

Numerical Methods for Resonance Calculations

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Resonant
MEMS: an
application

Resonances
via nonlinear
eigenprob-
lems

Resonances
via Perfectly
Matched
Layers

Conclusions

Backup slides

Outline

- 1 Resonant MEMS: an application
- 2 Resonances via nonlinear eigenproblems
- 3 Resonances via Perfectly Matched Layers
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Resonant RF MEMS

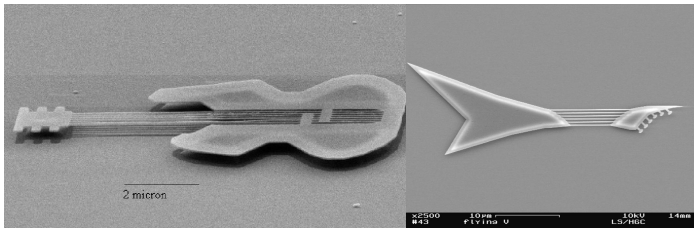
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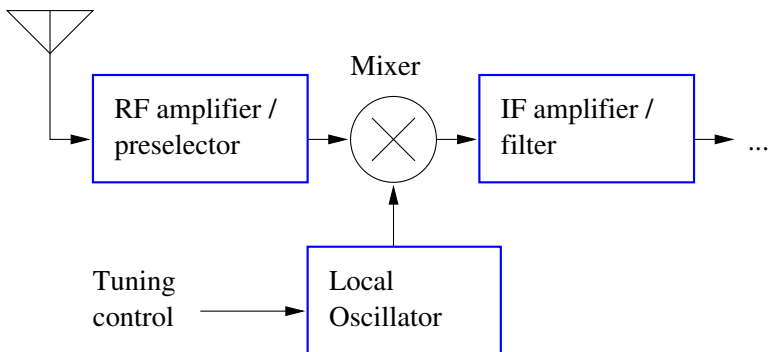
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Microguitars from Cornell University (1997 and 2003)

- MHz-GHz mechanical resonators
- Favorite application: radio on chip
- Close second: really high-pitch guitars

The Mechanical Cell Phone



- Your cell phone has many moving parts!
- What if we replace them with integrated MEMS?

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Ultimate Success

“Calling Dick Tracy!”



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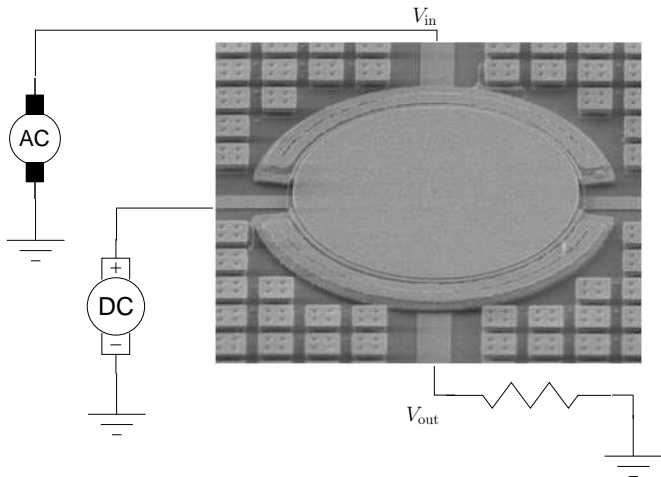
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Disk Resonator



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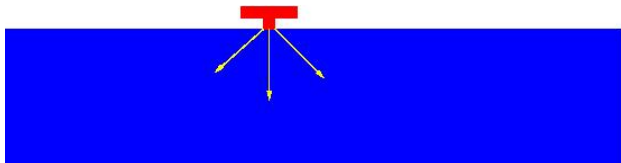
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Damping Mechanisms



Possible loss mechanisms:

- Fluid damping
- Material losses
- Thermoelastic damping
- **Anchor loss**

This is a resonance computation!

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Simple 1D Problem

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Consider 1D Schrödinger:

$$\left(-\frac{d^2}{dx^2} + V(x)\right)\psi = E\psi.$$

How do we:

- 1 Quickly compute resonances (nice enough V)?
- 2 Make sure the computations are correct?

