

# Iterative Residual Rescaling: An analysis and generalization of Latent Semantic Indexing

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Joint work with Rie Kubota Ando

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# The Document Representation Problem

**Goal:** Find a representation that succinctly describes the “meaning” of a “document” ...

... or in which we at least can determine if two “documents” have “similar” “meanings”, *without human labelings*.

- information retrieval
- multi-document summarization
- topic spotting
- creating/organizing knowledge resources

# The Vector Space Model (VSM)

*Documents:*

car  
engine  
hood  
tires  
truck  
trunk

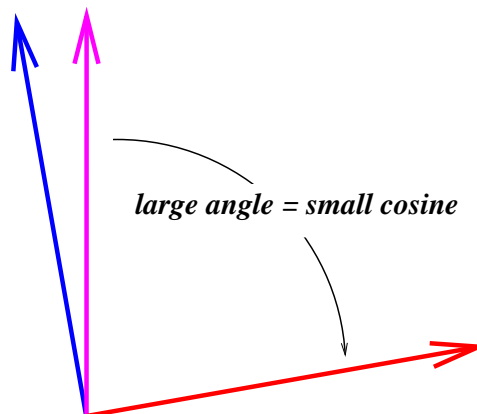
car  
emissions  
hood  
make  
model  
trunk

Chomsky  
corpus  
noun  
parsing  
tagging  
wonderful

*Term-document  
matrix D:*

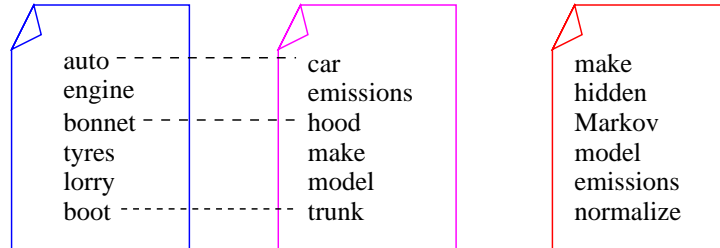
1	1	0	car
0	0	1	Chomsky
0	0	1	corpus
0	1	0	emissions
1	0	0	engine
1	1	0	hood
0	1	0	make
0	1	0	model
0	0	1	noun
0	0	1	parsing
0	0	1	tagging
1	0	0	tires
1	0	0	truck
1	1	0	trunk
0	0	1	wonderful

*Vector space:*



# Problems: Synonymy & Polysemy

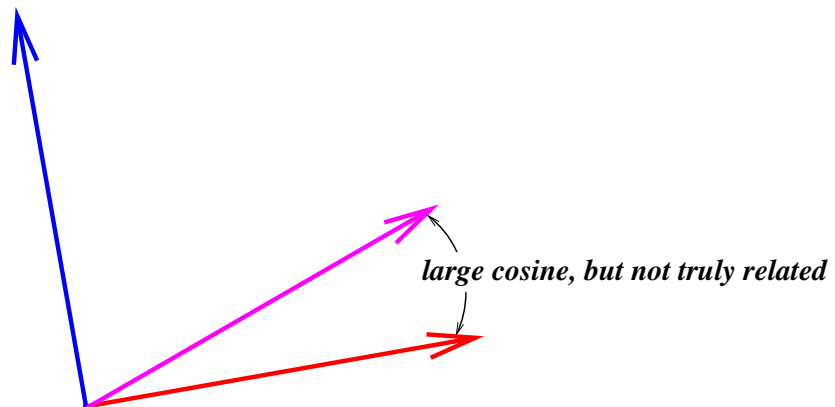
*Documents:*



*Term-document matrix D:*

1	0	0	auto
1	0	0	bonnet
1	0	0	boot
0	1	0	car
0	1	1	emissions
1	0	0	engine
0	0	1	hidden
0	1	0	hood
1	0	0	lorry
0	1	1	make
0	0	1	Markov
0	1	1	model
0	0	1	normalize
0	0	0	tyres
0	1	0	trunk
1	0	0	tyres

*Vector space:*



## Approach: Subspace Projection

Given a term-document matrix  $D$ , **project** the document vectors into a different subspace so that vector cosines more accurately represent semantic similarity.

In a **lower dimensional** space, synonym vectors may not be orthogonal.

**Latent Semantic Indexing** [Deerwester, Dumais, Furnas, Landauer, Harshman 1990] seeks to uncover such hidden semantic relations through projection methods.

