

Lecture 2: Radiosity

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Information

- Office Hours
 - Wed: 2-3 Upson 5142
- Web-page
- www.cs.cornell.edu/courses/cs665/2004fa/
 - Tentative schedule
 - Homeworks, lecture notes, will be on-line
 - Check for updates and announcements

Classic Ray Tracing

- Image-based
- Gathering approach
 - from the light sources (direct illumination)
 - from the reflected direction (perfect specular)
 - from the refracted direction (perfect specular)
- All other contributions are ignored!
 - Not a complete solution

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Whitted RT Assumptions

- Light Source: point light source
 - Hard shadows
 - Single shadow ray direction
- Material: Blinn-Phong model
 - Diffuse with specular peak
- Light Propagation
 - Occluding objects
 - Specular interreflections only
 - trace rays in mirror reflection direction only

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Other approaches

- Classic ray tracing:
 - Only perfect specular and perfect refraction/reflection
 - View-dependent
- Radiosity (1984)
 - Pure diffuse
 - View-independent
- Monte Carlo Ray Tracing (1986)
 - Global Illumination for any environment

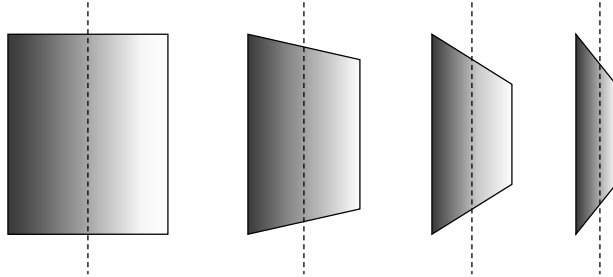
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Radiosity Advantages

- Physically based approach for diffuse environments
- Can model diffuse interactions, color bleeding, indirect lighting and penumbra (area light sources)
- Boundary element (finite element) problem
- Accounts for very high percentage of total energy transfer

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Key Idea #1: diffuse only

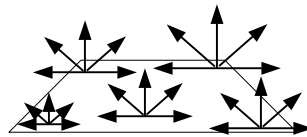


- Radiance independent of direction
- Surface looks the same from any viewpoint
- No specular reflections

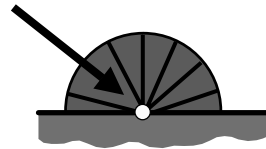
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Diffuse surfaces

- Diffuse emitter
 $L(x \rightarrow \Theta) = \text{constant over } \Theta$



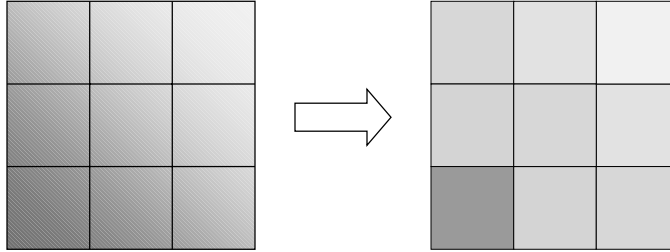
- Diffuse reflector
Reflectivity constant



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Key Idea #2: “constant” polygons

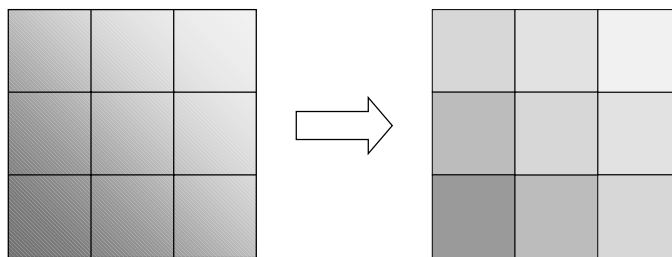
- Radiosity solution is an approximation, due to discretization of scene into patches