Simple 1D Problem

Consider 1D Schrödinger:

$$\left(-\frac{d^2}{dx^2} + V(x)\right)\psi = E\psi.$$

If $\text{supp}(V) \subset [a, b]$, write

$$\left(-\frac{d^2}{dx^2} + V(x) - k^2\right)\psi = 0, x \in (a, b)$$

$$\left(\frac{d}{dx} - ik\right)\psi = 0, x = b$$

$$\left(\frac{d}{dx} + ik\right)\psi = 0, x = a$$

$\text{Im } k \geq 0$ for eigenvalues, $\text{Im } k < 0$ for resonances.

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Pseudospectral Discretization

Sample ψ at Chebyshev nodes and approximate $d\psi/dx$ by differentiating the interpolant:

$$\left(-D^2 + V(x) - k^2\right) \psi = 0, x \in (a, b)$$

$$(D - ik) \psi = 0, x = b$$

$$(D + ik) \psi = 0, x = a$$

Now linearize (introduce auxiliary variable $\phi = k\psi$) to get an ordinary generalized eigenvalue problem.

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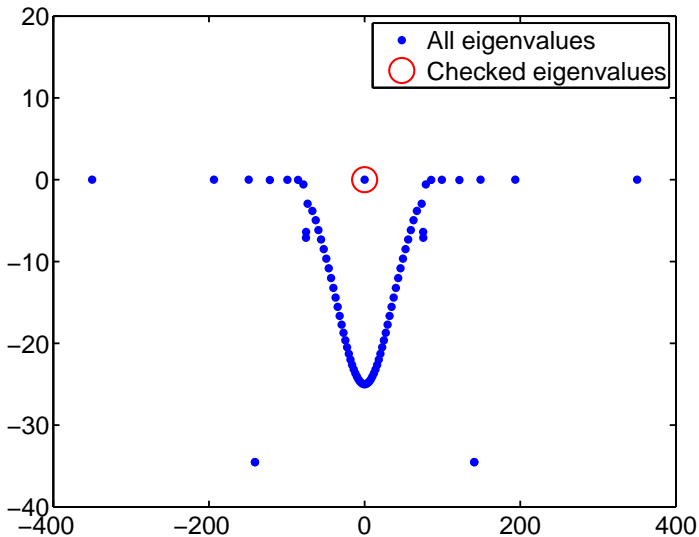
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Is it that easy?



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Backward Error Analysis

If $\hat{\psi}$ is a numerical solution, there is some \hat{V} s.t.

$$\left(-\frac{d^2}{dx^2} + \hat{V}(x) - k^2 \right) \hat{\psi} = 0, x \in (a, b)$$

First-order sensitivity to changes in \hat{V} is

$$\begin{aligned} \delta k &= \frac{\int_a^b \hat{\psi}(\delta V)\hat{\psi}}{2k \int_a^b \hat{\psi}^2 + i(\hat{\psi}^2(a) + \hat{\psi}^2(b))} \\ &= \frac{\int_a^b \hat{\psi}(H_V - k^2)\hat{\psi}}{2k \int_a^b \hat{\psi}^2 + i(\hat{\psi}^2(a) + \hat{\psi}^2(b))}. \end{aligned}$$

Compute \hat{V} by evaluating residual for approximate $\hat{\psi}$ on a fine mesh.

Backward Error Analysis

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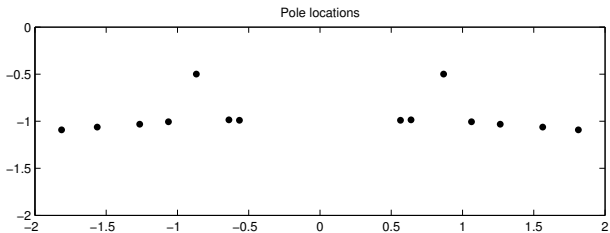
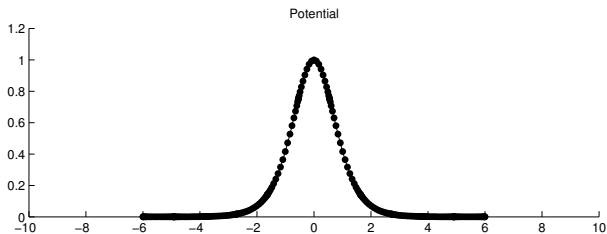
First-order sensitivity to changes in \hat{V} is

$$\delta k = \frac{\int_a^b \hat{\psi}(\delta V) \hat{\psi}}{2k \int_a^b \hat{\psi}^2 + i(\hat{\psi}^2(a) + \hat{\psi}^2(b))}.$$

Now think about perturbing from a truncated potential to a non-compactly supported potential. Above bound says this is okay as long as $|V|/\exp(2\operatorname{Im}(k)|x|) \rightarrow 0$ as $|x| \rightarrow \infty$.

