

Simulating RF MEMS

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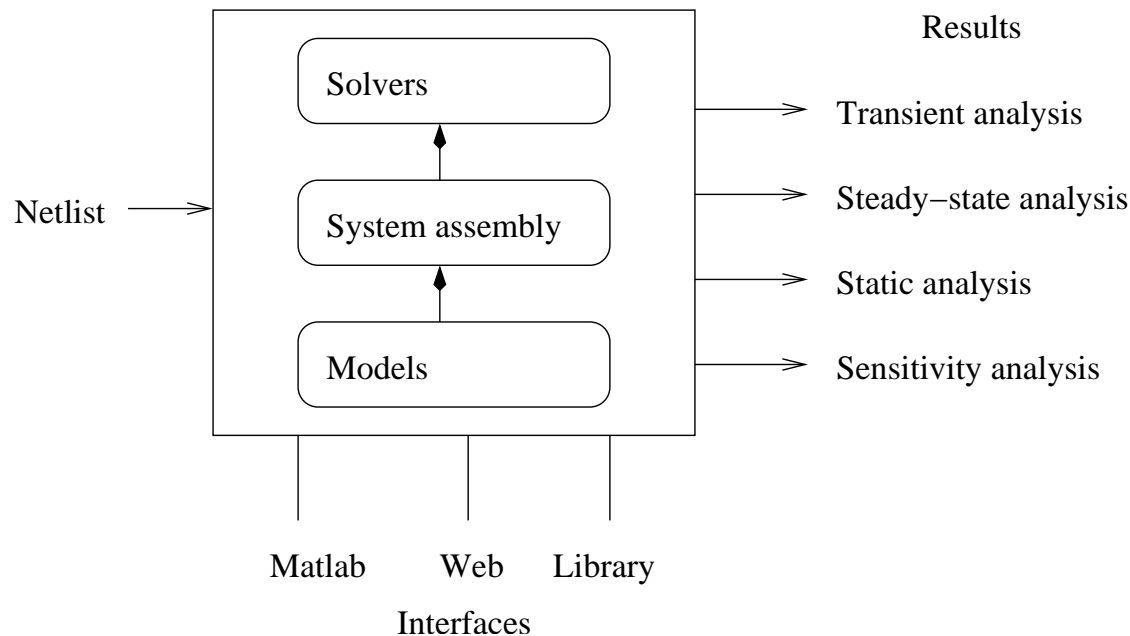
Collaborators

Faculty	Grad students
A. Agogino (ME) Z. Bai (Math/CS) J. Demmel (Math/CS) S. Govindjee (CEE) R. Howe (EE)	D. Bindel (CS) J.V. Clark (AS&T) D. Garmire (CS) T. Koyama (CEE) R. Kamalian (ME) J. Nie (Math) S. Bhave (EE)

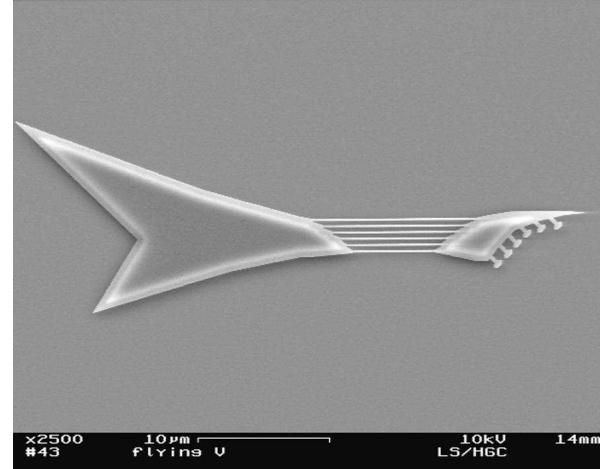
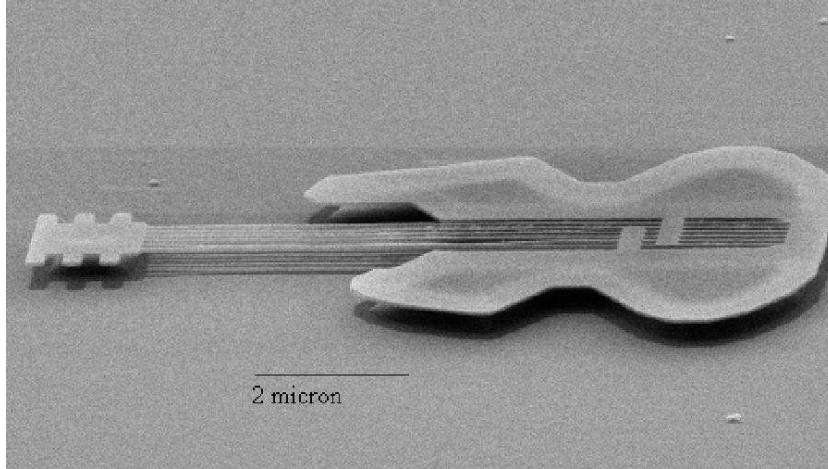
SUGAR

