

## Lecture 5 Shortest Paths and Transitive Closure

### 5.1 Single-Source Shortest Paths

Let  $G = (V, E)$  be an undirected graph and let  $\ell$  be a function assigning a nonnegative length to each edge. Extend  $\ell$  to domain  $V \times V$  by defining  $\ell(v, v) = 0$  and  $\ell(u, v) = \infty$  if  $(u, v) \notin E$ . Define the *length*<sup>2</sup> of a path  $p = e_1 e_2 \dots e_n$  to be  $\ell(p) = \sum_{i=1}^n \ell(e_i)$ . For  $u, v \in V$ , define the *distance*  $d(u, v)$  from  $u$  to  $v$  to be the length of a shortest path from  $u$  to  $v$ , or  $\infty$  if no such path exists. The *single-source shortest path problem* is to find, given  $s \in V$ , the value of  $d(s, u)$  for every other vertex  $u$  in the graph.

If the graph is unweighted (*i.e.*, all edge lengths are 1), we can solve the problem in linear time using BFS. For the more general case, here is an algorithm due to Dijkstra [28]. Later on we will give an  $O(m + n \log n)$  implementation using Fibonacci heaps. The algorithm is a type of greedy algorithm: it builds a set  $X$  vertex by vertex, always taking vertices closest to  $X$ .

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<sup>2</sup>In this context, the terms “length” and “shortest” applied to a path refer to  $\ell$ , not the number of edges in the path.

**Algorithm 5.1 (Dijkstra's Algorithm)**

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 $X := \{s\};$ 
 $D(s) := 0;$ 
for each  $u \in V - \{s\}$  do
     $D(u) := \ell(s, u);$ 
while  $X \neq V$  do
    let  $u \in V - X$  such that  $D(u)$  is minimum;
     $X := X \cup \{u\};$ 
    for each edge  $(u, v)$  with  $v \in V - X$  do
         $D(v) := \min(D(v), D(u) + \ell(u, v))$ 
end while

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The final value of  $D(u)$  is  $d(s, u)$ . This algorithm can be proved correct by showing that the following two invariants are maintained by the while loop:

- for any  $u$ ,  $D(u)$  is the distance from  $s$  to  $u$  along a shortest path through only vertices in  $X$ ;
- for any  $u \in X$ ,  $v \notin X$ ,  $D(u) \leq D(v)$ .

**5.2 Reflexive Transitive Closure**

Let  $E$  denote the adjacency matrix of the directed graph  $G = (V, E)$ . Using Boolean matrix multiplication, the matrix  $E^2$  has a 1 in position  $uv$  iff there is a path of length exactly 2 from vertex  $u$  to vertex  $v$ ; *i.e.*, iff there exists a vertex  $w$  such that  $(u, w), (w, v) \in E$ . Similarly, one can prove by induction on  $k$  that  $(E^k)_{uv} = 1$  iff there is a path of length exactly  $k$  from  $u$  to  $v$ .

The reflexive transitive closure of  $G$  is

$$\begin{aligned}
 E^* &= I \vee E \vee E^2 \vee \dots \\
 &= I \vee E \vee E^2 \vee \dots \vee E^{n-1} \\
 &= (I \vee E)^{n-1}.
 \end{aligned}$$

The infinite join is equal to the finite one because if there is a path connecting  $u$  and  $v$ , then there is one of length at most  $n - 1$ .

Suppose that two  $n \times n$  Boolean matrices can be multiplied in time  $M(n)$ . Then  $E^* = (I \vee E)^{n-1}$  can be calculated in time  $O(M(n) \log n)$  by squaring  $E$   $\log n$  times. We will show below how to calculate  $E^*$  in time  $O(M(n))$ . Conversely, if there is an algorithm to compute  $E^*$  in time  $T(n)$ , then  $M(n)$  is  $O(T(n))$  (under the reasonable assumption that  $M(3n)$  is  $O(M(n))$ ): to multiply  $A$  and  $B$ , place them strategically into a  $3n \times 3n$  matrix, then take its reflexive transitive closure:

$$\begin{bmatrix} 0 & A & 0 \\ 0 & 0 & B \\ 0 & 0 & 0 \end{bmatrix}^* = \begin{bmatrix} I & A & AB \\ 0 & I & B \\ 0 & 0 & I \end{bmatrix}.$$

The product  $AB$  can be read off from the upper right-hand block.

Here is a divide and conquer algorithm to find  $E^*$  in time  $M(n)$ .

**Algorithm 5.2 (Reflexive Transitive Closure)**

1. Divide  $E$  into 4 submatrices  $A, B, C, D$  of size roughly  $\frac{n}{2} \times \frac{n}{2}$  such that  $A$  and  $D$  are square.

$$E = \left[ \begin{array}{c|c} A & B \\ \hline C & D \end{array} \right]$$

2. Recursively compute  $D^*$ . Compute

$$F = A + BD^*C .$$

Recursively compute  $F^*$ .

3. Set

$$E^* = \left[ \begin{array}{c|c} F^* & F^*BD^* \\ \hline D^*CF^* & D^* + D^*CF^*BD^* \end{array} \right] .$$

Essentially, we are partitioning the set of vertices into two disjoint sets  $U$  and  $V$ , where  $A$  describes the edges from  $U$  to  $U$ ,  $B$  describes edges from  $U$  to  $V$ ,  $C$  describes edges from  $V$  to  $U$ , and  $D$  describes edges from  $V$  to  $V$ . We compute reflexive transitive closures on these sets recursively and use this information to describe the reflexive transitive closure of  $E$ . Note that we compute two reflexive transitive closures, a few matrix multiplications (whose complexity is given by  $M$ ) and a few matrix additions (whose complexity is assumed to be quadratic) of matrices of roughly half the size of  $E$ . This gives the recurrence

$$T(n) = 2T\left(\frac{n}{2}\right) + cM\left(\frac{n}{2}\right) + d\left(\frac{n}{2}\right)^2$$

where  $c$  and  $d$  are constants. Under the quite reasonable assumption that  $M(2n) \geq 4M(n)$ , the solution to this recurrence is  $O(M(n))$ .

### 5.3 All-Pairs Shortest Paths

Let  $E$  denote the adjacency matrix of a directed graph with edge weights. Replace the 1's in  $E$  by the edge weights and the 0's by  $\infty$ . Apply Algorithm 5.2 to calculate  $E^*$ , except use  $+$  instead of  $\wedge$  and  $\min$  instead of  $\vee$ . We will show next time that this solves the all-pairs shortest path problem.