Backward Error Analysis

Example: truncate Eckart potential $\cosh^{-2}(x)$



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More General Picture

Consider Schrödinger with compactly supported V in R^d .
On resolvent set,

$$\begin{aligned}(H_V - E)\psi &= f \text{ on } \Omega \\ \frac{\partial \psi}{\partial n} - B(E)\psi &= 0 \text{ on } \Gamma\end{aligned}$$

where $B(E)$ is the Dirichlet-to-Neumann map on $\partial\Omega$
Admits a variational formulation:

$$\begin{aligned}I(\psi) &= \frac{1}{2} \int_{\Omega} \left((\nabla \psi)^T (\nabla \psi) + \psi (V - E) \psi \right) d\Omega + \\ &\quad \frac{1}{2} \int_{\Gamma} \psi B(E) \psi d\Gamma - \int_{\Omega} \psi f d\Omega.\end{aligned}$$

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Rayleigh Quotient Analogue

Now define a residual for an approximate eigenpair:

$$r(\psi, E) = \int_{\Omega} \left((\nabla \psi)^T (\nabla \psi) + \psi (V - E) \psi \right) + \int_{\Gamma} \psi B(E) \psi.$$

Take variations and use symmetry of B :

$$\begin{aligned} \delta r(\psi, E) &= 2 \int_{\Omega} \delta \psi [(-\Delta + V - E)\psi] + \\ &2 \int_{\Gamma} \delta \psi \left[\frac{\partial \psi}{\partial n} - B(E)\psi \right] + \\ &\delta E \left[\int_{\Omega} \psi^2 - \int_{\Gamma} \psi B'(E)\psi \right] \end{aligned}$$

Rayleigh Quotient Analogue

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We now implicitly define a differentiable function $\tilde{E}(\psi)$ in the neighborhood of an eigenpair (ψ, E_*) , with $r(\psi, E(\psi)) = 0$ and $E(\psi) = E_*$. Such a function should exist if

$$\int_{\Omega} \psi^2 - \int_{\Gamma} \psi B'(E) \psi \neq 0$$

Stationary precisely when (ψ, E) an eigenpair.

Sensitivity

Now assume δV a compactly-supported perturbation, and look at effect of δV on Rayleigh quotient analogue. Gives that isolated eigenvalues change like

$$\delta E = \frac{\int_{\Omega} \delta V \psi^2}{\int_{\Omega} \psi^2 - \int_{\Gamma} \psi B'(E) \psi}$$

Can also write in terms of a residual for ψ as a solution for the potential $V + \delta V$:

$$\delta E = \frac{\int_{\Omega} \psi (-\Delta + (V + \delta V) - E) \psi}{\int_{\Omega} \psi^2 - \int_{\Gamma} \psi B'(E) \psi}.$$

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Some Computational Issues

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In general, using the domain equation + DtN map to find resonances is problematic because:

- 1 The DtN map is nonlocal, expensive to work with computationally.
- 2 The Green's function (and hence the DtN map) for an elastic half space problem is hard to write down.
- 3 Nonlinear eigenvalue problems are trickier than linear problems to solve.

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Perfectly Matched Layers

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- Complex coordinate transformation
- Generates a “perfectly matched” absorbing layer
- Idea works with general linear wave equations
 - Electromagnetics (Bereng er, 1994)
 - Quantum mechanics – *exterior complex scaling* (Simon, 1979)
 - Elasticity in standard finite element framework (Basu and Chopra, 2003)

Model Problem

- Domain: $x \in [0, \infty)$
- Governing eq:

$$\frac{\partial^2 u}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} = 0$$