- Subdivide scene into small polygons

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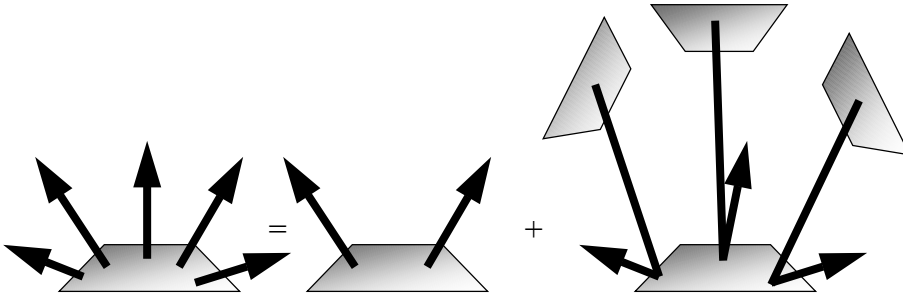
Constant radiance approximation



- Radiance is constant over a surface element
 $L(x) = \text{constant over } x$
- surface element i : $L(x) = L_i$

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Radiosity Equation



Emitted radiosity = self-emitted radiosity + received & reflected radiosity

$$Radiosity_i = Radiosity_{self,i} + \sum_{j=1}^N a_{j \rightarrow i} Radiosity_j$$

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Radiosity Equation

- Radiosity equation for each polygon i

$$Radiosity_1 = Radiosity_{self,1} + \sum_{j=1}^N a_{j \rightarrow 1} Radiosity_j$$

$$Radiosity_2 = Radiosity_{self,2} + \sum_{j=1}^N a_{j \rightarrow 2} Radiosity_j$$

...

$$Radiosity_N = Radiosity_{self,N} + \sum_{j=1}^N a_{j \rightarrow N} Radiosity_j$$

- N equations; N unknown variables

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Radiosity algorithm

- Subdivide the scene into small polygons
- Compute for each polygon a constant illumination value
- Choose a viewpoint, and display the visible polygons

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Radiosity algorithm

- Subdivide the scene in small polygons
- Compute for each polygon a constant illumination value
- Choose a viewpoint, and display the visible polygons
- Choose a new viewpoint
- ... and another
- ... and another

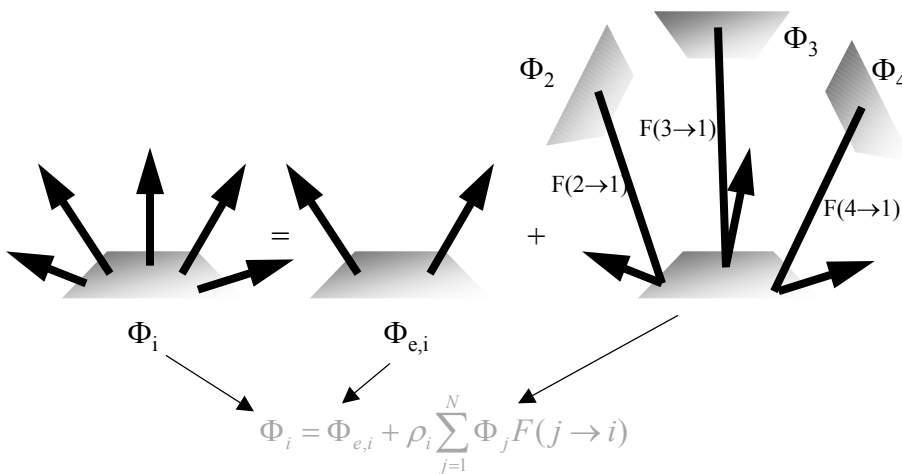
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Radiosity: Typical Image



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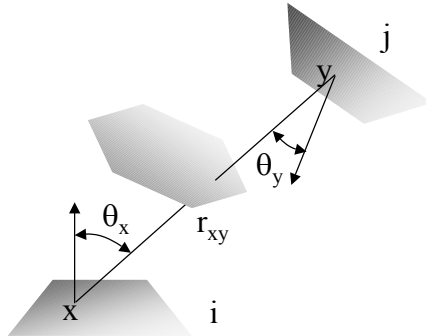
Energy Conservation Equation



