

Lecture 5: Rendering Equation

Chapter 2 in Advanced GI

Fall 2004

Kavita Bala

Computer Science

Cornell University

Radiometry

- Radiometry: measurement of light energy
- Defines relation between
 - Power
 - Energy
 - Radiance
 - Radiosity

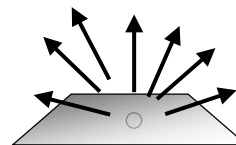
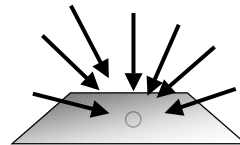
Power

- Energy: Symbol: Q ; unit: Joules
- Power: Energy per unit time (dQ/dt)
 - Aka. “radiant flux” in this context
- Symbol: P or Φ ; unit: Watts (Joules / sec)
 - Photons per second
 - All further quantities are derivatives of P (flux densities)

© Kavita Bala, Computer Science, Cornell University

Irradiance

- Power per unit area (dP/dA)
 - That is, area density of power
 - It is defined with respect to a surface
- Symbol: E ; unit: W / m^2
 - Measurable as power on a small-area detector
 - Area power density exiting a surface is called *radiant exitance* (M) or *radiosity* (B) but has the same units



© Kavita Bala, Computer Science, Cornell University

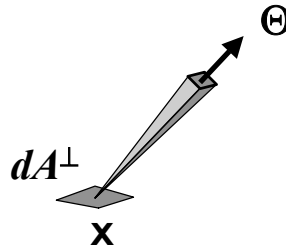
Radiance

- Radiance is radiant energy at x in direction θ : 5D function

- $L(x \rightarrow \Theta)$: Power
 - per unit projected surface area
 - per unit solid angle

$$L(x \rightarrow \Theta) = \frac{d^2 P}{dA^\perp d\omega_\Theta}$$

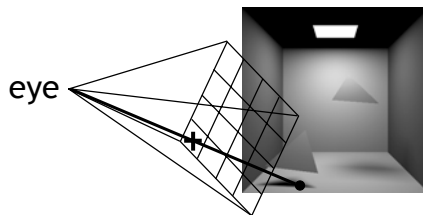
- units: Watt / m².sr



© Kavita Bala, Computer Science, Cornell University

Why is radiance important?

- Response of a sensor (camera, human eye) is proportional to radiance



- Pixel values in image proportional to radiance received from that direction

© Kavita Bala, Computer Science, Cornell University

Relationships

- Radiance is the fundamental quantity

$$L(x \rightarrow \Theta) = \frac{d^2 P}{dA^\perp d\omega_\Theta}$$

- Power:

$$P = \int_{\text{Area}} \int_{\text{Solid Angle}} L(x \rightarrow \Theta) \cdot \cos \theta \cdot d\omega_\Theta \cdot dA$$

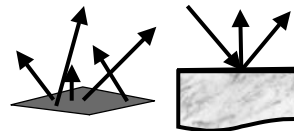
- Radiosity:

$$B = \int_{\text{Solid Angle}} L(x \rightarrow \Theta) \cdot \cos \theta \cdot d\omega_\Theta$$