- Fourier transform:

$$\frac{d^2 \hat{u}}{dx^2} + k^2 \hat{u} = 0$$

- Solution:

$$\hat{u} = c_{\text{out}} e^{-ikx} + c_{\text{in}} e^{ikx}$$

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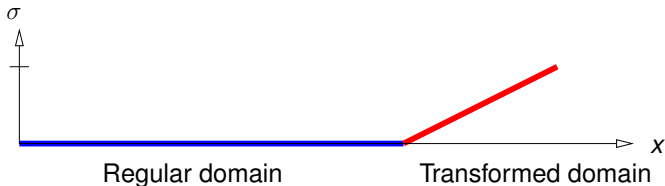
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Model with Perfectly Matched Layer



$$\frac{d\tilde{x}}{dx} = \lambda(x) \text{ where } \lambda(s) = 1 - i\sigma(s)$$

$$\frac{d^2\hat{u}}{d\tilde{x}^2} + k^2\hat{u} = 0$$

$$\hat{u} = c_{\text{out}}e^{-ik\tilde{x}} + c_{\text{in}}e^{ik\tilde{x}}$$

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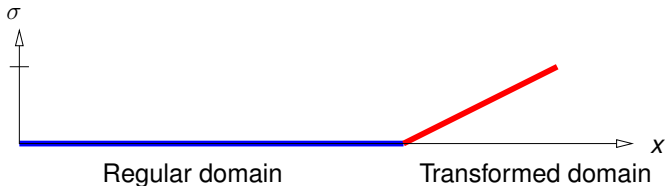
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Model with Perfectly Matched Layer



$$\frac{d\tilde{x}}{dx} = \lambda(x) \text{ where } \lambda(s) = 1 - i\sigma(s),$$

$$\frac{1}{\lambda} \frac{d}{dx} \left(\frac{1}{\lambda} \frac{d\hat{u}}{dx} \right) + k^2 \hat{u} = 0$$

$$\hat{u} = c_{\text{out}} e^{-ikx - k\Sigma(x)} + c_{\text{in}} e^{ikx + k\Sigma(x)}$$

$$\Sigma(x) = \int_0^x \sigma(s) ds$$

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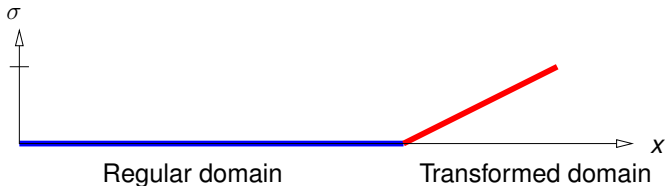
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Model with Perfectly Matched Layer



If solution clamped at $x = L$ then

$$\frac{c_{\text{in}}}{c_{\text{out}}} = O(e^{-k\gamma}) \text{ where } \gamma = \Sigma(L) = \int_0^L \sigma(s) ds$$

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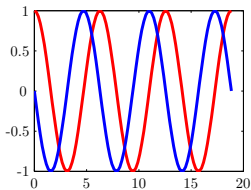
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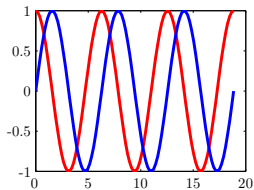
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Model Problem Illustrated