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Compute Form Factors

$$F(j \rightarrow i) = \frac{1}{A_j} \iint_{A_i} \iint_{A_j} \frac{\cos \theta_x \cdot \cos \theta_y}{\pi \cdot r_{xy}^2} \cdot V(x, y) \cdot dA_y \cdot dA_x$$



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Form Factors Invariant

$$F(j \rightarrow i) = \frac{1}{A_j} \iint_{A_i} \iint_{A_j} \frac{\cos \theta_x \cdot \cos \theta_y}{\pi \cdot r_{xy}^2} \cdot V(x, y) \cdot dA_y \cdot dA_x$$

$$F(i \rightarrow j) = \frac{1}{A_i} \iint_{A_j} \iint_{A_i} \frac{\cos \theta_x \cdot \cos \theta_y}{\pi \cdot r_{xy}^2} \cdot V(x, y) \cdot dA_y \cdot dA_x$$

$$F(i \rightarrow j)A_i = F(j \rightarrow i)A_j$$

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Radiosity Equation

- Radiosity for each polygon i

$$\forall i: B_i = B_{e,i} + \rho_i \sum_{j=1}^N B_j F(i \rightarrow j)$$

- Linear system
 - B_i : radiosity of patch i (unknown)
 - $B_{e,i}$: emission of patch i (known)
 - ρ_i : reflectivity of patch i (known)
 - $F(i \rightarrow j)$: form-factor (coefficients of matrix)

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Linear System

$$\begin{bmatrix} 1 - \rho_1 F_{1 \rightarrow 1} & -\rho_1 F_{1 \rightarrow 2} & \dots & -\rho_1 F_{1 \rightarrow n} \\ -\rho_2 F_{2 \rightarrow 1} & 1 - \rho_2 F_{2 \rightarrow 2} & \dots & -\rho_2 F_{2 \rightarrow n} \\ \dots & \dots & \dots & \dots \\ -\rho_n F_{n \rightarrow 1} & -\rho_n F_{n \rightarrow 2} & \dots & 1 - \rho_n F_{n \rightarrow n} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \dots \\ B_n \end{bmatrix} = \begin{bmatrix} B_{e,1} \\ B_{e,2} \\ \dots \\ B_{e,n} \end{bmatrix}$$

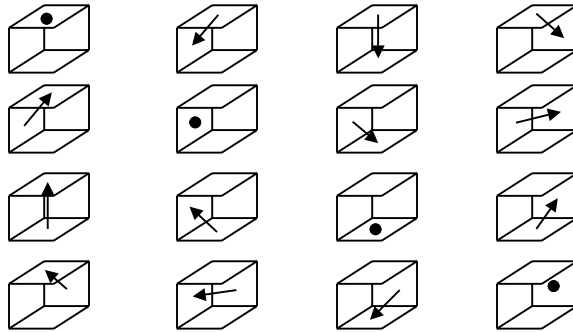
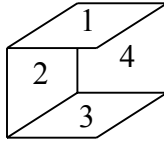
known

known

↓
unknown

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Linear System



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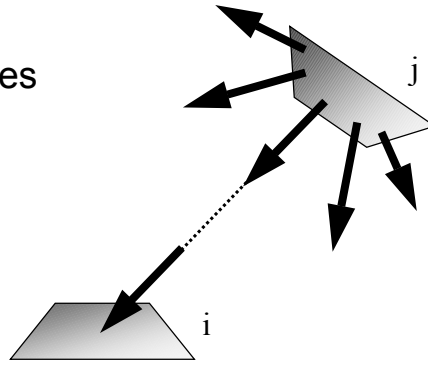
Radiosity Algorithm

- Subdivide scene in polygons
 - mesh that determines final solution
- Compute Form Factors
 - transfer of energy between polygons
- Solve linear system
 - results in power (color) per polygon
- Pick a viewpoint and display
 - loop

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Form Factor

- $F_{j \rightarrow i}$ = the fraction of power emitted by j, which is received by i
- Area
 - if i is smaller, it receives less power
- Orientation
 - if i faces j, it receives more power
- Distance
 - if i is further away, it receives less power