© Kavita Bala, Computer Science, Cornell University

Outline

- Light Model



- Radiance

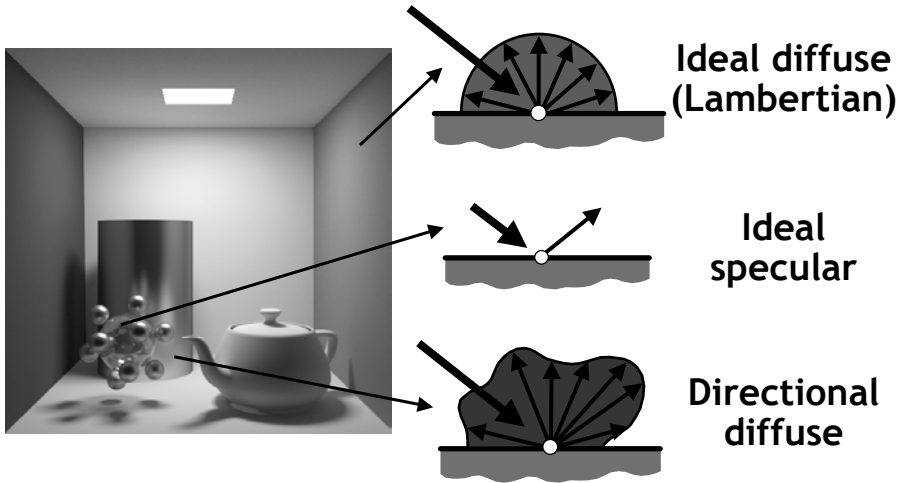
- **Materials: Interaction with light**



- Rendering equation

© Kavita Bala, Computer Science, Cornell University

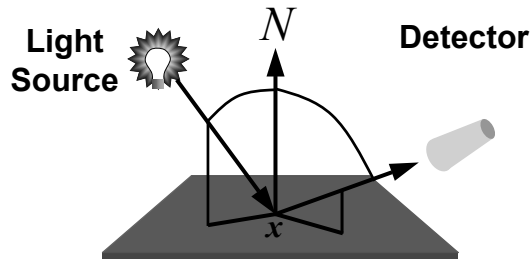
Materials - Three Forms



© Kavita Bala, Computer Science, Cornell University

BRDF

- Bidirectional Reflectance Distribution Function



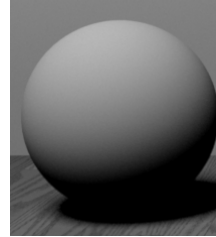
$$f_r(x, \Psi \rightarrow \Theta) = \frac{dL(x \rightarrow \Theta)}{dE(x \leftarrow \Psi)} = \frac{dL(x \rightarrow \Theta)}{L(x \leftarrow \Psi) \cos(N_x, \Psi) d\omega_\Psi}$$

© Kavita Bala, Computer Science, Cornell University

BRDF special case: ideal diffuse

Pure Lambertian

$$f_r(x, \Psi \rightarrow \Theta) = \frac{\rho_d}{\pi}$$



$$\rho_d = \frac{\text{Energy}_{out}}{\text{Energy}_{in}} \quad 0 \leq \rho_d \leq 1$$

© Kavita Bala, Computer Science, Cornell University

Properties of the BRDF

- Reciprocity:

$$f_r(x, \Psi \rightarrow \Theta) = f_r(x, \Theta \rightarrow \Psi)$$

- Therefore, notation: $f_r(x, \Psi \leftrightarrow \Theta)$
- Important for bidirectional tracing

© Kavita Bala, Computer Science, Cornell University

Properties of the BRDF

- Bounds:

$$0 \leq f_r(x, \Psi \leftrightarrow \Theta) \leq \infty$$

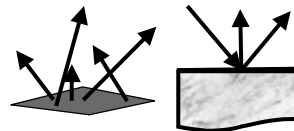
- Energy conservation:

$$\forall \Psi \int_{\Theta} f_r(x, \Psi \leftrightarrow \Theta) \cos(N_x, \Theta) d\omega_{\Theta} \leq 1$$

© Kavita Bala, Computer Science, Cornell University

Outline

- Light Model



- Radiance

- Materials: Interaction with light



- Rendering equation

© Kavita Bala, Computer Science, Cornell University

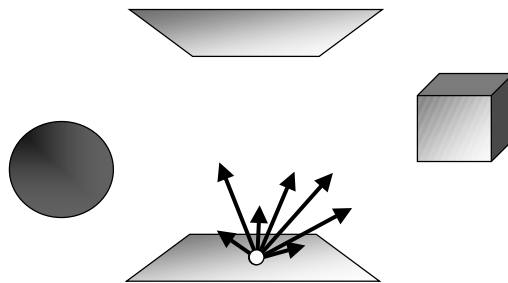
Light Transport

- Goal
 - Describe steady-state radiance distribution in scene
- Assumptions:
 - Geometric Optics
 - Achieves steady state instantaneously
- Related:
 - Neutron Transport (neutrons)
 - Gas Dynamics (molecules)

© Kavita Bala, Computer Science, Cornell University

Radiance represents equilibrium

- Radiance values at all points in the scene and in all directions expresses the equilibrium
- 4D function: only on surfaces