Goal: “Be SPICE to the MEMS world”

- Fast enough for early design stages
- Simple enough to attract users
- Support design, analysis, optimization, synthesis
- Verify models by comparison to measurement



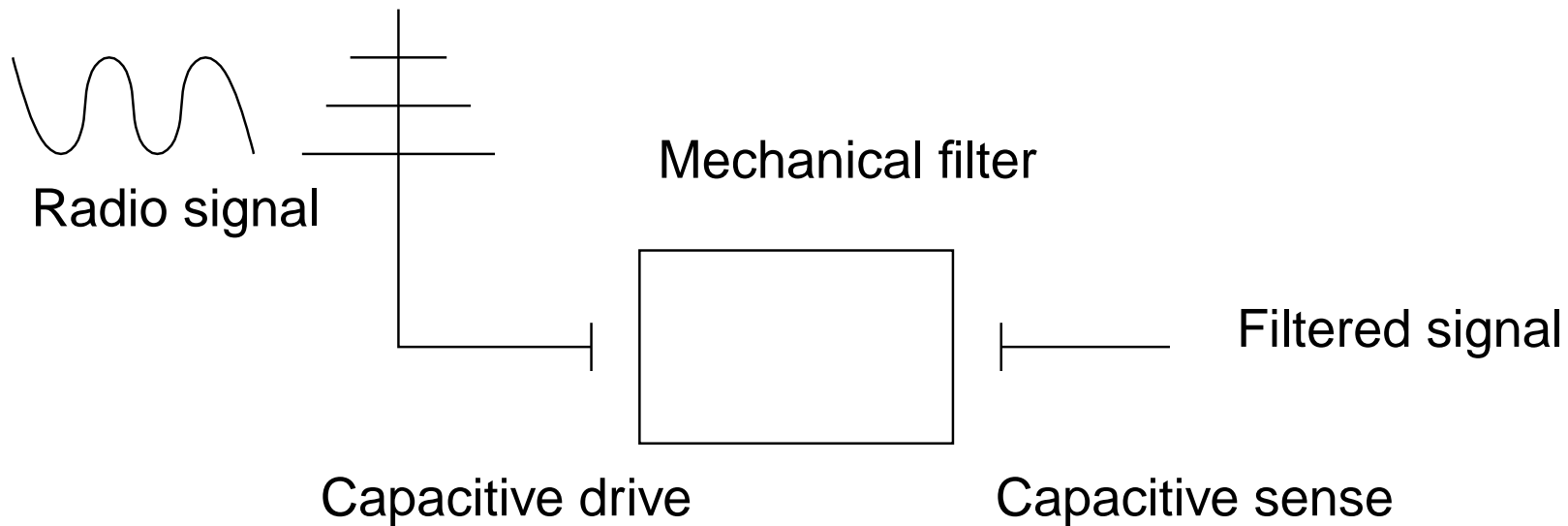
Why RF resonators?



Microguitars from Cornell University (1997 and 2003)

- Frequency references
- Sensing elements
- Filter elements
- Neural networks
- Really high-pitch guitars

Micromechanical filters



- Mechanical high-frequency (high MHz-GHz) filter
- Saves power and cost over electronic filters
- Advantage over piezo-actuated quartz SAW filters
 - Integrated into chip
 - Low power

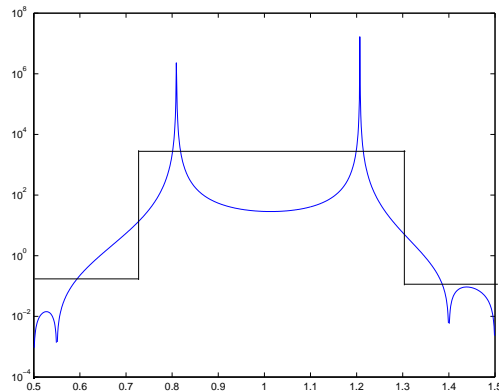
Governing equations: forced response

Time domain:

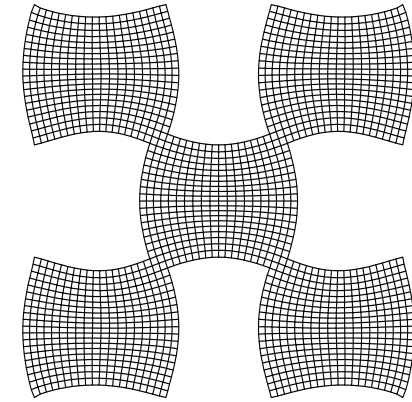
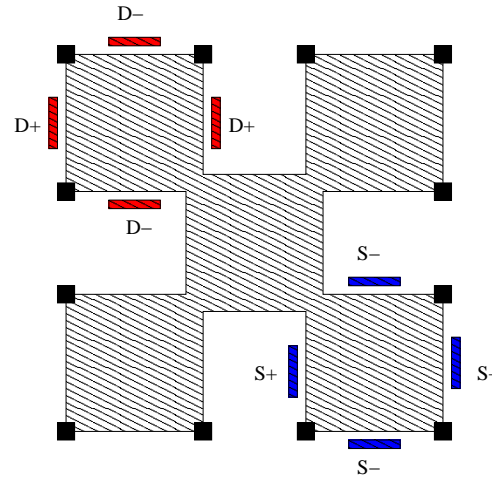
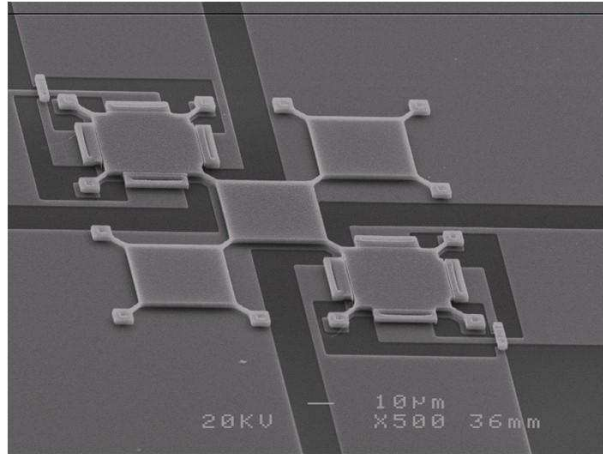
$$\begin{aligned}Mu'' + Cu' + Ku &= P\phi \\ y &= V^T u\end{aligned}$$

Frequency domain:

$$\begin{aligned}H(\omega) &= V^T (-\omega^2 M + i\omega C + K)^{-1} P \\ \hat{y} &= H\hat{\phi}\end{aligned}$$

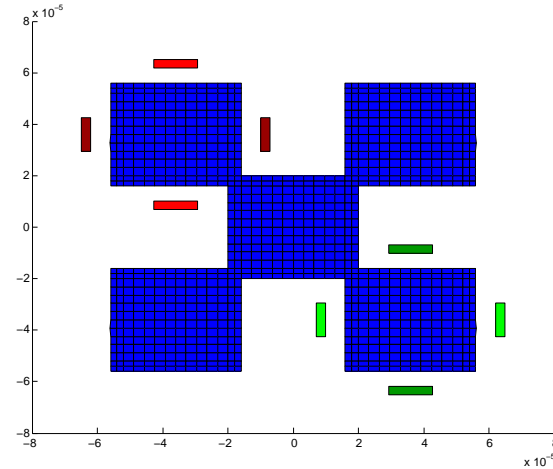
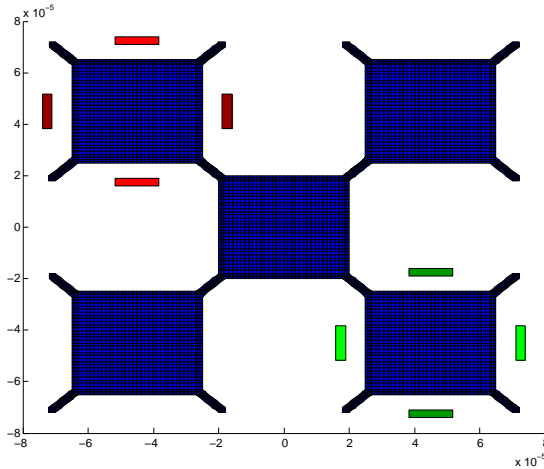