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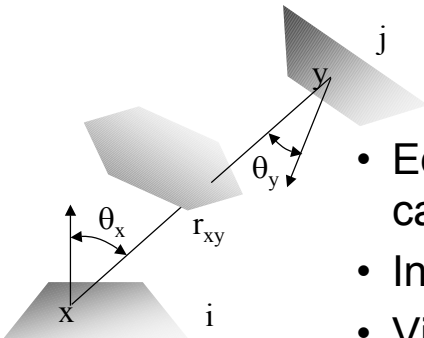
Form Factors - how to compute?

- Closed Form
 - Analytic
- Hemicube
- Monte-Carlo

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Form Factor – Analytical

$$F(j \rightarrow i) = \frac{1}{A_j} \iint_{A_i, A_j} \frac{\cos \theta_x \cdot \cos \theta_y}{\pi \cdot r_{xy}^2} \cdot V(x, y) \cdot dA_y \cdot dA_x$$

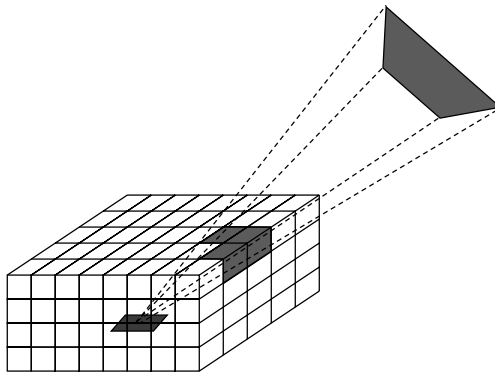


- Equations for special cases (polygons)
- In general hard problem
- Visibility makes it harder

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Form Factors - Hemicube

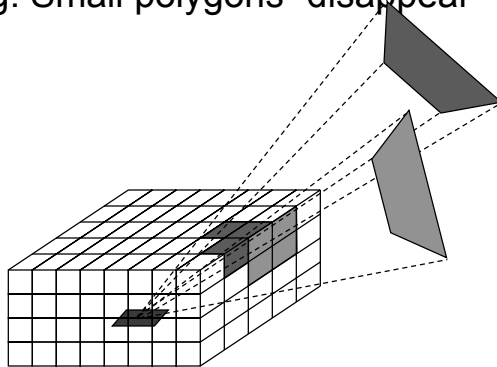
- Project patch on hemicube
- Add hemicube cells to compute form factor



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Form Factors - Hemicube

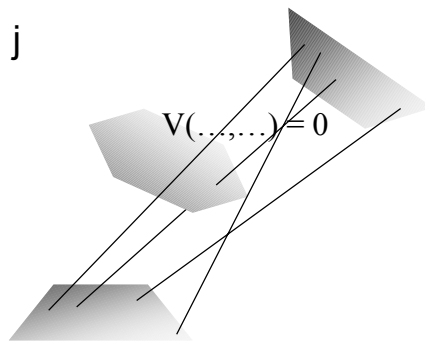
- Depth information per pixel evaluates visibility
- FFs for all polygons in scene
- Hardware rendering (Z-buffer)
- Severe aliasing: Small polygons “disappear”



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FF - Monte Carlo

- Generate point on patch i
- Generate point on patch j
- Evaluate integrand
- Compute average



$$\langle F(j \rightarrow i) \rangle = \frac{1}{N \cdot A_j} \sum_{k=1}^N \frac{\cos \theta_{x_k} \cdot \cos \theta_{y_k}}{p(x_k, y_k) \cdot \pi \cdot r_{x_k y_k}^2} \cdot V(x_k, y_k)$$

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Form Factors

- Visibility checks are most expensive operation
- FFs are usually computed when needed
 - computationally expensive
 - memory $O(N^2)$

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Radiosity Algorithm

- Subdivide scene in polygons
 - mesh that determines final solution
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 - transfer of energy between polygons
- Solve linear system
 - results in power (color) per polygon
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 - loop