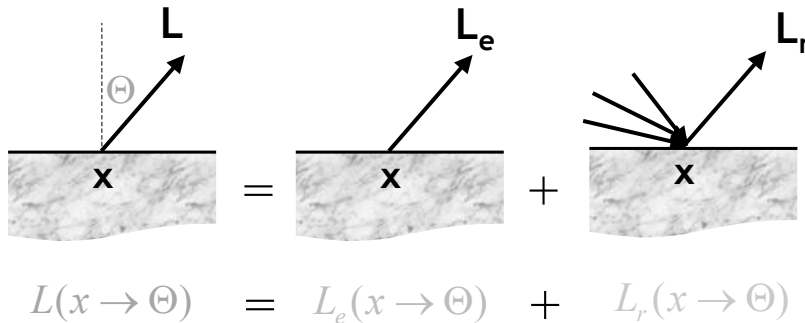
© Kavita Bala, Computer Science, Cornell University

Rendering Equation (RE)

- RE describes energy transport in scene
- Input
 - Light sources
 - Surface geometry
 - Reflectance characteristics of surfaces
- Output: value of radiance at all surface points in all directions

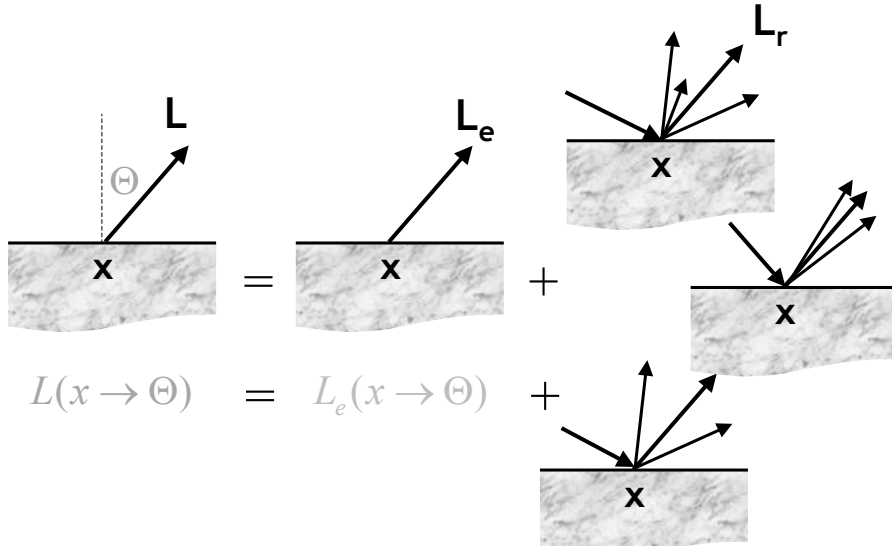
© Kavita Bala, Computer Science, Cornell University

Rendering Equation


$$L(x \rightarrow \Theta) = L_e(x \rightarrow \Theta) + L_r(x \rightarrow \Theta)$$

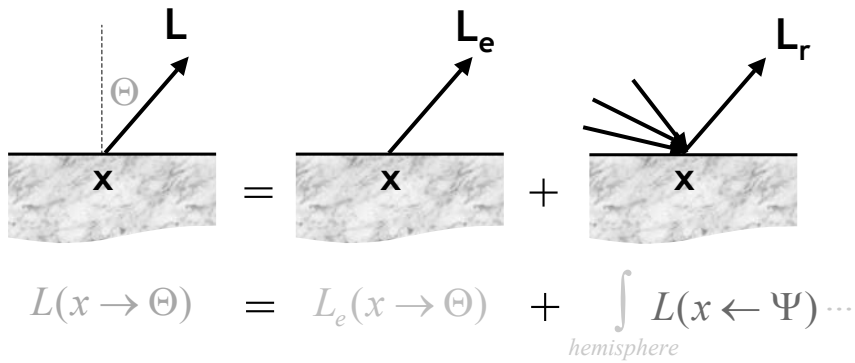
© Kavita Bala, Computer Science, Cornell University

Rendering Equation



© Kavita Bala, Computer Science, Cornell University

Rendering Equation



© Kavita Bala, Computer Science, Cornell University

Rendering Equation

$$f_r(x, \Psi \leftrightarrow \Theta) = \frac{dL(x \rightarrow \Theta)}{dE(x \leftarrow \Psi)}$$