Applications (a sampling): [Dumais 1991, 1993, 1994, 1995], [Landauer+Littman 1990], [Foltz 1990, 1996], [Foltz+Dumais 1992], [Dumais+Nielsen 1992], [Foltz+al 1996, 1998a, 1998b], [Landauer+al 1997, 1998], [Schütze+Silverstein 1997], [Soboroff+al 1998], [Wolfe+al 1998], [Weimer-Hastings, 1999], [Jiang+al 1999b], [Kurimo 2000] [Weimer-Hastings+al, 1999], [Schone+Jurafsky 2000, 2001]

## Talk Outline

- Introduction: Latent Semantic Indexing (LSI)
- A new analysis: relating LSI's potential to the **uniformity** of the underlying topic-document distribution [Ando+Lee 2001]
- A new algorithm: Iterative Residual Rescaling **automatically compensates for non-uniformity** [Ando 2000; Ando+Lee 2001]
- Experimental results

# Introduction to LSI

# Singular Value Decomposition

The SVD is the matrix factorization underlying LSI.

Let the  $m \times n$  term-document matrix  $D$  have rank  $r$ .

$$\begin{array}{c}
 \mathbf{D} \\
 \left[ \begin{array}{c} | \\ | \\ | \\ \vdots \\ | \\ | \\ | \\ | \end{array} \right] \\
 \begin{array}{c} d_1 \quad d_2 \quad \dots \quad d_n \end{array}
 \end{array}
 =
 \begin{array}{c}
 \mathbf{U} \\
 \left[ \begin{array}{c} | \\ | \\ | \\ \vdots \\ | \\ | \end{array} \right] \\
 \begin{array}{c} u_1 \dots u_r \end{array}
 \end{array}
 \times
 \begin{array}{c}
 \mathbf{\Sigma} \\
 \left[ \begin{array}{ccc} \sigma_1 & & 0 \\ & \sigma_2 & \\ 0 & & \ddots \\ & & & \sigma_r \end{array} \right]
 \end{array}
 \times
 \begin{array}{c}
 \mathbf{V}^T \\
 \left[ \begin{array}{c} \text{---} v_1 \text{---} \\ \text{---} v_2 \text{---} \\ \vdots \\ \text{---} v_r \text{---} \end{array} \right]
 \end{array}
 \end{array}$$

$u_i$ : **left singular vectors**; form a basis for  $\text{range}(D)$

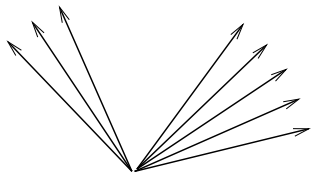
$\sigma_i$ : **singular values** (assume in sorted order); all positive

(Each  $u_i$  is an *eigenvector* of  $DD^T$  with eigenvalue  $\sigma_i^2$ )

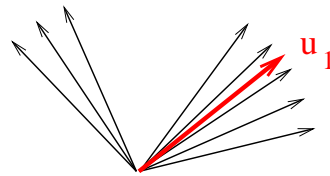


# SVD: Geometric View

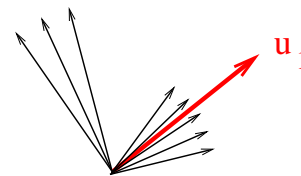
Recall: 
$$\begin{bmatrix} | & & | \\ \vdots & & \vdots \\ | & & | \end{bmatrix}^d = \begin{bmatrix} | & & | \\ \vdots & & \vdots \\ | & & | \end{bmatrix}^u \begin{bmatrix} \sigma_1 & & \\ & \sigma_2 & \\ & & \sigma_r \end{bmatrix} \begin{bmatrix} | & & | \\ \vdots & & \vdots \\ | & & | \end{bmatrix}^{v'}$$



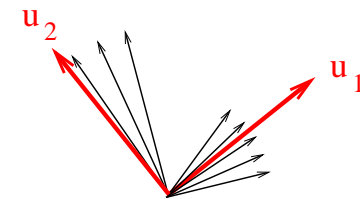
Start with document vectors



Choose direction  $\mathbf{u}$  maximizing projections  
( $\sigma$  : "sizes" of max. projection)



Compute residuals (subtract projections)



Repeat to get next  $\mathbf{u}$  (orthogonal to previous  $\mathbf{u}_i$ 's)