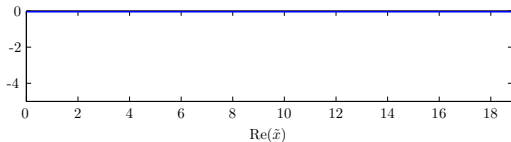
Outgoing $\exp(-i\tilde{x})$



Incoming $\exp(i\tilde{x})$



Transformed coordinate



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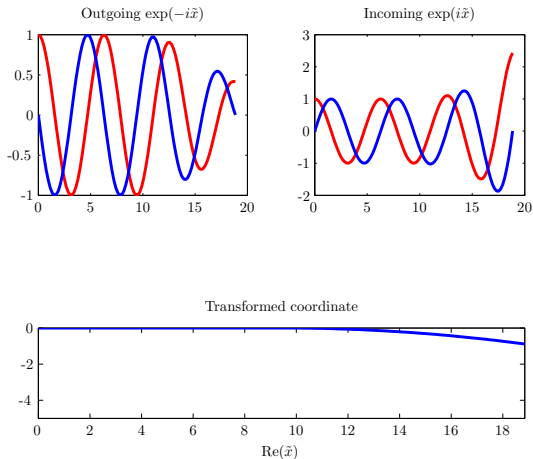
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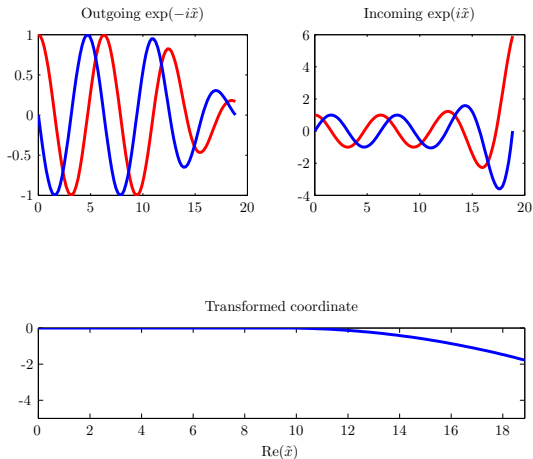
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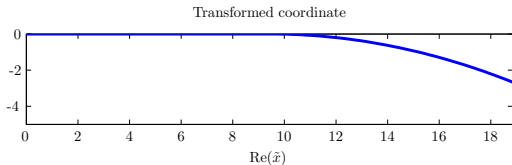
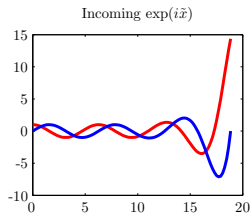
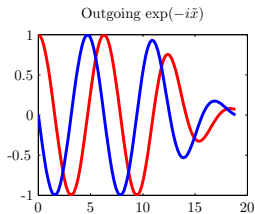
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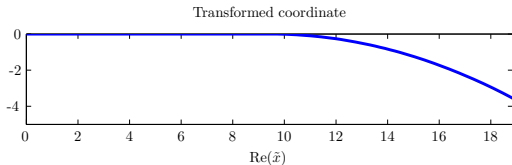
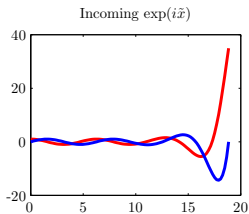
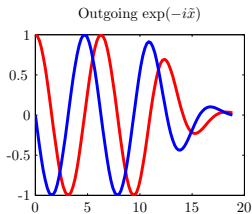
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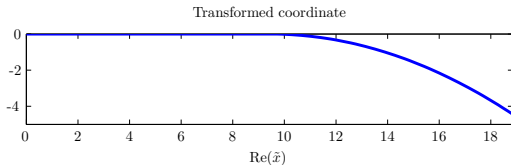
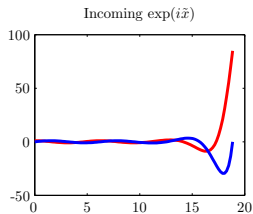
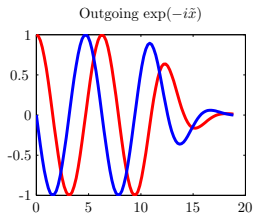
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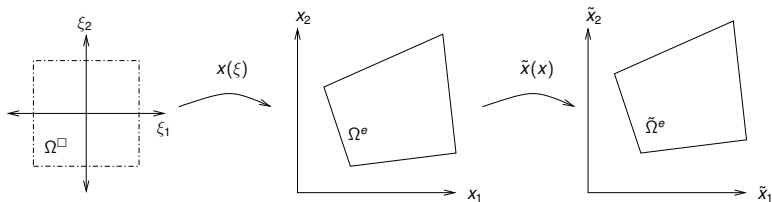
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Finite Element Implementation



- Combine PML and isoparametric mappings

$$\mathbf{k}^e = \int_{\Omega^\square} \tilde{\mathbf{B}}^T \mathbf{D} \tilde{\mathbf{B}} \tilde{J} d\Omega^\square$$

$$\mathbf{m}^e = \int_{\Omega^\square} \rho \mathbf{N}^T \mathbf{N} \tilde{J} d\Omega^\square$$

- Matrices are *complex symmetric*

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Variational Principles

- Variational form for complex symmetric eigenproblems:
 - Hermitian (Rayleigh quotient):

$$\rho(v) = \frac{v^* K v}{v^* M v}$$

- Complex symmetric (modified Rayleigh quotient):

$$\theta(v) = \frac{v^T K v}{v^T M v}$$

- First-order accurate eigenvectors \implies
Second-order accurate eigenvalues.
- Key: relation between left and right eigenvectors.