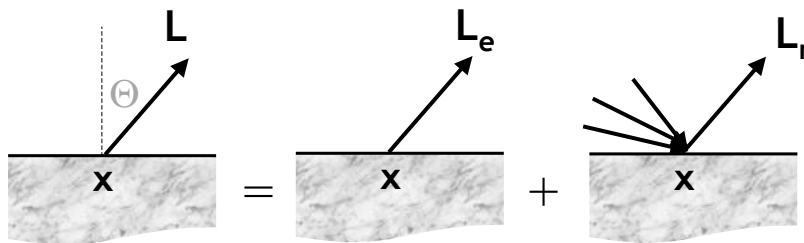
$$dL(x \rightarrow \Theta) = f_r(x, \Psi \leftrightarrow \Theta) dE(x \leftarrow \Psi)$$

$$dL(x \rightarrow \Theta) = f_r(x, \Psi \leftrightarrow \Theta) L(x \leftarrow \Psi) \cos(N_x, \Psi) d\omega_\Psi$$

$$L_r(x \rightarrow \Theta) = \int_{\text{hemisphere}} f_r(x, \Psi \leftrightarrow \Theta) L(x \leftarrow \Psi) \cos(N_x, \Psi) d\omega_\Psi$$

© Kavita Bala, Computer Science, Cornell University

Rendering Equation

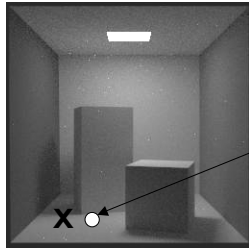


$$L(x \rightarrow \Theta) = L_e(x \rightarrow \Theta) + \int_{\text{hemisphere}} L(x \leftarrow \Psi) f_r(x, \Psi \leftrightarrow \Theta) \cos(N_x, \Psi) d\omega_\Psi$$

- Applicable for each wavelength

© Kavita Bala, Computer Science, Cornell University

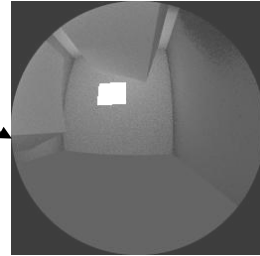
Rendering Equation



$$\underline{L(x \rightarrow \Theta)} = L_e(x \rightarrow \Theta) +$$

$$\int_{\text{hemisphere}} \underline{L(x \leftarrow \Psi)} f_r(x, \Psi \leftrightarrow \Theta) \cos(\mathbf{N}_x, \Psi) d\omega_\Psi$$

incoming radiance



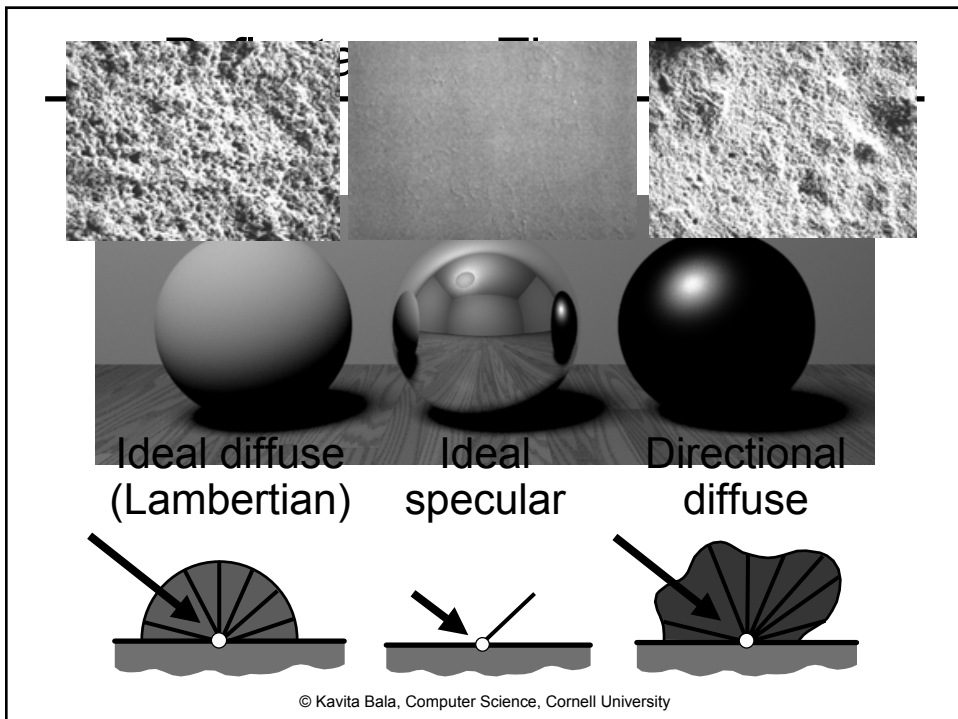
© Kavita Bala, Computer Science, Cornell University