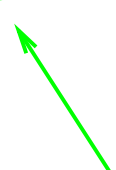
More formally, find  $r = \text{rank}(D)$  vectors such that

$$\mathbf{u} = \arg \max_{\mathbf{x}: |\mathbf{x}|=1} \sum_{j=1}^n |r_j|^2 \cos^2(\angle(\mathbf{x}, r_j)) \quad (\text{"weighted average"})$$

# Latent Semantic Indexing

LSI projects  $D$  into the  $h$ -dimensional subspace spanned by  $u_1, \dots, u_h$ .

$$\begin{array}{c}
 \mathbf{D}' \\
 \left[ \begin{array}{c} | \\ | \\ | \\ \dots \\ | \\ | \\ | \end{array} \right] \\
 \begin{array}{c} d_1 \quad d_2 \quad \dots \quad d_n \\ | \\ | \\ | \end{array}
 \end{array}
 =
 \begin{array}{c}
 \mathbf{U} \\
 \left[ \begin{array}{c} | \\ | \\ | \\ \dots \\ | \\ | \\ | \end{array} \right] \\
 \begin{array}{c} u_1 \quad \dots \quad u_r \\ | \\ | \\ | \end{array}
 \end{array}
 \times
 \begin{array}{c}
 \mathbf{\Sigma}' \\
 \left[ \begin{array}{c} \sigma_1 \quad \dots \quad \sigma_h \quad 0 \\ \vdots \quad \vdots \quad \vdots \quad \vdots \\ 0 \quad \dots \quad \sigma_{h+1} \quad \dots \quad \sigma_r \end{array} \right]
 \end{array}
 \times
 \begin{array}{c}
 \mathbf{V}^T \\
 \left[ \begin{array}{c} \text{---} v_1 \text{---} \\ \text{---} v_2 \text{---} \\ \vdots \\ \text{---} v_r \text{---} \end{array} \right]
 \end{array}$$


  
 Set all but the first  $h$  to 0

**Theorem:** This is the optimum (in two-norm) rank- $h$  approximation to  $D$ . (Note that it selects the  $h$  basis vectors that maximize projections.)

## LSI (continued)

Recall: LSI computes the optimum rank- $h$  approximation to  $D$ .

**But this does not mean LSI does the best job at representing document relationships** – just the best job at being close to  $D$ .

“Whether [LSI] is superior in practical situations with general collections remains to be verified.” Baeza-Yates and Ribeiro-Neto, *Modern Information Retrieval*, 1999.

(See e.g. [Dumais+al 1998])

**We desire an analysis based on the underlying semantic relationships.**

# Analyzing LSI

# Topic Model

For a given set of  $n$  documents, we assume there exists the following unknown quantities:

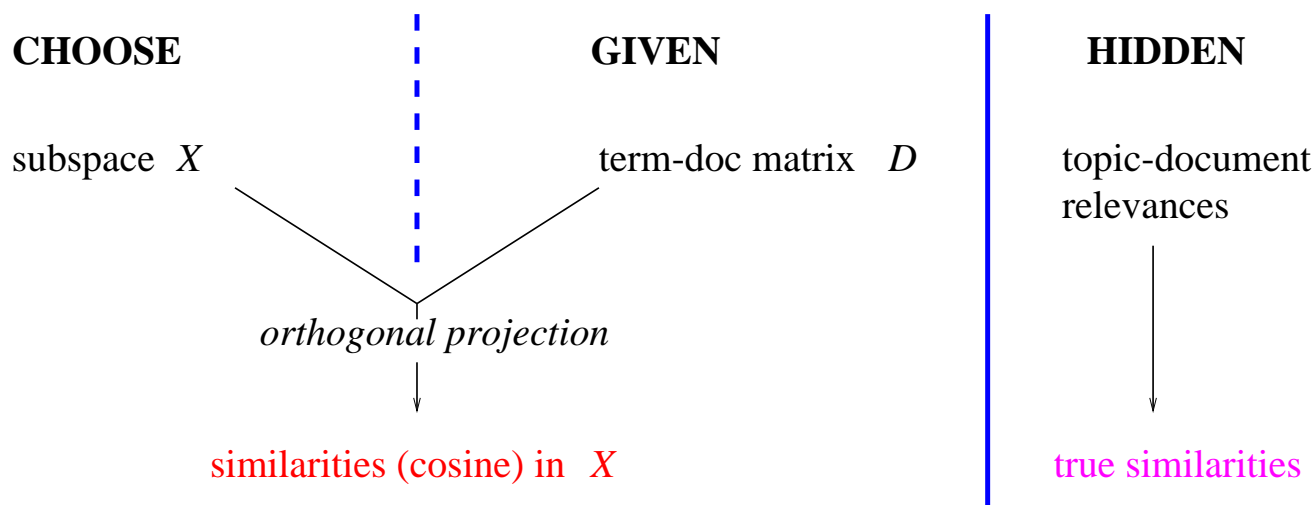
- a set of  $k < n$  underlying topics
- (normalized) document-topic relevance scores