First proposed design: Checkerboard



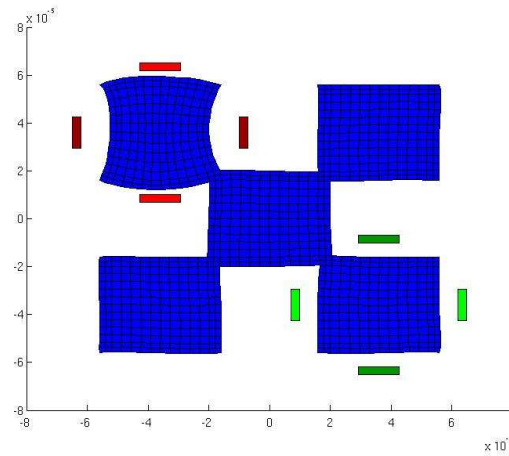
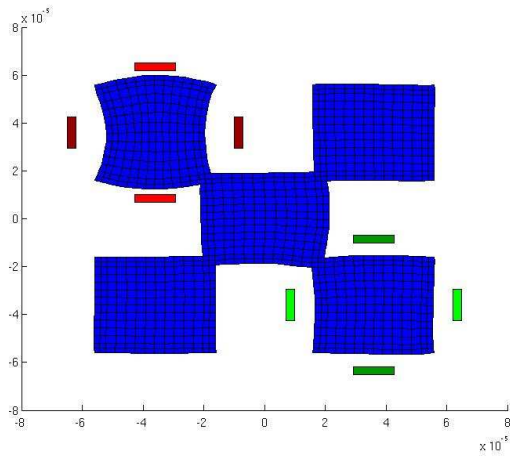
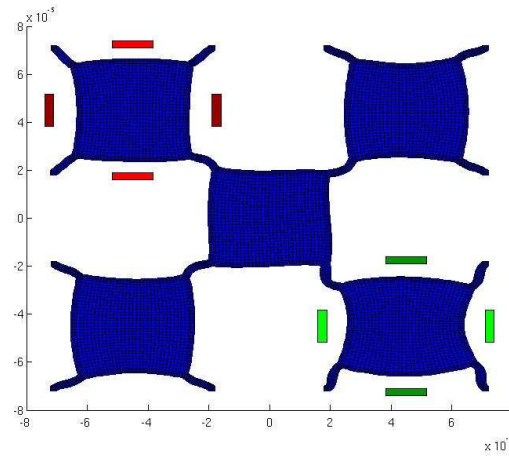
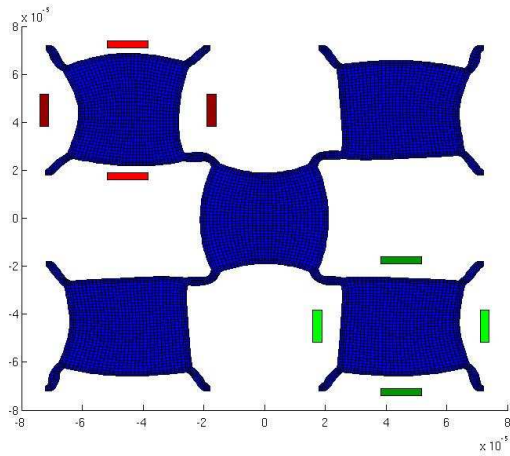
- Array of loosely coupled resonators
- Anchored at outside corners
- Excited at **northwest** corner
- Sensed at **southeast** corner
- Surfaces move only a few nanometers

Design questions



- Where should drive and sense be placed?
- How should the individual resonators be connected?
- How should the system be anchored?
- How many components? What topology?
- What size should the components be?

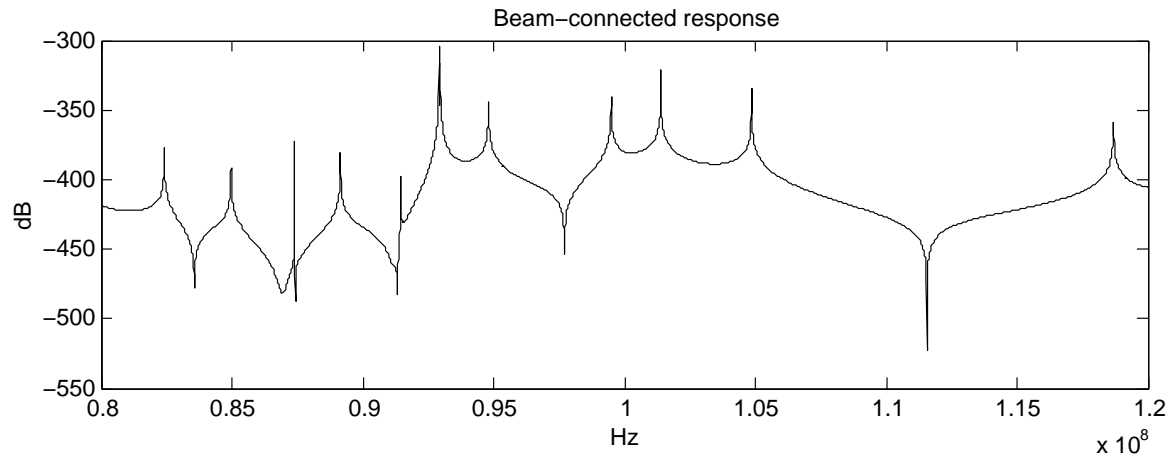
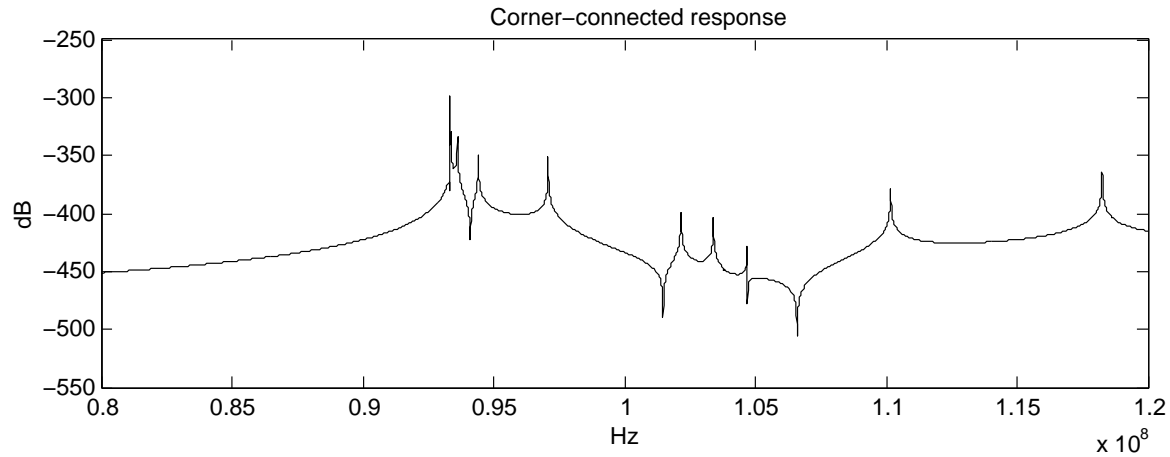
Checkerboard response