Summary

- Geometric Optics
- Goal:
 - to compute steady-state radiance values in scene
- Rendering equation:
 - mathematical formulation of problem that global illumination algorithms must solve

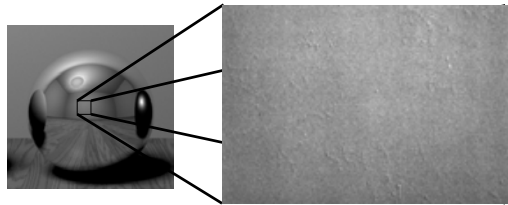
© Kavita Bala, Computer Science, Cornell University

Shading Models



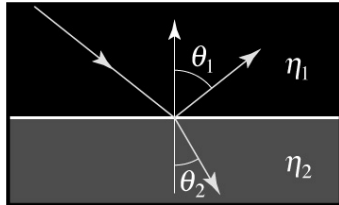
Ideal Specular Reflection

- Calculated from Fresnel's equations
- Exact for polished surfaces
- Basis of early ray-tracing methods



© Kavita Bala, Computer Science, Cornell University

Fresnel Equations



$$\eta_1 \sin \theta_1 = \eta_2 \sin \theta_2$$

$$F_p = \frac{\eta_2 \cos \theta_1 - \eta_1 \cos \theta_2}{\eta_2 \cos \theta_1 + \eta_1 \cos \theta_2}$$

$$F_s = \frac{\eta_1 \cos \theta_1 - \eta_2 \cos \theta_2}{\eta_1 \cos \theta_1 + \eta_2 \cos \theta_2}$$

© Kavita Bala, Computer Science, Cornell University

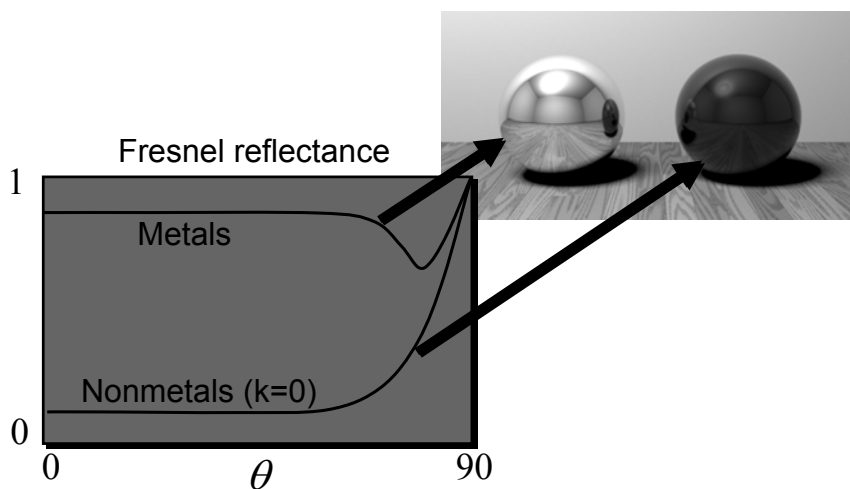
Fresnel Reflectance

$$F = \frac{(|F_s|^2 + |F_p|^2)}{2} \quad \text{for unpolarized light}$$

- Equations apply for metals and nonmetals
 - for metals, use complex index $\eta = n+ik$
 - for nonmetals, $k=0$