These define the hidden true topic-based document similarities:

$$\text{sim}(\text{doc}, \text{doc}') = \sum_{\text{topics } t} \text{rel}(\text{doc}, t) \times \text{rel}(\text{doc}', t)$$

and we desire a subspace in which vector cosines approximate these true similarities closely.

# Subspace Projections



Let  $\mathcal{X}^{opt}$  be the subspace with *minimum* similarity error (and dimensionality)

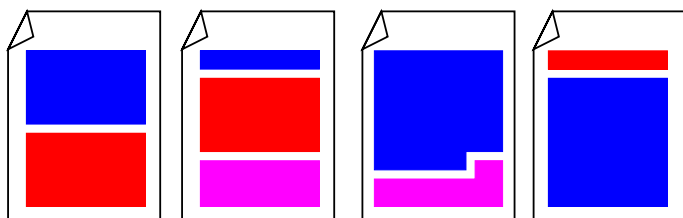
where  $\text{error}(\mathcal{X}) = \left\| \left[ \text{sim}(\text{doc}_i, \text{doc}_j) \right] - \underline{d_i^{\mathcal{X}} \cdot d_j^{\mathcal{X}}} \right\|_2$

How close is  $\mathcal{X}^{LSI}$  to  $\mathcal{X}^{opt}$ ? Let's define some useful quantities ...

## Dominance and Non-Uniformity

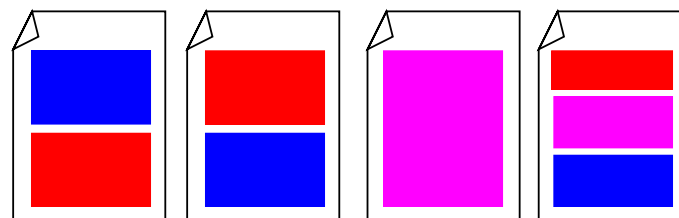
The (hidden) **dominance** of a topic in the document collection is defined as:

$$\text{Dom}(t) = \sqrt{\sum_{\text{doc}} \text{rel}(\text{doc}, t)^2}$$



$\text{Dom} \gg \text{Dom} \gg \text{Dom}$

*non-uniformity* =  $\text{Dom} / \text{Dom}$  is high



$\text{Dom} = \text{Dom} = \text{Dom}$

non-uniformity is low

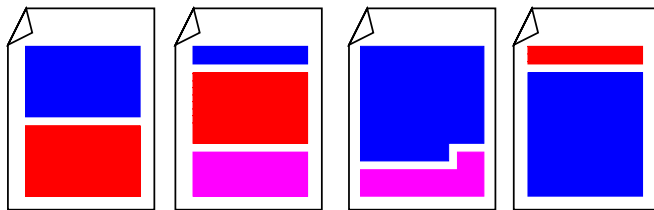
We assume a dominance ordering on the topics, most dominant first.

Intuitively, less dominant topics risk being “lost”.

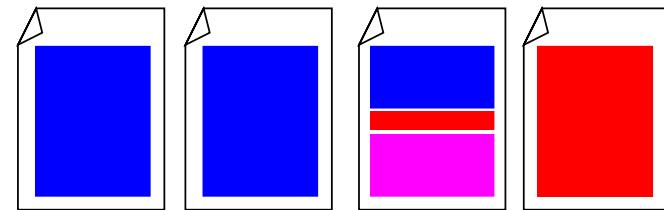
## Document Sharing and Difficulty

The (hidden) degree to which topics share documents is defined as:

$$\text{DocSharing} = \sqrt{\sum_{t \neq t'} \left( \sum_{\text{doc}} \text{rel}(\text{doc}, t) \text{rel}(\text{doc}, t') \right)^2}$$



more document sharing among topics



less document sharing (same dominances)

Intuitively, when document sharing is high, distinguishing between topics is difficult. ([Papadimitriou+al 1997] assume low document sharing.)