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Relation to the DtN approach

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PML provides a *local rational approximation* to the DtN conditions. Suppose regions 1, 2, and 3 are the ordinary domain, the boundary, and the PML. Eliminating the variables from region 3 in $(K - \lambda M)\psi = 0$ yields something like the DtN version of the eigenvalue / resonance problem.

DtN approximation in PML

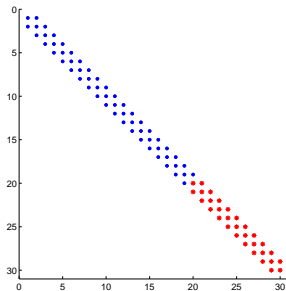
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- Start with $(K - \omega^2 M)u = e_1$
- Schur complement to eliminate PML unknowns
- Compare last coefficient with exact (discrete) BC

DtN approximation in PML

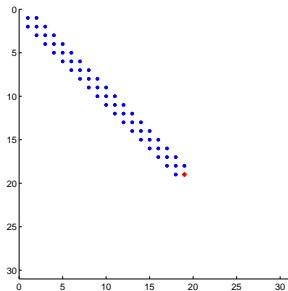
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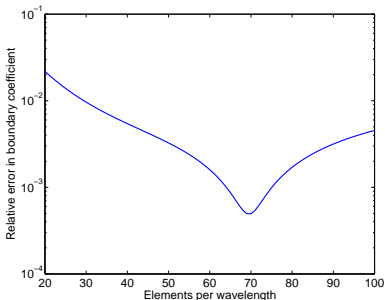
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- Start with $(K - \omega^2 M)u = e_1$
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DtN approximation in PML



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Conclusions

- 1 Can compute resonances via nonlinear eigenvalue problems
- 2 Can also use PMLs / complex scaling
- 3 Want error estimates along with computations; nonlinear variational approach is a useful.

See also:

<http://www.cims.nyu.edu/~dbindel/matscat/>

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Disk Resonator Simulations

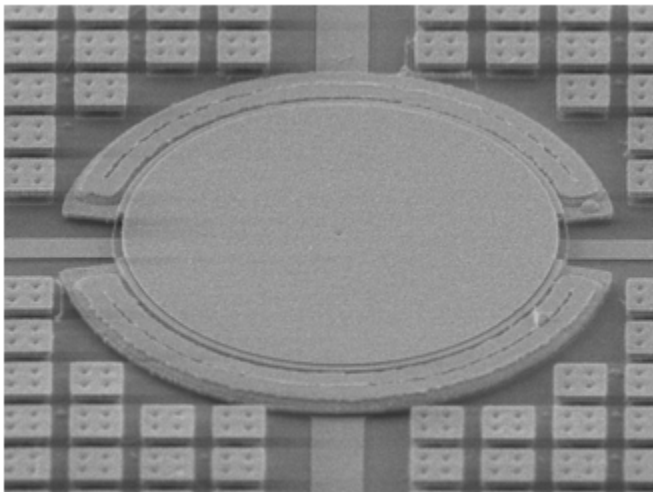
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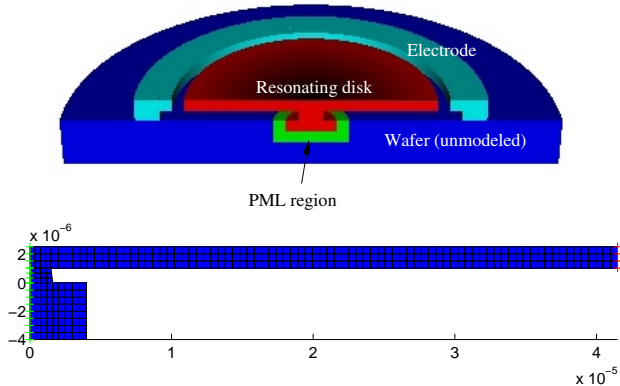
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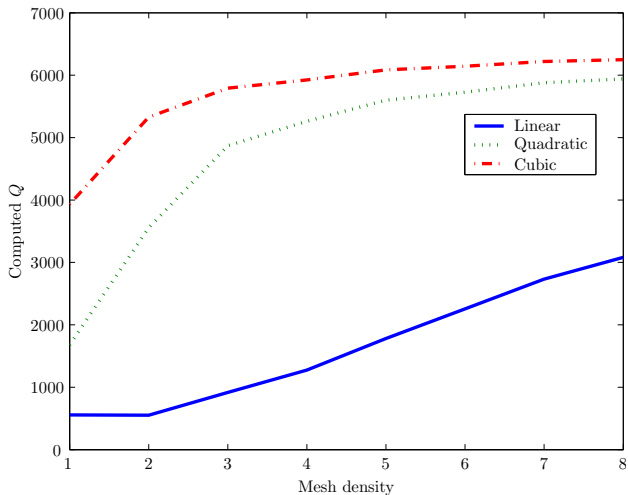
Disk Resonator Mesh