© Kavita Bala, Computer Science, Cornell University

Metal vs. Nonmetal



© Kavita Bala, Computer Science, Cornell University

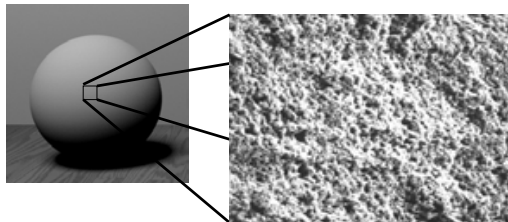
Mies van der Rohe's unbuilt Courtyard House



© Kavita Bala, Computer Science, Cornell University

Ideal Diffuse Reflection

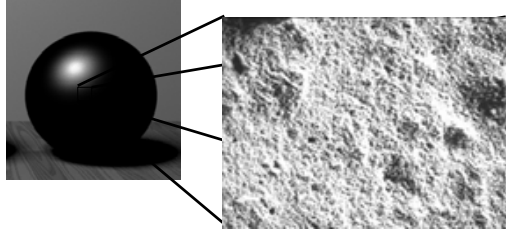
- Characteristic of multiple scattering materials
- An idealization but reasonable for matte surfaces
- Basis of most radiosity methods
- BRDF is a constant function



© Kavita Bala, Computer Science, Cornell University

Directional Diffuse Reflection

- Characteristic of most rough surfaces
- Described by the BRDF



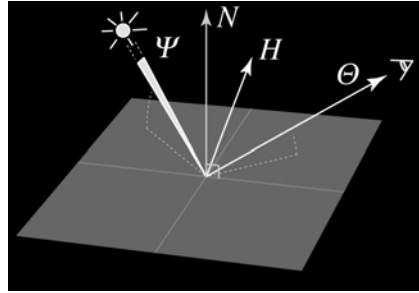
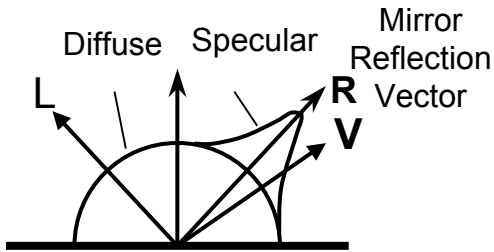
© Kavita Bala, Computer Science, Cornell University

Classes of Models for the BRDF

- Plausible simple functions
 - Phong 1975;
- Physics-based models
 - Cook/Torrance, 1981; He et al. 1992;
- Empirically-based models
 - Ward 1992, Lafortune model

© Kavita Bala, Computer Science, Cornell University

Phong Reflection Model

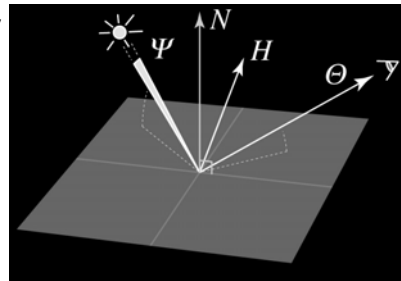
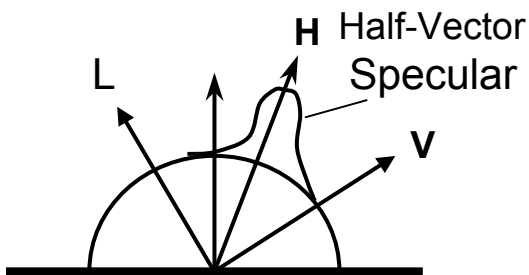


$$\text{Diffuse} = k_d (\bar{N} \cdot \bar{L}) \quad \text{Specular} = k_s (\bar{R} \cdot \bar{V})^n$$

$$f_r(\Theta \leftrightarrow \Psi) = k_s \frac{(R \cdot \Theta)^n}{(N \cdot \Psi)} + k_d$$

© Kavita Bala, Computer Science, Cornell University

The Blinn-Phong Model

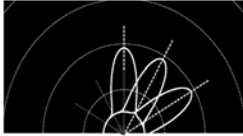


$$f_r(\Theta \leftrightarrow \Psi) = k_s \frac{(N \cdot H)^n}{(N \cdot \Psi)} + k_d$$