95 MHz

100 MHz

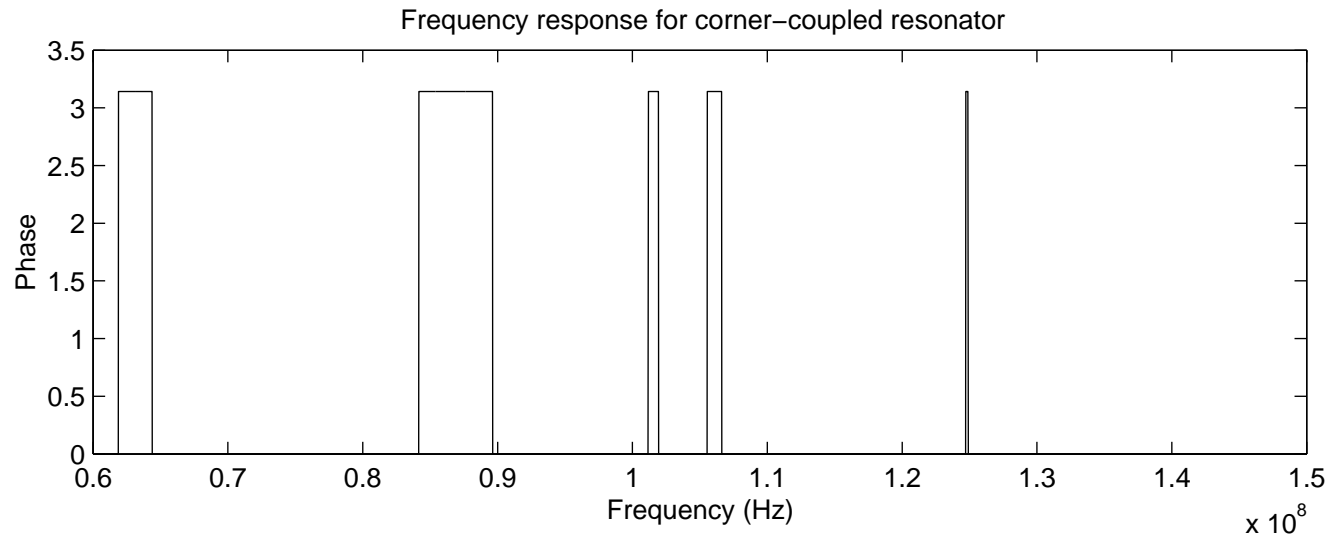
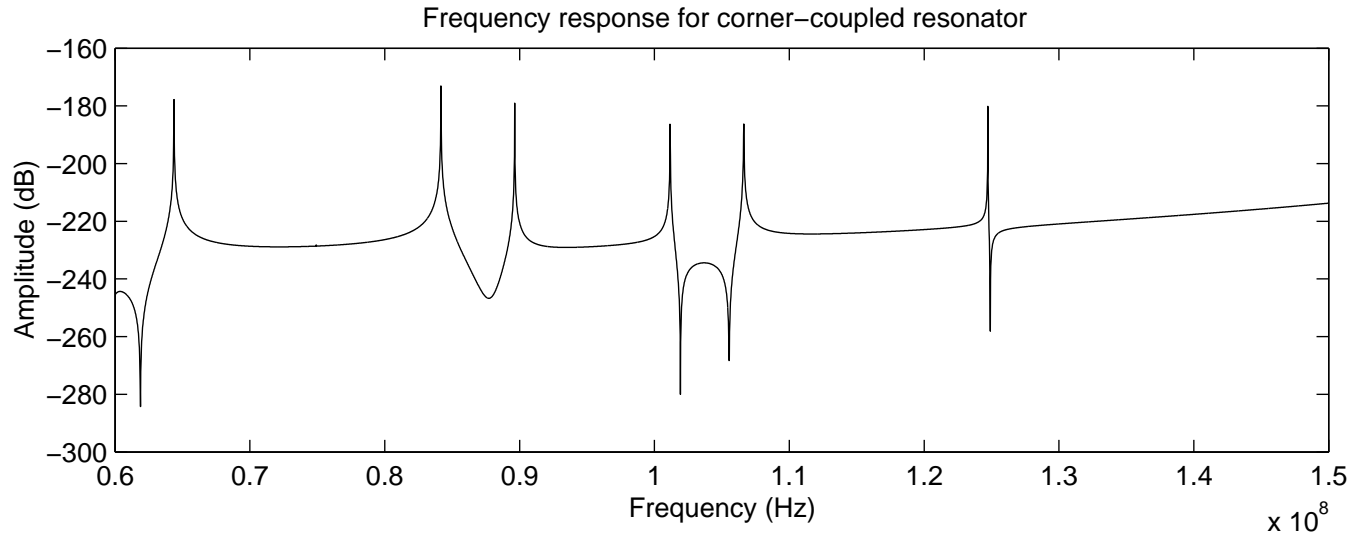
Checkerboard response