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How To Solve Linear System

- Matrix Inversion
- Gathering methods
 - Jacobi iteration
 - Gauss-Seidel
- Shooting
 - Southwell iteration
 - Improved Southwell iteration

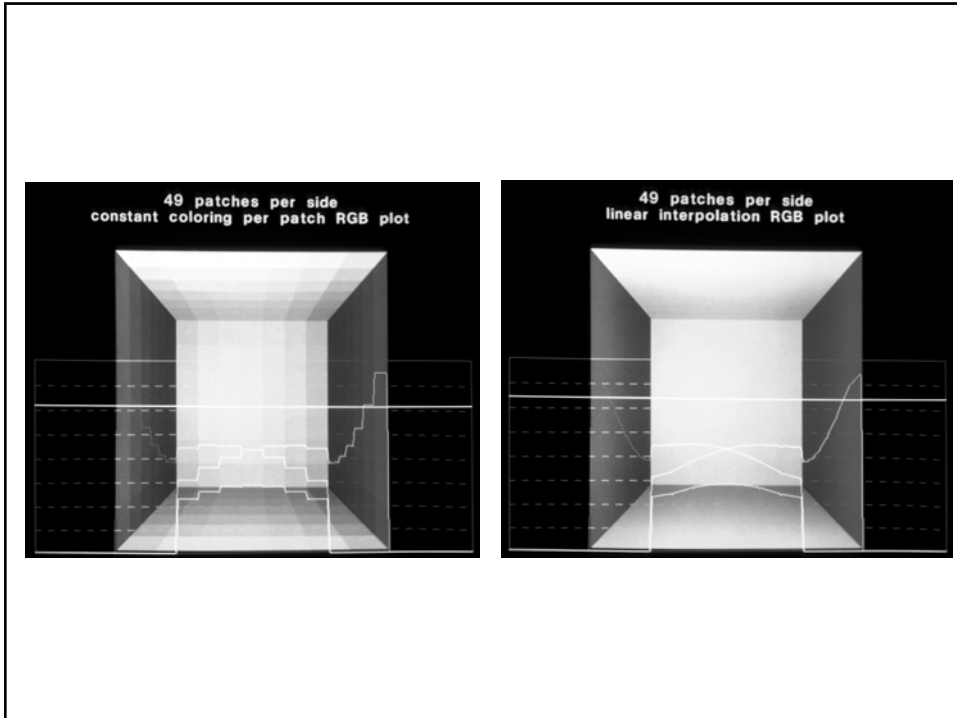
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Matrix Inversion

$$\begin{bmatrix} B_1 \\ B_2 \\ \dots \\ B_n \end{bmatrix} = \begin{bmatrix} 1 - \rho_1 F_{1 \rightarrow 1} & -\rho_1 F_{1 \rightarrow 2} & \dots & -\rho_1 F_{1 \rightarrow n} \\ -\rho_2 F_{2 \rightarrow 1} & 1 - \rho_2 F_{2 \rightarrow 2} & \dots & -\rho_2 F_{2 \rightarrow n} \\ \dots & \dots & \dots & \dots \\ -\rho_n F_{n \rightarrow 1} & -\rho_n F_{n \rightarrow 2} & \dots & 1 - \rho_n F_{n \rightarrow n} \end{bmatrix}^{-1} \begin{bmatrix} B_{e,1} \\ B_{e,2} \\ \dots \\ B_{e,n} \end{bmatrix}$$

$O(n^3)$

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Iterative approaches

- Jacobi iteration
- Start with initial guess for energy distribution (light sources)
- Update radiosity/power of all patches based on the previous guess

$$B_i = B_{e,i} + \rho_i \sum_{j=1}^N B_j F(i \rightarrow j)$$

↙
↘

new value
old values

- Repeat until converged

Jacobi

- For all patches i ($i=1\dots N$) : $B_i^{(0)} = B_{e,i}$
- while not converged:
 - for all patches i ($i=1\dots N$)

$$B_i^{(g)} = B_{e,i} + \rho_i \sum_{j=1}^N B_j^{(g-1)} F(i \rightarrow j)$$

update of 1 patch requires evaluation of N FFs

Improved Gathering

- Jacobi iteration only uses values of previous iterations to compute new values
- Gauss-Seidel iteration
 - New values used immediately
 - Slightly better convergence

