicity and continuity ( $s_{i j} \leq s_{l m}$ )
- Lazy connectivity: add a cut if current solution is not connected

If disconnected regions explained with phase 1


Then Phase 1 must appear in at least one of these points

- Symmetry breaking:
- Renaming of pure phases
- Ordering of the peak locations $e_{j k}$ (per basis pattern)


## $\square$ Quantifier-free linear arithmetic

## Experimental Results

- Illustration on Al-Li-Fe system



## Conclusion and Future work



- Novel SMT encoding for Materials Discovery
- Good performance on synthetic data:
- Scales to realistic sized problems (~50 points)
- Provides physically-meaningful solutions
- Good accuracy (>90\% precision and recall)
- Outperforms both Constraint Programming and Mixed Integer Programming direct translations of the SMT model
- Future work: online adaptive sampling during data collection
- Exciting results analyzing and explaining real-world data


## THANK YOU!

Intelligent Information
Systems Institute

## Extra slides

## Runtime

| \# Points | Unknown <br> Phases | Arithmetic + Z3 <br> $(\mathbf{s})$ | Set-based + CPLEX <br> $(\mathbf{s})$ |  |
| :---: | :---: | :---: | :---: | :---: |
| 10 | 3 | 8 | 0.5 |  |
|  | 6 | 12 | Timeout |  |
| 15 | 3 | 13 | 0.5 |  |
|  | 6 | 20 | Timeout | Z3 scales to <br> realistic sized <br> problems! |
| 18 | 3 | 29 | 384.8 |  |
|  | 6 | 125 | Timeout |  |
| 29 | 3 | 78 | 276 |  |
|  | 6 | 186 | Timeout |  |
| 45 | 6 | 518 | Timeout |  |

Arithmetic encoding translated to CP and MIP:

- MIP is appealing because it can optimize the objective
- They don't scale $\rightarrow$ SMT solving strategy


## Precision/Recall



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## Robustness

- Remove some peaks to simulate experimental noise
- Size = 15 points

| Missing Peaks | Precision | Recall |
| :---: | :---: | :---: |
| 1 | 96.1 | 99.6 |
| 2 | 96.3 | 99.3 |
| 3 | 96.7 | 99.5 |
| 4 | 95.3 | 98.9 |
| 5 | 94.8 | 99.7 |



Solutions are still accurate. Runtime increases approx linearly.

## Previous Work 1: Cluster Analysis [Long et al., 2007]



Feature vector

$$
\longrightarrow C_{x y}=\frac{\sum_{i=1}^{n}\left(x_{i}-\bar{x}\right)\left(y_{i}-\bar{y}\right)}{\left[\sum_{i=1}^{n}\left(x_{i}-\bar{x}\right)^{2} \sum_{i=1}^{n}\left(y_{i}-\bar{y}\right)^{2}\right]^{1 / 2}} \longrightarrow D=(1-C) / 2
$$

Pearson correlation coefficients Distance matrix
$\downarrow$
Hierarchical Agglomerative Clustering

Drawback: Requires sampling of pure phases, detects phase regions (not phases), overlooks peak shifts, may violate physical constraints (phase continuity, etc.).

## Previous Work 2: NMF [Long et al., 2009]



Drawback: Overlooks peak shifts (linear combination only), may violate physical constraints (phase continuity, etc.).

## SMT formulation

- Parameters
- Number of pure phases $K$, tolerance $\varepsilon$
- Key components
- Variables peak positions per base
- Shifts per point
- Point $p$ is explained by base $k$
- New arithmetic-based encoding:
- Real variables $e_{i j}$ for the peak locations in each $B_{i}$
- Real variables for the shift coefficients $s_{i j}$ (per base, per point)
- An observed peak $p$ is explained if $\left|p-s_{i j}-e_{i j}\right| \leq \varepsilon$ (Match the height of the peaks)
- Bound the number of missing peaks $\leq T$