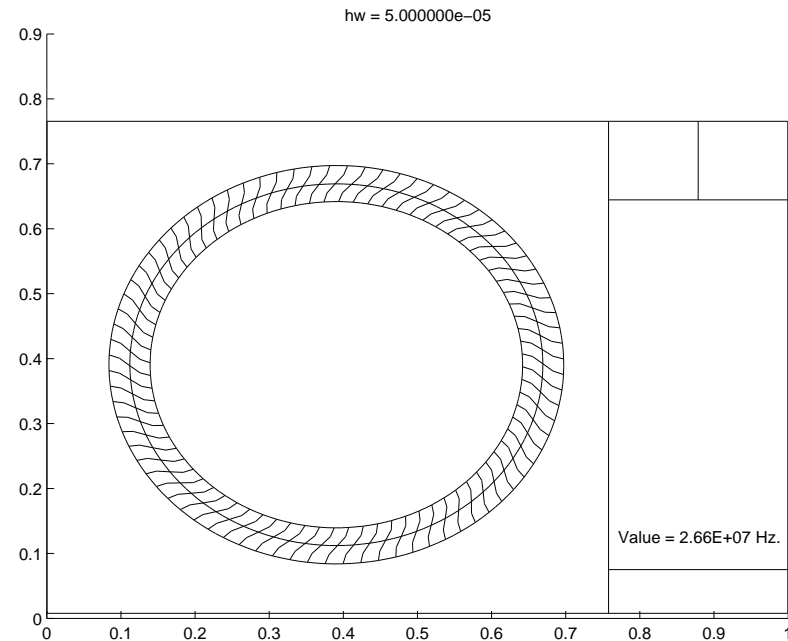
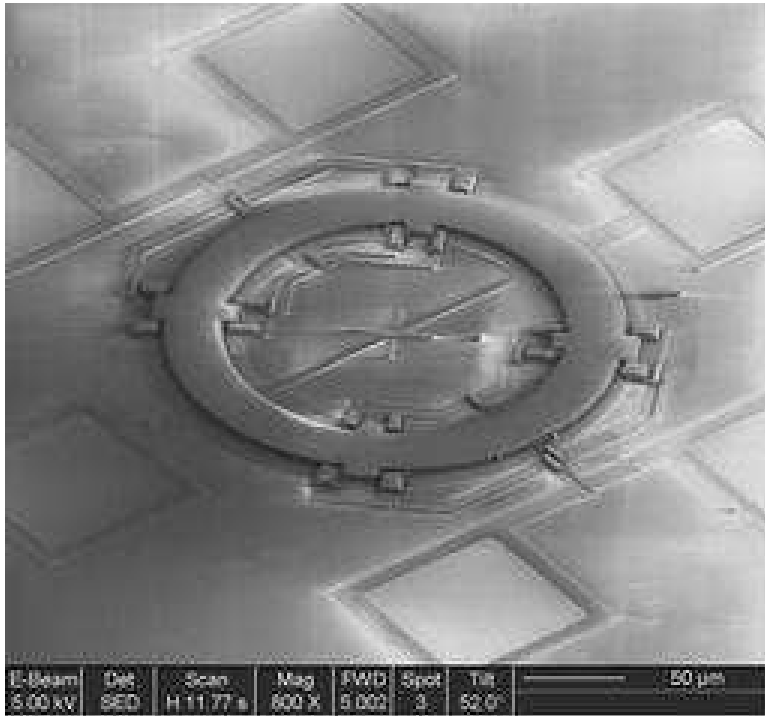
Corner-connected details