## Structure of Main Result

The distance between  $\mathcal{X}^{LSI}$  and  $\mathcal{X}^{opt}$  can be bounded by a function of:

- $\text{error}(\mathcal{X}^{VSM})$  and  $\text{error}(\mathcal{X}^{opt})$ ,
- the amount of document sharing between topics, and
- **the non-uniformity of the topic-document distribution**, as measured by a ratio of topic dominances.

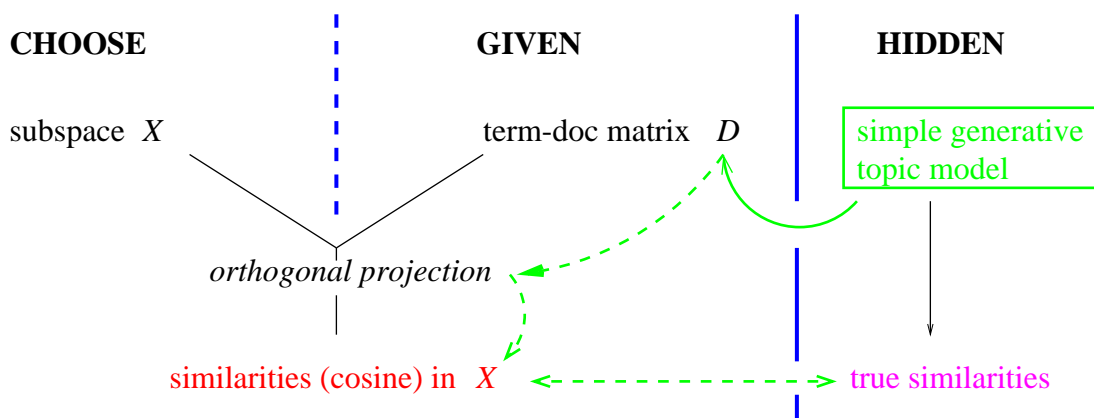
assuming that  $\text{error}(\mathcal{X}^{VSM})$  doesn't swamp certain topic dominances.

The proof relies on:

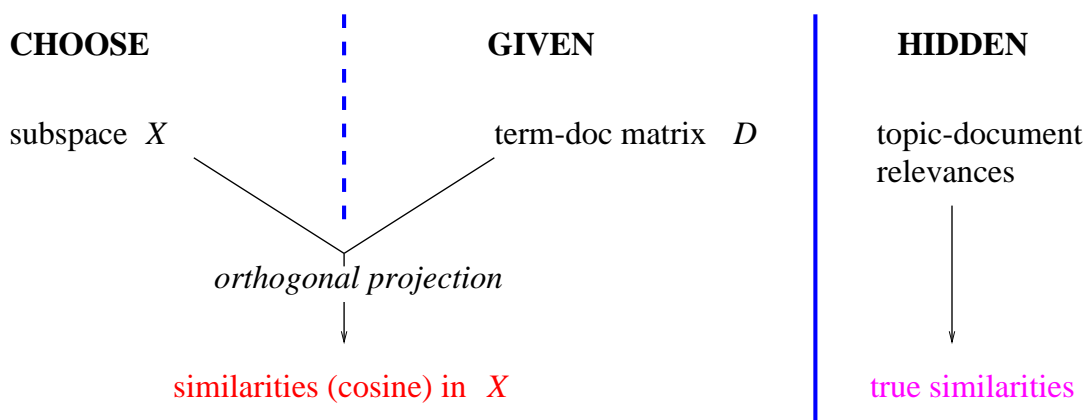
- 1) a *subspace perturbation theorem* [Stewart 1973, Davis+Kahan 1970] relating subspace distances to certain singular values, and
- 2) *sensitivity* theorems relating certain singular values to topic dominances.