Gauss-Seidel

- For all patches i ($i=1\dots N$) : $B_i^{(0)} = B_{e,i}$
- while not converged:
 - for all patches i ($i=1\dots N$)

$$B_i^{(g)} = B_{e,i} + \rho_i \sum_{j=1}^{i-1} B_j^{(g)} F(i \rightarrow j) + \rho_i \sum_{j=i}^N B_j^{(g-1)} F(i \rightarrow j)$$

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Example



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Progressive Radiosity

- Gathering: $O(n^2)$ /iteration
 - Still too slow
- Can use “shooting” as opposed to “gathering” approach
- 1-2% of all emitting and reflecting surfaces can account for very high percentage of energy

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Southwell Iteration

- “Shooting” method
- Start with initial guess for light distribution (light sources)
- Select patch and distribute its energy over all polygons

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Southwell Iteration (Wrong)

- For all patches i ($i=1..N$) :
 - $B_i^{(0)} = B_{e,i}$
- while not converged:
 - select shooting patch k with $B_k^{(g-1)} \neq 0$
 - for all patches i ($i=1..N$)

with n FF evaluations, n patches are updated!

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Southwell Iteration

- Keep record of “unshot” radiosity/energy per patch
- Repeat shooting of unshot energy until converged

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Southwell Iteration (Correct)

- For all patches i ($i=1..N$) :
 - $B_i^{(0)} = B_{e,i}$ $\Delta B_i^{(0)} = B_{e,i}$
- while not converged:
 - select shooting patch k with $\Delta B_k^{(g-1)} \neq 0$
 - for all patches i ($i=1..N$)
 - $\Delta B_k^{(g)} = 0$

with n FF evaluations, n patches are updated!

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Progressive Radiosity

- Solution time is fast: $O(n)$ for first results
- Can monotonically approach the complete diffuse radiosity solution

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Progressive Refinement

- Southwell selects shooting patches in no particular order
- Progressive refinement radiosity selects patch with largest unshot energy
- First image is generated fairly quickly!

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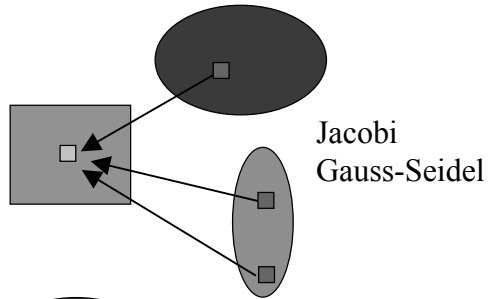
PR + Ambient term

- PR gives an estimate for each radiosity value that is smaller than the real value
- Estimate can be improved by using ambient term
 - Add all unshot energy
 - Distribute total unshot energy equally over all patches
- Solution has improved energy distribution

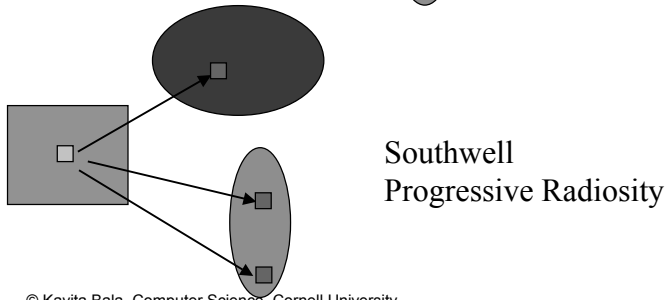
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Gathering vs. Shooting

- Gathering



- Shooting



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Comparison

Gauss-
Seidel



Southwell
+ sorting

Southwell



Southwell
+ sorting
+ ambient

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 - Loop over different viewpoints

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