Beam-connected details

Checkerboard response: 4-by-4



Shear ring resonator



- Ring is driven in a shearing motion
- Can couple ring to other resonators

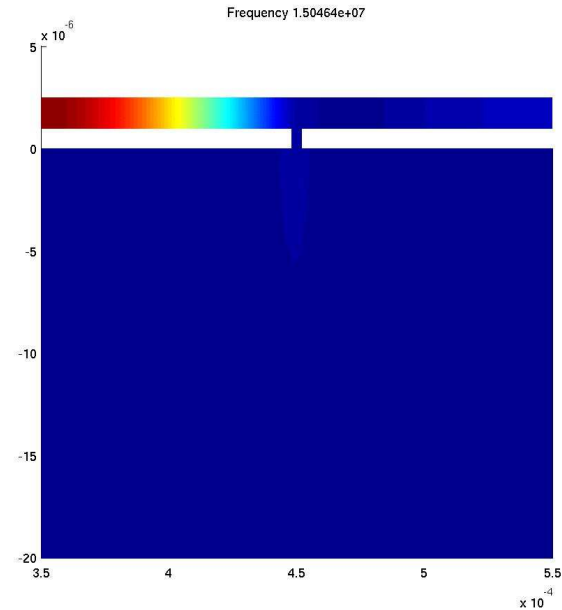
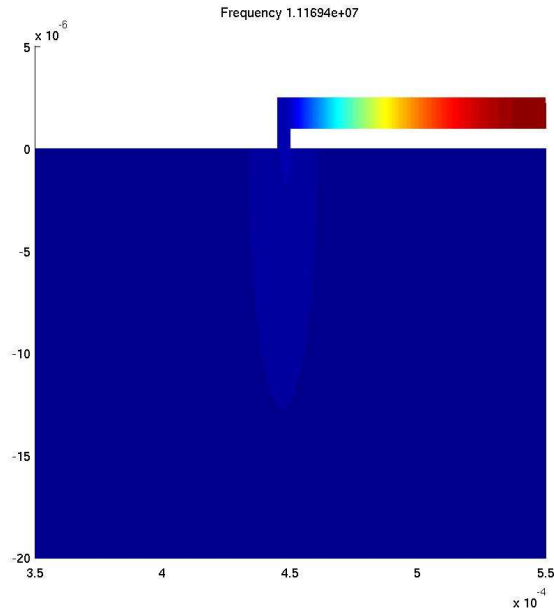
Current questions

- How do we model damping?
- How do we compute frequency response quickly?
- How do we track dependence on geometry?
- How do we optimize designs?

Energy loss and Q

- Goal: strong output signal and high Q
- Challenge: Model details of energy loss
 - Anchor loss
 - Thermoelastic damping
 - Akheiser damping
 - Air damping
- How are losses affected by fabrication errors (e.g. anchor misalignment)?

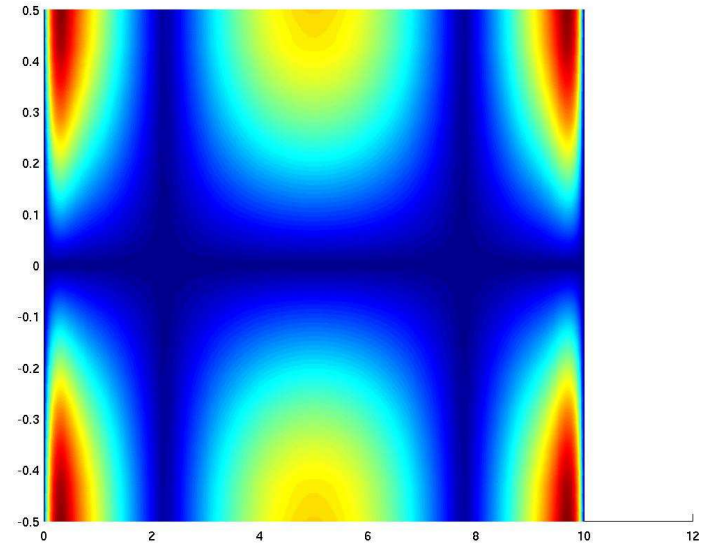
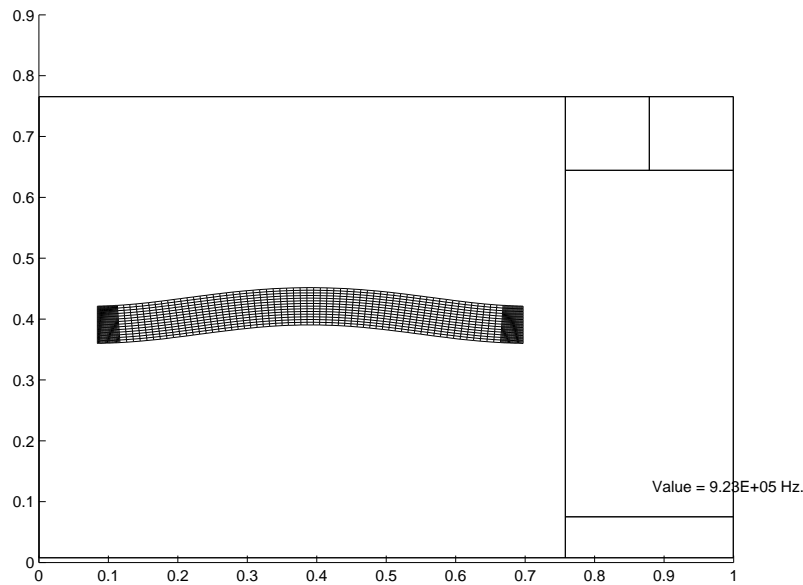
Anchor loss



$f_{\text{damp}} \approx 11.5\text{MHz}$ and $Q \approx 50$ $f_{\text{damp}} \approx 15\text{MHz}$ and $Q \approx 160$

