

Lecture 10

*Lecturer: Lukas Kroc**Scribe: Nitin Gupta*

1 Introduction

Algorithms

- Don't ask complexity
- Don't ask correctness
- Ask them if they are useful
- Achieve communication at Shannon limit

Examples

- Belief Propagation in Bayesian Networks
- Viterbi Algorithm (PDAs)
- Kalman Filter (Airplanes)
- Turbo Algorithm - first to meet Shannon limit

Outline

- Problem Statement
- Graphical Models
 - Bayesian Networks
 - Factor Graphs
 - Pairwise Markov Random Fields
- Equivalence of Graphical Models

Reference: Yedidia, Freeman, Weiss. "Understanding Belief Propagation and its generalization".

2 Problem Statement

- Discrete system, state vector \vec{x} , $x_i \in Dom$
- Weight of each state (configuration), $weight(\vec{x}) \in \mathbb{R}_0^+$
- Represent the weight concisely \Rightarrow Graphical Models
 - Graph (directed or undirected)
 - $V \sim$ state variables
 - $E \sim$ (in)dependencies

– Weights are “distributed” among the nodes and edges

Special Case

Configurations $(\vec{x}) \sim$ possible worlds in some problem space

$weight(\vec{x}) = P[\vec{X} = \vec{x}]$, where P is the probability of some event occurring.

- Joint Probability $P[\vec{X} = \vec{x}]$
- Marginal Probability $P[X_i = x_i] = \sum_{\vec{x}_{-i}} P[\vec{X} = \vec{x}]$, where $\vec{x}_i \triangleq (x_j)_{j \neq i}$

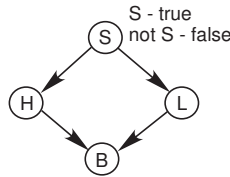
Questions (Tasks/Queries)

- Compute the marginal probabilities
- Compute the most likely configuration $\operatorname{argmax}_{\vec{x}} weight(\vec{x})$

Inference is the mechanism to answer queries ($\#P$ -complete problems)

3 Bayesian Networks

- Directed Acyclic Graph (DAG)
- V = state variables
- Independence Property: X_i is independent of Non-descendants(X_i) given Parents(X_i)

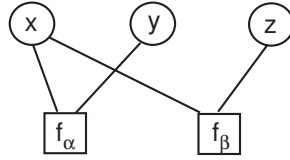


$$\begin{aligned}
 P(s, h, l, b) &= P(b|s, h, l) P(s, h, l) \\
 &= P(b|h, l) P(h, l|s) P(s) \\
 &= P(b|h, l) P(h|s) P(l|s) P(s) \\
 \Rightarrow P[\vec{X} = \vec{x}] &= \prod_i P[X_i | Par(X_i)]
 \end{aligned}$$

- In Bayesian Networks, we may compute the probability of a given node given some evidence $P[X_i = x_i | evidence]$

4 Factor Graphs

- Undirected bipartite graph
- Two kinds of nodes:
 1. Variables $\bigcirc x_i \in Dom$
 2. Factors $\square f_\alpha(\vec{x}_\alpha) \in \mathbb{R}_0^+$, where \vec{x}_α is a subvector of \vec{x}
- $weight(\vec{x}) \triangleq \prod_\alpha f_\alpha(\vec{x}_\alpha)$



- SAT: $(x \vee y) \wedge (\neg x \vee z)$
Let $\alpha = (x \vee y)$ and $\beta = (\neg x \vee z)$

$$f_\alpha = \begin{cases} 1 & \text{iff } (x \vee y) \\ 0 & \text{otherwise} \end{cases}$$

$$f_\beta = \begin{cases} 1 & \text{iff } (\neg x \vee z) \\ 0 & \text{otherwise} \end{cases}$$

- Probabilistic Interpretation

$$\begin{aligned}
 P[\vec{X} = \vec{x}] &\propto \text{weight}(\vec{x}) \\
 &= \frac{1}{z} \text{weight}(\vec{x}), \text{ where } z = \sum_{\vec{x}} \text{weight}(\vec{x})
 \end{aligned}$$