## Related Work

[Papadimitriou+al 1997, Azar+al 2001, Story 1996, Ding 1999] etc. assume a *generative* model in which LSI “works”



Cf. our framework:



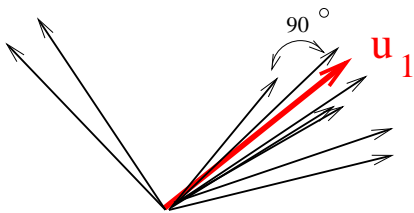
(cf. [Bartell+Cottrell+Belew 1992; 1995, Isbell+Viola 1998])

# The Iterative Residual Rescaling (IRR) Algorithm

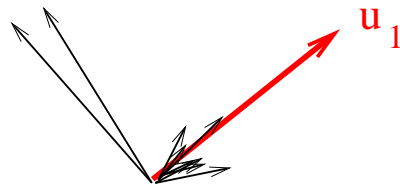
## Non-uniformity: Geometric Interpretation

LSI finds a sequence of  $h$  basis vectors such that

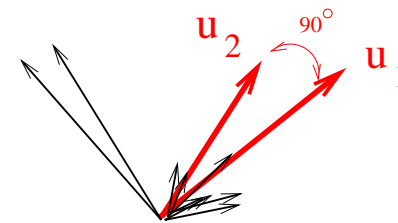
$$\mathbf{u} = \arg \max_{\mathbf{x}: |\mathbf{x}|=1} \sum_{j=1}^n |r_j|^2 \cos^2(\angle(\mathbf{x}, r_j)) \quad (\text{"weighted average"})$$



Choose direction  $\mathbf{u}$   
maximizing projections



Compute residuals



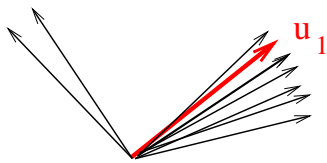
Repeat to get next  $\mathbf{u}$   
(orthogonal to previous  $\mathbf{u}_i$ 's)

dominant topics bias the choice

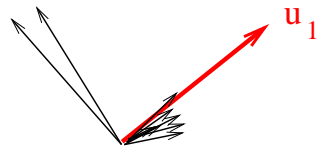
## IRR: First Version

$$\mathbf{u} = \arg \max_{\mathbf{x}: |\mathbf{x}|=1} \sum_{j=1}^n |r_j|^2 \cos^2(\angle(\mathbf{x}, r_j)) \quad (\text{"weighted average"})$$

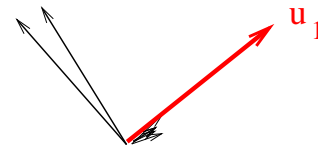
Compensate for non-uniformity by **rescaling** the residuals by the  $q$ th power of their length at each iteration. [Ando 2000]



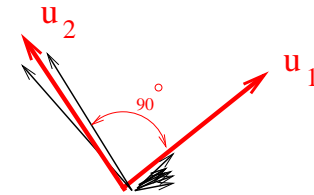
Choose direction  $\mathbf{u}$   
maximizing projections



Compute residuals



Rescale residuals  
(relative diffs rise)



Repeat to get next  $\mathbf{u}$   
(orthogonal to previous  $\mathbf{u}_i$ 's)

Good results, but how do we pick the scaling factor  $q$ ?

We need a *principled* way to choose amount of re-scaling.

## Scaling Factor Determination

Consider the following function of non-uniformity:  $\sum_t (\text{Dom}(t)^2 / n)^2$

- one giant topic  $\rightarrow 1$
- $k$  same-size topics with no document sharing  $\rightarrow 1/k$

We'd like to set the scaling factor  $q$  to this quantity to compensate for non-uniformity ...

but we don't know it!

We can roughly *approximate* it in our model by

$\sum_{d_i, d_j} \cos^2(\angle(d_i, d_j)) / n^2$ . (coarse assumptions: small input error, single-topic documents)

We set  $q$  to a linear function of this approximation.

# Experiments

## Experimental Framework: Data

We used TREC documents, with topic labels as validation. (Stop-words removed; no term weighting; only single-topic documents (no topic sharing) to facilitate scoring).

**Controlled distributions:** we artificially altered topic dominances to study their effects on LSI and IRR's performance

- For a set of  $k$  topics, for a sequence of increasingly non-uniform distributions, ten 50-document sets were selected randomly for each.

**Uncontrolled distributions:** we simulated retrieval results.

- For each keyword in a randomly-chosen set of 15, all documents containing that keyword were selected to create a document set.



## Evaluation Metrics

**Kappa average precision**: degree to which same-topic document pairs have high similarity scores, corrected for chance

**Clustering score**: degree to which a clustering has “pure” clusters but preserves topic integrity [cf. Slonim and Tishby 2000]

We record the **floor** and **ceiling** results over 6 clustering algorithms.

**A high-quality subspace should enable good results for *many* clustering algorithms.**

[To simplify presentation, we do not discuss dimensionality selection issues]

(Switch to slides on experimental results now)