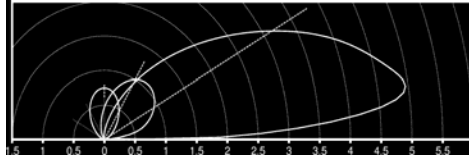
© Kavita Bala, Computer Science, Cornell University

Phong: Reality Check

Phong model



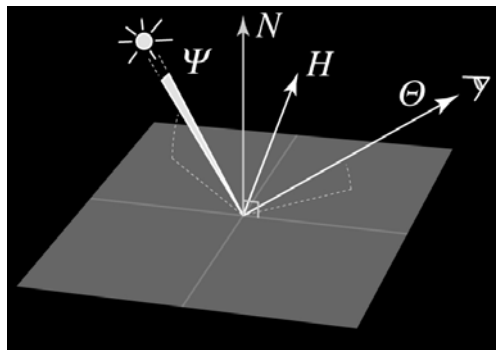
Physics-based model



- Computationally simple, visually pleasing
- Doesn't represent physical reality
 - Energy not conserved
 - Not reciprocal
 - Maximum always in specular direction

© Kavita Bala, Computer Science, Cornell University

The Modified Blinn-Phong Model



$$f_r(\Theta \leftrightarrow \Psi) = k_s (N \cdot H)^n + k_d$$

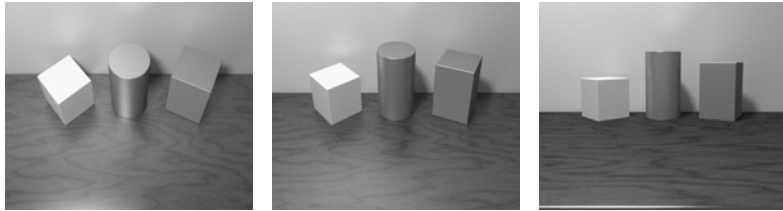
© Kavita Bala, Computer Science, Cornell University

Phong: Reality Check

Real photographs



Phong model

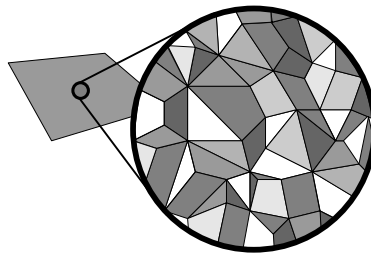


Therefore, physically-based models

© Kavita Bala, Computer Science, Cornell University

Cook-Torrance BRDF Model

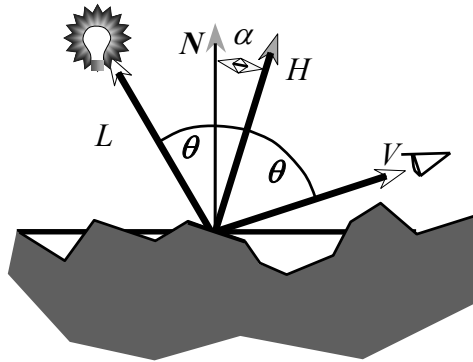
- A *microfacet* model
 - Surface modeled as random collection of planar facets
 - Incoming ray hits exactly one facet, at random
- Input: probability distribution of facet angle



© Kavita Bala, Computer Science, Cornell University

Facet Reflection

- H vector used to define facets that contribute



© Kavita Bala, Computer Science, Cornell University

Cook-Torrance BRDF Model

$$R_s = \frac{F \cdot DG}{\pi (N \cdot L)(N \cdot V)}$$

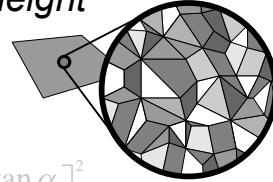
Fresnel Reflectance

- “Specular” term (really directional diffuse)
- Fresnel reflectance for smooth facet

© Kavita Bala, Computer Science, Cornell University

Facet Distribution

- D function describes distribution of H
- Formula due to Beckmann
 - derivation based on Gaussian height distribution