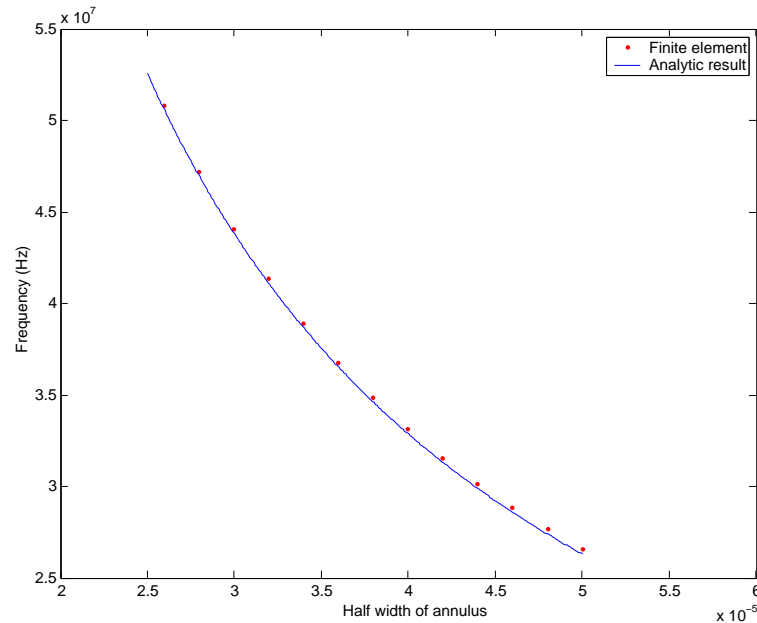
- Impose artificial boundary conditions (ABCs)
- Mimic a semi-infinite domain (non-reflecting BC)
- Two main classes: easy + inaccurate, hard + accurate

Thermoelastic losses



- Heating coupled to volumetric strain rate
- Diffusion of heat \implies irreversible loss
- Zener approximated the effect for beams
- Finite element discretization works more generally
- Accelerate solution with a perturbation method

Mode tracking

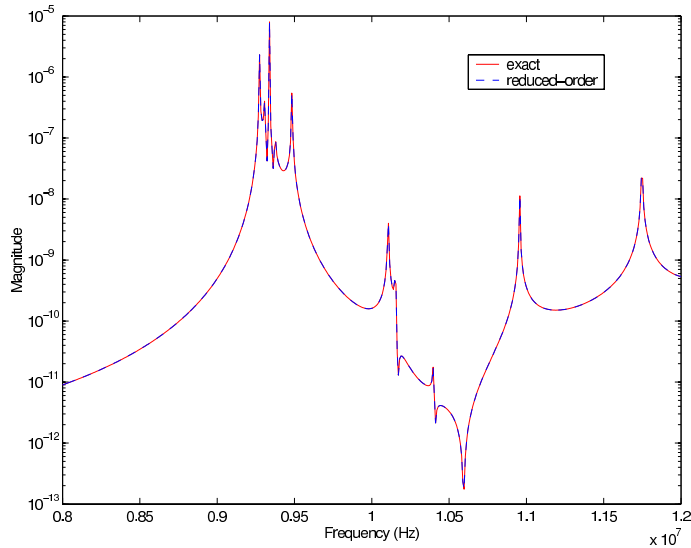


- Differentiate eigenvalue equation
$$K(s)q(s) = \lambda(s)M(s)q(s)$$
- Predictor-corrector iteration
- Convergence criteria, step control based on
$$|q(s_k)^T q(s_{k+1})|$$

Reduction of governing equations

- Typically reduce the problem size while computing.
- Seek the best approximate solution from a family of shapes
- Basis of
 - Finite element methods (infinite-dim \rightarrow finite)
 - Iterative methods for eigenvalue problems
 - Iterative solvers for linear systems
 - Lumped circuit models (modal mass and stiffness)
- Trick is to choose a good family of approximants

Model reduction



Sun	Ultra	10	
	Sec		n
ROM:	28	4834	
Full:	1474	50	

- Approximate with a set of global shape functions
 - Chosen from a Krylov subspace
 - Chosen from analysis of substructures
- Preserve second order system structure

Transfer function optimization

- Choose geometry to make a good bandpass filter
- What is a “good bandpass filter?”
 - $|H(\omega)|$ is big on $[\omega_l, \omega_r]$
 - $|H(\omega)|$ is tiny outside this interval
- How do we optimize?
 - Overton’s gradient sampling method
 - Use Byers-Boyd-Balikrishnan algorithm for distance to instability to minimize $|H(\omega)|$ on $[\omega_l, \omega_r]$
 - Small Hamiltonian eigenproblem (with ROM)

Software framework

- Simulations done with FEAPMEX
 - Matlab interface to the FEAP finite element code
 - Provides both FEAP and Matlab capabilities
 - Interface code is publically available

Conclusions

- RF MEMS are an interesting source of computational problems
 - Understanding the physics
 - Applying numerical tools

<http://bsac.berkeley.edu/cadtools/sugar/sugar/>

<http://www.cs.berkeley.edu/~dbindel/feapmex.html>