- Axisymmetric model with bicubic mesh
- About 10K nodal points in converged calculation

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Mesh Convergence



Cubic elements converge with reasonable mesh density

- Resonant MEMS: an application
- Resonances via nonlinear eigenproblems
- Resonances via Perfectly Matched Layers
- Conclusions
- Backup slides

Response of the Disk Resonator

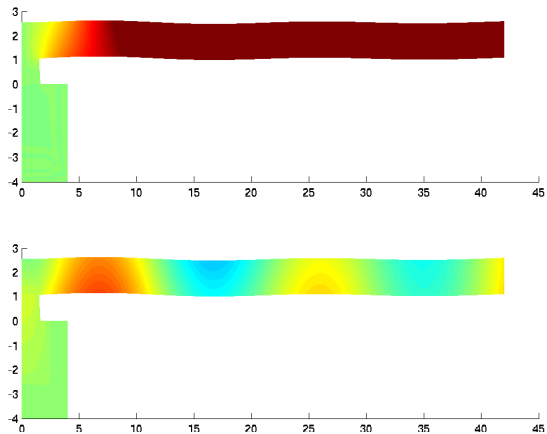
Resonant
MEMS: an
application

Resonances
via nonlinear
eigenprob-
lems

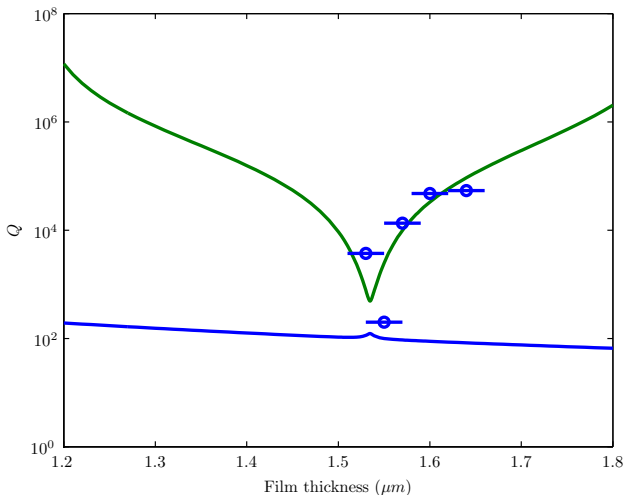
Resonances
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Conclusions

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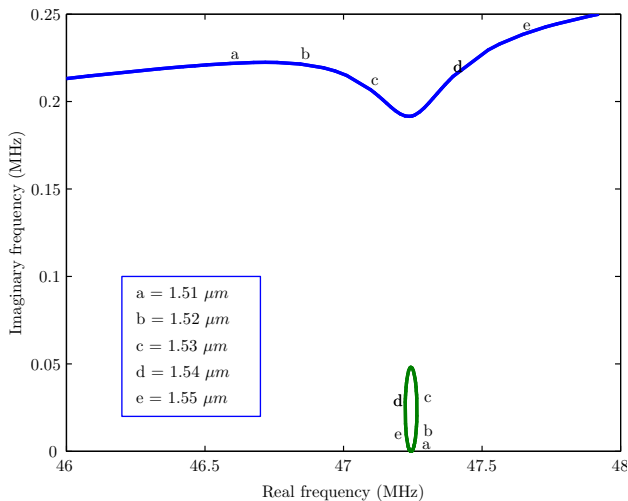
Variation in Quality of Resonance



Simulation and lab measurements vs. disk thickness

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Explanation of Q Variation



Interaction of two nearby eigenmodes

Resonant
MEMS: an
application

Resonances
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eigenprob-
lems

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