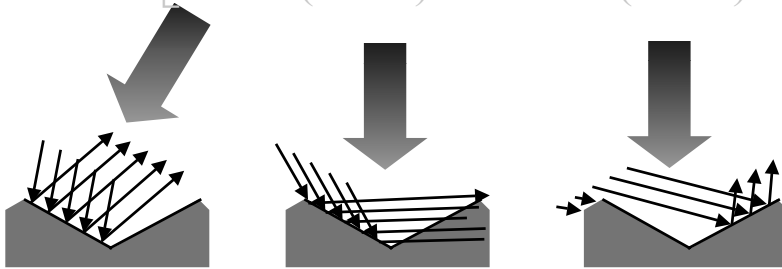


$$D = \frac{1}{m^2 \cos^4 \alpha} e^{-\left[\frac{\tan \alpha}{m}\right]^2}$$

© Kavita Bala, Computer Science, Cornell University

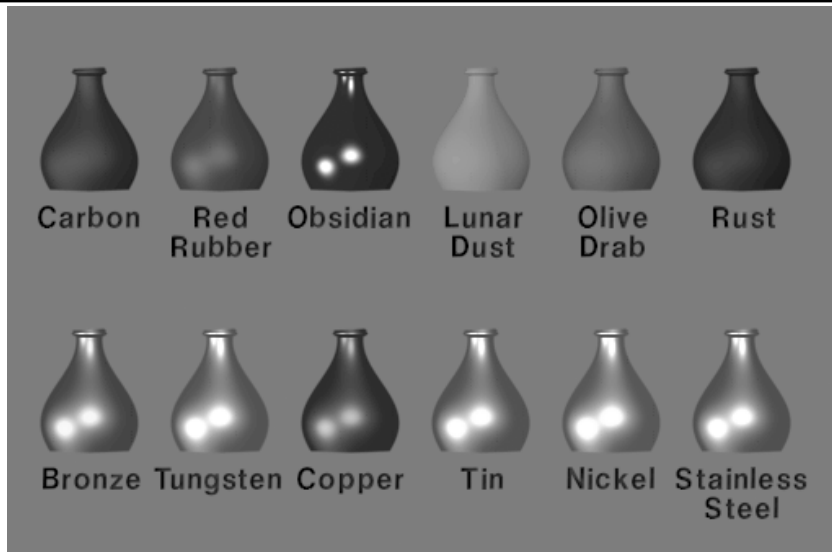
Masking and Shadowing

$$G = \min \left[1, \frac{2(N \cdot H)(N \cdot V)}{(V \cdot H)}, \frac{2(N \cdot H)(N \cdot L)}{(V \cdot H)} \right]$$



© Kavita Bala, Computer Science, Cornell University

Rob Cook's vases



Source: Cook, Torrance 1981

© Kavita Bala, Computer Science, Cornell University

Empirical BRDF Representation

- Generalized Phong model (Lafortune 1997)
- Used to represent:
 - Measured data
 - Wave optics reflectance model
- Features:
 - Efficient and compact
 - Easily added to rendering algorithms

© Kavita Bala, Computer Science, Cornell University

Ward Model

- Physically valid
 - Energy conserving
 - Satisfies reciprocity: $f_r(\Theta_i \rightarrow \Theta_r) = f_r(\Theta_r \rightarrow \Theta_i)$
- Based on empirical data
- Isotropic and anisotropic materials



© Kavita Bala, Computer Science, Cornell University

Ward Model: Isotropic

$$f_s = \rho_s \frac{1}{4\pi\alpha^2} \frac{\exp(-\frac{\tan^2 \theta_h}{\alpha^2})}{\sqrt{(\vec{N} \cdot \vec{V})(\vec{N} \cdot \vec{L})}}$$

- where,
 - α is surface roughness

© Kavita Bala, Computer Science, Cornell University

Ward Model: Anisotropic

$$f_s = \rho_s \frac{1}{4\pi\alpha_x\alpha_y} \sqrt{\frac{\vec{N} \cdot \vec{L}}{\vec{N} \cdot \vec{V}}} \exp\left(-2 \frac{\left(\frac{\vec{H} \cdot \hat{x}}{\alpha_x}\right)^2 + \left(\frac{\vec{H} \cdot \hat{y}}{\alpha_y}\right)^2}{1 + \vec{H} \cdot \vec{N}}\right)$$

- where,
 - α_x, α_y are surface roughness in \hat{x}, \hat{y}
 - \hat{x}, \hat{y} are mutually perpendicular to the normal